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## Research article

# The existence of a compact global attractor for a class of competition model 

Yanxia Wu*

School of Mathematic and Quantitative Economics, Shandong University of Finance and Economics, Jinan 250014, P.R.China

* Correspondence: Email: wuyxmath@163.com; Tel: +86053182617651; Fax: +86053182617651.


#### Abstract

This paper is concerned with the existence of a compact global attractor for a class of competition model in $n$-dimensional ( $n \geq 1$ ) domains. Using mathematical induction and more detailed interpolation estimates, especially Gagliardo-Nirenberg inequality, we obtain the existence of a compact global attractor, which implies the uniform boundedness of the global solutions. In particular, we get that the Shigesada-Kawasaki-Teramoto competition model has a compact global attractor for $n<10$. The result of the S-K-T model extends the existence results of compact global attractor in [21] from $n<8$ to $n<10$, and extends the uniform boundedness results of the global solutions in [17] to the non-convex domain.


Keywords: competition model; global existence; global attractor; uniform boundedness
Mathematics Subject Classification: 35A01, 35B41, 35K57, 92D40

## 1. Introduction and main results

In population dynamics, N. Shegesada, K. Kawasaki and E. Teromoto [15] proposed the following quasilinear competition model with cross-diffusion,

$$
\begin{cases}u_{t}=\Delta\left[\left(d_{1}+\rho_{11} u+\rho_{12} v\right) u\right]+u\left(a_{1}-b_{1} u-c_{1} v\right), & x \in \Omega, t>0,  \tag{1.1}\\ v_{t}=\Delta\left[\left(d_{2}+\rho_{21} u+\rho_{22} v\right) v\right]+v\left(a_{2}-b_{2} u-c_{2} v\right), & x \in \Omega, t>0, \\ \frac{\partial u}{\partial v}=\frac{\partial v}{\partial v}=0, & x \in \partial \Omega, t>0, \\ u(x, 0)=u_{0}(x) \geqslant 0, v(x, 0)=v_{0}(x) \geqslant 0, & x \in \Omega,\end{cases}
$$

where the functions $u, v$ are the population densities of the two competing species and the initial values $u_{0}, v_{0}$ are nonnegative functions, which are not identically zero. $\Omega$ is a bounded smooth region in $\mathbb{R}^{n}$ with $v$ as its unit outward normal vector to $\partial \Omega$. The constants $a_{j}, b_{j}, c_{j}, d_{j}(j=1,2)$ are all positive, and the constants $\rho_{i j}(i, j=1,2)$ are nonnegative, where $d_{1}$ and $d_{2}$ are the random diffusion rates, $\rho_{11}$, $\rho_{22}$ are the self-diffusion rates which represent intraspecific population pressures, and $\rho_{12}, \rho_{21}$ are the so-called cross-diffusion rates which represent the interspecific population pressures.

When $\rho_{i j}=0(i, j=1,2),(1.1)$ is reduces to the well-known Lotka-Volterra competition-diffusion system, which has been researched intensively. When $\rho_{12}$ or $\rho_{21}$ is positive, (1.1) is a strongly coupled parabolic system, which has received much attention, since it occurs frequently in biological and chemical models. H. Amann considered a general class of strongly coupled parabolic systems and established the local existence (in time) and uniqueness results in a series of papers [1-3]. Roughly speaking, H. Amann showed that if $u_{0}, v_{0}$ in $W^{1, p}(\Omega)$ with $p>n$, then (1.1) has a unique solution $u, v$ defined in $\left(0, t_{0}\right)$ with $t_{0}>0$ small.

The global existence of nonnegative solutions to (1.1) is considered under some restrictive hypotheses on the smallness of cross-diffusion pressures or on the space dimension. For the case $\rho_{12}>0, \rho_{21}>0$, if $\rho_{11}=\rho_{22}=0$, J. Kim [8] proved the global existence of classical solutions by energy method when $n=1$ and $d_{1}=d_{2}$. Later, S. Shim [16] improved J. Kim's results and obtained the uniform boundedness of the global solutions in time by interpolated estimates. P. Deuring [6] proved the global existence of classical solutions when $n \geqslant 1$ and $\rho_{12}, \rho_{21}$ are small enough depending on the $C^{2, \alpha}$ norm of initial values $u_{0}, v_{0}$. If the self-diffusion rates $\rho_{11}$ and $\rho_{22}$ are not zero, A. Yagi [22] proved the global existence of solutions when $n=2$ and $0<\rho_{12}<8 \rho_{11}, 0<\rho_{21}<8 \rho_{22}$, he also proved the same results for $\rho_{22}=\rho_{21}=0$ and $\rho_{11}>0$. In addition, Y. Li and C. Zhao [13] obtained the global existence of classical solutions when $n \geqslant 1, d_{1}=d_{2}$ and $\frac{\rho_{12}}{\rho_{22}}+\frac{\rho_{21}}{\rho_{11}}=2$.

For the case of $\rho_{21}=0$, (1.1) becomes the following system

$$
\begin{cases}u_{t}=\Delta\left[\left(d_{1}+\rho_{11} u+\rho_{12} v\right) u\right]+u\left(a_{1}-b_{1} u-c_{1} v\right), & x \in \Omega, t>0,  \tag{1.2}\\ v_{t}=\Delta\left[\left(d_{2}+\rho_{22} v\right) v\right]+v\left(a_{2}-b_{2} u-c_{2} v\right), & x \in \Omega, t>0, \\ \frac{\partial u}{\partial v}=\frac{\partial v}{\partial v}=0, & x \in \partial \Omega, t>0, \\ u(x, 0)=u_{0}(x) \geqslant 0, v(x, 0)=v_{0}(x) \geqslant 0, & x \in \Omega\end{cases}
$$

Y. Lou, W. Ni and Y. Wu [14] established a global existence of classical solutions to (1.2) for $n \leqslant 2$ and $\rho_{11}$ is merely assumed nonnegative but $\rho_{12}$ and $\rho_{22}$ are allowed to be positive, which is the only available result for smooth solutions with $\rho_{11}=0$. When $\rho_{11}$ is positive, Y. Choi, R. Lui and Y. Yamada [4, 5] obtained some results on the global existence of the solutions to (1.2) with the restrictions $n<6$ and $\rho_{22}>0$. P. Tuoc [20] showed the global existence of solutions for $n<10$. The global existence of solutions for arbitrary $n$ under some restrictions on coefficients are investigated (see [7,9, 11, 19]). For the uniform boundedness of the global solutions, D. Le, L. Nguyen and T. Nguyen [12] using the semigroup techniques obtained the global attractor for $n<6$, which implies the uniform boundedness of the global solutions. Q. Xu and Y. Zhao [21] obtained the global attractor for $n<8$. And Y. Tao and M. Winkler [17] showed the boundedness of the solutions for $n<10$ when $\Omega \in \mathbb{R}^{n}$ is a bounded convex domain with smooth boundary.

In this paper, we considered the following more general strongly coupled parabolic system

$$
\begin{cases}u_{t}=\nabla \cdot(P(u, v) \nabla u+Q(u, v) \nabla v)+u f(u, v), & x \in \Omega, t>0,  \tag{1.3}\\ v_{t}=\nabla \cdot(R(v) \nabla v)+v g(u, v), & x \in \Omega, t>0, \\ \frac{\partial u}{\partial v}=\frac{\partial v}{\partial v}=0, & x \in \partial \Omega, t>0, \\ u(x, 0)=u_{0}(x) \geqslant 0, v(x, 0)=v_{0}(x) \geqslant 0, & x \in \Omega .\end{cases}
$$

Due to the absence of the cross-diffusion term in the $v$-equation, the diffusion matrix of (1.3) is triangular. H. Amann [3] showed that if one can obtain $u \in L^{\infty}, v \in L^{\infty}$, then the solution of (1.3)
exists globally in time. D. Le [10] proved that if $u \in L^{n}, v \in L^{\infty}$, then the system (1.3) has a global attractor with finite Hausdorff dimension, which attracts all the solutions of (1.3). D. Le, L. Nguyen and T. Nguyen [12] improved the results of that in [10]. In order to state their results, we first introduce the following definition.
Definition 1.1. (see [10], Definition 2.1 ) Assume that there exists a solution ( $u, v$ ) of system (1.3) defined on a subinterval I of $\mathbb{R}^{+}$. Let $\mathcal{P}$ be the set of function $\omega$ on I such that there exists a positive constant $C_{0}$, which may generally depend on the parameters of the system and the $W^{1, p_{0}}$ norm of the initial value ( $u_{0}, v_{0}$ ), such that

$$
\omega(t) \leqslant C_{0}, \quad \forall t \in I
$$

Furthermore, if $I=(0, \infty)$, then there exists a positive constant $C_{\infty}$ that depends only on the parameters of the system, but does not depend on the initial value of $\left(u_{0}, v_{0}\right)$, such that

$$
\lim _{t \downarrow \infty} \sup \omega(t) \leqslant C_{\infty} .
$$

If $\omega \in \mathcal{P}$ and $I=(0, \infty)$, one says $\omega$ is ultimately uniformly bounded.
In [12], D. Le, L. Nguyen and T. Nguyen suppose that
(H1) There exist a continuous function $\Phi$ and positive constant $d$ such that the differentiable functions $P, Q, R$ satisfying

$$
P(u, v) \geqslant d(1+u)>0, \quad|Q(u, v)| \leqslant \Phi(v) u, \quad R(v) \geqslant d>0, \quad \forall u, v \geqslant 0 .
$$

$(\mathrm{H} 2)$ There exists a nonnegative continuous function $C(v)$ such that

$$
|f(u, v)| \leqslant C(v)(1+u), \quad g(u, v) u^{p} \leqslant C(v)\left(1+u^{p+1}\right), \quad \forall u, v \geqslant 0, p>0 .
$$

Under the above hypotheses $(\mathrm{H} 1)$ and $(\mathrm{H} 2)$, the authors proved the following results.
Lemma 1.2. (see [12], Theorem 2.4) Assume (H1) and (H2) hold. Let ( $u, v$ ) be a nonnegative solution to (1.3) with its maximal existence interval I. If $\|u\|_{q, r,[t, t+1] \times \Omega}=\left(\int_{t}^{t+1}\|u(\cdot, s)\|_{q, \Omega}^{r} d s\right)^{1 / r} \quad($ as a function in $t$ ) is in $\mathcal{P}$ for some $q, r$ satisfying

$$
\begin{equation*}
\frac{1}{r}+\frac{n}{2 q}=1-\chi, \quad q \in\left[\frac{n}{2(1-\chi)}, \infty\right], \quad r \in\left[\frac{1}{1-\chi}, \infty\right] \text { with some } \chi \in(0,1), \tag{1.4}
\end{equation*}
$$

then there exists an absorbing ball where all solutions will enter eventually. Thus, if the system (1.3) is autonomous then there is a compact global attractor with finite Hausdorff dimension in $\mathscr{B}$, which attracts all solutions, with

$$
\mathscr{B}=\left\{(u, v) \in W^{1, p_{0}}(\Omega) \times W^{1, p_{0}}(\Omega): u(x) \geqslant 0, v(x) \geqslant 0, \forall x \in \Omega\right\} .
$$

In this paper, we impose some conditions on the functions $P, Q, R, f, g$ in system (1.3) as follows. (A1) The functions $P, Q, R$ are differentiable in there variables, and there exist constants $\beta>0, b>0$ and continuous function $\phi(v) \geqslant 0$ for $v \geqslant 0$, such that

$$
\begin{equation*}
P(u, v) \geqslant d u^{\beta}, \quad|Q(u, v)| \leqslant \phi(v) u, \quad R(v) \geqslant d, \quad R^{\prime}(v) \geqslant 0 . \tag{1.5}
\end{equation*}
$$

(A2) For the reaction terms $(f, g)$, we assume that there exist positive constants $a, b, c, \alpha$ and nonnegative continuous functions $f_{1}(u, v), \varphi(v)$, such that

$$
\begin{equation*}
f(u, v)=a-b u^{\alpha}-f_{1}(u, v), \quad g(u, v) \leqslant \varphi(v)(1-c u)^{\frac{\alpha+1}{2}} . \tag{1.6}
\end{equation*}
$$

Remark 1. Our assumptions (A1)-(A2) on ( $P, Q, R, f, g$ ) in this paper satisfy (H1)-(H2) in [12].
Now, we state our main results.
Theorem 1.3. Suppose (A1)-(A2) hold and $\left(u_{0}, v_{0}\right) \in \mathscr{B}$ with some $p_{0}>n$. Then (1.3) has a compact global attractor with finite Hausdorff dimension in the space $\mathscr{B}$, which attracts all the solutions, for any given $\alpha>0, \beta>0$ and $n \leqslant 2$, but we need the following corresponding assumptions in (B1)-(B2) for $n>2$,
(B1) For $0<\beta \leqslant \frac{n-2}{6}$,
(i) if $0<\alpha \leqslant \frac{n+4}{n-2} \beta$, then $n^{2}-2(1+4 \beta) n+4 \beta<0$;
(ii) if $\frac{n+4}{n-2} \beta<\alpha<\beta+1$, then $n<2(\alpha+3 \beta)$;
(iii) if $\alpha \geqslant \beta+1$, then $n<2(2 \alpha+2 \beta-1)$.
(B2) For $\beta>\frac{n-2}{6}$, then
(i) if $0<\alpha \leqslant \beta+1$, then $n^{2}-2(1+4 \beta) n+4 \beta<0$;
(ii) if $\beta+1<\alpha<\frac{n+4}{n-2} \beta$, then $n^{2}-2(\alpha+3 \beta) n+4(\alpha-1)<0$;
(iii) if $\alpha \geqslant \frac{n+4}{n-2} \beta$, then $n<2(2 \alpha+2 \beta-1)$.

Theorem 1.4. Assume $n<10$ and $\left(u_{0}, v_{0}\right) \in \mathscr{B}$ with some $p_{0}>n$, then (1.2) has a compact global attractor with finite Hausdorff dimension in the space $\mathscr{B}$, which attracts all the solutions.

Remark 2. Theorem 1.3 and Theorem 1.4 imply the uniform boundedness of the global solutions to the systems (1.3) and (1.2), respectively.

This paper is organized as follows. In section 2, we shall prove the existence of a compact global attractor with finite Hausdorff dimension to system (1.3). As an application, we consider the Shegesada-Kawasaki-Teromoto competition model (1.2), and get the existence of a global attractor for $n<10$ in section 3 .

## 2. The existence of a global attractor to (1.3)

We shall first give the uniform Gronwall inequality, which will be frequently used in our proof.
Lemma 2.1. (the uniform Gronwall inequality) (see [18] Chapt. 3, Lemma 1.1). Suppose positive Lipschitz functions $y(t), r(t), h(t)$ defined on $\left[t_{0},+\infty\right]$ satisfy

$$
y^{\prime}(t) \leqslant r(t) y(t)+h(t),
$$

and

$$
\int_{t}^{t+\tau} r(s) d s \leqslant r_{0}, \quad \int_{t}^{t+\tau} h(s) d s \leqslant h_{0}, \quad \int_{t}^{t+\tau} y(s) d s \leqslant c_{0}, \quad \forall t \geqslant t_{0}
$$

with $\tau, r_{0}, h_{0}$ and $c_{0}$ some positive constants. Then it holds that

$$
y(t+\tau) \leqslant\left(\frac{c_{0}}{\tau}+h_{0}\right) e^{r_{0}}, \quad \forall t \geqslant t_{0} .
$$

For given initial data $u_{0}(x), v_{0}(x) \in \mathscr{B}$, it is standard to show that the solutions of (1.3) are still nonnegative. Then using comparison principle for parabolic equation on the $v$-equation of (1.3), it is easy to see

$$
\begin{equation*}
\|v(\cdot, t)\|_{L^{\infty}(\Omega)} \in \mathcal{P} \tag{2.1}
\end{equation*}
$$

For the solution $u$, it is easy to get the following properties.

Lemma 2.2. The solution $u$ of (1.3) satisfies

$$
\begin{equation*}
\|u(\cdot, t)\|_{L^{1}(\Omega)} \in \mathcal{P} \tag{2.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega} u^{\alpha+1} d x d s \in \mathcal{P} \tag{2.3}
\end{equation*}
$$

Proof. Integrating the $u$-equation of (1.3) by parts and noting the condition of $f(u, v)$ in (A2), we get

$$
\begin{equation*}
\frac{d}{d t} \int_{\Omega} u d x \leqslant a \int_{\Omega} u d x-b \int_{\Omega} u^{\alpha+1} d x, \tag{2.4}
\end{equation*}
$$

which together with Hölder inequality $\|u\|_{L^{1}(\Omega)} \leqslant\|u\|_{L^{\alpha+1}(\Omega)}\|1\|_{L^{\frac{\alpha+1}{\alpha}(\Omega)}}$ gives

$$
\begin{equation*}
\frac{d}{d t} \int_{\Omega} u d x \leqslant a \int_{\Omega} u d x-\frac{b}{|\Omega|^{\alpha}}\left(\int_{\Omega} u d x\right)^{\alpha+1} . \tag{2.5}
\end{equation*}
$$

Then the comparison principle of ordinary differential equation implies (2.2) holds. Integrate (2.4) from $t$ to $t+1$ and use (2.2) to yield (2.3).

For the solution $v$, we will prove the following result, which plays an important role in the following estimates of $u$ in Theorem 2.4. In the rest of our paper, $C_{i}(i=1,2, \cdots)$ are some positive constants, and we will not point out them one by one.

Lemma 2.3. For $n \geqslant 1$, the solution $v$ of (1.3) satisfies

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega}|\nabla v|^{4} d x d s \in \mathcal{P} \tag{2.6}
\end{equation*}
$$

Proof. In order to prove (2.6), we first show

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega}|\nabla \cdot(R(v) \nabla v)|^{2} d x d s \in \mathcal{P}, \tag{2.7}
\end{equation*}
$$

then we prove

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega}|R(v) \nabla v|^{4} d x d s \in \mathcal{P} . \tag{2.8}
\end{equation*}
$$

Recalling the condition of $R(v) \geqslant d$ in (A1), (2.8) ensures (2.6) holds.
Now, we first deal with the proof of (2.7). For this purpose, multiplying the second equation of (1.3) by $v$ and integrating by parts, we have

$$
\frac{1}{2} \frac{d}{d t} \int_{\Omega} v^{2} d x+\int_{\Omega} R(v)|\nabla v|^{2} d x=\int_{\Omega} v^{2} g(u, v) d x .
$$

Integrating the above equation over $[t, t+1]$, we obtain

$$
d \int_{t}^{t+1} \int_{\Omega}|\nabla v|^{2} d x d s \leqslant \frac{1}{2}\|v(t)\|_{L^{2}(\Omega)}^{2}+C_{1} \int_{t}^{t+1} \int_{\Omega}(1-c u)^{\frac{\alpha+1}{2}} d x d s,
$$

by $R(v) \geqslant d$ in (A1), $g(u, v) \leqslant \varphi(v)(1-c u)^{\frac{\alpha+1}{2}}$ in (A2) and the fact (2.1). Therefore, it is known by (2.1) and (2.2) that

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega}|\nabla v|^{2} d x d s \in \mathcal{P} \tag{2.9}
\end{equation*}
$$

Next, we multiply the $v$-equation of (1.3) by $R(v) v_{t}$ and integrate by parts to get

$$
\begin{aligned}
\int_{\Omega} R(v) v_{t}^{2} d x & =\int_{\Omega} R(v) v_{t} \nabla \cdot(R(v) \nabla v) d x+\int_{\Omega} R(v) v_{t} v g(u, v) d x \\
& =-\int_{\Omega} \nabla\left(R(v) v_{t}\right) \cdot(R(v) \nabla v) d x+\int_{\Omega} R(v) v_{t} v g(u, v) d x \\
& =-\frac{1}{2} \frac{d}{d t} \int_{\Omega} R^{2}(v)|\nabla v|^{2} d x+\int_{\Omega} R(v) v_{t} v g(u, v) d x \\
& \leqslant-\frac{1}{2} \frac{d}{d t} \int_{\Omega} R^{2}(v)|\nabla v|^{2} d x+\frac{d}{2} \int_{\Omega} v_{t}^{2} d x+\frac{c_{2}}{2} \int_{\Omega}(1+u)^{\alpha+1} d x,
\end{aligned}
$$

here, we use Hölder inequality, the condition of $g(u, v)$ in (A2) and (2.1).
Due to $R(v) \geqslant d$, thus

$$
\begin{equation*}
\frac{d}{d t} \int_{\Omega} R^{2}(v)|\nabla v|^{2} d x+d \int_{\Omega} v_{t}^{2} d x \leqslant C_{2} \int_{\Omega}(1+u)^{\alpha+1} d x \tag{2.10}
\end{equation*}
$$

In view of (2.1), (2.3), (2.9) and using the uniform Gronwall inequality on

$$
\frac{d}{d t} \int_{\Omega} R^{2}(v)|\nabla v|^{2} d x \leqslant C_{2} \int_{\Omega}(1+u)^{\alpha+1} d x
$$

we obtain

$$
\begin{equation*}
\int_{\Omega} R^{2}(v)|\nabla v|^{2} d x \in \mathcal{P} \tag{2.11}
\end{equation*}
$$

Moreover, integrate (2.10) over $[t, t+1]$ to know

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega} v_{t}^{2}(x, s) d x d s \in \mathcal{P} \tag{2.12}
\end{equation*}
$$

By the $v$-equation of (1.3) and noting (2.1), we have

$$
\begin{aligned}
\int_{\Omega}|\nabla \cdot(R(v) \nabla v)|^{2} d x & =\int_{\Omega}\left[v_{t}-v g(u, v)\right]^{2} d x \\
& \leqslant 2 \int_{\Omega} v_{t}^{2} d x+C_{3}+C_{4} \int_{\Omega} u^{\alpha+1} d x
\end{aligned}
$$

this together with (2.12) and (2.3) gives (2.7).
Next, we will prove (2.8). Denote $\xi=R(v) \nabla v$ and note $R^{\prime}(v) \geqslant 0$ in (A1) to get

$$
\begin{aligned}
\int_{\Omega}|\xi|^{4} d x & =\int_{\Omega} R(v)|\xi|^{2} \xi \cdot \nabla v d x \\
& =-\int_{\Omega} v \nabla \cdot\left(R(v)|\xi|^{2} \xi\right) d x \\
& =-\int_{\Omega} v \frac{R^{\prime}(v)}{R(v)}|\xi|^{4} d x-\int_{\Omega} v R(v)|\xi|^{2} \nabla \cdot \xi d x-2 \int_{\Omega} v R(v) \xi \cdot(\nabla \xi \cdot \xi) d x \\
& \leqslant-\int_{\Omega} v R(v)|\xi|^{2} \nabla \cdot \xi d x-2 \int_{\Omega} v R(v) \xi \cdot(\nabla \xi \cdot \xi) d x .
\end{aligned}
$$

By Hölder inequality, we can get

$$
-\int_{\Omega} v R(v)|\xi|^{2} \nabla \cdot \xi d x \leqslant\|v R(v)\|_{L^{\infty}(\Omega)}\|\xi\|_{L^{4}(\Omega)}^{2}\|\nabla \cdot \xi\|_{L^{2}(\Omega)}
$$

and

$$
-2 \int_{\Omega} v R(v) \xi \cdot(\nabla \xi \cdot \xi) d x \leqslant\|v R(v)\|_{L^{\infty}(\Omega)}\|\xi\|_{L^{4}(\Omega)}^{2}\|\nabla \xi\|_{L^{2}(\Omega)}
$$

thus

$$
\begin{equation*}
\|\xi\|_{L^{4}(\Omega)}^{2} \leqslant\|v R(v)\|_{L^{\infty}(\Omega)}\left(\|\nabla \cdot \xi\|_{L^{2}(\Omega)}+2\|\nabla \xi\|_{L^{2}(\Omega)}\right) . \tag{2.13}
\end{equation*}
$$

Now, we will prove

$$
\begin{equation*}
\|\nabla \xi\|_{L^{2}(\Omega)} \leqslant C_{6}\|\nabla \cdot \xi\|_{L^{2}(\Omega)} . \tag{2.14}
\end{equation*}
$$

Noting $\xi=R(v) \nabla v$, then we have

$$
\begin{align*}
& \nabla \cdot \xi=\nabla \cdot(R(v) \nabla v)=R^{\prime}(v)|\nabla v|^{2}+R(v) \Delta v, \\
& \nabla \xi=\nabla(R(v) \nabla v)=R^{\prime}(v)(\nabla v)^{T} \nabla v+R(v) \nabla^{2} v, \tag{2.15}
\end{align*}
$$

where we see $\nabla v$ as a row vector, $(\nabla v)^{T}$ is the transpose of $\nabla v$, and $\nabla^{2} v$ is a matrix.
By (2.15) and the standard elliptic regularity $\left\|\nabla^{2} v\right\|_{L^{2}(\Omega)} \leqslant C_{5}\|\Delta v\|_{L^{2}(\Omega)}$, we can prove (2.14) holds.
Therefore, in virtue of (2.13) and (2.14), we obtain

$$
\|\xi\|_{L^{4}(\Omega)}^{2} \leqslant\left(1+2 C_{6}\right)\|v R(v)\|_{L^{\infty}(\Omega)}\|\nabla \cdot \xi\|_{L^{2}(\Omega)} .
$$

This together with (2.7) and (2.1) indicates that (2.8) holds. This completes the proof of Lemma 2.3.

Next, we shall give the critical estimates in our paper.
Theorem 2.4. The solution $u$ of (1.3) satisfies

$$
\begin{gather*}
\|u\|_{L^{\bar{p}}(\Omega)} \in \mathcal{P},  \tag{2.16}\\
\int_{t}^{t+1} \int_{\Omega} u^{\bar{p}+\alpha} d x d s \in \mathcal{P} \tag{2.17}
\end{gather*}
$$

and

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega} u^{\bar{p}+\beta-2}|\nabla u|^{2} d x d s \in \mathcal{P} \tag{2.18}
\end{equation*}
$$

for $\bar{p}$ satisfying (i) $\bar{p}=\alpha+2 \beta$ or (ii) $\bar{p}>\alpha+2 \beta$ and $(n-2) \bar{p} \leqslant 3 n \beta$.
Proof. Multiplying the first equation in (1.3) by $u^{p-1}$ with $p>1$, and integrating on $\Omega$ by parts, we have

$$
\begin{aligned}
\frac{1}{p} \frac{d}{d t} \int_{\Omega} u^{p} d x= & -\int_{\Omega} \nabla u^{p-1} \cdot[P(u, v) \nabla u+Q(u, v) \nabla v] d x+\int_{\Omega} u^{p} f(u, v) d x \\
= & -(p-1) \int_{\Omega} u^{p-2} P(u, v)|\nabla u|^{2} d x-(p-1) \int_{\Omega} u^{p-2} Q(u, v) \nabla u \cdot \nabla v d x \\
& +\int_{\Omega} u^{p} f(u, v) d x .
\end{aligned}
$$

Recalling the condition of $f(u, v)$ in (A2) and $|Q(u, v)| \leqslant \phi(v) u$ in (A1), we have

$$
\int_{\Omega} u^{p} f(u, v) d x \leqslant a \int_{\Omega} u^{p} d x-b \int_{\Omega} u^{p+\alpha} d x
$$

and

$$
\begin{aligned}
\left|-\int_{\Omega} u^{p-2} Q(u, v) \nabla u \cdot \nabla v d x\right| & \leqslant \int_{\Omega} u^{p-2}|Q(u, v) \| \nabla u \cdot \nabla v| d x \\
& \leqslant\|\phi(v)\|_{\infty} \int_{\Omega}\left|u^{p-1} \nabla u \cdot \nabla v\right| d x \\
& =\|\phi(v)\|_{\infty} \int_{\Omega}\left|u^{\frac{p+\beta-2}{2}} \nabla u \cdot u^{\frac{p-\beta}{2}} \nabla v\right| d x \\
& \leqslant \frac{d}{2} \int_{\Omega} u^{p+\beta-2}|\nabla u|^{2} d x+\frac{C_{7}}{p-1} \int_{\Omega} u^{p-\beta}|\nabla v|^{2} d x,
\end{aligned}
$$

by Hölder inequality.
Combining these estimates and $P(u, v) \geqslant d u^{\beta}$ in (A1), then

$$
\begin{align*}
& \frac{1}{p} \frac{d}{d t} \int_{\Omega} u^{p} d x+\frac{d(p-1)}{2} \int_{\Omega} u^{p+\beta-2}|\nabla u|^{2} d x+b \int_{\Omega} u^{p+\alpha} d x  \tag{2.19}\\
& \leqslant a \int_{\Omega} u^{p} d x+C_{7} \int_{\Omega} u^{p-\beta}|\nabla v|^{2} d x .
\end{align*}
$$

Case I: $p \leqslant \alpha+2 \beta$. In this case, we have $2(p-\beta) \leqslant p+\alpha$.
Applying Hölder inequality and Young's inequality to the last term of (2.19), we have

$$
\begin{aligned}
C_{7} \int_{\Omega} u^{p-\beta}|\nabla v|^{2} d x & \leqslant \frac{b}{2} \int_{\Omega} u^{2 p-2 \beta} d x+C_{8} \int_{\Omega}|\nabla v|^{4} d x \\
& \leqslant \frac{b}{2} \int_{\Omega} u^{p+\alpha} d x+C_{8} \int_{\Omega}|\nabla v|^{4} d x+C_{9} .
\end{aligned}
$$

Consequently, (2.19) becomes

$$
\begin{align*}
& \frac{1}{p} \frac{d}{d t} \int_{\Omega} u^{p} d x+\frac{d(p-1)}{2} \int_{\Omega} u^{p+\beta-2}|\nabla u|^{2} d x+\frac{b}{2} \int_{\Omega} u^{p+\alpha} d x  \tag{2.20}\\
& \leqslant a \int_{\Omega} u^{p} d x+C_{8} \int_{\Omega}|\nabla v|^{4} d x+C_{9} .
\end{align*}
$$

Obviously, (2.20) entails

$$
\begin{equation*}
\frac{1}{p} \frac{d}{d t} \int_{\Omega} u^{p} d x \leqslant a \int_{\Omega} u^{p} d x+C_{8} \int_{\Omega}|\nabla v|^{4} d x+C_{9} . \tag{2.21}
\end{equation*}
$$

For the above inequality (2.21), if we can show

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega} u^{p} d x d s \in \mathcal{P} \tag{2.22}
\end{equation*}
$$

then (2.6) and the uniform Gronwall inequality yield

$$
\begin{equation*}
\|u\|_{L^{p}(\Omega)} \in \mathcal{P} . \tag{2.23}
\end{equation*}
$$

Furthermore, integrating (2.20) from $t$ to $t+1$, we can obtain

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega} u^{p+\alpha} d x d s \in \mathcal{P} \tag{2.24}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega} u^{p+\beta-2}|\nabla u|^{2} d x d s \in \mathcal{P} . \tag{2.25}
\end{equation*}
$$

Now, we will use mathematical induction to prove that (2.22) holds for $p=\alpha+2 \beta$. There exists some $k \in N_{+}$such that $1 \leqslant \alpha+2 \beta-k \alpha \leqslant \alpha+1$. Denote $p_{0}=\alpha+2 \beta-k \alpha, p_{m}=p_{m-1}+\alpha(m=1,2, \cdots, k)$. On one hand, using (2.3) and Hölder inequality, it is easy to see that (2.22) holds for $p=p_{0}$. On the other hand, we suppose (2.22) holds for $p=p_{m-1}$, then (2.24) means that (2.22) holds for $p=p_{m-1}+\alpha=p_{m}$. Hence the mathematical induction ensures that (2.22) holds for $p=p_{k}=\alpha+2 \beta$.

Therefore, (2.23)-(2.25) hold for $p=\alpha+2 \beta$, which implies (2.16)-(2.18) hold for $\bar{p}=\alpha+2 \beta$.
Case II: $p>\alpha+2 \beta$. In this case, we assume $(n-4) p \leqslant(3 n-4) \beta$.
Let $w_{p}=u^{\frac{p+\beta}{2}}$ and denote $w_{p}$ as $w$ sometimes for simplicity, then (2.19) can be written as

$$
\begin{align*}
& \frac{1}{p} \frac{d}{d t} \int_{\Omega} w^{\frac{2 p}{p+\beta}} d x+\frac{2 d(p-1)}{(p+\beta)^{2}} \int_{\Omega}|\nabla w|^{2} d x+b \int_{\Omega} w^{\frac{2(p+\alpha)}{p+\beta}} d x \\
& \quad \leqslant a \int_{\Omega} w^{\frac{2 p}{p+\beta}} d x+C_{7} \int_{\Omega} w^{\frac{2(p-\beta)}{p+\beta}}|\nabla v|^{2} d x \\
& \quad \leqslant a \int_{\Omega} w^{\frac{2 p}{p+\beta}} d x+C_{7}\left\|w^{\frac{2(p-\beta)}{p+\beta}}\right\|_{L^{2}(\Omega)}\|\nabla v\|_{L^{4}(\Omega)}^{2}  \tag{2.26}\\
& \quad=a\|w\|_{L^{\frac{2 p}{p}}}^{\frac{2 p}{p+\beta}}+C_{7}\|w\|_{L^{\frac{2 p}{p}(p)}}^{\frac{2(p-\beta)}{p+\beta}}\|\nabla v\|_{L^{4}(\Omega)}^{2},
\end{align*}
$$

by the Hölder inequality.
The conditions $p>\alpha+2 \beta$ and $(n-4) p \leqslant(3 n-4) \beta$ implies

$$
\frac{2(p+\alpha)}{p+\beta}<\frac{4(p-\beta)}{p+\beta} \leqslant \frac{2 n}{n-2},
$$

here $\frac{2 n}{n-2}$ can be replaced by $+\infty$ for $n=2$.
It is known by Gagliardo-Nirenberg inequality that

$$
\begin{equation*}
\|w\|_{L^{\frac{4(p-\beta)}{p+\beta}(\Omega)}} \leqslant C_{10}\|w\|_{L^{\frac{2 p}{p+\beta}(\Omega)}}^{1-\theta}\|\nabla\|_{L^{2}(\Omega)}^{\theta}+C_{10}\|w\|_{L^{1}(\Omega)}, \tag{2.27}
\end{equation*}
$$

with

$$
\theta=\frac{n(p+\beta)(p-2 \beta)}{2(p-\beta)(2 p+n \beta)} .
$$

Using (2.27) and Young's inequality, we have

$$
\begin{aligned}
& C_{7}\|w\|_{L^{\frac{4(p-\beta)}{p+\beta}(\Omega)}}^{\substack{\frac{2(p-\beta)}{p+\beta}}}\|\nabla v\|_{L^{4}(\Omega)}^{2} \\
& \leqslant C_{11}\|w\|_{L^{\frac{2 p-p}{p+\beta}(\Omega)}}^{\frac{2(p-\beta)(1-\theta)}{p+p)}}\|\nabla w\|_{L^{2}(\Omega)}^{\frac{2 q(p-\beta)}{p+\beta}}\|\nabla v\|_{L^{4}(\Omega)}^{2}+C_{11}\|w\|_{L^{1}(\Omega)}^{\frac{2(p-\beta)}{p+\beta}}\|\nabla v\|_{L^{4}(\Omega)}^{2} \\
& \leqslant \varepsilon\|\nabla w\|_{L^{2}(\Omega)}^{2}+C_{\varepsilon}\|w\|_{L^{\frac{2 p}{p+\beta}(\Omega)}}^{m_{1}}\|\nabla v\|_{L^{4}(\Omega)}^{m_{2}}+C_{11}\|w\|_{L^{1}(\Omega)}^{\frac{4(p-\beta)}{p+\beta}}+C_{11}\|\nabla v\|_{L^{4}(\Omega)}^{4},
\end{aligned}
$$

with

$$
m_{1}=\frac{2(p-\beta)(1-\theta)}{p+\beta-\theta(p-\beta)}, \quad m_{2}=\frac{2(p+\beta)}{p+\beta-\theta(p-\beta)} .
$$

Let $\varepsilon=\frac{d(p-1)}{(p+\beta)^{2}}$, then (2.26) becomes

$$
\begin{align*}
& \frac{1}{p} \frac{d}{d t} \int_{\Omega} w^{\frac{2 p}{p+\beta}} d x+\frac{d(p-1)}{(p+\beta)^{2}} \int_{\Omega}|\nabla w|^{2} d x+b \int_{\Omega} w^{\frac{2(p+\alpha)}{p+\beta}} d x \\
& \leqslant a\|w\|_{\frac{2 p}{p+\beta}}^{\frac{2 p}{p+p}(\Omega)}+C_{\varepsilon}\|w\|_{L^{\frac{2 p}{p p}}(\Omega)}^{m_{1}}\|\nabla v\|_{L^{4}(\Omega)}^{m_{2}}+C_{11}\|w\|_{L^{1}(\Omega)}^{\frac{4 p+\beta)}{p+\beta}}+C_{11}\|\nabla v\|_{L^{4}(\Omega)}^{4} . \tag{2.28}
\end{align*}
$$

Let $y(t)=\|w\|_{L^{\frac{2 p}{p+\beta}(\Omega)}}^{\substack{\frac{2 p}{p+\beta}}}, h(t)=C_{11}\|w\|_{L^{L}(\Omega)}^{\frac{4 p-\beta)}{p+\beta}}+C_{11}\|\nabla v\|_{L^{4}(\Omega)}^{4}$, then we have

$$
\begin{equation*}
\frac{1}{p} \frac{d}{d t} y(t) \leqslant a y(t)+C_{\varepsilon} y(t)^{\frac{(p+\beta) m_{1}}{2 p}}\|\nabla v\|_{L^{4}(\Omega)}^{m_{2}}+h(t) . \tag{2.29}
\end{equation*}
$$

For the case of $y(t) \leqslant 1$, obviously we have

$$
\begin{equation*}
y(t)=\int_{\Omega} w^{\frac{2 p}{p+\beta}} d x \in \mathcal{P} . \tag{2.30}
\end{equation*}
$$

Since $p>\alpha+2 \beta$, (2.30) implies $\|w\|_{L^{1}(\Omega)} \in \mathcal{P}$ by Hölder inequality. Let

$$
(n-2) p \leqslant 3 n \beta
$$

then a direct calculation shows that $m_{2} \leqslant 4$. Consequently, (2.6) and Hölder inequality give

$$
\begin{equation*}
\|\nabla v\|_{L^{4}(\Omega)}^{m_{2}} \in \mathcal{P} \tag{2.31}
\end{equation*}
$$

Furthermore, integrating (2.28) from $t$ to $t+1$ yields

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega} w^{\frac{2(p+\alpha)}{p+\beta}} d x d s \in \mathcal{P} \tag{2.32}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{t}^{t+1} \int_{\Omega}|\nabla w|^{2} d x d s \in \mathcal{P} . \tag{2.33}
\end{equation*}
$$

For the case of $y(t)>1$, denote $r(t)=a+C_{\varepsilon}\|\nabla v\|_{L^{4}(\Omega)}^{m_{2}}$, then

$$
\begin{equation*}
\frac{1}{p} \frac{d}{d t} y(t) \leqslant r(t) y(t)+h(t), \tag{2.34}
\end{equation*}
$$

here, we used the fact

$$
\frac{(p+\beta) m_{1}}{2 p}=\frac{(3 n-4) \beta-(n-4) p}{(4 p-n p+4 n \beta)}<1 .
$$

It is easy to see that (2.31) implies $\int_{t}^{t+1} r(s) d s \in \mathcal{P}$ for $(n-2) p \leqslant 3 n \beta$, thus if we can show

$$
\begin{equation*}
\int_{t}^{t+1} y(s) d s \in \mathcal{P}, \quad \int_{t}^{t+1} h(s) d s \in \mathcal{P} \tag{2.35}
\end{equation*}
$$

then using the uniform Gronwall inequality to the inequality (2.34), we obtain (2.30). Similarly, integrate (2.28) over $[t, t+1]$ to obtain (2.32) and (2.33).

Now, we prove $(2.35)$ for $(n-2) p=3 n \beta$. In order to get $\int_{t}^{t+1} h(s) d s \in \mathcal{P}$, recalling (2.6), the key step is to deal with

$$
\begin{equation*}
\int_{t}^{t+1}\|w\|_{L^{1}(\Omega)}^{\frac{4(p-\beta)}{p+\beta}} d s \in \mathcal{P} \tag{2.36}
\end{equation*}
$$

since the Minkowski's inequality ensures

$$
\int_{t}^{t+1} h(s) d s \leqslant C_{11} \int_{t}^{t+1}\|w\|_{L^{\prime}(\Omega)}^{\frac{4(p-\beta)}{p+\beta}} d s+C_{11} \int_{t}^{t+1}\|\nabla v\|_{L^{4}(\Omega)}^{4} d s
$$

Now, we will prove $\int_{t}^{t+1} y(s) d s \in \mathcal{P}$ and (2.36) by mathematical induction, simultaneously. For the case of $n>2$, there exists some $\bar{k} \in N_{+}$such that $\alpha+2 \beta<\frac{3 n \beta}{n-2}-\bar{k} \alpha \leqslant 2 \alpha+2 \beta$. Denote $q_{0}=\frac{3 n \beta}{n-2}-\bar{k} \alpha, q_{m}=q_{m-1}+\alpha(m=1,2, \cdots, \bar{k})$. Since we have proved (2.17) for $\bar{p}=\alpha+2 \beta$, it is easy to get $\int_{t}^{t+1} y(s) d s \in \mathcal{P}$ for $p=q_{0}$ by Hölder inequality. In addition, noting that $\frac{q_{0}+\beta}{2} \leqslant \frac{2 \alpha+3 \beta}{2}<\alpha+2 \beta$ and (2.16) holds for $\bar{p}=\alpha+2 \beta$, using Hölder inequality we obtain $\left\|w_{q_{0}}\right\|_{L^{1}(\Omega)} \in \mathcal{P}$, which indicates that the result (2.36) is true for $p=q_{0}$. On the other hand, assume $\int_{t}^{t+1} y(s) d s \in \mathcal{P}$ and (2.36) hold for $p=q_{m-1}$, then (2.32) holds for $p=q_{m-1}$. According to the definition $w_{p}=u^{\frac{p+\beta}{2}}$, it is easy to see

$$
\left(w_{q_{m-1}}\right)^{\frac{2\left(q_{m-1}++\infty\right)}{q_{m-1}+\beta}}=\left(w_{q_{m}}\right)^{\frac{2 q_{m}}{q_{m}+\beta}},
$$

thus $\int_{t}^{t+1} y(s) d s \in \mathcal{P}$ for $p=q_{m}$. Moreover, the assumption implies (2.30) holds for $p=q_{m-1}$ and hence

$$
\left\|w_{q_{m}}\right\|_{L^{1}(\Omega)} \leqslant C \|\left. w_{q_{m-1}}\right|_{L^{2}} ^{\frac{2 q_{m-1}}{\tau_{m-1}-1+\beta}},
$$

by $q_{m-1}>\alpha+2 \beta$ and Hölder inequality with some $C>0$. And thus (2.36) holds for $p=q_{m}$.
Above all, for the case of $n>2$, we have proved (2.35) with $p=\frac{3 n \beta}{n-2}$. Therefore, (2.30), (2.32) and (2.33) hold for $p=\frac{3 n \beta}{n-2}$, which implies (2.16)-(2.18) hold for $\bar{p} \leqslant \frac{3 n \beta}{n-2}$. Similarly, we can prove (2.16)-(2.18) hold for any positive constant $\bar{p}>\alpha+2 \beta$ if $n \leqslant 2$.

This complete the proof of Theorem 2.4.

Next, we will use Lemma 1.2 and Theorem 2.4 to give the proof of Theorem 1.3.
proof of Theorem 1.3. Let $s=\bar{p}+\alpha$, then by (2.17),

$$
\int_{t}^{t+1}\|u\|_{L^{s}(\Omega)}^{s} d s=\int_{t}^{t+1} \int_{\Omega} u^{\bar{p}+\alpha} d x d s \in \mathcal{P} .
$$

Define

$$
\begin{gathered}
1-\chi=\frac{1}{s}+\frac{n}{2 s}=\frac{n+2}{2 s}=\frac{n+2}{2(\bar{p}+\alpha)}, \\
A=s-\frac{n}{2(1-\chi)}=\frac{2 s}{n+2}>0, \quad B=s-\frac{1}{1-\chi}=\frac{n s}{n+2}>0 .
\end{gathered}
$$

By Lemma 1.2, we also need $\chi \in(0,1)$, which is equivalent to

$$
\begin{equation*}
n<2(\bar{p}+\alpha-1) . \tag{2.37}
\end{equation*}
$$

It is known by Gagliardo-Nirenberg inequality that

$$
\|w\|_{L^{*}(\Omega)} \leqslant C_{12}\left(\|\nabla w\|_{L^{2}(\Omega)}+\|w\|_{L^{1}(\Omega)}\right),
$$

with $2^{*}=2 n /(n-2)$.
Let $l=\frac{\bar{p}+\beta}{2}$ and $r=2 l, q=2^{*} l$, then $w=u^{l}$ and

$$
\int_{t}^{t+1}\|u\|_{L^{q}(\Omega)}^{r} d s=\int_{t}^{t+1}\|w\|_{L^{2^{*}}(\Omega)}^{2} d s \leqslant 2 C_{12}\left[\int_{t}^{t+1}\|\nabla w\|_{L^{2}(\Omega)}^{2} d s+\sup _{[t, t+1]}\|w\|_{L^{1}(\Omega)}^{2}\right] .
$$

The estimate $\|w\|_{L^{1}(\Omega)} \in \mathcal{P}$ comes from (2.16) by Hölder inequality, which together with (2.18) indicates

$$
\int_{t}^{t+1}\|u\|_{L^{q}(\Omega)}^{r} d s \in \mathcal{P}
$$

Let

$$
\begin{gathered}
1-\chi=\frac{1}{r}+\frac{n}{2 q}=\frac{1}{l}\left(\frac{1}{2}+\frac{n}{2 \cdot 2^{*}}\right)=\frac{n}{4 l}=\frac{n}{2(\bar{p}+\beta)}, \\
A=q-\frac{n}{2(1-\chi)}=\frac{2(\bar{p}+\beta)}{n-2}>0, \quad B=r-\frac{1}{1-\chi}=\frac{n-2}{n}(\bar{p}+\beta)>0 .
\end{gathered}
$$

By Lemma 1.2, we also need $\chi \in(0,1)$, which means

$$
\begin{equation*}
n<2(\bar{p}+\beta) . \tag{2.38}
\end{equation*}
$$

Comparing (2.37) and (2.38), we choose $n<2(\bar{p}+\alpha-1)$ if $\alpha>\beta+1$, otherwise, we choose $n<2(\bar{p}+\beta)$. In addition, recall $\bar{p}$ satisfies (i) $\bar{p}=\alpha+2 \beta$ or (ii) $\bar{p}>\alpha+2 \beta$ and $(n-2) \bar{p} \leqslant 3 n \beta$ in Theorem 2.4, hence we can assign any positive number to $\bar{p}$ for $n \leqslant 2$, but we choose $\bar{p}=\frac{3 n \beta}{n-2}$ if $0<\alpha \leqslant \frac{n+4}{n-2} \beta$, otherwise, we choose $\bar{p}=\alpha+2 \beta$ for $n>2$. Consequently, combining these analysis we can obtain Theorem 1.3.

## 3. The uniform boundedness of the solutions to S-K-T model for $n<10$

In this part, we will consider the boundedness of the global solutions to the following S-K-T model

$$
\begin{cases}u_{t}=\Delta\left[\left(d_{1}+\rho_{11} u+\rho_{12} v\right) u\right]+u\left(a_{1}-b_{1} u-c_{1} v\right), & x \in \Omega, t>0,  \tag{3.1}\\ v_{t}=\Delta\left[\left(d_{2}+\rho_{22} v\right) v\right]+v\left(a_{2}-b_{2} u-c_{2} v\right), & x \in \Omega, t>0, \\ \frac{\partial u}{\partial v}=\frac{\partial v}{\partial v}=0, & x \in \partial \Omega, t>0, \\ u(x, 0)=u_{0}(x) \geqslant 0, v(x, 0)=v_{0}(x) \geqslant 0, & x \in \Omega .\end{cases}
$$

Proof of Theorem 1.4. Comparing with the divergence form of system (1.3), we have

$$
\begin{gathered}
P(u, v)=d_{1}+2 \rho_{11} u+\rho_{12} v, Q(u, v)=\rho_{12} u, R(v)=d_{2}+2 \rho_{22} v, \\
f(u, v)=a_{1}-b_{1} u-c_{1} v, g(u, v)=a_{2}-b_{2} u-c_{2} v .
\end{gathered}
$$

It is easy to see that $P, Q, R$ and $f, g$ satisfy the conditions in (A1) and (A2), respectively, with $\alpha=$ $\beta=1$.

Theorem 1.3 gives Theorem 1.4 for $n \leqslant 2$ directly. Moreover, a simple computation shows (B2) (i) in Theorem 1.3 holds for $2<n<8$ and (B1) (i) holds for $8 \leqslant n<10$. This completes the proof of Theorem 1.4.

Remark 3. Our result implies the uniform boundedness of the global solutions to the system (3.1). This result extends the existence results of global attractor in [21] from $n<8$ to $n<10$, and extends the uniform boundedness results of the global solutions in [17] to the non-convex domain.

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## Conflict of interest

The author declares no conflicts of interest in this paper.

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