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## Theory article

# Traveling waves for a nonlocal dispersal SIRS epidemic model with age structure

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**Abstract:** This paper focuses on a SIRS infectious model of nonlocal dispersal adopted with age structure. We primarily investigate the existence and nonexistence of traveling wave solutions connecting the disease-free equilibrium state and the endemic equilibrium state. To be more precise, we obtain the existence of traveling wave solutions by constructing suitable upper and lower solutions and then applying Schauder's fixed point theorem when  $R_0 > 1$  and  $c > c^*$ . In addition, we prove the nonexistence of traveling wave solutions by applying the Laplace transform for  $R_0 > 1$  and  $0 < c < c^*$ .

**Keywords:** nonlocal dispersal; age structure; traveling waves; SIRS model; Laplace transform **Mathematics Subject Classification:** 35K57, 92D30

## 1. Introduction

Population dynamic models with age structure have a long history from articles of Lotka [16] in 1907 and Sharp and Lotka [24] in 1911. The first nonlinear age-structured model was proposed by Gurtin and MacCamy [18] in 1974. The theory of traveling wave solutions of reaction-diffusion systems has attracted much attention due to its significant nature in biology, chemistry, epidemiology and physics. Ducrot and Magal [3] researched the existence of traveling wave solutions for infectionage structured model with local diffusion by the methods of upper-lower solutions and Schauder's fixed point theorem. More recently, the traveling wave solutions of age-structured models received a lot of interest in the literature and we refer to [3–5, 26, 29] for more results about this topic.

The article is devoted to the study of traveling wave solutions of the nonlocal dispersal SIRS

epidemic model with age structure

$$\begin{cases} \frac{\partial}{\partial t}S(t,x) = d[J * S(t,x) - S(t,x)] - S(t,x) \int_{0}^{A} \beta(a)i(t,a,x)da + \delta R(t,x), \\ \frac{\partial}{\partial t}i(t,a,x) + \frac{\partial}{\partial a}i(t,a,x) = d[J * i(t,a,x) - i(t,a,x)] - \gamma i(t,a,x), \\ \frac{\partial}{\partial t}R(t,x) = d[J * R(t,x) - R(t,x)] + \gamma \int_{0}^{A}i(t,a,x)da - \delta R(t,x), \\ i(t,0,x) = S(t,x) \int_{0}^{A} \beta(a)i(t,a,x)da, \end{cases}$$
(1.1)

where  $(t, a, x) \in \mathbb{D} \triangleq \mathbb{R}_+ \times (0, A] \times \mathbb{R}$  and

$$(J * S - S)(t, x) \triangleq \int_{\mathbb{R}} J(x - y)S(t, y)dy - S(t, x),$$
$$(J * i - i)(t, a, x) \triangleq \int_{\mathbb{R}} J(x - y)i(t, a, y)dy - i(t, a, x),$$
$$(J * R - R)(t, x) \triangleq \int_{\mathbb{R}} J(x - y)R(t, y)dy - R(t, x).$$

S(t, x) and R(t, x) represent the densities of susceptible and removed individuals located at time t and position x and i(t, a, x) represents the density of infected individuals located at time t and location x with age a. And  $a \ge 0$  is the time since individuals were infected. Based on the actual situation, we assume that the age of infection is a constant.  $A \in (0, +\infty)$  means the maximum age of infection. Therefore, we assume that the maximum infection age A is a sufficiently large constant and i(t, A, x) = 0 throughout this paper. The parameter d > 0 represents the diffusion rate of individuals. The function  $\beta(a)$  denotes the infection age-specific transmission rate.  $\gamma > 0$  is the recovery rate of the infected individuals and  $\delta > 0$  is the loss of immunity rate. Since there are no birth or death rates in this model,  $N(t, x) = S(t, x) + \int_0^A i(t, a, x)da + R(t, x)$  is a constant for all  $t \ge 0$ . Therefore, we assume that the initial value of (1.1) is  $S(0, x) + \int_0^A i(0, a, x)da + R(0, x) = S_0$ . And in this whole paper we assume  $\delta > \gamma$  and we mainly apply this assumption in Lemma 3.3. Moreover, J(x - y) denotes the probability of jumping from position y to position x and J \* S(t, x) denotes the total number of susceptible individuals located at time t, moving from the whole space to position x. In this paper, we give the following assumptions.

(A1)  $J \in C^1(\mathbb{R}), J(x) = J(-x) \ge 0, \int_{\mathbb{R}} J(x) dx = 1 \text{ and } J \text{ is compactly supported.}$ 

(A2) The map  $a \rightarrow \beta(a)$  is almost everywhere bounded and belongs to  $L^{\infty}(0, A]$ .

Kermack and McKendrick [14] first proposed a compartmental model to describe the spread of infectious diseases in 1927. Since then, the SIR epidemic model and its various adaptations have been widely studied in pathology [22, 26, 30, 32, 34]. In epidemiology, traveling wave solutions have attracted a great deal of attention, which denote propagation through space at a constant velocity. In order to control and prevent diseases, it is crucial to determine whether traveling wave solutions exist. Therefore, many studies utilize spatially and temporally correlated models to investigate the existence of traveling wave solutions [15, 21, 29, 31, 33].

Hosono and Ilyas [7] investigated the reaction-diffusion equation with the nonlinear reaction term. They verified the existence of a noncritical traveling wave solution. However, it is worth mentioning that the model involves the classical Laplacian diffusion in [7], which is also called the local diffusion. The local diffusion denotes that a population at position x will only be affected by variations in the population near position x, which is deficient in describing diffusion [1, 6, 10, 12, 17, 21]. To overcome the limitations of diffusion of individuals, the Laplacian operator can be replaced by the nonlocal diffusion J \* u - u. Traveling wave solutions of infectious disease models with nonlocal diffusion terms have drawn great attention in recent years. For example, Yang et al. [33] studied the existence and nonexistence of traveling wave solutions in a Kermack-McKendrick epidemic model with nonlocal diffusion. They established a non-empty closed convex cone on a bounded closed interval and constructed appropriate upper and lower solutions and then obtained a nonlinear operator of an ordinary differential system. By applying Schauder's fixed point theorem, they proved the existence of nontrivial traveling wave solutions. Furthermore, Yang et al. [31, 32] also investigated the traveling wave solutions of the SIR epidemic model with critical wave speed. After that, Ma and Yuan [17] studied the traveling wave solutions of the nonlocal dispersal SIRS model with spatio-temporal delay. Qiao et al. [21] researched the traveling wave solutions of the nonlocal dispersal SEIR model with standard incidence.

In addition, age is one of the important features in describing epidemics due to the fact that individuals of different ages may have different survivability and behaviors in their natural conditions. For example, hand-foot-mouth disease, chickenpox, measles, and influenza are all susceptible to occur in childhood. Novel coronavirus infections are universally susceptible to the population and can occur in all age groups, but are less common in children under three years of age. disease is mainly concentrated in older people over the age of sixty-five and the virus is easily exacerbated. Therefore, age structure is a significant factor in studying the epidemic patterns of infectious diseases. In recent years, lots of age-structure models have been proposed in the epidemic spread (see [2,8,9,13,19,20,29]). For instance, Ducrot et al. [5] studied the existence of traveling wave solutions for multigroup age-structure models. At the same time, Ducrot and Magal [3] researched the existence of traveling wave solutions for the infection-age structured model with diffusion. In addition, Ducrot and Magal [4] also proposed the SI infectious disease model with external supplies and age structure. And age is the time since the individuals were infected. They proved the existence of traveling wave solutions by constructing suitable upper and lower solutions and applying Schauder's Meanwhile, they studied the convergence behavior at positive infinity by fixed point theorem. constructing a suitable Lyapunov functional. In addition, Tian and Guo [26] obtained the existence of traveling wave solutions of nonlocal dispersal Fisher-KPP model with age structure. In recent years, Kang and Ruan [11] have proposed an age-structure SIS infectious disease model with nonlocal diffusion

$$\begin{cases} \left(\frac{\partial}{\partial t} + \frac{\partial}{\partial a}\right) S(t, a, x) = d[\mathcal{L}S](t, a, x) - (\lambda(t, a, x) + \mu(a, x)) S(t, a, x) + \gamma(a, x)I(t, a, x), \\ \left(\frac{\partial}{\partial t} + \frac{\partial}{\partial a}\right) I(t, a, x) = d[\mathcal{L}I](t, a, x) + \lambda(t, a, x)S(t, a, x) - (\mu(a, x) + \gamma(a, x))I(t, a, x), \\ S(t, 0, x) = \int_{0}^{a^{+}} \int_{\Omega} \beta(a, x, y)S(t, a, y) dy da, t > 0, \end{cases}$$
(1.2)

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with

$$I(t, 0, x) = 0$$
,  $S(0, a, x) = S_0(a, x)$ ,  $I(0, a, x) = I_0(a, x)$ ,

where  $a \ge 0, t \ge 0, x \in \Omega \subset \mathbb{R}^N$  and the nonlocal operator  $\mathcal{L}$  is defined by

$$[\mathcal{L}u](t,a,x) := (J * u - u)(t,a,x) = \int_{\Omega} J(x-y)u(t,a,y)dy - u(t,a,x).$$

And  $\mu(a, x)$  and  $\gamma(a, x)$  represent the mortality and recovery rates, respectively, for individuals of age *a* at location *x*.  $\lambda(t, a, x)$  is the infectivity of infected individuals to susceptible individuals of age *a* at time *t* in position *x*.  $\beta(a, x, y)$  indicates the birth rate of individuals of age *a* on position *y* giving birth to newborns at position *x*. They prove the existence of traveling wave solutions by constructing upper and lower solutions in [11]. We can refer to [15, 22, 23, 25, 28, 34] for the relevant conclusions on the research of traveling wave solutions for many infectious disease models. As far as we know, there are few researches on the traveling wave solutions of epidemic models with age structure [4, 29].

This paper is structured as follows. In Section 2, we give some key preliminaries of this paper. Then, we establish the existence of traveling wave solutions for  $c > c^*$  in Section 3. Section 4 obtains the nonexistence of traveling wave solutions for  $0 < c < c^*$  by using the Laplace transform. We draw the conclusions in Section 5.

### 2. Preliminaries

In this section, we present some preliminaries and the characteristic equation.

Let  $N(t, x) = S(t, x) + \int_0^A i(t, a, x)da + R(t, x)$ . The system (1.1) can be rewritten as the following system:

$$\begin{cases} \frac{\partial}{\partial t}N(t,x) = d[J*N(t,x) - N(t,x)],\\ \frac{\partial}{\partial t}i(t,a,x) + \frac{\partial}{\partial a}i(t,a,x) = d[J*i(t,a,x) - i(t,a,x)] - \gamma i(t,a,x),\\ \frac{\partial}{\partial t}R(t,x) = d[J*R(t,x) - R(t,x)] + \gamma \int_{0}^{A}i(t,a,x)da - \delta R(t,x),\\ i(t,0,x) = \left(N(t,x) - \int_{0}^{A}i(t,a,x)da - R(t,x)\right)\int_{0}^{A}\beta(a)i(t,a,x)da. \end{cases}$$
(2.1)

The homogeneous system for (2.1) always exists a disease-free equilibrium ( $S_0, 0, 0$ ), where  $S_0$  denotes the density of susceptible individuals at the start of the infection. In addition, if the basic reproduction number  $R_0 = S_0 \int_0^A \beta(a) e^{-\gamma a} da > 1$ , the homogeneous system for (2.1) exists a unique endemic equilibrium ( $S_0, i^*(a), R^*$ ), where

$$i^*(a) = \frac{\delta\gamma}{\delta + \gamma} \left( S_0 - \frac{1}{\int_0^A \beta(a) \mathrm{e}^{-\gamma a} \mathrm{d}a} \right) \frac{\mathrm{e}^{-\gamma a}}{1 - \mathrm{e}^{-\gamma A}} \text{ and } R^* = \frac{\gamma}{\delta + \gamma} \left( S_0 - \frac{1}{\int_0^A \beta(a) \mathrm{e}^{-\gamma a} \mathrm{d}a} \right)$$

Our purpose in this paper is to discuss the traveling wave solutions connecting the disease-free equilibrium and the endemic equilibrium. More precisely, we aim to study the traveling wave solutions of system (2.1) with the form

$$(N(t, x), i(t, a, x), R(t, x)) = (N(z), i(a, z), R(z)), \ z = x + ct,$$
(2.2)

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where the parameter c > 0 indicates the wave speed. Substituting (2.2) into (2.1) and replacing  $\widehat{N}$ ,  $\widehat{i}$ ,  $\widehat{R}$  with N, i, R, we deduce the following system:

$$\begin{cases} cN'(z) = d[J * N(z) - N(z)], \\ c\frac{\partial}{\partial z}i(a, z) + \frac{\partial}{\partial a}i(a, z) = d[J * i(a, z) - i(a, z)] - \gamma i(a, z), \\ cR'(z) = d[J * R(z) - R(z)] + \gamma \int_{0}^{A}i(a, z)da - \delta R(z), \\ i(0, z) = \left(N(z) - \int_{0}^{A}i(a, z)da - R(z)\right) \int_{0}^{A}\beta(a)i(a, z)da. \end{cases}$$

$$(2.3)$$

Thus, the solution of system (2.3) connecting ( $S_0$ , 0, 0) and ( $S_0$ ,  $i^*(a)$ ,  $R^*$ ) is a special solution, which satisfies the asymptotic boundary conditions

$$(N, i, R) (-\infty) = (S_0, 0, 0),$$
  
(N, i, R) (+\infty) = (S\_0, i^\*(a), R^\*). (2.4)

We intend to obtain the existence of traveling waves of system (2.1), which satisfies  $N(\pm \infty) = S_0$ . Since N(z) is a constant, system (2.3) can be simplified by removing the first equation to the following system:

$$\begin{cases} c\frac{\partial}{\partial z}i(a,z) + \frac{\partial}{\partial a}i(a,z) = d[J*i(a,z) - i(a,z)] - \gamma i(a,z), \\ cR'(z) = d[J*R(z) - R(z)] + \gamma \int_0^A i(a,z)da - \delta R(z), \\ i(0,z) = \left(S_0 - \int_0^A i(a,z)da - R(z)\right) \int_0^A \beta(a)i(a,z)da, \end{cases}$$
(2.5)

which satisfies the asymptotic boundary conditions

$$(i, R) (-\infty) = (0, 0) = E_0,$$
  

$$(i, R) (+\infty) = (i^*(a), R^*) = E_*.$$
(2.6)

Assume that  $R_0 = S_0 \int_0^A \beta(a) e^{-\gamma a} da > 1$ . By linearizing the third equation of system (2.5) around the disease-free equilibrium (0,0) and letting  $i(a, z) = e^{\lambda z} \phi(a)$ , we can obtain the characteristic equation as follows:

$$F_1(\lambda, c) = S_0 \int_0^A \beta(a) e^{g(\lambda, c)a} da - 1,$$
 (2.7)

where  $g(\lambda, c) = d\left(\int_{\mathbb{R}} J(x)e^{\lambda x}dx - 1\right) - \gamma - c\lambda$  and the function  $\phi$  satisfies  $\phi'(a) = g(\lambda, c)\phi(a)$ . Notice that

$$F_{1}(0,c) = S_{0} \int_{0}^{A} \beta(a) e^{-\gamma a} da - 1 = R_{0} - 1 > 0,$$
  

$$\frac{\partial F_{1}(\lambda,c)}{\partial c} = -\lambda S_{0} \int_{0}^{A} \beta(a) e^{g(\lambda,c)a} da < 0,$$
  

$$\frac{\partial F_{1}(\lambda,c)}{\partial \lambda}\Big|_{\lambda=0} = -cS_{0} \int_{0}^{A} \beta(a) e^{-\gamma a} a da < 0,$$
  

$$\frac{\partial^{2} F_{1}(\lambda,c)}{\partial \lambda^{2}} = S_{0} \int_{0}^{A} \beta(a) e^{g(\lambda,c)a} a \left(a \left(g_{\lambda}(\lambda,c)\right)^{2} + g_{\lambda\lambda}(\lambda,c)\right) da > 0.$$
(2.8)

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In order to construct  $R_{+}(z)$ , we consider the following function and study its properties:

$$F_2(\lambda, c) = d \int_{\mathbb{R}} J(x) \mathrm{e}^{-\lambda x} \mathrm{d}x - d - \delta - c\lambda + \frac{\gamma}{R^*} M,$$

where *M* is a positive constant to be determined and *M* can be taken to be  $e^{(\lambda_1 - \lambda_3)z_3}$  in Lemma 3.3. And  $\lambda_1, \lambda_3$  can be seen in Lemma 2.1 and  $z_3$  can be obtained from  $R_+(z)$ . Notice that

$$F_{2}(0,c) = -\delta + \frac{\gamma}{R^{*}}M,$$

$$\frac{\partial F_{2}(\lambda,c)}{\partial \lambda}\Big|_{\lambda=0} = -c < 0,$$

$$\frac{\partial F_{2}(\lambda,c)}{\partial c} = -\lambda < 0,$$

$$\frac{\partial^{2} F_{2}(\lambda,c)}{\partial \lambda^{2}} = d \int_{\mathbb{R}} J(x)x^{2}e^{\lambda x}dx > 0.$$
(2.9)

Based on (2.8) and (2.9), we can obtain the following lemma.

**Lemma 2.1.** If  $R_0 = S_0 \int_0^A \beta(a) e^{-\gamma a} da > 1$ , then there exist positive constants  $c_i^*$  and  $\lambda_i^*$  such that

$$F_i(\lambda_i^*, c_i^*) = 0$$
 and  $\frac{\partial F_i(\lambda, c)}{\partial \lambda}\Big|_{(\lambda_i^*, c_i^*)} = 0, \quad i = 1, 2.$ 

Furthermore,

- (i) when  $c \in (0, c_1^*)$ , it is known that  $F_1(\lambda, c) > 0$  holds for all  $\lambda \ge 0$ ;
  - when  $c > c_1^*$ ,  $F_1(\lambda, c) = 0$  has two positive roots  $\lambda_1(c)$  and  $\lambda_2(c)$  satisfying

$$0 < \lambda_1(c) < \lambda_1^* < \lambda_2(c) < +\infty.$$

In addition, when  $c > c_1^*$ ,  $F_1(\lambda, c)$  is less than zero in  $\lambda \in (\lambda_1(c), \lambda_2(c))$  and greater than zero beyond  $[\lambda_1(c), \lambda_2(c)]$ .

- (ii) When  $c \in (0, c_2^*)$ , it is known that  $F_2(\lambda, c) > 0$  holds for all  $\lambda \ge 0$ ;
  - when  $c > c_2^*$ ,  $F_2(\lambda, c) = 0$  has two positive roots  $\lambda_3(c)$  and  $\lambda_4(c)$  satisfying

$$0 < \lambda_3(c) < \lambda_2^* < \lambda_4(c).$$

In addition, when  $c > c_2^*$ ,  $F_2(\lambda, c)$  is less than zero in  $\lambda \in (\lambda_3(c), \lambda_4(c))$  and greater than zero beyond  $[\lambda_3(c), \lambda_4(c)]$ .

**Remark 2.1.** When  $\delta = 0$  and  $\gamma = 0$ , we obtain  $c_2^* = 0$ ,  $\lambda_3 = 0$ . Therefore, we get  $c_2^* < c_1^*$  and  $\lambda_3 < \lambda_1$  by choosing  $\delta$  and  $\gamma$  small enough. Taking  $c^* = c_1^*$ , we consider  $c^*$  as the critical wave speed in this paper.

**Remark 2.2.** The function  $\phi(a)$  satisfies the equation  $\phi'(a) = g(\lambda, c)\phi(a)$  for  $c > c^*$ . In the process of deriving the characteristic equation, it can be obtained that  $\phi(0) = S_0 \int_0^{+\infty} \beta(a)\phi(a)da$ .

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#### **3.** Existence of traveling wave solutions with $c > c^*$

In this section, we assume  $c > c^*$  and give the definitions of the upper solution and lower solution. To construct the suitable upper and lower solutions, we assume that  $\delta$  and  $\gamma$  are small enough throughout this paper (see Remark 2.1 and (3.3)). Then, the existence of traveling wave solutions is proved by using Schauder's fixed point theorem.

**Definition 3.1.** A pair of the continuous functions  $\Phi_+ = (i_+(a, z), R_+(z))$  and  $\Phi_- = (i_-(a, z), R_-(z))$  are called the upper solution and lower solution of system (2.5), if there exists a finite set  $S = \{Z_i \in \mathbb{R} : i = 1, 2, ..., m\}$  such that  $\Phi'_+, \Phi'_-$  exist and are bounded for  $z \in \mathbb{R}nS$ , and satisfy

$$\begin{cases} c\frac{\partial}{\partial z}i_{+}(a,z) + \frac{\partial}{\partial a}i_{+}(a,z) \ge d[J*i_{+}(a,z) - i_{+}(a,z)] - \gamma i_{+}(a,z), \\ cR'_{+}(z) \ge d[J*R_{+}(z) - R_{+}(z)] + \gamma \int_{0}^{A}i_{+}(a,z)da - \delta R_{+}(z), \\ i_{+}(0,z) \ge \left(S_{0} - \int_{0}^{A}i_{+}(a,z)da - R_{-}(z)\right) \int_{0}^{A}\beta(a)i_{+}(a,z)da, \end{cases}$$
(3.1)

and

$$\begin{cases} c \frac{\partial}{\partial z} i_{-}(a, z) + \frac{\partial}{\partial a} i_{-}(a, z) \leq d[J * i_{-}(a, z) - i_{-}(a, z)] - \gamma i_{-}(a, z), \\ cR'_{-}(z) \leq d[J * R_{-}(z) - R_{-}(z)] + \gamma \int_{0}^{A} i_{-}(a, z) da - \delta R_{-}(z), \\ i_{-}(0, z) \leq \left( S_{0} - \int_{0}^{A} i_{-}(a, z) da - R_{+}(z) \right) \int_{0}^{A} \beta(a) i_{-}(a, z) da, \end{cases}$$
(3.2)

for  $z \in \mathbb{R}nS$ , respectively.

Let  $\varepsilon > 0$  be small enough and  $\varepsilon_1 = \varepsilon + \varepsilon^2$ . Next, we define two continuous functions  $\Phi_+ = (i_+(a, z), R_+(z))$  and  $\Phi_- = (i_-(a, z), R_-(z))$  as follows:

$$i_{+}(a,z) = \begin{cases} e^{\lambda_{1}z}\phi(a), & z \leq z_{1}, \\ i^{*}(a) + \varepsilon_{1}e^{-\lambda_{z}}\phi(a), & z > z_{1}, \end{cases} \quad i_{-}(a,z) = \begin{cases} 0, & z \leq z_{2}, \\ i^{*}(a) - \varepsilon_{1}e^{-\lambda_{z}}\phi(a), & z > z_{2}, \\ i^{*}(a) - \varepsilon_{1}e^{-\lambda_{z}}\phi(a), & z > z_{2}, \end{cases}$$

$$R_{+}(z) = \begin{cases} R^{*}e^{\lambda_{3}z}, & z \leq z_{3}, \\ R^{*} + \varepsilon e^{-\lambda_{z}}, & z > z_{3}, \end{cases} \quad R_{-}(z) = \begin{cases} 0, & z \leq z_{4}, \\ R^{*} - \varepsilon e^{-\lambda_{z}}, & z > z_{4}, \end{cases}$$
(3.3)

where  $z_1, z_3 > 0$ ,  $z_2 < z_4 < 0$  and  $\lambda > 0$  is a small enough constant.

**Remark 3.1.** By the expressions for  $i_{-}(a, z)$  and  $R_{-}(z)$ , it follows that  $z_{2} = -\frac{1}{\lambda} \ln \frac{R^{*}}{\varepsilon} - \frac{1}{\lambda} \ln \frac{\delta e^{-\gamma a}}{(1+\varepsilon)\phi(a)}$  and  $z_{4} = -\frac{1}{\lambda} \ln \frac{R^{*}}{\varepsilon}$ . And it is easy to hold that  $z_{2} < z_{4}$ , e.g., when  $\gamma = \frac{1}{A}$ , where A is a sufficiently large constant.

**Lemma 3.1.** *The function*  $i_+(a, z)$  *satisfies* 

$$\begin{cases} c\frac{\partial}{\partial z}i_{+}(a,z) + \frac{\partial}{\partial a}i_{+}(a,z) \ge d[J*i_{+}(a,z) - i_{+}(a,z)] - \gamma i_{+}(a,z), \\ i_{+}(0,z) \ge \left(S_{0} - \int_{0}^{A}i_{+}(a,z)da - R_{-}(z)\right)\int_{0}^{A}\beta(a)i_{+}(a,z)da, \end{cases}$$
(3.4)

for  $z \neq z_1$ .

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*Proof.* For the first equation of system (3.4), when  $z < z_1$ ,  $i_+(a, z) = e^{\lambda_1 z} \phi(a)$ . Thus, we just need to prove

$$c\lambda_1 \mathrm{e}^{\lambda_1 z} \phi(a) + \mathrm{e}^{\lambda_1 z} \phi'(a) \ge d\left(\int_{\mathbb{R}} J(z-y) \mathrm{e}^{\lambda_1 y} \phi(a) \mathrm{d}y\right) - (\gamma + d) \mathrm{e}^{\lambda_1 z} \phi(a).$$

It is sufficient to prove

$$\frac{\phi'(a)}{\phi(a)} \ge d \int_{\mathbb{R}} J(x) \mathrm{e}^{\lambda_1 x} \mathrm{d}x - \gamma - d - c\lambda_1.$$

Recalling Remark 2.2, the above inequality holds.

When  $z > z_1$ ,  $i_+(a, z) = i^*(a) + \varepsilon_1 e^{-\lambda z} \phi(a)$ , we need to prove

$$-c\lambda\varepsilon_{1}\mathrm{e}^{-\lambda z}\phi(a) + i^{*\prime}(a) + \varepsilon_{1}\mathrm{e}^{-\lambda z}\phi'(a) \ge d \int_{\mathbb{R}} J(z-y)\left(i^{*}(a) + \varepsilon_{1}\mathrm{e}^{-\lambda y}\phi(a)\right)dy$$
$$- (d+\gamma)(i^{*}(a) + \varepsilon_{1}\mathrm{e}^{-\lambda z}\phi(a)).$$

It is enough to verify

$$\frac{\phi'(a)}{\phi(a)} \ge d \int_{\mathbb{R}} J(x) \mathrm{e}^{-\lambda x} \mathrm{d}x - \gamma - d + c\lambda.$$

That is to say,

$$g(\lambda_1) \ge g(\lambda) + 2c\lambda.$$
 (3.5)

When  $\lambda > 0$  is small enough, (3.5) is established.

For the second equation of the system (3.4), when  $z < z_1$ ,  $i_+(a, z) = e^{\lambda_1 z} \phi(a)$ . Therefore, it is sufficient to demonstrate

$$e^{\lambda_{1}z}\phi(0) \ge \left(S_{0} - \int_{0}^{A} i_{+}(a,z)da - R_{-}(z)\right)e^{\lambda_{1}z}\int_{0}^{A}\beta(a)\phi(a)da.$$
(3.6)

Recalling Remark 2.2, inequality (3.6) holds.

When  $z > z_1$ ,  $i_+(a, z) = i^*(a) + \varepsilon_1 e^{-\lambda z} \phi(a)$ . We need to show

$$i^{*}(0) + \varepsilon_{1} e^{-\lambda z} \phi(0) \ge \left( S_{0} - \int_{0}^{A} i_{+}(a, z) da - R_{-}(z) \right) \int_{0}^{A} \beta(a) \left( i^{*}(a) + \varepsilon_{1} e^{-\lambda z} \phi(a) \right) da.$$
(3.7)

Due to  $\phi(0) = S_0 \int_0^A \beta(a)\phi(a)da$  and  $i^*(0) > \left(S_0 - \int_0^A i_+(a,z)da - R_-(z)\right) \int_0^A \beta(a)i^*(a)da$ , it is evident that (3.7) is true.

**Lemma 3.2.** *The function*  $i_{-}(a, z)$  *satisfies* 

$$\begin{cases} c\frac{\partial}{\partial z}i_{-}(a,z) + \frac{\partial}{\partial a}i_{-}(a,z) \leq d[J * i_{-}(a,z) - i_{-}(a,z)] - \gamma i_{-}(a,z), \\ i_{-}(0,z) \leq \left(S_{0} - \int_{0}^{A}i_{-}(a,z)\mathrm{d}a - R_{+}(z)\right)\int_{0}^{A}\beta(a)i_{-}(a,z)\mathrm{d}a, \end{cases}$$
(3.8)

for  $z \neq z_2$ .

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*Proof.* For the first equation of system (3.8), when  $z < z_2$ ,  $i_-(a, z) = 0$ . Therefore, it is obviously true. When  $z > z_2$ ,  $i_-(a, z) = i^*(a) - \varepsilon_1 e^{-\lambda z} \phi(a)$ . We need to show

$$c\lambda\varepsilon_{1}e^{-\lambda z}\phi(a) + i^{*'}(a) - \varepsilon_{1}e^{-\lambda z}\phi'(a) \leq d \int_{\mathbb{R}} J(z-y)\left(i^{*}(a) - \varepsilon_{1}e^{-\lambda y}\phi(a)\right)dy - (d+\gamma)\left(i^{*}(a) - \varepsilon_{1}e^{-\lambda z}\phi(a)\right).$$
(3.9)

(3.9) can be simplified to

$$\frac{\phi'(a)}{\phi(a)} \ge d \int_{\mathbb{R}} J(x) \mathrm{e}^{-\lambda x} \mathrm{d}x - \gamma - d + c\lambda.$$

That is to say,

$$g(\lambda_1) \ge g(\lambda) + 2c\lambda. \tag{3.10}$$

When  $\lambda > 0$  is small enough, (3.10) holds.

For the second equation of system (3.8), when  $z < z_2$ ,  $i_-(a, z) = 0$ . It is clearly true. When  $z > z_2$ ,  $i_-(a, z) = i^*(a) - \varepsilon_1 e^{-\lambda z} \phi(a)$ . We need to show

$$i^{*}(0) - \varepsilon_{1} e^{-\lambda z} \phi(0)$$

$$\leq \left( S_{0} - \int_{0}^{A} \left( i^{*}(a) - \varepsilon_{1} e^{-\lambda z} \phi(a) \right) \mathrm{d}a - R_{+}(z) \right) \int_{0}^{A} \beta(a) \left( i^{*}(a) - \varepsilon_{1} e^{-\lambda z} \phi(a) \right) \mathrm{d}a.$$

$$(3.11)$$

Next, we need to discuss the two cases of  $R_+(z)$  in (3.11).

When  $z_2 < z < z_3$ ,  $R_+(z) = R^* e^{\lambda_3 z}$ . It is sufficient to ensure that

$$i^{*}(0) - \varepsilon_{1} \mathrm{e}^{-\lambda z} \phi(0) \leq \left( S_{0} - \int_{0}^{A} i^{*}(a) \mathrm{d}a + \varepsilon_{1} \mathrm{e}^{-\lambda z} \int_{0}^{A} \phi(a) \mathrm{d}a - R^{*} \mathrm{e}^{\lambda_{3} z} \right)$$

$$\left( \int_{0}^{A} \beta(a) i^{*}(a) \mathrm{d}a - \varepsilon_{1} \mathrm{e}^{-\lambda z} \int_{0}^{+\infty} \beta(a) \phi(a) \mathrm{d}a \right).$$
(3.12)

(3.12) can be simplified to

$$\left(\varepsilon_{1}e^{-\lambda z}\int_{0}^{A}\phi(a)da - R^{*}e^{\lambda_{3}z} + R^{*}\right)\int_{0}^{A}\beta(a)i^{*}(a)da + \left(\int_{0}^{A}i^{*}(a)da - \varepsilon_{1}e^{-\lambda z}\int_{0}^{A}\phi(a)da + R^{*}e^{\lambda_{3}z}\right)\varepsilon_{1}e^{-\lambda z}\int_{0}^{A}\beta(a)\phi(a)da \ge 0.$$
(3.13)

Under the conditions that

$$\varepsilon_1 e^{-\lambda z_3} \int_0^A \phi(a) da - R^* e^{\lambda_3 z_3} + R^* \ge 0$$
 (3.14)

and

$$\int_{0}^{A} i^{*}(a) \mathrm{d}a - \varepsilon_{1} \mathrm{e}^{-\lambda z} \int_{0}^{A} \phi(a) \mathrm{d}a + R^{*} \mathrm{e}^{\lambda_{3} z} \ge 0$$
(3.15)

the inequality (3.13) holds. In addition, (3.14) is equal to

$$(1+\varepsilon)\int_0^A \phi(a)\mathrm{d}a \ge 1. \tag{3.16}$$

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We can choose  $\phi(0) = \frac{g(\lambda_1)}{e^{g(\lambda_1)A} - 1}$  and  $\varepsilon_1$  small enough to guarantee (3.15) and (3.16) hold. When  $z > z_3$ ,  $R_+(z) = R^* + \varepsilon e^{-\lambda z}$ . It is to prove that

$$i^{*}(0) - \varepsilon_{1} \mathrm{e}^{-\lambda z} \phi(0) \leq \left( S_{0} - \int_{0}^{A} i^{*}(a) \mathrm{d}a - R^{*} + \varepsilon_{1} \mathrm{e}^{-\lambda z} \int_{0}^{A} \phi(a) \mathrm{d}a - \varepsilon \mathrm{e}^{-\lambda z} \right)$$

$$\left( \int_{0}^{A} \beta(a) i^{*}(a) \mathrm{d}a - \varepsilon_{1} \mathrm{e}^{-\lambda z} \int_{0}^{A} \beta(a) \phi(a) \mathrm{d}a \right).$$

$$(3.17)$$

(3.17) can be simplified to

$$\varepsilon e^{-\lambda z} \left( (1+\varepsilon) \int_{0}^{A} \phi(a) da - 1 \right) \int_{0}^{A} \beta(a) i^{*}(a) da + \left( \int_{0}^{A} i^{*}(a) da + R^{*} - \varepsilon_{1} e^{-\lambda z} \int_{0}^{A} \phi(a) da + \varepsilon e^{-\lambda z} \right) \left( \varepsilon_{1} e^{-\lambda z} \int_{0}^{A} \beta(a) \phi(a) da \right) \ge 0.$$
(3.18)

Due to  $\phi(0) = \frac{g(\lambda_1)}{e^{g(\lambda_1)A}-1}$ , then  $(1 + \varepsilon) \int_0^A \phi(a) da \ge 1$  holds. Since  $\varepsilon_1$  is small enough, then

$$\int_{0}^{A} i^{*}(a) \mathrm{d}a + R^{*} - \varepsilon_{1} \mathrm{e}^{-\lambda z} \int_{0}^{A} \phi(a) \mathrm{d}a + \varepsilon \mathrm{e}^{-\lambda z} \ge 0$$
(3.19)

is true. Therefore, (3.17) holds.

**Lemma 3.3.** The function  $R_+(z)$  satisfies

$$cR'_{+}(z) \ge d[J * R_{+}(z) - R_{+}(z)] + \gamma \int_{0}^{A} i_{+}(a, z) da - \delta R_{+}(z), \qquad (3.20)$$

## for $z \neq z_3$ .

*Proof.* When  $z < z_3$ ,  $R_+(z) = R^* e^{\lambda_3 z}$ . It is necessary to demonstrate

$$c\lambda_3 R^* e^{\lambda_3 z} \ge d \int_{\mathbb{R}} J(z-y) R^* e^{\lambda_3 y} dy - (d+\delta) R^* e^{\lambda_3 z} + \gamma \int_0^A i_+(a,z) da.$$

That is to say, we only need to prove this simplified expression as follows:

$$d \int_{\mathbb{R}} J(z-y) e^{\lambda_3(y-z)} dy - d - \delta + \frac{\gamma}{R^*} e^{-\lambda_3 z} \int_0^A i_+(a,z) da - c\lambda_3 \le 0.$$
(3.21)

At this point, (3.21) can be organized in the following inequalities:

$$F_2(\lambda_3,c) - \frac{\gamma}{R^*} \left( M - \mathrm{e}^{-\lambda_3 z} \int_0^A i_+(a,z) \mathrm{d}a \right) \leq 0.$$

Since  $F_2(\lambda_3, c) = 0$ , we need to demonstrate

$$M \ge e^{-\lambda_3 z} \int_0^A i_+(a, z) \mathrm{d}a.$$
(3.22)

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Next, we will consider different cases for  $i_+(a, z)$ .

If  $z < z_1$ , then  $i_+(a, z) = e^{\lambda_1 z} \phi(a)$ . Noticing that  $\int_0^A \phi(a) da = 1$ , we can choose  $M = e^{(\lambda_1 - \lambda_3)z_3}$  to ensure that (3.22) holds.

If  $z > z_1$ , then  $i_+(a, z) = i^*(a) + \varepsilon_1 e^{-\lambda z} \phi(a)$ . We just need to verify

$$e^{(\lambda_1 - \lambda_3)z_3} \ge e^{-\lambda_3 z} \int_0^A \left( i^*(a) + \varepsilon_1 e^{-\lambda z} \phi(a) \right) \mathrm{d}a.$$
(3.23)

Simplifying (3.23), we obtain

$$e^{(\lambda_1 - \lambda_3)z_3} e^{\lambda_3 z_1} \ge \int_0^A i^*(a) da + \varepsilon_1 e^{-\lambda z_1}.$$
(3.24)

Since  $\lambda_3 < \lambda_1$  and  $z_1 < z < z_3$ , it follows that the left side of (3.24) is greater than 1. When  $\varepsilon_1 > 0$  is sufficiently small,  $\varepsilon_1 e^{-\lambda z_1}$  tends to zero. By taking  $S_0 \le 1$  so that  $\int_0^A i^*(a) da \le 1$ , we have that (3.24) holds.

When  $z > z_3$ ,  $R_+(z) = R^* + \varepsilon e^{-\lambda z}$ ,  $i_+(a, z) \le i^*(a) + \varepsilon_1 e^{-\lambda(z \vee z_1)} \phi(a)$ , where  $z \vee z_1 := \max \{z, z_1\}$ . It is to prove that

$$-c\lambda\varepsilon e^{-\lambda z} \ge d \int_{\mathbb{R}} J(z-y) \left(R^* + \varepsilon e^{-\lambda y}\right) dy - (d+\delta) \left(R^* + \varepsilon e^{-\lambda z}\right) + \gamma \int_0^A \left(i^*(a) + \varepsilon_1 e^{-\lambda(z\vee z_1)}\phi(a)\right) da.$$
(3.25)

Due to

$$\left| d \int_{\mathbb{R}} J(x) \mathrm{e}^{-\lambda x} \mathrm{d}x - d + c\lambda \right| \to 0 \quad \text{as} \quad \lambda \to 0,$$

then there exists  $\delta_1 > 0$ , for any  $\lambda \in (0, \delta_1)$ ,

$$\left| d \int_{\mathbb{R}} J(x) \mathrm{e}^{-\lambda x} \mathrm{d}x - d + c\lambda \right| < \eta_1.$$
(3.26)

Thus, (3.25) can be simplified to

$$d \int_{\mathbb{R}} J(x) e^{-\lambda x} dx - d + c\lambda - \delta + \gamma (1+\varepsilon) e^{-\lambda (z \vee z_1 - z)} \int_0^A \phi(a) da$$

$$\leq \eta_1 - \delta + \gamma (1+\varepsilon).$$
(3.27)

We can choose  $\eta_1 = \delta - \gamma(1 + \varepsilon)$ , then (3.25) holds.

**Lemma 3.4.** *The function*  $R_{-}(z)$  *satisfies* 

$$cR'_{-}(z) \le d[J * R_{-}(z) - R_{-}(z)] + \gamma \int_{0}^{A} i_{-}(a, z) da - \delta R_{-}(z),$$
 (3.28)

for  $z \neq z_4$ .

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*Proof.* When  $z < z_4$ ,  $R_-(z) = 0$ . Thus, it is obviously true.

When  $z > z_4$ ,  $R_-(z) = R^* - \varepsilon e^{-\lambda z}$ . We need to show

$$c\varepsilon\lambda e^{-\lambda z} \le d \int_{\mathbb{R}} J(z-y) \left( R^* - \varepsilon e^{-\lambda y} \right) dy - (d+\delta) \left( R^* - \varepsilon e^{-\lambda z} \right) + \gamma \int_0^A i_-(a,z) da.$$
(3.29)

Since  $z_2 < z_4$  when A is sufficiently large, (3.29) reduces to

$$d\int_{\mathbb{R}} J(x) \mathrm{e}^{-\lambda x} \mathrm{d}x - d + c\lambda \leqslant \delta - \gamma (1 + \varepsilon).$$
(3.30)

Due to

$$\left| d \int_{\mathbb{R}} J(x) \mathrm{e}^{-\lambda x} \mathrm{d}x - d + c\lambda \right| \to 0 \quad \text{as} \quad \lambda \to 0,$$

then there exists  $\delta_1 > 0$ , for any  $\lambda \in (0, \delta_1)$ ,

$$\left| d \int_{\mathbb{R}} J(x) \mathrm{e}^{-\lambda x} \mathrm{d}x - d + c\lambda \right| < \eta_1.$$
(3.31)

We choose

$$\eta_1 = \delta - \gamma (1 + \varepsilon), \tag{3.32}$$

then (3.29) holds true.

For any b > 0, define the bounded closed convex set

 $C_b = \{i_0 \in C([-b, b]): \quad i_-(0, z) \le i_0(z) \le i_+(0, z)\}.$ 

Next, we study the operator  $T : C_b \to C([-b, b])$  given by

$$T(i_0)(z) = \left(S_0 - \int_0^A i(a, z) da - R(z)\right) \int_0^A \beta(a) i(a, z) da,$$

where i is the solution of the problem

$$\begin{cases} c\frac{\partial}{\partial z}i(a,z) + \frac{\partial}{\partial a}i(a,z) = d[J*i(a,z) - i(a,z)] - \gamma i(a,z), & a > 0, \quad z \in (-b,b), \\ i(0,z) = i_0(z), \quad z \in (-b,b), \\ i(a,\pm b) = i_-(a,\pm b), \quad a > 0, \end{cases}$$
(3.33)

while R is the solution of the problem

$$\begin{cases} cR'(z) = d[J * R(z) - R(z)] + \gamma \int_0^A i(a, z) da - \delta R(z), & z \in (-b, b), \\ R(\pm b) = R_-(\pm b). \end{cases}$$
(3.34)

Therefore, the existence of solutions to systems (3.33) and (3.34) can be converted to the existence of a fixed point for the operator *T*.

Now, we can present the main result of the existence of traveling waves in this section.

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**Theorem 3.1.** (*Existence of traveling waves*) We assume that  $R_0 > 1$ , for any  $c > c^*$ , system (2.5) has a solution that connect the disease-free equilibrium  $E_0$  and the endemic equilibrium  $E_*$ .

*Proof.* From the definition of  $C_b$ , it can be shown that  $C_b$  is closed, convex and bounded. Moreover, by the similar argument in [17], we have operator T is completely continuous and  $T(C_b) \subset C_b$ . Using the Schauder's fixed theorem, T has a fixed point  $i_0$ . Let  $(i_b(a, z), R_b(z))(z \in (-b, b))$  be the solution of systems (3.33) and (3.34) for any fixed b > 0. To obtain the existence of traveling wave solutions in  $\mathbb{R}$ , we choose an increasing sequence  $\{b_n\}_{n=1}^{+\infty}$  such that  $b_n > \max\{z_1, z_3\}$  and  $\lim_{n \to +\infty} b_n = +\infty$ . By similar arguments in [3, Section 4.4] and [4, Proposition 2.5], for the sequence  $(i_{b_n}, R_{b_n})$ , we can extract a subsequence by a standard diagonal extract argument, denoted by  $\{i_{b_{n_k}}\}_{k\in N}$ ,  $\{R_{b_{n_k}}\}_{k\in N}$ , which tend towards functions (i, R) in the following topologies  $i_{b_{n_k}} \to i$  and  $R_{b_{n_k}} \to R$  as  $k \to +\infty$  uniformly on every bounded closed interval and pointwise on  $\mathbb{R}$  for any given a > 0. Due to the fact that J is compactly supported, applying the Lebesgue dominated convergence theorem, we obtain the following results:

$$\lim_{k \to +\infty} \int_{-\infty}^{+\infty} J(y) i_{b_{n_k}}(a, z-y) \mathrm{d}y = \int_{-\infty}^{+\infty} J(y) i(a, z-y) \mathrm{d}y = J * i(a, z)$$

and

$$\lim_{k \to +\infty} \int_{-\infty}^{+\infty} J(y) R_{b_{n_k}}(z-y) \mathrm{d}y = \int_{-\infty}^{+\infty} J(y) R(z-y) \mathrm{d}y = J * R(z)$$

for any  $z \in \mathbb{R}$ . Therefore, we have that i(a, z) and R(z) satisfy system (2.5). Note the fact that

$$i_{-}(a,z) \le i(a,z) \le i_{+}(a,z), \ R_{-}(z) \le R(z) \le R_{+}(z), \quad \forall z \in \mathbb{R},$$
 (3.35)

and

$$\lim_{z \to -\infty} (i_{-}(a, z), R_{-}(z)) = (0, 0), \quad \lim_{z \to +\infty} (i_{-}(a, z), R_{-}(z)) = (i^{*}, R^{*}),$$

$$\lim_{z \to -\infty} (i_{+}(a, z), R_{+}(z)) = (0, 0), \quad \lim_{z \to +\infty} (i_{+}(a, z), R_{+}(z)) = (i^{*}, R^{*}),$$
(3.36)

we obtain

$$\lim_{z \to -\infty} (i(a, z), R(z)) = (0, 0), \quad \lim_{z \to +\infty} (i(a, z), R(z)) = (i^*, R^*).$$
(3.37)

Thus, (i(a, z), R(z)) satisfies the asymptotic boundary conditions (2.6). The proof is completed.

#### 4. Nonexistence of traveling waves with $c \in (0, c^*)$

In this section, we mainly focus on the nonexistence of traveling waves when  $0 < c < c^*$  with  $R_0 > 1$  by using the Laplace transform.

**Theorem 4.1.** (Nonexistence of traveling waves) Assume that  $R_0 > 1$ , for any speed  $c \in (0, c^*)$ , there exist no nontrivial traveling wave solutions (i(a, z), R(z)) of system (2.5) satisfying (2.6).

*Proof.* By contradiction, we assume that there exists a nontrivial traveling wave solution (i(a, z), R(z)) of system (2.5) that satisfies

$$(i, R) (-\infty) = (0, 0),$$
  
 $(i, R) (+\infty) = (i^*, R^*)$ 

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Due to  $R_0 = S_0 \int_0^A \beta(a) e^{-\gamma a} da > 1$  and  $(i, R) (-\infty) = (0, 0)$ , there exists  $\hat{z} < 0$  such that  $S_0 - I(z) - R(z) > \frac{S_0}{2} + \frac{1}{2\int_0^A \beta(a) e^{-\gamma a} da}$  for any  $z < \hat{z}$ , where  $I(z) = \int_0^A i(a, z) da$ . Integrating the first equation of (2.5) with respect to *a* from 0 to *A*, we have

$$cI'(z) = d(J * I(z) - I(z)) - \gamma I(z) + (S_0 - I(z) - R(z)) \int_0^A \beta(a)i(a, z)da$$
  
$$\geq d(J * I(z) - I(z)) - \gamma I(z) + \left(\frac{S_0}{2} + \frac{1}{2\int_0^A \beta(a)e^{-\gamma a}da}\right) \beta_1 I(z),$$
(4.1)

where  $\beta_1 = \inf_{a \in (0,A]} \beta(a)$ . For any  $z < \hat{z}$ , let  $H(z) = \int_{-\infty}^{z} I(s) ds$ . Integrating two sides of inequality (4.1) from  $-\infty$  to z, we obtain

$$cI(z) \ge d \int_{-\infty}^{z} (J * I(s) - I(s)) ds + \left[ \left( \frac{S_0}{2} + \frac{1}{2 \int_{0}^{A} \beta(a) e^{-\gamma a} da} \right) \beta_1 - \gamma \right] H(z).$$
(4.2)

By applying Fubini theorem, it holds that

$$\int_{-\infty}^{z} J * I(s) ds = \int_{-\infty}^{+\infty} \int_{-\infty}^{z} J(x) I(s-x) ds dx$$
  
= 
$$\int_{-\infty}^{+\infty} J(x) \int_{-\infty}^{z-x} I(s) ds dx = J * H(z).$$
 (4.3)

Substituting (4.3) into (4.2), we get

$$cI(z) \ge d(J * H(z) - H(z)) + \left[ \left( \frac{S_0}{2} + \frac{1}{2 \int_0^A \beta(a) e^{-\gamma a} da} \right) \beta_1 - \gamma \right] H(z).$$
(4.4)

Thanks to

$$\int_{-\infty}^{z} (J * H(s) - H(s)) ds = \int_{-\infty}^{z} \int_{-\infty}^{+\infty} J(x) (H(s - x) - H(s)) dx ds$$
$$= \int_{-\infty}^{z} \int_{-\infty}^{+\infty} (-x) J(x) \int_{0}^{1} H'(s - \theta x) d\theta dx ds$$
$$= \int_{0}^{1} \int_{-\infty}^{+\infty} (-x) J(x) \int_{-\infty}^{z} I(s - \theta x) ds dx d\theta$$
$$= \int_{-\infty}^{+\infty} (-x) J(x) \int_{0}^{1} H(z - \theta x) d\theta dx,$$

we have J \* H(z) - H(z) is integrable on  $(-\infty, z]$  for any  $z \in \mathbb{R}$ . From Eq (4.4), we obtain that H(z) is integrable on  $(-\infty, z]$  for any  $z \in \mathbb{R}$ . Then integrating both sides of inequality (4.4) from  $-\infty$  to z with  $z \leq \hat{z}$ , we have

$$\left[\left(\frac{S_0}{2} + \frac{1}{2\int_0^A \beta(a)e^{-\gamma a}da}\right)\beta_1 - \gamma\right]\int_{-\infty}^z H(s)ds \le cH(z) + d\int_{-\infty}^{+\infty} xJ(x)\int_0^1 H(z-\theta x)d\theta dx.$$

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Due to  $xH(z - \theta x)$  is non-increasing for  $\theta \in [0, 1]$  with any fixed  $z \in \mathbb{R}$ . We obtain

$$\left[\left(\frac{S_0}{2} + \frac{1}{2\int_0^A \beta(a)e^{-\gamma a}da}\right)\beta_1 - \gamma\right]\int_{-\infty}^z H(s)ds \leq \left(c + d\int_{-\infty}^{+\infty} xJ(x)dx\right)H(z).$$

By the property that *J* is an even function, we have  $\int_{-\infty}^{+\infty} x J(x) dx = 0$  holds. Thus, for any  $z \le \hat{z}$ , one gets

$$\left[\left(\frac{S_0}{2} + \frac{1}{2\int_0^A \beta(a)e^{-\gamma a}da}\right)\beta_1 - \gamma\right]\int_0^{+\infty} H(z-s)ds \le cH(z).$$

Since H(z) is increasing with respect to z, there exists some  $\tau > 0$  such that

$$\left[\left(\frac{S_0}{2} + \frac{1}{2\int_0^A \beta(a)e^{-\gamma a}da}\right)\beta_1 - \gamma\right]\tau H(z-\tau) \le cH(z).$$

Hence, there exists a constant  $\tau_0 > 0$  large enough and some  $v \in (0, 1)$  such that  $H(z - \tau_0) \le vH(z)$  for each  $z \le \hat{z}$ . Set  $Q(x) = H(x)e^{-\mu_1 x}$  and  $\mu_1 = \frac{1}{\tau_0} \ln \frac{1}{v}$ , then

$$Q(z - \tau_0) = H(z - \tau_0) e^{-\mu_1(z - \tau_0)} \le \nu H(z) e^{-\mu_1(z - \tau_0)} = Q(z)$$

Therefore, there exists  $Q_0 > 0$  such that  $Q(z) \le Q_0$  for any  $z \le \hat{z}$ , which implies

$$H(z) \leq Q_0 e^{\mu_1 z}$$
 for any  $z \leq \hat{z}$ .

It is noticed that

$$cI'(z) \leq d(J * I(z) - I(z)) + (S_0 ||\beta||_{\infty} - \gamma)I(z),$$

then there exists  $P_1 > 0$ , such that  $I(z) \le P_1 e^{\mu_1 z}$  for any  $z \le \hat{z}$ . Due to I(z) is bounded, it is possible to obtain

$$\sup_{z \in \mathbb{R}} \{I(z)e^{-\mu_1 z}\} < +\infty \quad \text{and} \quad \sup_{z \in \mathbb{R}} \{I'(z)e^{-\mu_1 z}\} < +\infty.$$
(4.5)

By the same process, we have

$$\sup_{z \in \mathbb{R}} \left\{ R(z) e^{-\mu_2 z} \right\} < +\infty \quad \text{and} \quad \sup_{z \in \mathbb{R}} \left\{ R'(z) e^{-\mu_2 z} \right\} < +\infty \quad \text{for some} \quad \mu_2 > 0.$$
(4.6)

According to (4.5) and (4.6), it can be obtained that

$$\sup_{z\in\mathbb{R}}\left\{\mathrm{e}^{-\mu_0 z}(I(z)+R(z))\right\}<+\infty$$

and

$$\sup_{z\in\mathbb{R}}\left\{\mathrm{e}^{-\mu_0 z}\int_0^A\beta(a)i(a,z)\mathrm{d}a\right\}<\sup_{z\in\mathbb{R}}\left\{||\beta||_{\infty}\mathrm{e}^{-\mu_0 z}I(z)\right\}<+\infty,$$

where  $\mu_0 = \min \{\mu_1, \mu_2\}$ . Therefore, we obtain

$$\sup_{z\in\mathbb{R}}\left\{e^{-2\mu_0 z}\left(I(z)+R(z)\right)\int_0^A \beta(a)i(a,z)\mathrm{d}a\right\}<+\infty.$$
(4.7)

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Next, we define

$$\tilde{I}(z) = \int_0^A \beta(a)i(a,z)\mathrm{d}a$$

and a two-sided Laplace transform of  $I(\cdot)$  by

$$L_I(\lambda) = \int_{-\infty}^{+\infty} e^{-\lambda z} I(z) dz$$

and a two-sided Laplace transform of  $\tilde{I}(\cdot)$  by

$$L_{\tilde{I}}(\lambda) = \int_{-\infty}^{+\infty} e^{-\lambda z} \int_{0}^{A} \beta(a)i(a, z) dadz$$

for  $\lambda \in \mathbb{C}$  with  $0 < \operatorname{Re} \lambda < \mu_0$ .

Then, in view of

$$d(J * I(z) - I(z)) - cI'(z) - \gamma I(z) + S_0 \int_0^A \beta(a)i(a, z)da = (I(z) + R(z)) \int_0^A \beta(a)i(a, z)da$$
(4.8)

and

$$\int_{-\infty}^{+\infty} e^{-\lambda z} J * I(z) dz = \int_{-\infty}^{+\infty} J(x) e^{-\lambda x} L_I(\lambda) dx,$$

we have

$$g(\lambda, c)L_{I}(\lambda) + S_{0}L_{\bar{I}}(\lambda) = \int_{-\infty}^{+\infty} e^{-\lambda z} \left(I(z) + R(z)\right) \int_{0}^{A} \beta(a)i(a, z) dadz.$$

$$(4.9)$$

By the property of the Laplace transform (see [27]), it follows that either there exists a real number  $\hat{\lambda}$  such that  $L_I(\lambda)$  and  $L_{\bar{I}}(\lambda)$  are analytic for  $\lambda \in \mathbb{C}$  with  $0 < \text{Re } \lambda < \hat{\lambda}$  and  $\lambda = \hat{\lambda}$  is singular point of  $L_I(\lambda)$  and  $L_{\bar{I}}(\lambda)$ , or  $L_I(\lambda)$  and  $L_{\bar{I}}(\lambda)$  are well defined for  $\lambda \in \mathbb{C}$  with  $\text{Re } \lambda > 0$ . Indeed, motivated by Zhou, Xu, Wei et al. [35, Section 3], we can obtain that the right-hand side of Eq (4.9) is well defined for  $\lambda \in \mathbb{C}$  with  $0 < \text{Re } \lambda < 2\mu_0$  according to (4.7). One can obtain that  $L_I(\lambda)$  and  $L_{\bar{I}}(\lambda)$  are well defined with  $\text{Re } \lambda > 0$ . Nevertheless, (4.9) can be rewritten as

$$\int_{-\infty}^{+\infty} e^{-\lambda z} \left[ g(\lambda, c)I(z) + S_0 \int_0^A \beta(a)i(a, z) da - (I(z) + R(z)) \int_0^A \beta(a)i(a, z) da \right] dz = 0.$$
(4.10)

It is evident from the definition of  $g(\lambda, c)$  and Lemma 2.1 that  $g(\lambda, c) \to +\infty$  as  $\lambda \to +\infty$ . This is a contradiction to Eq (4.10) and we complete the proof.

## 5. Conclusions

In this paper, we propose and consider a nonlocal dispersal SIRS infectious disease model with age structure that has practical significance. Due to the consideration of age structure, the investigation of traveling wave problem becomes more complicated. In addition, the epidemic system is non-monotone such that the theory for monotone semiflow can not be applied. To overcome these difficulties, we obtain the existence of traveling wave solutions by constructing appropriate upper and lower solutions and applying Schauder fixed point theorem. In fact, the solution of system (2.5) can be derived when the basic reproduction number  $R_0 > 1$  and the wave speed  $c > c^*$ . That is to say, infectious diseases can spread among populations when  $R_0 > 1$  and  $c > c^*$ . Furthermore, we prove the nonexistence of traveling wave solutions when  $0 < c < c^*$  with  $R_0 > 1$  by using the Laplace transform.

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## Use of AI tools declaration

The authors declare they have not used Artificial Intelligence (AI) tools in the creation of this article.

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# **Conflict of interest**

All authors declare no conflict of interest that could affect the publication of this paper.

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