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## Research article

# A symmetry theorem in two-phase heat conductors ${ }^{\dagger}$ 

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#### Abstract

We consider the Cauchy problem for the heat diffusion equation in the whole Euclidean space consisting of two media with different constant conductivities, where initially one medium has temperature 0 and the other has temperature 1 . Under the assumptions that one medium is bounded and the interface is of class $C^{2, \alpha}$, we show that if the interface is stationary isothermic, then it must be a sphere. The method of moving planes due to Serrin is directly utilized to prove the result.


Keywords: heat diffusion equation; two-phase heat conductors; Cauchy problem; stationary isothermic surface; method of moving planes; transmission conditions

## 1. Introduction

In the previous paper [7], we considered the Cauchy problem for the heat diffusion equation in the whole Euclidean space consisting of two media with different constant conductivities, where initially one medium has temperature 0 and the other has temperature 1 . There, the large time behavior, either stabilization to a constant or oscillation, of temperature was studied. The present paper deals with the case where one medium is bounded and the interface is of class $C^{2, \alpha}$, and introduces an overdetermined problem with the condition that the interface is stationary isothermic.

To be precise, let $\Omega$ consist of a finite number, say $m$, of bounded domains $\left\{\Omega_{j}\right\}$ in $\mathbb{R}^{N}$ with $N \geq 2$, where each $\partial \Omega_{j}$ is of class $C^{2, \alpha}$ for some $0<\alpha<1$ and $\bar{\Omega}_{i} \cap \bar{\Omega}_{j}=\emptyset$ if $i \neq j$. Denote by $\sigma=\sigma(x)(x \in$
$\mathbb{R}^{N}$ ) the conductivity distribution of the whole medium given by

$$
\sigma= \begin{cases}\sigma_{+} & \text {in } \Omega=\bigcup_{j=1}^{m} \Omega_{j},  \tag{1.1}\\ \sigma_{-} & \text {in } \mathbb{R}^{N} \backslash \Omega,\end{cases}
$$

where $\sigma_{-}, \sigma_{+}$are positive constants with $\sigma_{-} \neq \sigma_{+}$. The diffusion over such multiphase heat conductors has been dealt with also in [3,4,9-11].

We consider the unique bounded solution $u=u(x, t)$ of the Cauchy problem for the heat diffusion equation:

$$
\begin{equation*}
u_{t}=\operatorname{div}(\sigma \nabla u) \quad \text { in } \mathbb{R}^{N} \times(0,+\infty) \text { and } u=\mathcal{X}_{\Omega} \text { on } \mathbb{R}^{N} \times\{0\}, \tag{1.2}
\end{equation*}
$$

where $\mathcal{X}_{\Omega}$ denotes the characteristic function of the set $\Omega$. The maximum principle gives

$$
\begin{equation*}
0<u(x, t)<1 \text { for every }(x, t) \in \mathbb{R}^{N} \times(0,+\infty) . \tag{1.3}
\end{equation*}
$$

Our symmetry theorem is stated as follows.
Theorem 1.1. If there exists a function $a:(0,+\infty) \rightarrow(0,+\infty)$ satisfying

$$
\begin{equation*}
u(x, t)=a(t) \text { for every }(x, t) \in \partial \Omega \times(0,+\infty), \tag{1.4}
\end{equation*}
$$

then $\Omega$ must be a ball.
If $\partial \Omega$ is of class $C^{6}$, then Theorem 1.1 can be proved by the method employed in [3, Theorem 1.5 with the proof, pp. 335-341], where concentric balls are characterized. The proof there consists of four steps summarized as follows: (i) reduction of (1.2) to elliptic problems by the Laplace-Stieltjes transform $\lambda \int_{0}^{\infty} e^{-\lambda t} u(x, t) d t$ for all sufficiently large $\lambda>0$, (ii) construction of precise barriers based on the formal WKB approximation where the fourth derivatives of the distance function to $\partial \Omega$ together with the assumption (1.4) are used, (iii) showing that the mean curvature of $\partial \Omega$ is constant with the aid of the precise asymptotics as $\lambda \rightarrow \infty$ and the transmission conditions on the interface $\partial \Omega$, (iv) Alexandrov's soap bubble theorem [1] from which we conclude that $\partial \Omega$ must be a sphere.

The approach of the present paper is different from that in [3] and only requires $\partial \Omega$ to be of class $C^{2, \alpha}$ for some $\alpha>0$. Here the proof consists of two ingredients: (i) reduction to elliptic problems by the Laplace-Stieltjes transform $\lambda \int_{0}^{\infty} e^{-\lambda t} u(x, t) d t$ for some $\lambda$, for instance $\lambda=1$, (ii) the method of moving planes due to Serrin $[6,8,12,13]$ with the aid of the transmission conditions on $\partial \Omega$. To apply the method of moving planes, the solutions need to be of class $C^{2}$ up to the interface $\partial \Omega$ from each side, which is guaranteed if $\partial \Omega$ is of class $C^{2, \alpha}$.

## 2. Introducing a Laplace-Stieltjes transform

Let $u=u(x, t)$ be the unique bounded solution of (1.2) satisfying (1.4). We use the Gaussian bounds for the fundamental solutions of diffusion equations due to Aronson [2, Theorem 1, p. 891] (see also [5, p. 328]). Let $g=g(x, \xi, t)$ be the fundamental solution of $u_{t}=\operatorname{div}(\sigma \nabla u)$. Then there exist two positive constants $\lambda<\Lambda$ such that

$$
\begin{equation*}
\lambda t^{-\frac{N}{2}} e^{-\frac{|x-\xi|^{2}}{t t}} \leq g(x, \xi, t) \leq \Lambda t^{-\frac{N}{2}} e^{-\frac{|x-\xi|^{2}}{\Lambda t}} \tag{2.1}
\end{equation*}
$$

for all $(x, t),(\xi, t) \in \mathbb{R}^{N} \times(0,+\infty)$. Note that $u$ is represented as

$$
\begin{equation*}
u(x, t)=\int_{\Omega} g(x, \xi, t) d \xi \text { for }(x, t) \in \mathbb{R}^{N} \times(0,+\infty) . \tag{2.2}
\end{equation*}
$$

Define the function $v=v(x)$ by

$$
\begin{equation*}
v(x)=\int_{0}^{\infty} e^{-t} u(x, t) d t \text { for } x \in \mathbb{R}^{N} \tag{2.3}
\end{equation*}
$$

With the function $a$ in (1.4), we set $a^{*}=\int_{0}^{\infty} e^{-t} a(t) d t$. Then, (1.3) yields that $0<a^{*}<1$. Set

$$
\begin{equation*}
v^{+}=v \text { for } x \in \bar{\Omega} \quad \text { and } \quad v^{-}=v \text { for } x \in \mathbb{R}^{N} \backslash \Omega . \tag{2.4}
\end{equation*}
$$

Then we observe that

$$
\begin{array}{ll}
a^{*}<v^{+}<1 & \text { and } \\
0<v^{-}<\sigma^{*} \Delta v^{+}+v^{+}=1 \text { in } \Omega, \\
\text { and } & -\sigma_{-} \Delta v^{-}+v^{-}=0 \text { in } \mathbb{R}^{N} \backslash \bar{\Omega}, \\
v^{+}=v^{-}=a^{*} & \text { and }  \tag{2.8}\\
\sigma_{+} \frac{\partial v^{+}}{\partial n}=\sigma_{-} \frac{\partial v^{-}}{\partial n} \text { on } \partial \Omega, \\
\lim _{|x| \rightarrow \infty} v^{-}(x)=0 .
\end{array}
$$

Here, $n$ denotes the outward unit normal vector to $\partial \Omega$, the inequalities in (2.5) and (2.6) follow from the maximum principle, (2.7) expresses the transmission conditions on the interface $\partial \Omega$, and (2.8) follows from (2.1) and (2.2).

## 3. Proof of Theorem 1.1

Let us apply directly the method of moving planes due to Serrin $[6,8,12,13]$ to our problem in order to show that $\Omega$ must be a ball. The point is to apply the method to both the interior $\Omega$ and the exterior $\mathbb{R}^{N} \backslash \bar{\Omega}$ at the same time. For the method of moving planes for $\mathbb{R}^{N} \backslash \bar{\Omega}$, we refer to $[8,12]$. In this procedure, the supposition that $\Omega$ is not symmetric will lead us to the contradiction that the transmission conditions (2.7) do not hold.

Let $\gamma$ be a unit vector in $\mathbb{R}^{N}, \lambda \in \mathbb{R}$, and let $\pi_{\lambda}$ be the hyperplane $x \cdot \gamma=\lambda$. For large $\lambda, \pi_{\lambda}$ is disjoint from $\bar{\Omega}$; as $\lambda$ decreases, $\pi_{\lambda}$ intersects $\bar{\Omega}$ and cuts off from $\Omega$ an open cap $\Omega_{\lambda}=\Omega \cap\left\{x \in \mathbb{R}^{N}: x \cdot \gamma>\lambda\right\}$.

Denote by $\Omega^{\lambda}$ the reflection of $\Omega_{\lambda}$ with respect to the plane $\pi_{\lambda}$. Then, $\Omega^{\lambda}$ is contained in $\Omega$ at the beginning, and remains in $\Omega$ until one of the following events occurs:
(i) $\Omega^{\lambda}$ becomes internally tangent to $\partial \Omega$ at some point $p \in \partial \Omega \backslash \pi_{\lambda}$;
(ii) $\pi_{\lambda}$ reaches a position where it is orthogonal to $\partial \Omega$ at some point $q \in \partial \Omega \cap \pi_{\lambda}$ and the direction $\gamma$ is not tangential to $\partial \Omega$ at every point on $\partial \Omega \cap\left\{x \in \mathbb{R}^{N}: x \cdot \gamma>\lambda\right\}$.
Let $\lambda_{*}$ denote the value of $\lambda$ at which either (i) or (ii) occurs. We claim that $\Omega$ is symmetric with respect to $\pi_{\lambda_{\varepsilon}}$.

Suppose that $\Omega$ is not symmetric with respect to $\pi_{\lambda_{*}}$. Denote by $D$ the reflection of $\left(\mathbb{R}^{N} \backslash \bar{\Omega}\right) \cap\{x \in$ $\left.\mathbb{R}^{N}: x \cdot \gamma>\lambda_{*}\right\}$ with respect to $\pi_{\lambda_{*}}$. Let $\Sigma$ be the connected component of $\left(\mathbb{R}^{N} \backslash \bar{\Omega}\right) \cap\left\{x \in \mathbb{R}^{N}: x \cdot \gamma<\lambda_{*}\right\}$
whose boundary contains the points $p$ and $q$ in the respective cases (i) and (ii). Since $\Omega^{\lambda_{*}} \subset \Omega$, we notice that

$$
\Sigma \subset\left(\mathbb{R}^{N} \backslash \bar{\Omega}\right) \cap\left\{x \in \mathbb{R}^{N}: x \cdot \gamma<\lambda_{*}\right\} \subset D .
$$

Let $x^{\lambda_{*}}$ denote the reflection of a point $x \in \mathbb{R}^{N}$ with respect to $\pi_{\lambda_{*}}$, namely,

$$
\begin{equation*}
x^{\lambda_{*}}=x+2\left[\lambda_{*}-(x \cdot \gamma)\right] \gamma \tag{3.1}
\end{equation*}
$$

Using the functions $v^{ \pm}$defined in (2.4), we introduce the functions $w^{ \pm}=w^{ \pm}(x)$ by

$$
\begin{array}{ll}
w^{+}(x):=v^{+}(x)-v^{+}\left(x^{\lambda_{*}}\right) & \text { for } x \in \overline{\Omega^{\lambda_{*}}},  \tag{3.2}\\
w^{-}(x):=v^{-}(x)-v^{-}\left(x^{\lambda_{*}}\right) & \text { for } x \in \bar{\Sigma} .
\end{array}
$$

It then follows from (2.5)-(2.8) that

$$
\begin{array}{cl}
-\sigma_{+} \Delta w^{+}+w^{+}=0 \text { in } \Omega^{\lambda_{*}} & \text { and } w^{+} \geq 0 \text { on } \partial \Omega^{\lambda_{*}}, \\
-\sigma_{-} \Delta w^{-}+w^{-}=0 \text { in } \Sigma & \text { and } w^{-} \geq 0 \text { on } \partial \Sigma, \tag{3.4}
\end{array}
$$

and hence by the maximum principle

$$
\begin{equation*}
w^{+} \geq 0 \text { in } \Omega^{\lambda_{*}} \text { and } w^{-}>0 \text { in } \Sigma . \tag{3.5}
\end{equation*}
$$

Note that $w^{+}$can be zero in $\Omega^{\lambda_{*}}$ since some connected component $\Omega_{j}$ of $\Omega$ can be symmetric with respect to $\pi_{\lambda_{*}}$ and, in such a case, $w^{+} \equiv 0$ in $\Omega_{j}$. But $w^{-}$is strictly positive in $\Sigma$ since $\Omega$ is not symmetric with respect to $\pi_{\lambda_{*}}$.

Let us first consider the case (i). The first equality in (2.7) yields that $w^{+}(p)=w^{-}(p)=0$. Then, it follows from (3.5) and Hopf's boundary point lemma that

$$
\begin{equation*}
\frac{\partial w^{+}}{\partial n}(p) \leq 0<\frac{\partial w^{-}}{\partial n}(p), \tag{3.6}
\end{equation*}
$$

where we used the fact that $n$ is the outward unit normal vector to $\partial \Omega$ as well as the inward unit normal vector to $\partial \Sigma$. It thus follows from the definition (3.2) of $w^{ \pm}$that

$$
\left.\frac{\partial v^{+}(x)}{\partial n}\right|_{x=p} \leq\left.\frac{\partial\left(v^{+}\left(x^{\lambda_{*}}\right)\right)}{\partial n}\right|_{x=p} \quad \text { and }\left.\quad \frac{\partial v^{-}(x)}{\partial n}\right|_{x=p}>\left.\frac{\partial\left(v^{-}\left(x^{\lambda_{*}}\right)\right)}{\partial n}\right|_{x=p} .
$$

Reflection symmetry with respect to the plane $\pi_{\lambda_{*}}$ yields that

$$
\begin{equation*}
\left.\frac{\partial\left(v^{ \pm}\left(x^{\lambda_{*}}\right)\right)}{\partial n}\right|_{x=p}=\frac{\partial v^{ \pm}}{\partial n}\left(p^{\lambda_{*}}\right) . \tag{3.7}
\end{equation*}
$$

Indeed, we observe that

$$
n(p) \cdot \gamma=-n\left(p^{\lambda_{*}}\right) \cdot \gamma \text { and } n(p)-(n(p) \cdot \gamma) \gamma=n\left(p^{\lambda_{*}}\right)-\left(n\left(p^{\lambda_{*}}\right) \cdot \gamma\right) \gamma,
$$

and by using (3.1), we see that

$$
\nabla\left(v^{ \pm}\left(x^{\lambda_{*}}\right)\right)=\left(\nabla v^{ \pm}\right)\left(x^{\lambda_{*}}\right)-2\left(\left(\nabla v^{ \pm}\right)\left(x^{\lambda_{*}}\right) \cdot \gamma\right) \gamma .
$$

Then, combing these equalities yields (3.7). It thus follows that

$$
\begin{equation*}
\frac{\partial v^{+}}{\partial n}(p) \leq \frac{\partial v^{+}}{\partial n}\left(p^{\lambda_{*}}\right) \quad \text { and } \quad \frac{\partial v^{-}}{\partial n}(p)>\frac{\partial v^{-}}{\partial n}\left(p^{\lambda_{*}}\right) . \tag{3.8}
\end{equation*}
$$

On the other hand, the second equality in (2.7) shows that

$$
\sigma_{+} \frac{\partial v^{+}}{\partial n}(p)=\sigma_{-} \frac{\partial v^{-}}{\partial n}(p) \quad \text { and } \quad \sigma_{+} \frac{\partial \nu^{+}}{\partial n}\left(p^{\lambda_{*}}\right)=\sigma_{-} \frac{\partial v^{-}}{\partial n}\left(p^{\lambda_{*}}\right)
$$

which contradict (3.8).
Let us proceed to the case (ii). As in [13], by a translation and a rotation of coordinates, we may assume:

$$
\gamma=(1,0, \ldots, 0), \quad q=0, \quad \lambda_{*}=0 \text { and } n(q)=(0, \ldots, 0,1) .
$$

Since $\partial \Omega$ is of class $C^{2}$, there exists a $C^{2}$ function $\varphi: \mathbb{R}^{N-1} \rightarrow \mathbb{R}$ such that in a neighborhood of $q=0$, $\partial \Omega$ is represented as a graph $x_{N}=\varphi(\hat{x})$ where $\hat{x}=\left(x_{1}, \ldots, x_{N-1}\right) \in \mathbb{R}^{N-1}$, where

$$
\varphi(0)=0, \quad \nabla \varphi(0)=0, \quad \text { and } \quad n=\frac{1}{\sqrt{1+|\nabla \varphi|^{2}}}(-\nabla \varphi, 1)
$$

Since the event (ii) occurs at $\lambda=0$, we observe that the function $\frac{\partial \varphi}{\partial x_{1}}\left(0, x_{2}, \ldots, x_{N-1}\right)$ achieves its local maximum 0 at $\left(x_{2}, \ldots, x_{N-1}\right)=0 \in \mathbb{R}^{N-2}$, and hence

$$
\begin{equation*}
\frac{\partial^{2} \varphi}{\partial x_{1} \partial x_{j}}(0)=0 \text { for } j=2, \ldots, N-1 \tag{3.9}
\end{equation*}
$$

Notice that

$$
\begin{equation*}
w^{ \pm}(x)=v^{ \pm}\left(x_{1}, x_{2}, \ldots, x_{N}\right)-v^{ \pm}\left(-x_{1}, x_{2}, \ldots, x_{N}\right), \tag{3.10}
\end{equation*}
$$

since $x^{\lambda_{*}}=\left(-x_{1}, x_{2}, \ldots, x_{N}\right)$.
The equalities (2.7) at $(\hat{x}, \varphi(\hat{x})$ ) in a neighborhood of $q=0$ are read as

$$
\begin{align*}
& v^{ \pm}=a^{*},  \tag{3.11}\\
& \sigma_{+}\left(-\sum_{k=1}^{N-1} \frac{\partial \varphi}{\partial x_{k}} \frac{\partial v^{+}}{\partial x_{k}}+\frac{\partial v^{+}}{\partial x_{N}}\right)=\sigma_{-}\left(-\sum_{k=1}^{N-1} \frac{\partial \varphi}{\partial x_{k}} \frac{\partial v^{-}}{\partial x_{k}}+\frac{\partial v^{-}}{\partial x_{N}}\right) . \tag{3.12}
\end{align*}
$$

Differentiating (3.11) in $x_{i}$ for $i=1, \ldots, N-1$ yields that at $(\hat{x}, \varphi(\hat{x})$ )

$$
\begin{equation*}
\frac{\partial \nu^{ \pm}}{\partial x_{i}}+\frac{\partial \nu^{ \pm}}{\partial x_{N}} \frac{\partial \varphi}{\partial x_{i}}=0 . \tag{3.13}
\end{equation*}
$$

Then, differentiating (3.13) in $x_{j}$ for $j=1, \ldots, N-1$ yields that at $(\hat{x}, \varphi(\hat{x}))$

$$
\begin{equation*}
\frac{\partial^{2} v^{ \pm}}{\partial x_{j} \partial x_{i}}+\frac{\partial^{2} v^{ \pm}}{\partial x_{N} \partial x_{i}} \frac{\partial \varphi}{\partial x_{j}}+\frac{\partial^{2} v^{ \pm}}{\partial x_{j} \partial x_{N}} \frac{\partial \varphi}{\partial x_{i}}+\frac{\partial^{2} v^{ \pm}}{\partial x_{N}^{2}} \frac{\partial \varphi}{\partial x_{i}} \frac{\partial \varphi}{\partial x_{j}}+\frac{\partial v^{ \pm}}{\partial x_{N}} \frac{\partial^{2} \varphi}{\partial x_{j} \partial x_{i}}=0 . \tag{3.14}
\end{equation*}
$$

By letting $\hat{x}=0$ in these equalities, we obtain from (3.9) that

$$
\begin{equation*}
\frac{\partial v^{ \pm}}{\partial x_{i}}(0)=\frac{\partial^{2} v^{ \pm}}{\partial x_{1} \partial x_{j}}(0)=0 \text { for } i=1, \ldots, N-1 \text { and } j=2, \ldots, N-1 . \tag{3.15}
\end{equation*}
$$

Next, differentiating (3.12) in $x_{i}$ for $i=1, \ldots, N-1$ and letting $\hat{x}=0$ give

$$
\begin{equation*}
\sigma_{+} \frac{\partial^{2} v^{+}}{\partial x_{i} \partial x_{N}}(0)=\sigma_{-} \frac{\partial^{2} v^{-}}{\partial x_{i} \partial x_{N}}(0) \text { for } i=1, \ldots, N-1 . \tag{3.16}
\end{equation*}
$$

Since the functions $w^{ \pm}$are expressed as (3.10), with the aid of (3.15) we have that

$$
\begin{equation*}
w^{ \pm}(0)=\frac{\partial w^{ \pm}}{\partial x_{j}}(0)=\frac{\partial^{2} w^{ \pm}}{\partial x_{1} \partial x_{j}}(0)=0 \text { for } j=1, \ldots, N-1 . \tag{3.17}
\end{equation*}
$$

The relations (3.3)-(3.5) enable us to apply Serrin's corner point lemma (see [6, Lemma S, p. 214] or [8, Serrin's Corner Lemma, p. 393]) to show that

$$
\begin{equation*}
\frac{\partial^{2} w^{+}}{\partial s_{+}^{2}}(0) \geq 0 \text { and } \frac{\partial^{2} w^{-}}{\partial s_{-}^{2}}(0)>0 \text { with } s_{ \pm}=-\gamma \mp n=(-1,0, \ldots, 0, \mp 1), \tag{3.18}
\end{equation*}
$$

where $\frac{\partial^{2} w^{ \pm}}{\partial s_{ \pm}^{2}}$ denotes the second derivative of $w^{ \pm}$in the direction of $s_{ \pm}$. Note that each of the directions $s_{ \pm}$respectively enters $\Omega^{\lambda_{*}}, \Sigma$, transversally to both of the hypersurfaces $\partial \Omega$ and $\pi_{\lambda_{\star}}$. Thus, we have from (3.10) and (3.17) that

$$
\begin{equation*}
\frac{\partial^{2} w^{ \pm}}{\partial s_{ \pm}^{2}}(0)= \pm 2 \frac{\partial^{2} w^{ \pm}}{\partial x_{1} \partial x_{N}}(0)= \pm 4 \frac{\partial^{2} v^{ \pm}}{\partial x_{1} \partial x_{N}}(0) . \tag{3.19}
\end{equation*}
$$

It then follows from (3.18) that

$$
\begin{equation*}
\frac{\partial^{2} v^{-}}{\partial x_{1} \partial x_{N}}(0)<0 \leq \frac{\partial^{2} v^{+}}{\partial x_{1} \partial x_{N}}(0), \tag{3.20}
\end{equation*}
$$

which contradicts (3.16) with $i=1$. Thus $\Omega$ is symmetric with respect to $\pi_{\lambda_{\star}}$. Since the unit vector $\gamma$ is arbitrary, $\Omega$ must be a ball and Theorem 1.1 is proved.

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## Conflict of interest

The authors declare no conflict of interest.

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