



Research article

The existence and stability results of multi-order boundary value problems involving Riemann-Liouville fractional operators

Hasanen A. Hammad^{1,2,*}, Hassen Aydi^{3,4,5,*} and Manuel De la Sen⁶

¹ Department of Mathematics, Unaizah College of Sciences and Arts, Qassim University, Buraydah 52571, Saudi Arabia

² Department of Mathematics, Faculty of Science, Sohag University, Sohag 82524, Egypt

³ Institut Supérieur d'Informatique et des Techniques de Communication, Université de Sousse, H. Sousse 4000, Tunisia

⁴ China Medical University Hospital, China Medical University, Taichung 40402, Taiwan

⁵ Department of Mathematics and Applied Mathematics, Sefako Makgatho Health Sciences University, Ga-Rankuwa, South Africa

⁶ Institute of Research and Development of Processes, Department of Electricity and Electronics, Faculty of Science and Technology, University of the Basque Country, 48940-Leioa (Bizkaia), Spain

* **Correspondence:** Email: hassanein.hamad@science.sohag.edu.eg, hassen.aydi@isima.rnu.tn.

Abstract: In this paper, a general framework for the fractional boundary value problems is presented. The problem is created by Riemann-Liouville type two-term fractional differential equations with a fractional bi-order setup. Moreover, the boundary conditions of the suggested system are considered as mixed Riemann-Liouville integro-derivative conditions with four different orders, which it cover a variety of specific instances previously researched. Further, the provided problem's Hyers-Ulam stability and the possibility of a fixed-point approach solution are both investigated. Finally, to support our theoretical findings, an example is developed.

Keywords: Riemann-Liouville fractional derivative; coupled fractional boundary value problem; fixed point; Hyers-Ulam stability

Mathematics Subject Classification: 34A08, 34A12

1. Introduction and building system

The classical derivatives are local in nature, i.e., using classical derivatives we can describe changes in the neighborhood of a point, but using fractional derivatives we can describe changes in an interval.

Namely, a fractional derivative is nonlocal in nature. This property makes these derivatives suitable to simulate more physical phenomena such as earthquake vibrations, polymers, etc.

On the other hand, in the case of the heat conduction equation, the fractional order parameter α means the level of thermal conductivity. If $\alpha = 1$, the medium's thermal conductivity is normal; if $\alpha < 1$, the medium has weak conductivity; and if $\alpha \geq 1$, the medium has strong conductivity.

Further, in modeling various memory phenomena, it is observed that a memory process usually consists of two stages. One is short with permanent retention, and the other is governed by a simple model of fractional derivative. With the numerical least squares method, the fractional model perfectly fits the test data of memory phenomena in different disciplines, not only in mechanics but also in biology and psychology. Based on this model, it is found that the physical meaning of the fractional order is an index of memory. For more details, see [1, 2].

Fractional calculus and its applications have acquired a lot of interest in several disciplines of engineering and science such as biology, chemistry, physics, economics, control theory, signal and image processing, etc, see [3–5] and the references therein. Variant definitions for the fractional derivative have emerged over the years. The most famous ones are the Riemann-Liouville and Caputo fractional derivatives. In recent years, many nonlinear phenomena in numerous fields have been modeled by fractional differential equations. Due to the evolution of fractional calculus, these equations have emerged as a new branch of applied mathematics. Several works on the existence and multiplicity of solutions to fractional boundary value problems (FBVPs) have appeared in view of the qualitative properties of fractional differential equations.

Among the used methods to solve a FBVP, there are the variational methods used by Fix and Roop in [6] and Erwin and Roop in [7]. Also, some fixed point techniques have been applied successfully to ensure the existence of solutions of some FBVPs. Here, we may cite the works of Agarwal et al. [8], Benchohra et al. [9], Zhang [10], Ahmad and Nieto [11], etc. Going in the same direction, the critical point theory has been used to investigate the solutions for some FBVPs. For instance, see the works Jiao and Zhou [12] and Tang and Wu [13]. On the other hand, stability analysis of fractional differential equations with different types of initial and boundary conditions have attracted many researchers who discussed the analysis of stability in the setting of Ulam-Hyers (UH) and generalized UH theory. For more details, see [14–30].

In 2016, the boundary value problem (BVP) with 4-order Riemann-Liouville fractional (RLF) derivatives is studied by Niyom et al. [31]:

$$\begin{cases} \nu D^\rho(z(\tau)) + (1 - \nu)D^\theta(z(\tau)) = \Xi(\tau, z(\tau)), \tau \in [0, G], \rho \in [1, 2), \\ z(0) = 0, \varrho_1 D^{\eta_1} z(G) + (1 - \varrho_1)D^{\eta_2} z(G) = \xi_1, \end{cases} \quad (1.1)$$

under appropriate conditions. Also, Niyom et al. [32], modified the above problem under multiple orders of fractional integrals and derivatives as follows:

$$\begin{cases} \nu D^\rho(z(\tau)) + (1 - \nu)D^\theta(z(\tau)) = \Xi(\tau, z(\tau)), \tau \in [0, G], \rho \in [1, 2), \\ z(0) = 0, \varrho_2 I^{\sigma_1} z(G) + (1 - \varrho_2)I^{\sigma_2} z(G) = \xi_2. \end{cases} \quad (1.2)$$

In 2018, Xu et al. [33] examined the existence of solutions and UH stability for the FDEs

$$\begin{cases} \nu D^\rho(z(\tau)) + D^\theta(z(\tau)) = \Xi(\tau, z(\tau)), \tau \in [0, G], \rho \in [1, 2), \\ z(0) = 0, \varrho_1 D^{\eta_1} z(G) + I^{\sigma_2} z(G) = \xi_2. \end{cases} \quad (1.3)$$

They focused on the RLF derivative and integral issues of the two-term class of three-point BVPs, where the notions and parameters in (1.1) and (1.2) are defined below the system (1.4).

Now, utilizing the concepts from the works described above and combining them, we investigate a new category of coupled boundary value problems (CBVPs) that includes a multi-order RLF equation plus various linear integro-derivative boundary stipulations as follows:

$$\begin{cases} vD^\rho(z(\tau)) + (1-v)D^\theta(z(\tau)) = \Xi(\tau, z(\tau), r(\tau)), \tau \in [0, G], \rho \in [2, 3), \\ v^*D^{\rho^*}(r(\tau)) + (1-v^*)D^{\theta^*}(r(\tau)) = \Xi^*(\tau, r(\tau), z(\tau)), \tau \in [0, G], \rho^* \in [2, 3), \\ z(0) = 0, \varrho_1 D^{\eta_1} z(G) + (1-\varrho_1)D^{\eta_2} z(G) = \xi_1, \\ r(0) = 0, \varrho_1^* D^{\eta_1^*} r(G) + (1-\varrho_1^*)D^{\eta_2^*} r(G) = \xi_1^*, \\ \varrho_2 I^{s_1} z(G) + (1-\varrho_2)I^{s_2} z(G) = \xi_2, \varrho_2^* I^{s_1^*} r(G) + (1-\varrho_2^*)I^{s_2^*} r(G) = \xi_2^*, \end{cases} \quad (1.4)$$

where $2 < \theta < \rho$, $2 < \theta^* < \rho^*$, $v, v^*, \varrho_1, \varrho_2, \varrho_1^*, \varrho_2^* \in (0, 1]$, $0 \leq \eta_1, \eta_2 < \rho - \theta$, $0 \leq \eta_1^*, \eta_2^* < \rho^* - \theta^*$, $s_1, s_2, s_1^*, s_2^* \in \mathbb{R}^+$, D^q is the RLF derivative of order $q \in \{\rho, \theta, \rho^*, \theta^*, \eta_1, \eta_2, \eta_1^*, \eta_2^*\}$, I^m is the RLF integral of order $m \in \{s_1, s_2, s_1^*, s_2^*\}$ and $\Xi, \Xi^* : [0, G] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are continuous functions.

As many scholars are interested in exploring the idea of stability for various CBVPs, this can serve as inspiration for us to research the stability of complicated systems with added broad boundary stipulations. Consequently, to be more precise, the main objective of the current manuscript is to find some existing criteria for the solutions to a new general CBVP that includes a two-term fractional differential equation (FDE) (1.4) and multi-order RLF derivatives and integrals. The well-known standard fixed point (FP) theorems are employed in order to achieve this goal. Furthermore, in the follow-up, we examine the HU stability of the suggested problem (1.4) in the unique scenario when $\varrho_1 = \varrho_2 = 1$ and $\varrho_1^* = \varrho_2^* = 1$. Ultimately, to demonstrate the applicability of our theoretical results, two examples are provided. We think that the BVP that has been proposed is a generic one that incorporates a lot of fractional dynamical systems as special examples in the fields of physics and other applied disciplines.

2. Basic concepts

Let $G > 0$ and $U = [0, G]$. Assume that the piecewise continuous function space $PC(U, \mathbb{R}_+)$ equipped with the norms $\|z\| = \max\{|z(v)| : v \in U\}$ and $\|r\| = \max\{|r(v)| : v \in U\}$ is a Banach space (BS), then the products of these norms are also a BS under the norm $\|(z, r)\| = \|z\| + \|r\|$.

Assume also \mathfrak{Y}_1 and \mathfrak{Y}_2 represent the piecewise continuous function spaces described as

$$\mathfrak{Y}_1 = PC_1(U, \mathbb{R}) = \{z : U \rightarrow \mathbb{R}\} \text{ and } \mathfrak{Y}_2 = PC_2(U, \mathbb{R}) = \{r : U \rightarrow \mathbb{R}\},$$

with norms

$$\|z\|_{\mathfrak{Y}_1} = \sup\{|z(v)|, v \in U\} \text{ and } \|r\|_{\mathfrak{Y}_2} = \sup\{|r(v)|, v \in U\},$$

respectively. Clearly, the product $\mathfrak{Y} = \mathfrak{Y}_1 \times \mathfrak{Y}_2$ is a BS endowed with $\|(z, r)\|_{\mathfrak{Y}} = \|z\|_{\mathfrak{Y}_1} + \|r\|_{\mathfrak{Y}_2}$.

Definition 2.1. [34] For a real valued function $z : (0, \infty) \rightarrow \mathbb{R}$, the RLF integral operator of order ρ is described as

$$I^\rho z(\tau) = \frac{1}{\Gamma(\rho)} \int_0^\tau (\tau - \hbar)^{\rho-1} z(\hbar) d\hbar,$$

where $\Gamma(\cdot)$ is the Euler gamma function.

Definition 2.2. [34] The RLF derivative of order ρ of a function $z : (0, \infty) \rightarrow \mathbb{R}$ takes the form

$$D^\rho z(\tau) = \frac{1}{\Gamma(n - \rho)} \left(\frac{d}{d\tau} \right)^n \int_0^\tau (\tau - \hbar)^{n-\rho-1} z(\hbar) d\hbar, \quad n = [\rho] + 1.$$

where $[\rho]$ refers to the integer part of real number ρ .

Lemma 2.1. [34, 35] Assume that $\rho > 0$ and $z \in C(0, 1)$. Then the FDE $D^\rho z(\tau) = 0$ owns a general solution $z(\tau) = \sum_{j=1}^n O_j \tau^{\rho-j}$, where $j - 1 < \rho \leq j$ and the constants $O_1, O_2, \dots, O_n \in \mathbb{R}$.

Lemma 2.2. [34] Assume that $\rho > 0$ and $z \in C(0, 1)$. Then, we have

$$I^\rho D^\rho z(\tau) = z(\tau) + \sum_{j=1}^n O_j \tau^{\rho-j},$$

where $j - 1 < \rho \leq j$ and the constants $O_1, O_2, \dots, O_j \in \mathbb{R}$.

Lemma 2.3. [4] Assume that $\rho, \theta > 0$ with $\rho > \theta$, then $I_{0+}^\rho D_{0+}^\theta = I_{0+}^{\rho-\theta}$.

The auxiliary theorems that follows is also required.

Theorem 2.1. (Krasnoselskii's FP theorem [36]) Assume that S is a non-empty, closed, bounded and convex subset of a BS \mathfrak{J} . Let $\Omega, \Omega^* : S \rightarrow S$ be operators such that

- (1) $\Omega(z) + \Omega^*(r) \in S$, where $z, r \in S$;
- (2) Ω^* is a contraction mapping;
- (3) Ω is completely continuous.

Then there exists $z \in S$ so that $z = \Omega(z) + \Omega^*(z)$.

Theorem 2.2. (Banach FP theorem [37]) Every contraction self-mapping defined on a complete metric space admits a unique FP.

3. Existence results

We begin this section with the lemma below.

Lemma 3.1. The mappings z_0, r_0 are a solution for CBVP (1.4) if z_0, r_0 are solutions to the following integral equations:

$$\begin{aligned} & z(\tau) \\ = & \frac{\nu - 1}{\nu \Gamma(\rho - \theta)} \int_0^\tau (\tau - \hbar)^{\rho-\theta-1} z(\hbar) d\hbar + \frac{1}{\nu \Gamma(\rho)} \int_0^\tau (\tau - \hbar)^{\rho-1} \Xi(\hbar, z(\hbar), r(\hbar)) d\hbar \\ & + \frac{\tau^{\rho-1}}{\Phi} \left(\frac{\varrho_1 \nabla_4(\nu - 1)}{\nu} I^{\rho-\theta-\eta_1} z(G) - \frac{\varrho_2 \nabla_2(\nu - 1)}{\nu} I^{\rho-\theta-s_1} z(G) \right) \\ & + \frac{\nabla_4(1 - \varrho_1)(\nu - 1)}{\nu} I^{\rho-\theta-\eta_2} z(G) - \frac{\nabla_2(1 - \varrho_2)(\nu - 1)}{\nu} I^{\rho-\theta-s_2} z(G) \end{aligned}$$

$$\begin{aligned}
& + \frac{\varrho_1 \nabla_4}{\nu} I^{\rho-\eta_1} \Xi(G, z(G), r(G)) - \frac{\varrho_2 \nabla_2}{\nu} I^{\rho+s_1} \Xi(G, z(G), r(G)) + \nabla_2 \xi_2 - \nabla_4 \xi_1 \\
& + \left. \left(\frac{(1-\varrho_1) \nabla_4}{\nu} I^{\rho-\eta_2} \Xi(G, z(G), r(G)) - \frac{(1-\varrho_2) \nabla_2}{\nu} I^{\rho+s_2} \Xi(G, z(G), r(G)) \right) \right) \\
& - \frac{\tau^{\rho-2}}{\Phi} \left(\frac{\varrho_1 \nabla_3(\nu-1)}{\nu} I^{\rho-\theta-\eta_1} z(G) - \frac{\varrho_2 \nabla_1(\nu-1)}{\nu} I^{\rho-\theta-s_1} z(G) \right. \\
& + \frac{\nabla_3(1-\varrho_1)(\nu-1)}{\nu} I^{\rho-\theta-\eta_2} z(G) - \frac{\nabla_1(1-\varrho_2)(\nu-1)}{\nu} I^{\rho-\theta-s_2} z(G) \\
& + \frac{\varrho_1 \nabla_3}{\nu} I^{\rho-\eta_1} \Xi(G, z(G), r(G)) - \frac{\varrho_2 \nabla_1}{\nu} I^{\rho+s_1} \Xi(G, z(G), r(G)) + \nabla_1 \xi_2 - \nabla_3 \xi_1 \\
& \left. + \frac{(1-\varrho_1) \nabla_3}{\nu} I^{\rho-\eta_2} \Xi(G, z(G), r(G)) - \frac{(1-\varrho_2) \nabla_1}{\nu} I^{\rho+s_2} \Xi(G, z(G), r(G)) \right), \quad (3.1)
\end{aligned}$$

and

$$\begin{aligned}
r(\tau) = & \frac{\nu^* - 1}{\nu^* \Gamma(\rho^* - \theta^*)} \int_0^\tau (\tau - \hbar)^{\rho^* - \theta^* - 1} r(\hbar) d\hbar + \frac{1}{\nu^* \Gamma(\rho^*)} \int_0^\tau (\tau - \hbar)^{\rho^* - 1} \Xi^*(\hbar, r(\hbar), z(\hbar)) d\hbar \\
& + \frac{\tau^{\rho^* - 1}}{\Phi^*} \left(\frac{\varrho_1^* \nabla_4^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_1^*} r(G) - \frac{\varrho_2^* \nabla_2^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* + s_1^*} r(G) \right. \\
& + \frac{\nabla_4^*(1 - \varrho_1^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_2^*} r(G) - \frac{\nabla_2^*(1 - \varrho_2^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* + s_2^*} r(G) \\
& + \frac{\varrho_1^* \nabla_4^*}{\nu^*} I^{\rho^* - \eta_1^*} \Xi^*(G, r(G), z(G)) - \frac{\varrho_2^* \nabla_2^*}{\nu^*} I^{\rho^* + s_1^*} \Xi^*(G, r(G), z(G)) + \nabla_2^* \xi_2^* - \nabla_4^* \xi_1^* \\
& \left. + \frac{(1 - \varrho_1^*) \nabla_4^*}{\nu^*} I^{\rho^* - \eta_2^*} \Xi^*(G, r(G), z(G)) - \frac{(1 - \varrho_2^*) \nabla_2^*}{\nu^*} I^{\rho^* + s_2^*} \Xi^*(G, r(G), z(G)) \right) \\
& - \frac{\tau^{\rho^* - 2}}{\Phi^*} \left(\frac{\varrho_1^* \nabla_3^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_1^*} r(G) - \frac{\varrho_2^* \nabla_1^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* + s_1^*} r(G) \right. \\
& + \frac{\nabla_3^*(1 - \varrho_1^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_2^*} r(G) - \frac{\nabla_1^*(1 - \varrho_2^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* + s_2^*} r(G) \\
& + \frac{\varrho_1^* \nabla_3^*}{\nu^*} I^{\rho^* - \eta_1^*} \Xi^*(G, r(G), z(G)) - \frac{\varrho_2^* \nabla_1^*}{\nu^*} I^{\rho^* + s_1^*} \Xi^*(G, r(G), z(G)) + \nabla_1^* \xi_2^* - \nabla_3^* \xi_1^* \\
& \left. + \frac{(1 - \varrho_1^*) \nabla_3^*}{\nu^*} I^{\rho^* - \eta_2^*} \Xi^*(G, r(G), z(G)) - \frac{(1 - \varrho_2^*) \nabla_1^*}{\nu^*} I^{\rho^* + s_2^*} \Xi^*(G, r(G), z(G)) \right), \quad (3.2)
\end{aligned}$$

where

$$\begin{aligned}
\nabla_1 &= \frac{\varrho_1 \Gamma(\rho)}{\Gamma(\rho - \eta_1)} G^{\rho - \eta_1 - 1} + \frac{(1 - \varrho_1) \Gamma(\rho)}{\Gamma(\rho - \eta_2)} G^{\rho - \eta_2 - 1}, & \nabla_1^* &= \frac{\varrho_1^* \Gamma(\rho^*)}{\Gamma(\rho^* - \eta_1^*)} G^{\rho^* - \eta_1^* - 1} - \frac{(1 - \varrho_1^*) \Gamma(\rho^*)}{\Gamma(\rho^* - \eta_2^*)} G^{\rho^* - \eta_2^* - 1}, \\
\nabla_2 &= \frac{\varrho_1 \Gamma(\rho - 1)}{\Gamma(\rho - \eta_1 - 1)} G^{\rho - \eta_1 - 2} + \frac{(1 - \varrho_1) \Gamma(\rho - 1)}{\Gamma(\rho - \eta_2 - 1)} G^{\rho - \eta_2 - 2}, & \nabla_2^* &= \frac{\varrho_1^* \Gamma(\rho^* - 1)}{\Gamma(\rho^* - \eta_1^* - 1)} G^{\rho^* - \eta_1^* - 2} - \frac{(1 - \varrho_1^*) \Gamma(\rho^* - 1)}{\Gamma(\rho^* - \eta_2^* - 1)} G^{\rho^* - \eta_2^* - 2}, \\
\nabla_3 &= \frac{\varrho_2 \Gamma(\rho)}{\Gamma(\rho + s_1)} G^{\rho + s_1 - 1} + \frac{(1 - \varrho_2) \Gamma(\rho)}{\Gamma(\rho + s_2)} G^{\rho + s_2 - 1}, & \nabla_3^* &= \frac{\varrho_2^* \Gamma(\rho^*)}{\Gamma(\rho^* + s_1^*)} G^{\rho^* + s_1^* - 1} - \frac{(1 - \varrho_2^*) \Gamma(\rho^*)}{\Gamma(\rho^* + s_2^*)} G^{\rho^* + s_2^* - 1}, \\
\nabla_4 &= \frac{\varrho_2 \Gamma(\rho - 1)}{\Gamma(\rho + s_1 - 1)} G^{\rho + s_1 - 2} + \frac{(1 - \varrho_2) \Gamma(\rho - 1)}{\Gamma(\rho + s_2 - 1)} G^{\rho + s_2 - 2}, & \nabla_4^* &= \frac{\varrho_2^* \Gamma(\rho^* - 1)}{\Gamma(\rho^* + s_1^* - 1)} G^{\rho^* + s_1^* - 2} - \frac{(1 - \varrho_2^*) \Gamma(\rho^* - 1)}{\Gamma(\rho^* + s_2^* - 1)} G^{\rho^* + s_2^* - 2}, \\
\Phi &= \nabla_3 \nabla_2 - \nabla_1 \nabla_4, & \Phi^* &= \nabla_3^* \nabla_2^* - \nabla_1^* \nabla_4^*.
\end{aligned} \quad (3.3)$$

Proof. Let (z_0, r_0) be a solution for the Eq (1.4), then, we get

$$\begin{cases} D^\rho z_0(\tau) = \frac{(\nu-1)}{\nu} D^\theta z_0(\tau) + \frac{1}{\nu} \Xi(\tau, z_0(\tau), r_0(\tau)), \\ D^{\rho^*} r_0(\tau) = \frac{(\nu^*-1)}{\nu^*} D^{\theta^*} z_0(\tau) + \frac{1}{\nu^*} \Xi(\tau, r_0(\tau), z_0(\tau)). \end{cases} \quad (3.4)$$

Taking the RLF integration of order ρ from both sides of the first equation in (3.4), we have

$$z_0(\tau) = \frac{\nu-1}{\nu\Gamma(\rho-\theta)} \int_0^\tau (\tau-\hbar)^{\rho-\theta-1} z_0(\hbar) d\hbar + \frac{1}{\nu\Gamma(\rho)} \int_0^\tau (\tau-\hbar)^{\rho-1} \Xi(\tau, z_0(\tau), r_0(\tau)) d\hbar + O_1\tau^{\rho-1} + O_2\tau^{\rho-2} + O_3\tau^{\rho-3},$$

where O_1, O_2 and O_3 are real constants. From the first boundary stipulation of (1.4), for $\rho \in (2, 3)$, we have $O_3 = 0$. By Lemma 2.3, we can write

$$z_0(\tau) = \frac{\nu-1}{\nu} I^{\rho-\theta} z_0(\tau) + \frac{1}{\nu} I^\rho \Xi(\tau, z_0(\tau), r_0(\tau)) + O_1\tau^{\rho-1} + O_2\tau^{\rho-2}. \quad (3.5)$$

Using the RLF integral and derivative of order η and s , respectively with $\eta \in \{\eta_1, \eta_2\}$, $s \in \{s_1, s_2\}$, $0 < \eta < \rho - \theta$ and $2 < \theta < \rho$, we obtain

$$D^\eta z_0(\tau) = \frac{\nu-1}{\nu\Gamma(\rho-\theta-\eta)} \int_0^\tau (\tau-\hbar)^{\rho-\theta-\eta-1} z_0(\hbar) d\hbar + O_1 \frac{\Gamma(\rho)}{\Gamma(\rho-\eta)} \tau^{\rho-\eta-1} + \frac{1}{\nu\Gamma(\rho-\eta)} \int_0^\tau (\tau-\hbar)^{\rho-\eta-1} \Xi(\hbar, z_0(\hbar), r_0(\hbar)) d\hbar + O_2 \frac{\Gamma(\rho-1)}{\Gamma(\rho-\eta-1)} \tau^{\rho-\eta-2}.$$

and

$$I^s z_0(\tau) = \frac{\nu-1}{\nu\Gamma(\rho-\theta+s)} \int_0^\tau (\tau-\hbar)^{\rho-\theta+s-1} z_0(\hbar) d\hbar + O_1 \frac{\Gamma(\rho)}{\Gamma(\rho+s)} \tau^{\rho+s-1} + \frac{1}{\nu\Gamma(\rho+s)} \int_0^\tau (\tau-\hbar)^{\rho+s-1} \Xi(\hbar, z_0(\hbar), r_0(\hbar)) d\hbar + O_2 \frac{\Gamma(\rho-1)}{\Gamma(\rho+s-1)} \tau^{\rho+s-2}.$$

Replacing $\eta = \eta_1, \eta = \eta_2, s = s_1, s = s_2$ and using the boundary stipulations $\varrho_1 D^{\eta_1} z(G) + (1 - \varrho_1) D^{\eta_2} z(G) = \xi_1$ and $\varrho_2 I^{s_1} z(G) + (1 - \varrho_2) I^{s_2} z(G) = \xi_2$, we can write

$$\begin{aligned} \xi_1 &= \frac{\varrho_1(\nu-1)}{\nu\Gamma(\rho-\theta-\eta_1)} \int_0^G (G-\hbar)^{\rho-\theta-\eta_1-1} z_0(\hbar) d\hbar + \frac{(1-\varrho_1)(\nu-1)}{\nu\Gamma(\rho-\theta-\eta_2)} \int_0^G (G-\hbar)^{\rho-\theta-\eta_2-1} z_0(\hbar) d\hbar \\ &+ \frac{\varrho_1}{\nu\Gamma(\rho-\eta_1)} \int_0^G (G-\hbar)^{\rho-\eta_1-1} \Xi(\hbar, z_0(\hbar), r_0(\hbar)) d\hbar + O_1 \nabla_1 \\ &+ \frac{(1-\varrho_1)}{\nu\Gamma(\rho-\eta_2)} \int_0^G (G-\hbar)^{\rho-\eta_2-1} \Xi(\hbar, z_0(\hbar), r_0(\hbar)) d\hbar + O_2 \nabla_2, \end{aligned}$$

and

$$\begin{aligned} \xi_2 &= \frac{\varrho_2(\nu-1)}{\nu\Gamma(\rho-\theta+s_1)} \int_0^G (G-\hbar)^{\rho-\theta+s_1-1} z_0(\hbar) d\hbar + \frac{(1-\varrho_2)(\nu-1)}{\nu\Gamma(\rho-\theta+s_2)} \int_0^G (G-\hbar)^{\rho-\theta+s_2-1} z_0(\hbar) d\hbar \\ &+ \frac{\varrho_2}{\nu\Gamma(\rho+s_1)} \int_0^G (G-\hbar)^{\rho+s_1-1} \Xi(\hbar, z_0(\hbar), r_0(\hbar)) d\hbar + O_1 \nabla_3 \end{aligned}$$

$$+ \frac{(1 - \varrho_2)}{\nu \Gamma(\rho + s_2)} \int_0^G (G - \hbar)^{\rho + s_2 - 1} \Xi(\hbar, z_0(\hbar), r_0(\hbar)) d\hbar + O_2 \nabla_4,$$

which yields that

$$\begin{aligned} O_1 = & \frac{\varrho_1 \nabla_4 (\nu - 1)}{\nu} I^{\rho - \theta - \eta_1} z_0(G) - \frac{\varrho_2 \nabla_2 (\nu - 1)}{\nu} I^{\rho - \theta + s_1} z_0(G) \\ & + \frac{\nabla_4 (1 - \varrho_1) (\nu - 1)}{\nu} I^{\rho - \theta - \eta_2} z_0(G) - \frac{\nabla_2 (1 - \varrho_2) (\nu - 1)}{\nu} I^{\rho - \theta + s_2} z_0(G) \\ & + \frac{\varrho_1 \nabla_4}{\nu} I^{\rho - \eta_1} \Xi(G, z_0(G), r_0(G)) - \frac{\varrho_2 \nabla_2}{\nu} I^{\rho + s_1} \Xi(G, z_0(G), r_0(G)) + \nabla_2 \xi_2 - \nabla_4 \xi_1 \\ & + \frac{(1 - \varrho_1) \nabla_3}{\nu} I^{\rho - \eta_2} \Xi(G, z_0(G), r_0(G)) - \frac{(1 - \varrho_2) \nabla_1}{\nu} I^{\rho + s_2} \Xi(G, z_0(G), r_0(G)). \end{aligned}$$

and

$$\begin{aligned} O_2 = & \frac{\varrho_1 \nabla_3 (\nu - 1)}{\nu} I^{\rho - \theta - \eta_1} z_0(G) - \frac{\varrho_2 \nabla_1 (\nu - 1)}{\nu} I^{\rho - \theta + s_1} z_0(G) \\ & + \frac{\nabla_3 (1 - \varrho_1) (\nu - 1)}{\nu} I^{\rho - \theta - \eta_2} z_0(G) - \frac{\nabla_1 (1 - \varrho_2) (\nu - 1)}{\nu} I^{\rho - \theta + s_2} z_0(G) \\ & + \frac{\varrho_1 \nabla_3}{\nu} I^{\rho - \eta_1} \Xi(G, z_0(G), r_0(G)) - \frac{\varrho_2 \nabla_1}{\nu} I^{\rho + s_1} \Xi(G, z_0(G), r_0(G)) + \nabla_1 \xi_2 - \nabla_3 \xi_1 \\ & + \frac{(1 - \varrho_1) \nabla_3}{\nu} I^{\rho - \eta_2} \Xi(G, z_0(G), r_0(G)) - \frac{(1 - \varrho_2) \nabla_1}{\nu} I^{\rho + s_2} \Xi(G, z_0(G), r_0(G)) \Big), \end{aligned}$$

Substituting O_1 and O_2 in (1.4), we have the first part of the solution (3.1). With the same scenario followed above, the second part of the solution (3.2) can easily be obtained.

Now, we convert the problem to the FP problem. Based on Lemma 3.1, define an operator $\Omega : \mathfrak{J} \rightarrow \mathfrak{J}$ by

$$\Omega(z, r) = (\Omega_1(z, r), \Omega_2(z, r)),$$

where

$$\begin{aligned} & \Omega_1(z, r) \\ = & \frac{\nu - 1}{\nu \Gamma(\rho - \theta)} \int_0^\tau (\tau - \hbar)^{\rho - \theta - 1} z(\hbar) d\hbar + \frac{1}{\nu \Gamma(\rho)} \int_0^\tau (\tau - \hbar)^{\rho - 1} \Xi(\hbar, z(\hbar), r(\hbar)) d\hbar \\ & + \frac{\tau^{\rho - 1}}{\Phi} \left(\frac{\varrho_1 \nabla_4 (\nu - 1)}{\nu} I^{\rho - \theta - \eta_1} z(G) - \frac{\varrho_2 \nabla_2 (\nu - 1)}{\nu} I^{\rho - \theta + s_1} z(G) \right. \\ & + \frac{\nabla_4 (1 - \varrho_1) (\nu - 1)}{\nu} I^{\rho - \theta - \eta_2} z(G) - \frac{\nabla_2 (1 - \varrho_2) (\nu - 1)}{\nu} I^{\rho - \theta + s_2} z(G) \\ & + \frac{\varrho_1 \nabla_4}{\nu} I^{\rho - \eta_1} \Xi(G, z(G), r(G)) - \frac{\varrho_2 \nabla_2}{\nu} I^{\rho + s_1} \Xi(G, z(G), r(G)) + \nabla_2 \xi_2 - \nabla_4 \xi_1 \\ & \left. + \frac{(1 - \varrho_1) \nabla_4}{\nu} I^{\rho - \eta_2} \Xi(G, z(G), r(G)) - \frac{(1 - \varrho_2) \nabla_2}{\nu} I^{\rho + s_2} \Xi(G, z(G), r(G)) \right) \\ & - \frac{\tau^{\rho - 2}}{\Phi} \left(\frac{\varrho_1 \nabla_3 (\nu - 1)}{\nu} I^{\rho - \theta - \eta_1} z(G) - \frac{\varrho_2 \nabla_1 (\nu - 1)}{\nu} I^{\rho - \theta + s_1} z(G) \right) \end{aligned}$$

$$\begin{aligned}
& + \frac{\nabla_3(1-\varrho_1)(\nu-1)}{\nu} I^{\rho-\theta-\eta_2} z(G) - \frac{\nabla_1(1-\varrho_2)(\nu-1)}{\nu} I^{\rho-\theta+s_2} z(G) \\
& + \frac{\varrho_1 \nabla_3}{\nu} I^{\rho-\eta_1} \Xi(G, z(G), r(G)) - \frac{\varrho_2 \nabla_1}{\nu} I^{\rho+s_1} \Xi(G, z(G), r(G)) + \nabla_1 \xi_2 - \nabla_3 \xi_1 \\
& + \left. \frac{(1-\varrho_1) \nabla_3}{\nu} I^{\rho-\eta_2} \Xi(G, z(G), r(G)) - \frac{(1-\varrho_2) \nabla_1}{\nu} I^{\rho+s_2} \Xi(G, z(G), r(G)) \right), \quad (3.6)
\end{aligned}$$

and

$$\begin{aligned}
\Omega_2(z, r) = & \frac{\nu^* - 1}{\nu^* \Gamma(\rho^* - \theta^*)} \int_0^\tau (\tau - \hbar)^{\rho^* - \theta^* - 1} r(\hbar) d\hbar + \frac{1}{\nu^* \Gamma(\rho^*)} \int_0^\tau (\tau - \hbar)^{\rho^* - 1} \Xi^*(\hbar, r(\hbar), z(\hbar)) d\hbar \\
& + \frac{\tau^{\rho^* - 1}}{\Phi^*} \left(\frac{\varrho_1^* \nabla_4^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_1^*} r(G) - \frac{\varrho_2^* \nabla_2^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - s_1^*} r(G) \right. \\
& + \frac{\nabla_4^*(1 - \varrho_1^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_2^*} r(G) - \frac{\nabla_2^*(1 - \varrho_2^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - s_2^*} r(G) \\
& + \frac{\varrho_1^* \nabla_4^*}{\nu^*} I^{\rho^* - \eta_1^*} \Xi^*(G, r(G), z(G)) - \frac{\varrho_2^* \nabla_2^*}{\nu^*} I^{\rho^* + s_1^*} \Xi^*(G, r(G), z(G)) + \nabla_2^* \xi_2^* - \nabla_4^* \xi_1^* \\
& \left. + \frac{(1 - \varrho_1^*) \nabla_4^*}{\nu^*} I^{\rho^* - \eta_2^*} \Xi^*(G, r(G), z(G)) - \frac{(1 - \varrho_2^*) \nabla_2^*}{\nu^*} I^{\rho^* + s_2^*} \Xi^*(G, r(G), z(G)) \right) \\
& - \frac{\tau^{\rho^* - 2}}{\Phi^*} \left(\frac{\varrho_1^* \nabla_3^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_1^*} r(G) - \frac{\varrho_2^* \nabla_1^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - s_1^*} r(G) \right. \\
& + \frac{\nabla_3^*(1 - \varrho_1^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_2^*} r(G) - \frac{\nabla_1^*(1 - \varrho_2^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - s_2^*} r(G) \\
& + \frac{\varrho_1^* \nabla_3^*}{\nu^*} I^{\rho^* - \eta_1^*} \Xi^*(G, r(G), z(G)) - \frac{\varrho_2^* \nabla_1^*}{\nu^*} I^{\rho^* + s_1^*} \Xi^*(G, r(G), z(G)) + \nabla_1^* \xi_2^* - \nabla_3^* \xi_1^* \\
& \left. + \frac{(1 - \varrho_1^*) \nabla_3^*}{\nu^*} I^{\rho^* - \eta_2^*} \Xi^*(G, r(G), z(G)) - \frac{(1 - \varrho_2^*) \nabla_1^*}{\nu^*} I^{\rho^* + s_2^*} \Xi^*(G, r(G), z(G)) \right). \quad (3.7)
\end{aligned}$$

Remember that the solution to CBVP (1.4) is (z_0, r_0) iff (z_0, r_0) is a FP of Ω . We employ the following notation to streamline calculations:

$$\begin{aligned}
\Lambda_1 = & \frac{|\nu - 1| (\nabla_4 + \nabla_3 G^{-1})}{|\Phi|} \left(\frac{\varrho_1 G^{2\rho - \theta - \eta_1 - 1}}{\nu \Gamma(\rho - \theta - \eta_1 + 1)} + \frac{(1 - \varrho_1) G^{2\rho - \theta - \eta_2 - 1}}{\nu \Gamma(\rho - \theta - \eta_2 + 1)} \right) \\
& + \frac{|\nu - 1| (\nabla_2 + \nabla_1 G^{-1})}{|\Phi|} \left(\frac{\varrho_2 G^{2\rho - \theta + s_1 - 1}}{\nu \Gamma(\rho - \theta + s_1 + 1)} + \frac{(1 - \varrho_2) G^{2\rho - \theta + s_2 - 1}}{\nu \Gamma(\rho - \theta + s_2 + 1)} \right) \\
& + \frac{|\nu - 1| G^{\rho - \theta}}{\nu \Gamma(\rho - \theta + 1)}. \quad (3.8)
\end{aligned}$$

$$\Lambda_1^* = \frac{|\nu^* - 1| (\nabla_4^* + \nabla_3^* G^{-1})}{|\Phi^*|} \left(\frac{\varrho_1^* G^{2\rho^* - \theta^* - \eta_1^* - 1}}{\nu^* \Gamma(\rho^* - \theta^* - \eta_1^* + 1)} + \frac{(1 - \varrho_1^*) G^{2\rho^* - \theta^* - \eta_2^* - 1}}{\nu^* \Gamma(\rho^* - \theta^* - \eta_2^* + 1)} \right)$$

$$\begin{aligned}
& + \frac{|v^* - 1| (\nabla_4^* + \nabla_3^* G^{-1})}{|\Phi^*|} \left(\frac{\varrho_2^* G^{2\rho^* - \theta^* + s_1^* - 1}}{v^* \Gamma(\rho^* - \theta^* + s_1^* + 1)} + \frac{(1 - \varrho_2^*) G^{2\rho^* - \theta^* + s_2^* - 1}}{v^* \Gamma(\rho^* - \theta^* + s_2^* + 1)} \right) \\
& + \frac{|v^* - 1| G^{\rho^* - \theta^*}}{v^* \Gamma(\rho^* - \theta^* + 1)}. \tag{3.9}
\end{aligned}$$

$$\begin{aligned}
\Lambda_2 & = \frac{G^\rho}{v \Gamma(\rho + 1)} + \frac{\nabla_4 + \nabla_3 G^{-1}}{|\Phi|} \left(\frac{\varrho_1 G^{2\rho - \eta_1 - 1}}{v \Gamma(\rho - \eta_1 + 1)} + \frac{(1 - \varrho_1) G^{2\rho - \eta_2 - 1}}{v \Gamma(\rho - \eta_2 + 1)} \right) \\
& + \frac{\nabla_2 + \nabla_1 G^{-1}}{|\Phi|} \left(\frac{\varrho_2 G^{2\rho + s_1 - 1}}{v \Gamma(\rho + s_1 + 1)} + \frac{(1 - \varrho_2) G^{2\rho + s_2 - 1}}{v \Gamma(\rho + s_2 + 1)} \right). \tag{3.10}
\end{aligned}$$

$$\begin{aligned}
\Lambda_2^* & = \frac{G^{\rho^*}}{v^* \Gamma(\rho^* + 1)} + \frac{(\nabla_4^* + \nabla_3^* G^{-1})}{|\Phi^*|} \left(\frac{\varrho_1^* G^{2\rho^* - \eta_1^* - 1}}{v^* \Gamma(\rho^* - \eta_1^* + 1)} + \frac{(1 - \varrho_1^*) G^{2\rho^* - \eta_2^* - 1}}{v^* \Gamma(\rho^* - \eta_2^* + 1)} \right) \\
& + \frac{\nabla_4^* + \nabla_3^* G^{-1}}{|\Phi^*|} \left(\frac{\varrho_2^* G^{2\rho^* + s_1^* - 1}}{v^* \Gamma(\rho^* + s_1^* + 1)} + \frac{(1 - \varrho_2^*) G^{2\rho^* + s_2^* - 1}}{v^* \Gamma(\rho^* + s_2^* + 1)} \right). \tag{3.11}
\end{aligned}$$

Now, our main theorem is as follows:

Theorem 3.1. Assume that the mappings $\Xi, \Xi^* : U \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are continuous and there are constants $T_\Xi, \widetilde{T}_\Xi, T_{\Xi^*}, \widetilde{T}_{\Xi^*} > 0$ so that

$$|\Xi(\tau, z_1(\tau), z_2(\tau)) - \Xi(\tau, \widetilde{z}_1(\tau), \widetilde{z}_2(\tau))| \leq T_\Xi |z_1 - \widetilde{z}_1| + \widetilde{T}_\Xi |z_2 - \widetilde{z}_2|,$$

and

$$|\Xi^*(\tau, r_1(\tau), r_2(\tau)) - \Xi^*(\tau, \widetilde{r}_1(\tau), \widetilde{r}_2(\tau))| \leq T_{\Xi^*} |r_1 - \widetilde{r}_1| + \widetilde{T}_{\Xi^*} |r_2 - \widetilde{r}_2|,$$

for all $\tau \in U$ and $z_1, z_2, \widetilde{z}_1, \widetilde{z}_2, r_1, r_2, \widetilde{r}_1, \widetilde{r}_2 \in \mathbb{R}$. If $\widehat{T}\Lambda_4 + \Lambda_3 < 1$, then the considered problem (1.4) has a unique solution (US), where $\widehat{T} = \max\{T, T^*\}$, $T = \max\{T_\Xi, \widetilde{T}_\Xi\}$, $T^* = \max\{T_{\Xi^*}, \widetilde{T}_{\Xi^*}\}$, $\Lambda_1 + \Lambda_1^* = \Lambda_3$ and $\Lambda_2 + \Lambda_2^* = \Lambda_4$ and $\Lambda_1, \Lambda_1^*, \Lambda_2, \Lambda_2^*$ are described as (3.8)–(3.11), respectively.

Proof. Set $\sup_{v \in U} \Xi(\tau, 0, 0) = N < \infty$, $\sup_{v \in U} \Xi^*(\tau, 0, 0) = N^* < \infty$ and choose

$$\begin{aligned}
y & \geq \frac{\widehat{N}\Lambda_4}{1 - \widehat{T}\Lambda_4 - \Lambda_3} + \frac{(|\Phi| + |\Phi^*|) G^{\rho-1} (|\nabla_2 \xi_1| + |\nabla_4 \xi_2| + |\nabla_2^* \xi_1^*| + |\nabla_4^* \xi_2^*|)}{|\Phi| |\Phi^*| (1 - \widehat{T}\Lambda_4 - \Lambda_3)} \\
& + \frac{G^{\rho-2} (|\nabla_2 \xi_1| + |\nabla_4 \xi_2| + |\nabla_2^* \xi_1^*| + |\nabla_4^* \xi_2^*|)}{|\Phi| |\Phi^*| (1 - \widehat{T}\Lambda_4 - \Lambda_3)}, \tag{3.12}
\end{aligned}$$

where ∇_i and ∇_i^* , $i \in \{1, 2, 3, 4\}$, Φ and Φ^* are defined by (3.3) and $\widehat{N} = \max\{N, N^*\}$. As a first step, we show that $\Omega Q_y \subset Q_y$, where $Q_y = \{(z, r) \in \mathfrak{Y} : \|(z, r)\| \leq y\}$. For any $(z, r) \in Q_y$, we have

$$\|\Omega(z, r)\|_{\mathfrak{Y}} = \|\Omega_1(z, r)\|_{\mathfrak{Y}_1} + \|\Omega_2(z, r)\|_{\mathfrak{Y}_2} \tag{3.13}$$

From (3.6) and (3.7), we get

$$|\Omega_1(z, r)| \leq \frac{|v - 1|}{v \Gamma(\rho - \theta)} \int_0^\tau (\tau - \hbar)^{\rho - \theta - 1} |z(\hbar)| d\hbar$$

$$\begin{aligned}
& + \frac{1}{\nu \Gamma(\rho)} \int_0^\tau (\tau - \hbar)^{\rho-1} (|\Xi(\hbar, z(\hbar), r(\hbar)) - \Xi(\hbar, 0, 0)| + |\Xi(\hbar, 0, 0)|) d\hbar \\
& + \frac{G^{\rho-1}}{|\Phi|} \left(\frac{\varrho_1 \nabla_4 |\nu - 1|}{\nu} I^{\rho-\theta-\eta_1} |z(G)| - \frac{\varrho_2 \nabla_2 |\nu - 1|}{\nu} I^{\rho-\theta+s_1} |z(G)| \right. \\
& + \frac{\nabla_4 |1 - \varrho_1| (|\nu - 1|)}{\nu} I^{\rho-\theta-\eta_2} |z(G)| - \frac{\nabla_2 |1 - \varrho_2| |\nu - 1|}{\nu} I^{\rho-\theta+s_2} |z(G)| \\
& + \frac{\varrho_1 \nabla_4}{\nu} I^{\rho-\eta_1} [|\Xi(G, z(G), r(G)) - \Xi(G, 0, 0)| + |\Xi(G, 0, 0)|] \\
& - \frac{\varrho_2 \nabla_2}{\nu} I^{\rho+s_1} [|\Xi(G, z(G), r(G)) - \Xi(G, 0, 0)| + |\Xi(G, 0, 0)|] + |\nabla_2 \xi_2| + |\nabla_4 \xi_1| \\
& + \frac{(1 - \varrho_1) \nabla_4}{\nu} I^{\rho-\eta_2} [|\Xi(G, z(G), r(G)) - \Xi(G, 0, 0)| + |\Xi(G, 0, 0)|] \\
& - \frac{(1 - \varrho_2) \nabla_2}{\nu} I^{\rho+s_2} [|\Xi(G, z(G), r(G)) - \Xi(G, 0, 0)| + |\Xi(G, 0, 0)|] \Big) \\
& - \frac{G^{\rho-2}}{\Phi} \left(\frac{\varrho_1 \nabla_3 |\nu - 1|}{\nu} I^{\rho-\theta-\eta_1} |z(G)| - \frac{\varrho_2 \nabla_1 |\nu - 1|}{\nu} I^{\rho-\theta+s_1} |z(G)| \right. \\
& + \frac{\nabla_3 |1 - \varrho_1| (|\nu - 1|)}{\nu} I^{\rho-\theta-\eta_2} |z(G)| - \frac{\nabla_1 |1 - \varrho_2| |\nu - 1|}{\nu} I^{\rho-\theta+s_2} |z(G)| \\
& + \frac{\varrho_1 \nabla_3}{\nu} I^{\rho-\eta_1} [|\Xi(G, z(G), r(G)) - \Xi(G, 0, 0)| + |\Xi(G, 0, 0)|] \\
& - \frac{\varrho_2 \nabla_1}{\nu} I^{\rho+s_1} [|\Xi(G, z(G), r(G)) - \Xi(G, 0, 0)| + |\Xi(G, 0, 0)|] + |\nabla_1 \xi_2| + |\nabla_3 \xi_1| \\
& + \frac{(1 - \varrho_1) \nabla_3}{\nu} I^{\rho-\eta_2} [|\Xi(G, z(G), r(G)) - \Xi(G, 0, 0)| + |\Xi(G, 0, 0)|] \\
& - \frac{(1 - \varrho_2) \nabla_1}{\nu} I^{\rho+s_2} [|\Xi(G, z(G), r(G)) - \Xi(G, 0, 0)| + |\Xi(G, 0, 0)|] \Big),
\end{aligned}$$

which implies that

$$\begin{aligned}
& \|\Omega_1(z, r)\|_{\mathfrak{S}_1} \\
& \leq (T \|(z, r)\| + N) \Lambda_2 + \|(z, r)\| \Lambda_1 + \frac{1}{|\Phi|} \left[G^{\rho-1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho-2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right] \\
& = (T \Lambda_2 + \Lambda_1) \|(z, r)\| + N \Lambda_2 + \frac{1}{|\Phi|} \left[G^{\rho-1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho-2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right]. \quad (3.14)
\end{aligned}$$

In the same scenario, we can write

$$\begin{aligned}
& \|\Omega_2(z, r)\|_{\mathfrak{S}_2} \tag{3.15} \\
& \leq (T^* \Lambda_2^* + \Lambda_1^*) \|(z, r)\| + N^* \Lambda_2^* + \frac{1}{|\Phi^*|} \left[G^{\rho-1} (|\nabla_2^* \xi_2^*| + |\nabla_4^* \xi_1^*|) + G^{\rho-2} (|\nabla_1^* \xi_2^*| + |\nabla_3^* \xi_1^*|) \right].
\end{aligned}$$

Applying (3.14) and (3.15) in (3.13) and using (3.12), we have

$$\begin{aligned}
\|\Omega(z, r)\|_{\mathfrak{S}} & = \|\Omega_1(z, r)\|_{\mathfrak{S}_1} + \|\Omega_2(z, r)\|_{\mathfrak{S}_2} \\
& = (T \Lambda_2 + \Lambda_1 + T^* \Lambda_2^* + \Lambda_1^*) \|(z, r)\| + N \Lambda_2 + N^* \Lambda_2^*
\end{aligned}$$

$$\begin{aligned}
& + \frac{1}{|\Phi|} \left[G^{\rho-1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho-2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right] \\
& + \frac{1}{|\Phi^*|} \left[G^{\rho-1} (|\nabla_2^* \xi_2^*| + |\nabla_4^* \xi_1^*|) + G^{\rho-2} (|\nabla_1^* \xi_2^*| + |\nabla_3^* \xi_1^*|) \right] \\
& \leq (T\Lambda_2 + \Lambda_1 + T^*\Lambda_2^* + \Lambda_1^*)y + N\Lambda_2 + N^*\Lambda_2^* \\
& + \frac{1}{|\Phi|} \left[G^{\rho-1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho-2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right] \\
& + \frac{1}{|\Phi^*|} \left[G^{\rho-1} (|\nabla_2^* \xi_2^*| + |\nabla_4^* \xi_1^*|) + G^{\rho-2} (|\nabla_1^* \xi_2^*| + |\nabla_3^* \xi_1^*|) \right] \\
& \leq (\widehat{T}\Lambda_4 + \Lambda_3)y + \widehat{N}\Lambda_4 \\
& + \frac{1}{|\Phi|} \left[G^{\rho-1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho-2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right] \\
& + \frac{1}{|\Phi^*|} \left[G^{\rho-1} (|\nabla_2^* \xi_2^*| + |\nabla_4^* \xi_1^*|) + G^{\rho-2} (|\nabla_1^* \xi_2^*| + |\nabla_3^* \xi_1^*|) \right] \\
& \leq y+
\end{aligned}$$

Hence, $\|\Omega(z, r)\|_{\mathfrak{Y}} \leq y$ and so $\Omega Q_y \subset Q_y$. For each $v \in U$ and for $z, r, \tilde{z}, \tilde{r} \in \mathfrak{Y}$, we get

$$\begin{aligned}
& |\Omega_1(z, r)(\tau) - \Omega_1(\tilde{z}, \tilde{r})(v)| \\
& \leq \frac{|v-1|}{v\Gamma(\rho-\theta)} \int_0^\tau (\tau-h)^{\rho-\theta-1} |z(h) - \tilde{z}(h)| dh \\
& + \frac{1}{v\Gamma(\rho)} \int_0^\tau (\tau-h)^{\rho-1} |\Xi(h, z(h), r(h)) - \Xi(h, \tilde{z}(h), \tilde{r}(h))| dh \\
& + \frac{G^{\rho-1}}{|\Phi|} \left(\frac{\varrho_1 \nabla_4 |v-1|}{v} I^{\rho-\theta-\eta_1} |z(G) - \tilde{z}(G)| - \frac{\varrho_2 \nabla_2 |v-1|}{v} I^{\rho-\theta+s_1} |z(G) - \tilde{z}(G)| \right. \\
& + \frac{\nabla_4 |1-\varrho_1| (|v-1|)}{v} I^{\rho-\theta-\eta_2} |z(G) - \tilde{z}(G)| - \frac{\nabla_2 |1-\varrho_2| |v-1|}{v} I^{\rho-\theta+s_2} |z(G) - \tilde{z}(G)| \\
& + \frac{\varrho_1 \nabla_4}{v} I^{\rho-\eta_1} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \\
& - \frac{\varrho_2 \nabla_2}{v} I^{\rho+s_1} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \\
& + \frac{(1-\varrho_1)\nabla_4}{v} I^{\rho-\eta_2} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \\
& \left. - \frac{(1-\varrho_2)\nabla_2}{v} I^{\rho+s_2} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \right) \\
& - \frac{G^{\rho-2}}{\Phi} \left(\frac{\varrho_1 \nabla_3 |v-1|}{v} I^{\rho-\theta-\eta_1} |z(G)| - \frac{\varrho_2 \nabla_1 |v-1|}{v} I^{\rho-\theta+s_1} |z(G)| \right. \\
& + \frac{\nabla_3 |1-\varrho_1| (|v-1|)}{v} I^{\rho-\theta-\eta_2} |z(G) - \tilde{z}(G)| - \frac{\nabla_1 |1-\varrho_2| |v-1|}{v} I^{\rho-\theta+s_2} |z(G) - \tilde{z}(G)| \\
& + \frac{\varrho_1 \nabla_3}{v} I^{\rho-\eta_1} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \\
& \left. - \frac{\varrho_2 \nabla_2}{v} I^{\rho+s_1} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \right)
\end{aligned}$$

$$\left. \begin{aligned} & + \frac{(1 - \varrho_1) \nabla_3}{\nu} I^{\rho - \eta_2} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \\ & - \frac{(1 - \varrho_2) \nabla_1}{\nu} I^{\rho + s_2} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \end{aligned} \right),$$

which leads to

$$\|\Omega_1(z, r) - \Omega_1(\tilde{z}, \tilde{r})\|_{\mathfrak{Y}_1} \leq T\Lambda_2 (\|z - \tilde{z}\| + \|r - \tilde{r}\|) + \|z - \tilde{z}\| \Lambda_1.$$

Similarly, one can obtain

$$\|\Omega_2(z, r) - \Omega_2(\tilde{z}, \tilde{r})\|_{\mathfrak{Y}_2} \leq T^* \Lambda_2^* (\|z - \tilde{z}\| + \|r - \tilde{r}\|) + \|r - \tilde{r}\| \Lambda_1^*.$$

Hence,

$$\begin{aligned} \|\Omega(z, r) - \Omega(\tilde{z}, \tilde{r})\|_{\mathfrak{Y}} & \leq \|\Omega_1(z, r) - \Omega_1(\tilde{z}, \tilde{r})\|_{\mathfrak{Y}_1} + \|\Omega_2(z, r) - \Omega_2(\tilde{z}, \tilde{r})\|_{\mathfrak{Y}_2} \\ & = T\Lambda_2 (\|z - \tilde{z}\| + \|r - \tilde{r}\|) + \|z - \tilde{z}\| \Lambda_1 \\ & \quad + T^* \Lambda_2^* (\|z - \tilde{z}\| + \|r - \tilde{r}\|) + \|r - \tilde{r}\| \Lambda_1^* \\ & = (\Lambda_1 + T\Lambda_2 + T^* \Lambda_2^*) \|z - \tilde{z}\| + (\Lambda_1^* + T^* \Lambda_2^* + T\Lambda_2) \|r - \tilde{r}\| \\ & \leq (\Lambda_1 + \widehat{T}\Lambda_4) \|z - \tilde{z}\| + (\Lambda_1^* + \widehat{T}\Lambda_4) \|r - \tilde{r}\| \\ & \leq (\widehat{T}\Lambda_4 + \Lambda_3) \|(z, r) - (\tilde{z}, \tilde{r})\|. \end{aligned}$$

Since $\widehat{T}\Lambda_4 + \Lambda_3 < 1$, then Ω is a contraction mapping. Using the contraction principle, Ω has a unique FP, which is the US for the CBVP (1.4).

Now, we present an existence result by applying Krasnoselskii's FP theorem.

Theorem 3.2. *Suppose that the mappings $\Xi, \Xi^* : U \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are continuous and there are positive constants $T_{\Xi}, \widehat{T}_{\Xi}, T_{\Xi^*}, \widehat{T}_{\Xi^*}$ so that*

$$|\Xi(\tau, z_1(\tau), z_2(\tau)) - \Xi(\tau, \tilde{z}_1(\tau), \tilde{z}_2(\tau))| \leq T_{\Xi} |z_1 - \tilde{z}_1| + \widehat{T}_{\Xi} |z_2 - \tilde{z}_2|,$$

and

$$|\Xi^*(\tau, r_1(\tau), r_2(\tau)) - \Xi^*(\tau, \tilde{r}_1(\tau), \tilde{r}_2(\tau))| \leq T_{\Xi^*} |r_1 - \tilde{r}_1| + \widehat{T}_{\Xi^*} |r_2 - \tilde{r}_2|,$$

for all $\tau \in U$ and $z_1, z_2, \tilde{z}_1, \tilde{z}_2, r_1, r_2, \tilde{r}_1, \tilde{r}_2 \in \mathbb{R}$. If there are $V(\tau), V^*(\tau) \in C(U, \mathbb{R}_+)$ so that

$$\Xi(\tau, z(\tau), r(\tau)) \leq V(\tau) \text{ and } \Xi^*(\tau, z(\tau), r(\tau)) \leq V^*(\tau),$$

for all $(\tau, z, r) \in U \times \mathbb{R} \times \mathbb{R}$ and $\Lambda_3 < 1$, then, the CBVP (1.4) has at least one solution.

Proof. Consider $\sup_{\tau \in U} |V(\tau)| = \|V\|$, $\sup_{\tau \in U} |V^*(\tau)| = \|V^*\|$ and the set $Q_x = \{(z, r) \in \mathfrak{Y} : \|(z, r)\| \leq x\}$, where

$$\begin{aligned} x & \geq \frac{\widehat{V}\Lambda_3}{1 - \Lambda_4} + \frac{(|\Phi| + |\Phi^*|) G^{\rho-1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1| + |\nabla_2^* \xi_2^*| + |\nabla_4^* \xi_1^*|)}{|\Phi| |\Phi^*| (1 - \Lambda_4)} \\ & \quad + \frac{(|\Phi| + |\Phi^*|) G^{\rho-2} (|\nabla_1 \xi_2| + |\nabla_1 \xi_1| + |\nabla_1^* \xi_2^*| + |\nabla_3^* \xi_1^*|)}{|\Phi| |\Phi^*| (1 - \Lambda_4)}, \end{aligned}$$

and $\nabla_i, \nabla_i^*, i \in \{1, 2, 3, 4\}$, Φ and Φ^* are defined by (3.3), $\widehat{V} = \max\{V, V^*\}$ and $\Lambda_3 = \Lambda_1 + \Lambda_1^*$. For any $(z, r) \in \mathcal{Q}_x$, define the operators $\Omega, \Omega^* : \mathfrak{Y} \rightarrow \mathfrak{Y}$ by

$$\Omega(z, r) = \widetilde{\Omega}_1(z, r) + \widetilde{\Omega}_2(z, r) \text{ and } \Omega^*(z, r) = \widehat{\Omega}_1(z, r) + \widehat{\Omega}_2(z, r),$$

where

$$\begin{aligned} \widetilde{\Omega}_1(z, r) = & \frac{\nu - 1}{\nu\Gamma(\rho - \theta)} \int_0^\tau (\tau - \hbar)^{\rho - \theta - 1} z(\hbar) d\hbar + \frac{\tau^{\rho-1}}{\Phi} \times \\ & \left(\frac{\varrho_1 \nabla_4(\nu - 1)}{\nu} I^{\rho - \theta - \eta_1} z(G) - \frac{\varrho_2 \nabla_2(\nu - 1)}{\nu} I^{\rho - \theta + s_1} z(G) \right. \\ & \left. + \frac{\nabla_4(1 - \varrho_1)(\nu - 1)}{\nu} I^{\rho - \theta - \eta_2} z(G) - \frac{\nabla_2(1 - \varrho_2)(\nu - 1)}{\nu} I^{\rho - \theta + s_2} z(G) \right) \\ & \frac{\tau^{\rho-2}}{\Phi} \left(\frac{\varrho_1 \nabla_3(\nu - 1)}{\nu} I^{\rho - \theta - \eta_1} z(G) - \frac{\varrho_2 \nabla_1(\nu - 1)}{\nu} I^{\rho - \theta + s_1} z(G) \right. \\ & \left. + \frac{\nabla_3(1 - \varrho_1)(\nu - 1)}{\nu} I^{\rho - \theta - \eta_2} z(G) - \frac{\nabla_1(1 - \varrho_2)(\nu - 1)}{\nu} I^{\rho - \theta + s_2} z(G) \right), \end{aligned} \quad (3.16)$$

$$\begin{aligned} \widehat{\Omega}_1(z, r) = & \frac{1}{\nu\Gamma(\rho)} \int_0^\tau (\tau - \hbar)^{\rho-1} \Xi(\hbar, z(\hbar), r(\hbar)) d\hbar + \frac{\tau^{\rho-1}}{\Phi} \times \\ & \left(\frac{\varrho_1 \nabla_4}{\nu} I^{\rho - \eta_1} \Xi(G, z(G), r(G)) - \frac{\varrho_2 \nabla_2}{\nu} I^{\rho + s_1} \Xi(G, z(G), r(G)) + \nabla_2 \xi_2 - \nabla_4 \xi_1 \right. \\ & \left. + \frac{(1 - \varrho_1) \nabla_4}{\nu} I^{\rho - \eta_2} \Xi(G, z(G), r(G)) - \frac{(1 - \varrho_2) \nabla_2}{\nu} I^{\rho + s_2} \Xi(G, z(G), r(G)) \right) \\ & - \frac{\tau^{\rho-2}}{\Phi} \left(\frac{\varrho_1 \nabla_3}{\nu} I^{\rho - \eta_1} \Xi(G, z(G), r(G)) - \frac{\varrho_2 \nabla_1}{\nu} I^{\rho + s_1} \Xi(G, z(G), r(G)) \right. \\ & \left. + \frac{(1 - \varrho_1) \nabla_3}{\nu} I^{\rho - \eta_2} \Xi(G, z(G), r(G)) - \frac{(1 - \varrho_2) \nabla_1}{\nu} I^{\rho + s_2} \Xi(G, z(G), r(G)) \right. \\ & \left. + \nabla_1 \xi_2 - \nabla_3 \xi_1 \right), \end{aligned} \quad (3.17)$$

$$\begin{aligned} \widetilde{\Omega}_2(z, r) = & \frac{\nu^* - 1}{\nu^* \Gamma(\rho^* - \theta^*)} \int_0^\tau (\tau - \hbar)^{\rho^* - \theta^* - 1} r(\hbar) d\hbar + \frac{\tau^{\rho^*-1}}{\Phi^*} \times \\ & \left(\frac{\varrho_1^* \nabla_4^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_1^*} r(G) - \frac{\varrho_2^* \nabla_2^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* + s_1^*} r(G) \right. \\ & \left. - \frac{\nabla_4^*(1 - \varrho_1^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_2^*} r(G) - \frac{\nabla_2^*(1 - \varrho_2^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* + s_2^*} r(G) \right) \\ & - \frac{\tau^{\rho^*-2}}{\Phi^*} \left(\frac{\varrho_1^* \nabla_3^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_1^*} r(G) - \frac{\varrho_2^* \nabla_1^*(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* + s_1^*} r(G) \right. \\ & \left. + \frac{\nabla_3^*(1 - \varrho_1^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* - \eta_2^*} r(G) - \frac{\nabla_1^*(1 - \varrho_2^*)(\nu^* - 1)}{\nu^*} I^{\rho^* - \theta^* + s_2^*} r(G) \right), \end{aligned} \quad (3.18)$$

and

$$\widehat{\Omega}_2(z, r) = \frac{1}{\nu^* \Gamma(\rho^*)} \int_0^\tau (\tau - \hbar)^{\rho^* - 1} \Xi^*(\hbar, r(\hbar), z(\hbar)) d\hbar + \frac{\tau^{\rho^*-1}}{\Phi^*} \times$$

$$\begin{aligned}
& \left(+ \frac{\varrho_1^* \nabla_4^*}{\nu^*} I^{\rho^* - \eta_1^*} \Xi^*(G, r(G), z(G)) - \frac{\varrho_2^* \nabla_2^*}{\nu^*} I^{\rho^* + s_1^*} \Xi^*(G, r(G), z(G)) + \nabla_2^* \xi_2^* - \nabla_4^* \xi_1^* \right. \\
& \left. + \frac{(1 - \varrho_1^*) \nabla_4^*}{\nu^*} I^{\rho^* - \eta_2^*} \Xi^*(G, r(G), z(G)) - \frac{(1 - \varrho_2^*) \nabla_2^*}{\nu^*} I^{\rho^* + s_2^*} \Xi^*(G, r(G), z(G)) \right) \\
& - \frac{\tau^{\rho^* - 2}}{\Phi^*} \left(\frac{\varrho_1^* \nabla_3^*}{\nu^*} I^{\rho^* - \eta_1^*} \Xi^*(G, r(G), z(G)) - \frac{\varrho_2^* \nabla_1^*}{\nu^*} I^{\rho^* + s_1^*} \Xi^*(G, r(G), z(G)) + \right. \\
& \left. + \frac{(1 - \varrho_1^*) \nabla_3^*}{\nu^*} I^{\rho^* - \eta_2^*} \Xi^*(G, r(G), z(G)) - \frac{(1 - \varrho_2^*) \nabla_1^*}{\nu^*} I^{\rho^* + s_2^*} \Xi^*(G, r(G), z(G)) \right. \\
& \left. + \nabla_1^* \xi_2^* - \nabla_3^* \xi_1^* \right). \tag{3.19}
\end{aligned}$$

We shall show that $\Omega(z, r) + \Omega^*(z, r) \in \mathcal{Q}_x$, for all $(z, r) \in \mathcal{Q}_x$. From (3.16) and (3.17), we have

$$\begin{aligned}
& \left| \widetilde{\Omega}_1(z, r)(\tau) + \widehat{\Omega}_1(z, r)(\tau) \right| \\
\leq & \|V\| \left[\frac{G^\rho}{\nu \Gamma(\rho + 1)} + \frac{\nabla_4 + \nabla_3 G^{-1}}{|\Phi|} \left(\frac{\varrho_1 G^{2\rho - \eta_1 - 1}}{\nu \Gamma(\rho - \eta_1 + 1)} + \frac{(1 - \varrho_1) G^{2\rho - \eta_2 - 1}}{\nu \Gamma(\rho - \eta_2 + 1)} \right) \right. \\
& \left. + \frac{\nabla_2 + \nabla_1 G^{-1}}{|\Phi|} \left(\frac{\varrho_2 G^{2\rho + s_1 - 1}}{\nu \Gamma(\rho + s_1 + 1)} + \frac{(1 - \varrho_2) G^{2\rho + s_2 - 1}}{\nu \Gamma(\rho + s_2 + 1)} \right) \right] \\
& + \|(z, r)\| \left[\frac{|\nu - 1| G^{\rho - \theta}}{\nu \Gamma(\rho - \theta + 1)} + \frac{|\nu - 1| (\nabla_4 + \nabla_3 G^{-1})}{|\Phi|} \left(\frac{\varrho_1 G^{2\rho - \theta - \eta_1 - 1}}{\nu \Gamma(\rho - \theta - \eta_1 + 1)} + \frac{(1 - \varrho_1) G^{2\rho - \theta - \eta_2 - 1}}{\nu \Gamma(\rho - \theta - \eta_2 + 1)} \right) \right. \\
& \left. + \frac{|\nu - 1| (\nabla_2 + \nabla_1 G^{-1})}{|\Phi|} \left(\frac{\varrho_2 G^{2\rho - \theta + s_1 - 1}}{\nu \Gamma(\rho - \theta + s_1 + 1)} + \frac{(1 - \varrho_2) G^{2\rho - \theta + s_2 - 1}}{\nu \Gamma(\rho - \theta + s_2 + 1)} \right) \right. \\
& \left. + \frac{1}{|\Phi|} \left[G^{\rho - 1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho - 2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right] \right] \\
\leq & \|V\| \Lambda_1 + y \Lambda_2 + \frac{1}{|\Phi|} \left[G^{\rho - 1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho - 2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right]. \tag{3.20}
\end{aligned}$$

Analogously, using (3.18) and (3.19), we get

$$\begin{aligned}
& \left| \widetilde{\Omega}_2(z, r)(\tau) + \widehat{\Omega}_2(z, r)(\tau) \right| \\
\leq & \|V^*\| \Lambda_1^* + y \Lambda_2^* + \frac{1}{|\Phi^*|} \left[G^{\rho - 1} (|\nabla_2^* \xi_2^*| + |\nabla_4^* \xi_1^*|) + G^{\rho - 2} (|\nabla_1^* \xi_2^*| + |\nabla_3^* \xi_1^*|) \right]. \tag{3.21}
\end{aligned}$$

Combining (3.20) and (3.21), we obtain that

$$\begin{aligned}
|\Omega(z, r) + \Omega^*(z, r)| & \leq \left| \widetilde{\Omega}_1(z, r)(\tau) + \widehat{\Omega}_1(z, r)(\tau) \right| + \left| \widetilde{\Omega}_2(z, r)(\tau) + \widehat{\Omega}_2(z, r)(\tau) \right| \\
& = \|V\| \Lambda_1 + y \Lambda_2 + \frac{1}{|\Phi|} \left[G^{\rho - 1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho - 2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right] \\
& \quad + \|V^*\| \Lambda_1^* + y \Lambda_2^* + \frac{1}{|\Phi^*|} \left[G^{\rho - 1} (|\nabla_2^* \xi_2^*| + |\nabla_4^* \xi_1^*|) + G^{\rho - 2} (|\nabla_1^* \xi_2^*| + |\nabla_3^* \xi_1^*|) \right] \\
& = \widehat{V} \Lambda_3 + \Lambda_4 y + \frac{1}{|\Phi|} \left[G^{\rho - 1} (|\nabla_2 \xi_2| + |\nabla_4 \xi_1|) + G^{\rho - 2} (|\nabla_1 \xi_2| + |\nabla_3 \xi_1|) \right]
\end{aligned}$$

$$\begin{aligned}
& + \frac{1}{|\Phi^*|} \left[G^{\rho-1} (|\nabla_{25}^* \xi_2^*| + |\nabla_{45}^* \xi_1^*|) + G^{\rho-2} (|\nabla_{15}^* \xi_2^*| + |\nabla_{35}^* \xi_1^*|) \right] \\
& \leq x.
\end{aligned}$$

Thus, $\Omega(z, r) + \Omega^*(z, r) \in Q_x$. Hence the condition (1) of Theorem 2.1 is true. Next, we prove that $\Omega(z, r)$ is a contraction mapping. Let $(z, r), (\tilde{z}, \tilde{r}) \in Q_x$, then by (3.16), one has

$$\begin{aligned}
& \left| \tilde{\Omega}_1(z, r)(\tau) - \tilde{\Omega}_1(\tilde{z}, \tilde{r})(\tau) \right| \\
& \leq \frac{|v-1|}{v\Gamma(\rho-\theta)} \int_0^\tau (\tau-\hbar)^{\rho-\theta-1} |z(\hbar) - \tilde{z}(\hbar)| d\hbar + \frac{G^{\rho-1}}{\Phi} \times \\
& + \left(\frac{\varrho_1 \nabla_4 |v-1|}{v} I^{\rho-\theta-\eta_1} |z(G) - \tilde{z}(G)| - \frac{\varrho_2 \nabla_2 |v-1|}{v} I^{\rho-\theta+s_1} |z(G) - \tilde{z}(G)| \right. \\
& + \left. \frac{\nabla_4(1-\varrho_1)|v-1|}{v} I^{\rho-\theta-\eta_2} |z(G) - \tilde{z}(G)| - \frac{\nabla_2(1-\varrho_2)|v-1|}{v} I^{\rho-\theta+s_2} |z(G) - \tilde{z}(G)| \right) \\
& + \frac{G^{\rho-2}}{\Phi} \left(\frac{\varrho_1 \nabla_3 |v-1|}{v} I^{\rho-\theta-\eta_1} |z(G) - \tilde{z}(G)| - \frac{\varrho_2 \nabla_1 |v-1|}{v} I^{\rho-\theta+s_1} |z(G) - \tilde{z}(G)| \right. \\
& + \left. \frac{\nabla_3(1-\varrho_1)|v-1|}{v} I^{\rho-\theta-\eta_2} |z(G) - \tilde{z}(G)| - \frac{\nabla_1(1-\varrho_2)|v-1|}{v} I^{\rho-\theta+s_2} |z(G) - \tilde{z}(G)| \right) \\
& \leq \Lambda_1 \|z - \tilde{z}\|.
\end{aligned}$$

Similarly, we can write

$$\left| \tilde{\Omega}_2(z, r)(\tau) - \tilde{\Omega}_2(\tilde{z}, \tilde{r})(\tau) \right| \leq \Lambda_1^* \|r - \tilde{r}\|.$$

It follows that

$$\begin{aligned}
\|\Omega(z, r) - \Omega(\tilde{z}, \tilde{r})\|_{\mathfrak{Y}} & \leq \left\| \tilde{\Omega}_1(z, r) - \tilde{\Omega}_1(\tilde{z}, \tilde{r}) \right\|_{\mathfrak{Y}_1} + \left\| \tilde{\Omega}_2(z, r) - \tilde{\Omega}_2(\tilde{z}, \tilde{r}) \right\|_{\mathfrak{Y}_2} \\
& = \Lambda_3 \|(z, \tilde{z}) - (z, \tilde{z})\|.
\end{aligned}$$

Since $\Lambda_3 < 1$, then Ω_1 is a contraction mapping. Hence the condition (2) of Theorem 2.1 holds. The continuity of Ξ and Ξ^* lead to the continuity of Ω^* . If $(z, r) \in Q_x$, then

$$\begin{aligned}
\left\| \widehat{\Omega}_1(z, r) \right\|_{\mathfrak{Y}_1} & \leq \|V\| \left[\frac{G^\rho}{v\Gamma(\rho+1)} + \frac{\nabla_4 + \nabla_3 G^{-1}}{|\Phi|} \left(\frac{\varrho_1 G^{2\rho-\eta_1-1}}{v\Gamma(\rho-\eta_1+1)} + \frac{(1-\varrho_1)G^{2\rho-\eta_2-1}}{v\Gamma(\rho-\eta_2+1)} \right) \right. \\
& + \left. \frac{\nabla_2 + \nabla_1 G^{-1}}{|\Phi|} \left(\frac{\varrho_2 G^{2\rho+s_1-1}}{v\Gamma(\rho+s_1+1)} + \frac{(1-\varrho_2)G^{2\rho+s_2-1}}{v\Gamma(\rho+s_2+1)} \right) \right] \\
& = \Lambda_2 \|(z, r)\|.
\end{aligned}$$

Similarly, we have

$$\left\| \widehat{\Omega}_2(z, r) \right\|_{\mathfrak{Y}_2} \leq \Lambda_2^* \|(z, r)\|.$$

Hence,

$$\|\Omega^*(z, r)\|_{\mathfrak{Y}} \leq \left\| \widehat{\Omega}_1(z, r) \right\|_{\mathfrak{Y}_1} + \left\| \widehat{\Omega}_2(z, r) \right\|_{\mathfrak{Y}_2} \leq \Lambda_4 \|(z, r)\|, \text{ where } \Lambda_4 = \Lambda_2 + \Lambda_2^*.$$

This means that Ω^* is a uniformly bounded operator on Q_x . Finally, we prove that the operator Ω^* is completely continuous. Set for $(z, r) \in Q_x$, $\sup_{\tau \in U} \Xi(\tau, z(\tau), r(\tau)) = R$, and $\sup_{\tau \in U} \Xi^*(\tau, z(\tau), r(\tau)) = R^*$. Then, for each $\tau_1, \tau_2 \in U$ with $\tau_1 < \tau_2$, we get

$$\begin{aligned} & \left| \widehat{\Omega}_1(z, r)(\tau_2) - \widehat{\Omega}_1(z, r)(\tau_1) \right| \\ & \left| \frac{1}{\nu\Gamma(\rho)} \int_0^{\tau_2} (\tau_2 - \hbar)^{\rho-1} \Xi(\hbar, z(\hbar), r(\hbar)) d\hbar - \frac{1}{\nu\Gamma(\rho)} \int_0^{\tau_1} (\tau_1 - \hbar)^{\rho-1} \Xi(\hbar, z(\hbar), r(\hbar)) d\hbar \right. \\ & \frac{\tau_2^{\rho-1} - \tau_1^{\rho-1}}{\Phi} \left(\frac{\varrho_1 \nabla_4}{\nu} I^{\rho-\eta_1} \Xi(G, z(G), r(G)) - \frac{\varrho_2 \nabla_2}{\nu} I^{\rho+s_1} \Xi(G, z(G), r(G)) + \nabla_2 \xi_2 - \nabla_4 \xi_1 \right. \\ & \left. + \frac{(1-\varrho_1) \nabla_4}{\nu} I^{\rho-\eta_2} \Xi(G, z(G), r(G)) - \frac{(1-\varrho_2) \nabla_2}{\nu} I^{\rho+s_2} \Xi(G, z(G), r(G)) \right) \\ & \left. - \frac{\tau_2^{\rho-1} - \tau_1^{\rho-1}}{\Phi} \left(\frac{\varrho_1 \nabla_3}{\nu} I^{\rho-\eta_1} \Xi(G, z(G), r(G)) - \frac{\varrho_2 \nabla_1}{\nu} I^{\rho+s_1} \Xi(G, z(G), r(G)) \right. \right. \\ & \left. \left. \frac{(1-\varrho_1) \nabla_3}{\nu} I^{\rho-\eta_2} \Xi(G, z(G), r(G)) - \frac{(1-\varrho_2) \nabla_1}{\nu} I^{\rho+s_2} \Xi(G, z(G), r(G)) + \nabla_1 \xi_2 - \nabla_3 \xi_1 \right) \right| \\ & \leq \frac{R \left[2(\tau_2 - \tau_1)^\rho + |\tau_2^\rho - \tau_1^\rho| \right]}{\nu\Gamma(\rho+1)} + \frac{\tau_2^{\rho-1} - \tau_1^{\rho-1}}{|\Phi|} \left[\frac{R\varrho_1 \nabla_4 I^{\rho-\eta_1}}{\nu\Gamma(\rho-\eta_1+1)} + \frac{R\varrho_2 \nabla_2 I^{\rho+s_1}}{\nu\Gamma(\rho+s_1+1)} + |\nabla_2 \xi_2| + |\nabla_4 \xi_1| \right. \\ & \left. + \frac{R(1-\varrho_1) \nabla_4 I^{\rho-\eta_2}}{\nu\Gamma(\rho-\eta_2+1)} + \frac{R(1-\varrho_2) \nabla_2 I^{\rho+s_2}}{\nu\Gamma(\rho+s_2+1)} \right] + \frac{\tau_2^{\rho-2} - \tau_1^{\rho-2}}{|\Phi|} \left[\frac{R\varrho_1 \nabla_3 I^{\rho-\eta_1}}{\nu\Gamma(\rho-\eta_1+1)} + \frac{R\varrho_2 \nabla_1 I^{\rho+s_1}}{\nu\Gamma(\rho+s_1+1)} \right. \\ & \left. + \frac{R(1-\varrho_1) \nabla_3 I^{\rho-\eta_2}}{\nu\Gamma(\rho-\eta_2+1)} + \frac{R(1-\varrho_2) \nabla_1 I^{\rho+s_2}}{\nu\Gamma(\rho+s_2+1)} + |\nabla_1 \xi_2| + |\nabla_3 \xi_1| \right], \end{aligned}$$

which implies that

$$\left| \widehat{\Omega}_1(z, r)(\tau_2) - \widehat{\Omega}_1(z, r)(\tau_1) \right| \rightarrow 0 \text{ as } \tau_1 \rightarrow \tau_2.$$

Similarly

$$\left| \widehat{\Omega}_2(z, r)(\tau_2) - \widehat{\Omega}_2(z, r)(\tau_1) \right| \rightarrow 0 \text{ as } \tau_1 \rightarrow \tau_2.$$

Hence

$$\begin{aligned} |\Omega^*(z, r)(\tau_2) - \Omega^*(z, r)(\tau_1)| & \leq \left| \widehat{\Omega}_1(z, r)(\tau_2) - \widehat{\Omega}_1(z, r)(\tau_1) \right| + \left| \widehat{\Omega}_2(z, r)(\tau_2) - \widehat{\Omega}_2(z, r)(\tau_1) \right| \\ & \rightarrow 0 \text{ as } \tau_1 \rightarrow \tau_2, \end{aligned}$$

which yields that Ω^* is equicontinuous, and so Ω^* is relatively compact on Q_x . Since every compact operator is completely continuous, then by the Arzela-Ascoli theorem, Ω^* is completely continuous. Thus, condition (3) of Theorem 2.1 is satisfied. Hence, all conditions of Theorem 2.1 are satisfied. Consequently, the CBVP (1.4) has at least one solution.

4. Hyers-Ulam stability

In this part, we discuss the Hyers–Ulam stability of the CBVP

$$\begin{cases} \nu D^\rho(z(\tau)) + (1 - \nu)D^\theta(z(\tau)) = \Xi(\tau, z(\tau), r(\tau)), \\ \nu^* D^{\rho^*}(r(\tau)) + (1 - \nu^*)D^{\theta^*}(r(\tau)) = \Xi^*(\tau, r(\tau), z(\tau)), \\ z(0) = 0, r(0) = 0, D^{\eta_1}z(G) = \xi_1, D^{\eta_1^*}r(G) = \xi_1^*, \\ I^{s_1}z(G) = \xi_2, I^{s_1^*}r(G) = \xi_2^*, \end{cases} \quad (4.1)$$

for each $\tau \in [0, G]$ and $\rho \in [2, 3)$. The CBVP (4.1) is a special case of (1.4) when we take $\varrho_1 = \varrho_2 = 1$ and $\varrho_1^* = \varrho_2^* = 1$.

Definition 4.1. The CBVP (4.1) is called HU stable if there is a positive constant $\widehat{\Delta} > 0$ so that, for each $\epsilon, \epsilon^* > 0$ and $(z, r) \in \mathfrak{Y}$ as a solution to the inequalities

$$\begin{cases} |\nu D^\rho(z(\tau)) + (\nu - 1)D^\theta(z(\tau)) - \Xi(\tau, z(\tau), r(\tau))| \leq \epsilon, \\ |\nu^* D^{\rho^*}(r(\tau)) + (\nu^* - 1)D^{\theta^*}(r(\tau)) - \Xi^*(\tau, r(\tau), z(\tau))| \leq \epsilon^*, \end{cases}$$

there is a US $(\widetilde{z}, \widetilde{r}) \in \mathfrak{Y}$ with

$$\|(z, r) - (\widetilde{z}, \widetilde{r})\|_{\mathfrak{Y}} \leq \widehat{\Delta}\widehat{\epsilon}, \text{ for all } \nu \in U,$$

where $\widehat{\epsilon} = \max\{\epsilon, \epsilon^*\}$.

Theorem 4.1. Assume that $\Xi, \Xi^* : U \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are continuous maps and there are constants $T_\Xi, \widetilde{T}_\Xi, T_{\Xi^*}, \widetilde{T}_{\Xi^*} > 0$ so that

$$|\Xi(\tau, z_1(\tau), z_2(\tau)) - \Xi(\tau, \widetilde{z}_1(\tau), \widetilde{z}_2(\tau))| \leq T_\Xi |z_1 - \widetilde{z}_1| + \widetilde{T}_\Xi |z_2 - \widetilde{z}_2|,$$

and

$$|\Xi^*(\tau, r_1(\tau), r_2(\tau)) - \Xi^*(\tau, \widetilde{r}_1(\tau), \widetilde{r}_2(\tau))| \leq T_{\Xi^*} |r_1 - \widetilde{r}_1| + \widetilde{T}_{\Xi^*} |r_2 - \widetilde{r}_2|,$$

for all $\tau \in U$ and $z_1, z_2, \widetilde{z}_1, \widetilde{z}_2, r_1, r_2, \widetilde{r}_1, \widetilde{r}_2 \in \mathbb{R}$. Then, the CBVP (4.1) is HU stable provided that $\mathfrak{Q} = 1 - \frac{\partial \Xi^*}{(1-\varphi)(1-\varphi^*)} > 0$.

Proof. Let $\epsilon, \epsilon^* > 0$ and $(z, r) \in \mathfrak{Y}$ be so that

$$\begin{cases} |\nu D^\rho(z(\tau)) + (\nu - 1)D^\theta(z(\tau)) - \Xi(\tau, z(\tau), r(\tau))| \leq \epsilon, \\ |\nu^* D^{\rho^*}(r(\tau)) + (\nu^* - 1)D^{\theta^*}(r(\tau)) - \Xi^*(\tau, r(\tau), z(\tau))| \leq \epsilon^*. \end{cases}$$

Choose the functions ζ and ζ^* satisfying

$$\begin{cases} \nu D^\rho(z(\tau)) + (\nu - 1)D^\theta(z(\tau)) = \Xi(\tau, z(\tau), r(\tau)) + \zeta(\tau), \\ \nu^* D^{\rho^*}(r(\tau)) + (\nu^* - 1)D^{\theta^*}(r(\tau)) = \Xi^*(\tau, r(\tau), z(\tau)) + \zeta^*(\tau), \end{cases}$$

such that $|\zeta(\tau)| \leq \epsilon$ and $|\zeta^*(\tau)| \leq \epsilon^*$ for all $\tau \in U$. Then, we get

$$\begin{aligned} z(\tau) &= \frac{\nu - 1}{\nu} I^{\rho-\theta} z(\tau) + \frac{1}{\nu} I^\rho \Xi(\tau, z(\tau), r(\tau)) + \frac{1}{\nu} I^\rho \zeta(\tau) + \frac{\tau^{\rho-1}}{\Phi} \left(\frac{\nabla_4(\nu - 1)}{\nu} I^{\rho-\theta-\eta_1} z(G) \right. \\ &\quad \left. - \frac{\nabla_2(\nu - 1)}{\nu} I^{\rho-\theta+s_1} z(G) + \frac{\nabla_4}{\nu} I^{\rho-\eta_1} \Xi(G, z(G), r(G)) - \frac{\nabla_2}{\nu} I^{\rho+s_1} \Xi(G, z(G), r(G)) \right) \end{aligned}$$

$$\begin{aligned}
& + \frac{\nabla_4}{\nu} I^{\rho-\eta_1} \zeta(G) - \frac{\nabla_2}{\nu} I^{\rho+s_1} \zeta(G) + \nabla_2 \xi_2 - \nabla_4 \xi_1 \Big) + \frac{\tau^{\rho-2}}{\Phi} \left(\frac{\nabla_3(\nu-1)}{\nu} I^{\rho-\theta-\eta_1} z(G) \right. \\
& - \frac{\nabla_1(\nu-1)}{\nu} I^{\rho-\theta+s_1} z(G) + \frac{\nabla_3}{\nu} I^{\rho-\eta_1} \Xi(G, z(G), r(G)) - \frac{\nabla_1}{\nu} I^{\rho+s_1} \Xi(G, z(G), r(G)) \\
& \left. + \frac{\nabla_3}{\nu} I^{\rho-\eta_1} \zeta(G) - \frac{\nabla_1}{\nu} I^{\rho+s_1} \zeta(G) + \nabla_1 \xi_2 - \nabla_3 \xi_1 \right),
\end{aligned}$$

and

$$\begin{aligned}
r(\tau) = & \frac{\nu^* - 1}{\nu^*} I^{\rho^*-\theta^*} r(\tau) + \frac{1}{\nu^*} I^{\rho^*} \Xi^*(\tau, r(\tau), z(\tau)) + \frac{1}{\nu^*} I^{\rho^*} \zeta^*(\tau) + \frac{\tau^{\rho^*-1}}{\Phi^*} \left(\frac{\nabla_4^*(\nu^* - 1)}{\nu^*} I^{\rho^*-\theta^*-\eta_1^*} r(G) \right. \\
& - \frac{\nabla_2^*(\nu^* - 1)}{\nu^*} I^{\rho^*-\theta^*+s_1^*} r(G) + \frac{\nabla_4^*}{\nu^*} I^{\rho^*-\eta_1^*} \Xi^*(G, r(G), z(G)) - \frac{\nabla_2^*}{\nu^*} I^{\rho^*+s_1^*} \Xi^*(G, r(G), z(G)) \\
& + \frac{\nabla_4^*}{\nu^*} I^{\rho^*-\eta_1^*} \zeta^*(G) - \frac{\nabla_2^*}{\nu^*} I^{\rho^*+s_1^*} \zeta^*(G) + \nabla_2^* \xi_2^* - \nabla_4^* \xi_1^* \Big) - \frac{\tau^{\rho^*-2}}{\Phi^*} \left(\frac{\nabla_3^*(\nu^* - 1)}{\nu^*} I^{\rho^*-\theta^*-\eta_1^*} r(G) \right. \\
& - \frac{\nabla_1^*(\nu^* - 1)}{\nu^*} I^{\rho^*-\theta^*+s_1^*} r(G) + \frac{\nabla_3^*}{\nu^*} I^{\rho^*-\eta_1^*} \Xi^*(G, r(G), z(G)) - \frac{\nabla_1^*}{\nu^*} I^{\rho^*+s_1^*} \Xi^*(G, r(G), z(G)) \\
& \left. + \frac{\nabla_3^*}{\nu^*} I^{\rho^*-\eta_1^*} \zeta^*(G) - \frac{\nabla_1^*}{\nu^*} I^{\rho^*+s_1^*} \zeta^*(G) + \nabla_1^* \xi_2^* - \nabla_3^* \xi_1^* \right).
\end{aligned}$$

Let (\tilde{z}, \tilde{r}) be a US of the CBVP (4.1), then $\tilde{z}(\tau)$ and $\tilde{r}(\tau)$ are given by

$$\begin{aligned}
\tilde{z}(\tau) = & \frac{\nu-1}{\nu} I^{\rho-\theta} \tilde{z}(\tau) + \frac{1}{\nu} I^{\rho} \Xi(\tau, \tilde{z}(\tau), \tilde{r}(\tau)) + \frac{1}{\nu} I^{\rho} \zeta(\tau) + \frac{\tau^{\rho-1}}{\Phi} \left(\frac{\nabla_4(\nu-1)}{\nu} I^{\rho-\theta-\eta_1} \tilde{z}(G) \right. \\
& - \frac{\nabla_2(\nu-1)}{\nu} I^{\rho-\theta+s_1} \tilde{z}(G) + \frac{\nabla_4}{\nu} I^{\rho-\eta_1} \Xi(\tau, \tilde{z}(\tau), \tilde{r}(\tau)) - \frac{\nabla_2}{\nu} I^{\rho+s_1} \Xi(\tau, \tilde{z}(\tau), \tilde{r}(\tau)) \\
& + \frac{\nabla_4}{\nu} I^{\rho-\eta_1} \zeta(G) - \frac{\nabla_2}{\nu} I^{\rho+s_1} \zeta(G) + \nabla_2 \xi_2 - \nabla_4 \xi_1 \Big) + \frac{\tau^{\rho-2}}{\Phi} \left(\frac{\nabla_3(\nu-1)}{\nu} I^{\rho-\theta-\eta_1} \tilde{z}(G) \right. \\
& - \frac{\nabla_1(\nu-1)}{\nu} I^{\rho-\theta+s_1} \tilde{z}(G) + \frac{\nabla_3}{\nu} I^{\rho-\eta_1} \Xi(\tau, \tilde{z}(\tau), \tilde{r}(\tau)) - \frac{\nabla_1}{\nu} I^{\rho+s_1} \Xi(\tau, \tilde{z}(\tau), \tilde{r}(\tau)) \\
& \left. + \frac{\nabla_3}{\nu} I^{\rho-\eta_1} \zeta(G) - \frac{\nabla_1}{\nu} I^{\rho+s_1} \zeta(G) + \nabla_1 \xi_2 - \nabla_3 \xi_1 \right),
\end{aligned}$$

and

$$\begin{aligned}
& \tilde{r}(\tau) \\
= & \frac{\nu^* - 1}{\nu^*} I^{\rho^*-\theta^*} \tilde{r}(\tau) + \frac{1}{\nu^*} I^{\rho^*} \Xi^*(\tau, \tilde{r}(\tau), \tilde{z}(\tau)) + \frac{1}{\nu^*} I^{\rho^*} \zeta^*(\tau) + \frac{\tau^{\rho^*-1}}{\Phi^*} \left(\frac{\nabla_4^*(\nu^* - 1)}{\nu^*} I^{\rho^*-\theta^*-\eta_1^*} \tilde{r}(G) \right. \\
& - \frac{\nabla_2^*(\nu^* - 1)}{\nu^*} I^{\rho^*-\theta^*+s_1^*} \tilde{r}(G) + \frac{\nabla_4^*}{\nu^*} I^{\rho^*-\eta_1^*} \Xi^*(\tau, \tilde{r}(\tau), \tilde{z}(\tau)) - \frac{\nabla_2^*}{\nu^*} I^{\rho^*+s_1^*} \Xi^*(\tau, \tilde{r}(\tau), \tilde{z}(\tau)) \\
& + \frac{\nabla_4^*}{\nu^*} I^{\rho^*-\eta_1^*} \zeta^*(G) - \frac{\nabla_2^*}{\nu^*} I^{\rho^*+s_1^*} \zeta^*(G) + \nabla_2^* \xi_2^* - \nabla_4^* \xi_1^* \Big) - \frac{\tau^{\rho^*-2}}{\Phi^*} \left(\frac{\nabla_3^*(\nu^* - 1)}{\nu^*} I^{\rho^*-\theta^*-\eta_1^*} \tilde{r}(G) \right. \\
& - \frac{\nabla_1^*(\nu^* - 1)}{\nu^*} I^{\rho^*-\theta^*+s_1^*} \tilde{r}(G) + \frac{\nabla_3^*}{\nu^*} I^{\rho^*-\eta_1^*} \Xi^*(\tau, \tilde{r}(\tau), \tilde{z}(\tau)) - \frac{\nabla_1^*}{\nu^*} I^{\rho^*+s_1^*} \Xi^*(\tau, \tilde{r}(\tau), \tilde{z}(\tau))
\end{aligned}$$

$$+ \frac{\nabla_3^*}{\nu^*} I^{\rho^* - \eta_1^*} \zeta^*(G) - \frac{\nabla_1^*}{\nu^*} I^{\rho^* + s_1^*} \zeta^*(G) + \nabla_1^* \xi_2^* - \nabla_3^* \xi_1^* \Big).$$

Hence,

$$\begin{aligned} & |z(\tau) - \tilde{z}(\tau)| \\ \leq & \frac{|\nu - 1|}{\nu} I^{\rho - \theta} |z(\tau) - \tilde{z}(\tau)| + \frac{1}{\nu} I^\rho |\Xi(\tau, z(\tau), r(\tau)) - \Xi(\tau, \tilde{z}(\tau), \tilde{r}(\tau))| \\ & + \frac{G^{\rho-1}}{|\Phi|} \left(\frac{\nabla_4(\nu - 1)}{\nu} I^{\rho - \theta - \eta_1} |z(G) - \tilde{z}(G)| + \frac{\nabla_2(\nu - 1)}{\nu} I^{\rho - \theta + s_1} |z(G) - \tilde{z}(G)| \right. \\ & + \left. \frac{\nabla_4}{\nu} I^{\rho - \eta_1} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| + \frac{\nabla_2}{\nu} I^{\rho + s_1} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \right) \\ & + \frac{G^{\rho-2}}{|\Phi|} \left(\frac{\nabla_3(\nu - 1)}{\nu} I^{\rho - \theta - \eta_1} |z(G) - \tilde{z}(G)| + \frac{\nabla_1(\nu - 1)}{\nu} I^{\rho - \theta + s_1} |z(G) - \tilde{z}(G)| \right. \\ & + \left. \frac{\nabla_3}{\nu} I^{\rho - \eta_1} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \right. \\ & + \left. \frac{\nabla_1}{\nu} I^{\rho + s_1} |\Xi(G, z(G), r(G)) - \Xi(G, \tilde{z}(G), \tilde{r}(G))| \right) + \frac{1}{\nu} I^\rho |\zeta(\tau)| \\ & + \frac{G^{\rho-1}}{|\Phi|} \left(\frac{\nabla_4}{\nu} I^{\rho - \eta_1} |\zeta(G)| + \frac{\nabla_2}{\nu} I^{\rho + s_1} |\zeta(G)| \right) + \frac{G^{\rho-2}}{|\Phi|} \left(\frac{\nabla_3}{\nu} I^{\rho - \eta_1} |\zeta(G)| + \frac{\nabla_1}{\nu} I^{\rho + s_1} |\zeta(G)| \right), \end{aligned}$$

which implies that

$$\begin{aligned} \|z(\tau) - \tilde{z}(\tau)\| \leq & \left(\frac{G^{\rho-\theta} |\nu - 1|}{\nu \Gamma(\rho - \theta + 1)} + \frac{T G^{\rho-1}}{\nu \Gamma(\rho)} + \frac{T}{\nu \Gamma(\rho + 1)} + \frac{\nabla_4(\nu - 1) G^{2\rho - \theta - \eta_1 - 1}}{\nu |\Phi| \Gamma(\rho - \theta - \eta_1 + 1)} \right. \\ & + \frac{\nabla_2(\nu - 1) G^{2\rho - \theta + s_1 - 1}}{\nu |\Phi| \Gamma(\rho - \theta + s_1 + 1)} + \frac{T \nabla_4 G^{2\rho - \eta_1 - 1}}{\nu |\Phi| \Gamma(\rho - \eta_1 + 1)} + \frac{T \nabla_2 G^{2\rho + s_1 - 1}}{\nu |\Phi| \Gamma(\rho + s_1 + 1)} \\ & + \frac{\nabla_3(\nu - 1) G^{2\rho - \theta - \eta_1 - 2}}{\nu |\Phi| \Gamma(\rho - \theta - \eta_1 + 1)} + \frac{\nabla_1(\nu - 1) G^{2\rho - \theta + s_1 - 2}}{\nu |\Phi| \Gamma(\rho - \theta + s_1 + 1)} + \frac{\nabla_3 G^{2\rho - \theta - \eta_1 - 2}}{\nu |\Phi| \Gamma(\rho - \theta - \eta_1 + 1)} \\ & \left. + \frac{\nabla_1 G^{2\rho - \theta + s_1 - 2}}{\nu |\Phi| \Gamma(\rho - \theta + s_1 + 1)} \right) \|z(\tau) - \tilde{z}(\tau)\| \\ & + \left(\frac{T G^{\rho-1}}{\nu \Gamma(\rho)} + \frac{T \nabla_4 G^{2\rho - \eta_1 - 1}}{\nu |\Phi| \Gamma(\rho - \eta_1 + 1)} + \frac{T \nabla_2 G^{2\rho + s_1 - 1}}{\nu |\Phi| \Gamma(\rho + s_1 + 1)} + \frac{\nabla_3 G^{2\rho - \theta - \eta_1 - 2}}{\nu |\Phi| \Gamma(\rho - \theta - \eta_1 + 1)} \right. \\ & \left. + \frac{\nabla_1 G^{2\rho - \theta + s_1 - 2}}{\nu |\Phi| \Gamma(\rho - \theta + s_1 + 1)} \right) \|r(\tau) - \tilde{r}(\tau)\| + \\ & \frac{\varepsilon G^\rho}{\Gamma(\rho + 1)} + \frac{\varepsilon G^{\rho-1}}{|\Phi|} \left(\frac{\nabla_4 G^{\rho - \eta_1}}{\nu |\Phi| \Gamma(\rho - \eta_1 + 1)} + \frac{\nabla_2 G^{\rho + s_1}}{\nu |\Phi| \Gamma(\rho + s_1 + 1)} \right) \\ & + \frac{\varepsilon G^{\rho-2}}{|\Phi|} \left(\frac{\nabla_3 G^{\rho - \eta_1}}{\nu |\Phi| \Gamma(\rho - \eta_1 + 1)} + \frac{\nabla_1 G^{\rho + s_1}}{\nu |\Phi| \Gamma(\rho + s_1 + 1)} \right), \end{aligned}$$

where $T = \max\{T_\Xi, \tilde{T}_\Xi\}$. For simplicity, we consider

$$\wp = \frac{G^{\rho-\theta} |\nu - 1|}{\nu \Gamma(\rho - \theta + 1)} + \frac{T}{\nu \Gamma(\rho + 1)} + \frac{\nabla_4(\nu - 1) G^{2\rho - \theta - \eta_1 - 1}}{\nu |\Phi| \Gamma(\rho - \theta - \eta_1 + 1)} + \frac{\nabla_2(\nu - 1) G^{2\rho - \theta + s_1 - 1}}{\nu |\Phi| \Gamma(\rho - \theta + s_1 + 1)}$$

$$+ \frac{\nabla_3(v-1)G^{2\rho-\theta-\eta_1-2}}{v|\Phi|\Gamma(\rho-\theta-\eta_1+1)} + \frac{\nabla_1(v-1)G^{2\rho-\theta+s_1-2}}{v|\Phi|\Gamma(\rho-\theta+s_1+1)} + \mathfrak{D},$$

$$\begin{aligned} \mathfrak{D} &= \frac{TG^{\rho-1}}{v\Gamma(\rho)} + \frac{T\nabla_4G^{2\rho-\eta_1-1}}{v|\Phi|\Gamma(\rho-\eta_1+1)} + \frac{T\nabla_2G^{2\rho+s_1-1}}{v|\Phi|\Gamma(\rho+s_1+1)} \\ &\quad + \frac{\nabla_3G^{2\rho-\theta-\eta_1-2}}{v|\Phi|\Gamma(\rho-\theta-\eta_1+1)} + \frac{\nabla_1G^{2\rho-\theta+s_1-2}}{v|\Phi|\Gamma(\rho-\theta+s_1+1)}, \end{aligned}$$

and

$$\begin{aligned} S &= \frac{G^\rho}{\Gamma(\rho+1)} + \frac{G^{\rho-1}}{v|\Phi|} \left(\frac{\nabla_4G^{\rho-\eta_1}}{\Gamma(\rho-\eta_1+1)} + \frac{\nabla_2G^{\rho+s_1}}{\Gamma(\rho+s_1+1)} \right) \\ &\quad + \frac{G^{\rho-2}}{v|\Phi|} \left(\frac{\nabla_3G^{\rho-\eta_1}}{\Gamma(\rho-\eta_1+1)} + \frac{\nabla_1G^{\rho+s_1}}{\Gamma(\rho+s_1+1)} \right). \end{aligned}$$

It follows that

$$\|z(\tau) - \tilde{z}(\tau)\|_{\mathfrak{S}_1} - \frac{\mathfrak{D}}{1-\wp} \|r(\tau) - \tilde{r}(\tau)\|_{\mathfrak{S}_2} \leq \frac{S\varepsilon}{1-\wp}. \quad (4.2)$$

Similarly, one can obtain under $T^* = \max\{T_{\Xi^*}, \tilde{T}_{\Xi^*}\}$ and $|\zeta^*(\tau)| \leq \epsilon^*$ that

$$\|r(\tau) - \tilde{r}(\tau)\|_{\mathfrak{S}_2} - \frac{\mathfrak{D}^*}{1-\wp^*} \|z(\tau) - \tilde{z}(\tau)\|_{\mathfrak{S}_1} \leq \frac{S^*\varepsilon^*}{1-\wp^*}, \quad (4.3)$$

where

$$\begin{aligned} \wp^* &= \frac{G^{\rho^*-\theta^*}|v^*-1|}{v^*\Gamma(\rho^*-\theta^*+1)} + \frac{T^*}{v^*\Gamma(\rho^*+1)} + \frac{\nabla_4^*(v^*-1)G^{2\rho^*-\theta^*-\eta_1^*-1}}{v^*|\Phi^*|\Gamma(\rho^*-\theta^*-\eta_1^*+1)} \\ &\quad + \frac{\nabla_2^*(v^*-1)G^{2\rho^*-\theta^*+s_1^*-1}}{v^*|\Phi^*|\Gamma(\rho^*-\theta^*+s_1^*+1)} + \frac{\nabla_3^*(v^*-1)G^{2\rho^*-\theta^*-\eta_1^*-2}}{v^*|\Phi^*|\Gamma(\rho^*-\theta^*-\eta_1^*+1)} \\ &\quad + \frac{\nabla_1^*(v^*-1)G^{2\rho^*-\theta^*+s_1^*-2}}{v^*|\Phi^*|\Gamma(\rho^*-\theta^*+s_1^*+1)} + \mathfrak{D}^*, \end{aligned}$$

$$\begin{aligned} \mathfrak{D}^* &= \frac{T^*G^{\rho^*-1}}{v^*\Gamma(\rho^*)} + \frac{T^*\nabla_4^*G^{2\rho^*-\eta_1^*-1}}{v^*|\Phi^*|\Gamma(\rho^*-\eta_1^*+1)} + \frac{T^*\nabla_2^*G^{2\rho^*+s_1^*-1}}{v^*|\Phi^*|\Gamma(\rho^*+s_1^*+1)} \\ &\quad + \frac{\nabla_3^*G^{2\rho^*-\theta^*-\eta_1^*-2}}{v^*|\Phi^*|\Gamma(\rho^*-\theta^*-\eta_1^*+1)} + \frac{\nabla_1^*G^{2\rho^*-\theta^*-\eta_1^*-2}}{v^*|\Phi^*|\Gamma(\rho^*-\theta^*-\eta_1^*+1)}, \end{aligned}$$

and

$$\begin{aligned} S^* &= \frac{G^{\rho^*}}{v^*\Gamma(\rho^*+1)} + \frac{G^{\rho^*-1}}{v^*|\Phi^*|} \left(\frac{\nabla_4^*G^{\rho^*-\eta_1^*}}{\Gamma(\rho^*-\eta_1^*+1)} + \frac{\nabla_2^*G^{\rho^*+s_1^*}}{\Gamma(\rho^*+s_1^*+1)} \right) \\ &\quad + \frac{G^{\rho^*-2}}{v^*|\Phi^*|} \left(\frac{\nabla_3^*G^{\rho^*-\eta_1^*}}{\Gamma(\rho^*-\eta_1^*+1)} + \frac{\nabla_1^*G^{\rho^*+s_1^*}}{\Gamma(\rho^*+s_1^*+1)} \right). \end{aligned}$$

Inequalities (4.2) and (4.3) can be written as

$$\begin{bmatrix} 1 & -\frac{\varrho}{1-\varphi} \\ -\frac{\varrho^*}{1-\varphi^*} & 1 \end{bmatrix} \begin{bmatrix} \|z(\tau) - \tilde{z}(\tau)\|_{\mathfrak{S}_1} \\ \|r(\tau) - \tilde{r}(\tau)\|_{\mathfrak{S}_2} \end{bmatrix} \leq \begin{bmatrix} \frac{S\varepsilon}{1-\varphi} \\ \frac{S^*\varepsilon^*}{1-\varphi^*} \end{bmatrix}.$$

Hence

$$\begin{bmatrix} \|z(\tau) - \tilde{z}(\tau)\|_{\mathfrak{S}_1} \\ \|r(\tau) - \tilde{r}(\tau)\|_{\mathfrak{S}_2} \end{bmatrix} \leq \begin{bmatrix} \frac{1}{\varpi} & \frac{\varrho}{1-\varphi} \frac{1}{\varpi} \\ \frac{\varrho^*}{1-\varphi^*} \frac{1}{\varpi} & \frac{1}{\varpi} \end{bmatrix} \begin{bmatrix} \frac{S\varepsilon}{1-\varphi} \\ \frac{S^*\varepsilon^*}{1-\varphi^*} \end{bmatrix}, \quad (4.4)$$

where $\varpi = 1 - \frac{\varrho\varrho^*}{(1-\varphi)(1-\varphi^*)} > 0$. Based on System (4.4), one can write

$$\|z(\tau) - \tilde{z}(\tau)\|_{\mathfrak{S}_1} \leq \frac{1}{\varpi} \frac{S\varepsilon}{1-\varphi} + \frac{\varrho S^*\varepsilon^*}{(1-\varphi^*)(1-\varphi)\varpi},$$

and

$$\|r(\tau) - \tilde{r}(\tau)\|_{\mathfrak{S}_2} \leq \frac{\varrho^* S\varepsilon}{(1-\varphi^*)(1-\varphi)\varpi} + \frac{1}{\varpi} \frac{S^*\varepsilon^*}{1-\varphi^*},$$

which implies that

$$\begin{aligned} \|z(\tau) - \tilde{z}(\tau)\|_{\mathfrak{S}_1} + \|r(\tau) - \tilde{r}(\tau)\|_{\mathfrak{S}_2} &\leq \frac{1}{\varpi} \frac{S\varepsilon}{1-\varphi} + \frac{1}{\varpi} \frac{S^*\varepsilon^*}{1-\varphi^*} \\ &\quad + \frac{\varrho S^*\varepsilon^*}{(1-\varphi^*)(1-\varphi)\varpi} + \frac{\varrho^* S\varepsilon}{(1-\varphi^*)(1-\varphi)\varpi}. \end{aligned}$$

Let us consider $\widehat{\varepsilon} = \max\{\varepsilon, \varepsilon^*\}$ and

$$\widehat{\Delta} = \frac{1}{\varpi} \frac{S}{1-\varphi} + \frac{1}{\varpi} \frac{S^*}{1-\varphi^*} + \frac{\varrho S^*}{(1-\varphi^*)(1-\varphi)\varpi} + \frac{\varrho^* S}{(1-\varphi^*)(1-\varphi)\varpi} > 0.$$

Then, we have

$$\|(z, r) - (\tilde{z}, \tilde{r})\|_{\mathfrak{S}} \leq \widehat{\Delta} \widehat{\varepsilon}, \text{ for all } v \in U,$$

which yields that the CBVP (4.1) is HU stable. This completes the required proof.

5. Supportive example

Example 5.1. Consider the CBVP

$$\begin{cases} \frac{57}{64} D^{2.6}(z(\tau)) + \frac{7}{64} D^{2.1}(z(\tau)) = \tau^2 [\sin z(\tau) + \cos r(\tau)], \tau \in [0, \frac{1}{5}], \\ \frac{47}{54} D^{2.7}(z(\tau)) + \frac{7}{54} D^{2.2}(z(\tau)) = \tau^2 [\sin r(\tau) + \cos z(\tau)], \tau \in [0, \frac{1}{5}], \\ z(0) = 0, \varrho_1 D^{\frac{1}{4}} z(\frac{1}{5}) + (1 - \varrho_1) D^{\frac{1}{8}} z(\frac{1}{5}) = \frac{1}{18}, \\ r(0) = 0, \varrho_1^* D^{\frac{1}{3}} r(\frac{1}{5}) + (1 - \varrho_1^*) D^{\frac{1}{6}} r(\frac{1}{5}) = \frac{1}{16}, \\ \varrho_2 I^{\frac{4}{5}} z(\frac{1}{5}) + (1 - \varrho_2) I^{\frac{5}{3}} z(\frac{1}{5}) = \frac{5}{13}, \varrho_2^* I^{\frac{3}{4}} r(\frac{1}{5}) + (1 - \varrho_2^*) I^{\frac{7}{3}} r(\frac{1}{5}) = \frac{5}{17}. \end{cases} \quad (5.1)$$

where $\rho = 2.6$, $\theta = 2.1$, $\rho^* = 2.7$, $\theta^* = 2.2$, $\nu = \frac{57}{64}$, $\nu^* = \frac{47}{54}$, $\eta_1 = \frac{1}{4}$, $\eta_1^* = \frac{1}{3}$, $\eta_2 = \frac{1}{8}$, $\eta_2^* = \frac{1}{6}$, $s_1 = \frac{4}{5}$, $s_1^* = \frac{3}{4}$, $s_2 = \frac{5}{3}$, $s_2^* = \frac{7}{3}$, $\xi_1 = \frac{1}{18}$, $\xi_1^* = \frac{1}{16}$, $\xi_2 = \frac{5}{13}$, $\xi_2^* = \frac{5}{17}$ and $G = \frac{1}{5}$. Clearly $2 < \theta < \rho$, $2 < \theta^* < \rho^*$, $\nu, \nu^* \in (0, 1]$, $0 \leq \eta_1, \eta_2 < \rho - \theta$, $0 \leq \eta_1^*, \eta_2^* < \rho^* - \theta^*$, and $s_1, s_2, s_1^*, s_2^* \in \mathbb{R}^+$. Also, we have

$$|\Xi(\tau, z(\tau), r(\tau)) - \Xi(\tau, \bar{z}(\tau), \bar{r}(\tau))| \leq \left(\frac{1}{5}\right)^2 (|\sin z(\tau) - \sin \bar{z}(\tau)| + |\cos r(\tau) - \cos \bar{r}(\tau)|),$$

$$|\Xi^*(\tau, r(\tau), z(\tau)) - \Xi^*(\tau, \bar{r}(\tau), \bar{z}(\tau))| \leq \left(\frac{1}{5}\right)^2 (|\sin r(\tau) - \sin \bar{r}(\tau)| + |\cos z(\tau) - \cos \bar{z}(\tau)|).$$

It follows that $T = T^* = \widehat{T} = \frac{1}{25}$ and

$$|\Xi(\tau, z(\tau), r(\tau))| = |\tau^2 [\sin z(\tau) + \cos r(\tau)]| \leq \tau^2 (|\sin z(\tau)| + |\cos r(\tau)|) \leq \tau^2 = V(\tau),$$

$$|\Xi^*(\tau, r(\tau), z(\tau))| = |\tau^2 [\sin r(\tau) + \cos z(\tau)]| \leq \tau^2 (|\sin r(\tau)| + |\cos z(\tau)|) \leq \tau^2 = V^*(\tau).$$

If we take $\varrho_1 = \varrho_1^* = \frac{1}{4}$ and $\varrho_2 = \varrho_2^* = \frac{3}{4}$, we have $\varrho_1, \varrho_2, \varrho_1^*, \varrho_2^* \in (0, 1]$. We can easily calculate

$$\begin{aligned} \nabla_1 &\approx 0.110255, & \nabla_2 &\approx 0.494979, & \nabla_3 &\approx 0.007777, & \nabla_4 &\approx 0.058922, \\ \nabla_1^* &\approx 0.107356, & \nabla_2^* &\approx 0.734601, & \nabla_3^* &\approx 0.007162, & \nabla_4^* &\approx 0.044779, \\ \Phi &\approx 0.002646, & \Phi^* &\approx 0.000454, & \Lambda_1 &= 0.332710, & \Lambda_2 &= 0.300271, \\ \Lambda_1^* &= 0.512841, & \Lambda_2^* &= 0.530105, & \Lambda_3 &= 0.845551, & \Lambda_4 &= 0.830376. \end{aligned}$$

Hence, $\widehat{T}\Lambda_4 + \Lambda_3 \approx 0.878766 < 1$. From Theorem 3.1, the CBVP (5.1) has a US.

If we take $\varrho_1 = \varrho_1^* = 1$ and $\varrho_2 = \varrho_2^* = 1$, we get

$$\vartheta \approx 0.007583, \quad \vartheta^* \approx 0.058179, \quad \wp^* \approx 0.036841 \text{ and } \wp \approx 0.0782149.$$

Since $\beth = 1 - \frac{0.0004412}{0.8878256} \approx 0.999503 > 0$, then by Theorem 4.1, the CBVP (5.1) is HU stable with

$$\widehat{\Delta} = \frac{1}{\beth} \left(\frac{S}{1 - \wp} + \frac{S^*}{1 - \wp^*} + \frac{\vartheta S^*}{(1 - \wp^*)(1 - \wp)} + \frac{\vartheta^* S}{(1 - \wp^*)(1 - \wp)} \right) = 0.0258741 > 0.$$

6. Conclusions

Fractional calculus has found numerous miscellaneous applications connected with real-world problems as they appear in many fields of science and engineering, including fluid flow, signal and image processing, fractal theory, control theory, electromagnetic theory, fitting of experimental data, optics, potential theory, biology, chemistry, diffusion, and viscoelasticity. Due to the many applications that have been mentioned, this branch has become of interest to many writers. Therefore, in this paper, the existence of solutions to a system of two-term FDEs with a fractional bi-order involving the Riemann-Liouville derivative has been established. Also, the considered boundaries are mixed Riemann-Liouville integro-derivative conditions with four different orders. Further, HU stability is studied, and an illustrative example has been introduced. Ultimately, we conclude that our results are new and are considered a further development of the qualitative analysis of fractional differential equations.

Acknowledgments

The authors thank the Basque Government for Grant IT1555-22.

Conflict of interest

The authors declare that they have no conflict of interests.

References

1. I. Podlubny, Geometric and physical interpretation of fractional integration and fractional differentiation, *Fract. Calc. Appl. Anal.*, **5** (2002), 367–386. <https://doi.org/10.48550/arXiv.math/0110241>
2. M. Du, Z. Wang, H. Hu, Measuring memory with the order of fractional derivative, *Sci. Rep.*, **3** (2013), 3431. <https://doi.org/10.1038/srep03431>
3. A. A. Kilbas, O. I. Marichev, S. G. Samko, *Fractional integrals and derivatives: Theory and applications*, 1993.
4. I. Podlubny, *Fractional differential equations: An introduction to fractional derivatives, fractional differential equations, to methods of their solution and some of their applications*, Academic Press, 1999.
5. J. Sabatier, O. P. Agrawal, J. A. T. Machado, *Advances in fractional calculus: Theoretical developments and applications in physics and engineering*, Dordrecht: Springer, 2007. <https://doi.org/10.1007/978-1-4020-6042-7>
6. G. J. Fix, J. P. Roop, Least squares finite-element solution of a fractional order two-point boundary value problem, *Comput. Math. Appl.*, **48** (2004), 1017–1033. <https://doi.org/10.1016/j.camwa.2004.10.003>
7. J. Erwin, J. P. Roop, Variational formulation for the stationary fractional advection dispersion equation, *Numer. Meth. Part. D. E.*, **22** (2006), 558–576. <https://doi.org/10.1002/num.20112>
8. R. P. Agarwal, M. Benchohra, S. Hamani, A survey on existence results for boundary value problems of nonlinear fractional differential equations and inclusions, *Acta Appl. Math.*, **109** (2010), 973–1033. <https://doi.org/10.1007/s10440-008-9356-6>
9. M. Benchohra, S. Hamani, S. K. Ntouyas, Boundary value problems for differential equations with fractional order and nonlocal conditions, *Nonlinear Anal. Theor.*, **71** (2009), 2391–2396. <https://doi.org/10.1016/j.na.2009.01.073>
10. S. Zhang, Positive solutions to singular boundary value problem for nonlinear fractional differential equation, *Comput. Math. Appl.*, **59** (2010), 1300–1309. <https://doi.org/10.1016/j.camwa.2009.06.034>
11. B. Ahmad, J. J. Nieto, Existence results for a coupled system of nonlinear fractional differential equations with three-point boundary conditions, *Comput. Math. Appl.*, **58** (2009), 1838–1843. <https://doi.org/10.1016/j.camwa.2009.07.091>

12. F. Jiao, Y. Zhou, Existence of solutions for a class of fractional boundary value problems via critical point theory, *Comput. Math. Appl.*, **62** (2011), 1181–1199. <https://doi.org/10.1016/j.camwa.2011.03.086>
13. C. L. Tang, X. P. Wu, Some critical point theorems and their applications to periodic solution for second order Hamiltonian systems, *J. Differ. Equations*, **248** (2010), 660–692. <https://doi.org/10.1016/j.jde.2009.11.007>
14. D. Vivek, K. Kanagarajan, S. Harikrishnan, Analytic study on nonlocal initial value problems for pantograph equations with Hilfer-Hadamard fractional derivative, *Int. J. Math. Appl.*, **6** (2018), 21-32.
15. H. A. Hammad, M. De la Sen, Analytical solution of Urysohn integral equations by fixed point technique in complex valued metric spaces, *Mathematics*, **7** (2019), 852. <https://doi.org/10.3390/math7090852>
16. C. Wang, T. Z. Xu, Stability of the nonlinear fractional differential equations with the right-sided Riemann-Liouville fractional derivative, *Discrete Cont. Dyn. S*, **10** (2017), 505–521. <https://doi.org/10.3934/dcdss.2017025>
17. N. Mehmood, N. Ahmad, Existence results for fractional order boundary value problem with nonlocal non-separated type multi-point integral boundary conditions, *AIMS Math.*, **5** (2020), 385–398. <https://doi.org/10.3934/math.2020026>
18. Humaira, H. A. Hammad, M. Sarwar, M. De la Sen, Existence theorem for a unique solution to a coupled system of impulsive fractional differential equations in complex-valued fuzzy metric spaces, *Adv. Differ. Equ.* **2021** (2021), 242. <https://doi.org/10.1186/s13662-021-03401-0>
19. W. Al-Sadi, M. Hussein, T. Q. S. Abdullah, Existence and stability criterion for the results of fractional order Φ_p -Laplacian operator boundary value problem, *Comput. Methods Diff. E.*, **9** (2021), 1042–1058. <https://doi.org/10.22034/CMDE.2021.32807.1580>
20. K. R. Prasad, M. Khuddush, D. Leela, Existence, uniqueness and Hyers-Ulam stability of a fractional order iterative two-point boundary value Problems, *Afr. Math.*, **32** (2021), 1227–1237. <https://doi.org/10.1007/s13370-021-00895-5>
21. H. A. Hammad, M. Zayed, Solving a system of differential equations with infinite delay by using tripled fixed point techniques on graphs, *Symmetry*, **14** (2022), 1388. <https://doi.org/10.3390/sym14071388>
22. H. A. Hammad, M. Zayed, Solving systems of coupled nonlinear Atangana-Baleanu-type fractional differential equations, *Bound. Value Probl.*, **2022** (2022), 101. <https://doi.org/10.1186/s13661-022-01684-0>
23. A. Devi, A. Kumar, Stability results and existence for fractional differential equation involving Atangana-Baleanu derivative with nonlocal integral conditions, *Int. J. Appl. Comput. Math.*, **8** (2022), 228. <https://doi.org/10.1007/s40819-022-01406-1>
24. N. Abdellouahab, B. Tellab, K. Zennir, Existence and Stability results of a nonlinear fractional integro-differential equation with integral boundary conditions, *Kragujevac J. Math.*, **46** (2022), 685–699. <https://doi.org/10.46793/KgJMat2205.685A>

25. H. A. Hammad, H. Aydi, H. Işık, M. De la Sen, Existence and stability results for a coupled system of impulsive fractional differential equations with Hadamard fractional derivatives, *AIMS Math.*, **8** (2023), 6913–6941. <https://doi.org/10.3934/math.2023350>
26. R. P. Agarwal, S. Hristova, D. O'Regan, Boundary value problems for fractional differential equations of Caputo type and Ulam type stability: Basic concepts and study, *Axioms*, **12** (2023), 226. <https://doi.org/10.3390/axioms12030226>
27. L. P. Castro, A. S. Silva, On the existence and stability of solutions for a class of fractional Riemann-Liouville initial value problems, *Mathematics*, **11** (2023), 297. <https://doi.org/10.3390/math11020297>
28. H. A. Hammad, R. A. Rashwan, A. Nafea, M. E. Samei, S. Noeiaghdam, Stability analysis for a tripled system of fractional pantograph differential equations with nonlocal conditions, *J. Vib. Control.*, 2023. <https://doi.org/10.1177/10775463221149232>
29. F. Develia, O. Duman, Existence and stability analysis of solution for fractional delay differential equations, *Filomat*, **37** (2023), 1869–1878. <https://doi.org/10.2298/FIL2306869D>
30. Y. Alruwaily, L. Almaghamisi, K. Karthikeyan, El-S El-hady, Existence and uniqueness for a coupled system of fractional equations involving Riemann-Liouville and Caputo derivatives with coupled Riemann-Stieltjes integro-multipoint boundary conditions, *AIMS Math.*, **8** (2023), 10067–10094. <https://doi.org/10.3934/math.2023510>
31. H. A. Hammad, P. Agarwal, S. Momani, F. Alsharari, Solving a fractional-order differential equation using rational symmetric contraction mappings, *Fractal Fract.*, **5** (2021), 159. <https://doi.org/10.3390/fractalfract5040159>
32. S. K. Ntouyas, J. Tariboon, Fractional boundary value problems with multiply orders of fractional derivatives and integrals, *Electron. J. Differ. Eq.*, **2017** (2017), 100.
33. L. Xu, Q. Dong, G. Li, Existence and Hyers-Ulam stability for three-point boundary value problems with Riemann-Liouville fractional derivatives and integrals, *Adv. Differ. Equ.*, **2018** (2018), 458. <https://doi.org/10.1186/s13662-018-1903-5>
34. A. A. Kilbas, H. M. Srivastava, J. J. Trujillo, *Theory and applications of fractional differential equations*, Elsevier, 2006.
35. S. Z. Rida, A. A. M. Arafa, Y. A. Gaber, Solution of the fractional epidemic model by L-ADM, *J. Fract. Calc. Appl.*, **7** (2016), 189–195.
36. M. A. Krasnoselskii, Two remarks on the method of successive approximations, *Usp. Mat. Nauk.*, **10** (1955), 123–127.
37. S. Banach, Sur les opérations dans les ensembles abstraits et leur application aux équations intégrales, *Fund. Math.*, **3** (1922), 133–181.



AIMS Press

©2023 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (<http://creativecommons.org/licenses/by/4.0>)