



*Research article*

## **Bionic design and multi-objective optimization of thin-walled structures inspired by conchs**

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**Abstract:** Thin-walled structures have been widely used in various parts of vehicle subsystems because of their high-efficiency impact energy absorption and lightweight characteristics. However, the impact deformation mode of conventional thin-walled structures is unstable and the energy absorption efficiency is low. Therefore, a series of novel bionic conch structures (BCS) are proposed to find a more excellent crashworthiness design in this study. First, the finite element simulation model of BCS verified by experiments is established. Then, the energy absorption characteristics of bionic conch structures, and conventional single-cell and multi-cell tubes under axial loading are compared by employing finite element simulation. The results show that the thin-walled structures inspired by conchs have a higher energy absorption efficiency than the other two structures with the same mass. In addition, the influence of main design parameters (wall thickness, inner and outer ring diameter, and the number of inner and outer panels) on the crashworthiness of BCS is studied through parameter design and factor significance analysis. Finally, the optimal geometric configuration is found by combining the approximation model and multi-objective particle swarm optimization, and the crashworthiness of BCS is further optimized. The bionic crashworthiness design and optimization framework proposed in this study can also provide a reference for other engineering protective structures.

**Keywords:** thin-walled structures; multi-objective optimization; energy absorption; bionic design; crashworthiness

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## 1. Introduction

To strengthen the protection of passengers in traffic accidents, realize the lightweight and improve the impact energy absorption efficiency, thin-walled structures have been widely used as energy absorbers during the past two decades. For example, Wierzbicki and Abramowicz [1], Krolak et al. [2], Langseth et al. [3] and Xiang et al. [4] studied the energy absorption characteristics of single-walled columns under axial impact loading. It was found that the energy absorption capacity of the single-walled structure is still insufficient and prone to Euler buckling, which greatly reduces the energy absorption efficiency of thin-walled structures. Many teams have conducted academic research on multi-cell thin-walled structures through experiments [5–8], simulations [9–12], and theoretical analyses [13–15]. For example, Zhang et al. [16] analyzed the axial impact energy absorption of different square multi-cell aluminum tubes with the same mass and found that the multi-cell structure with more walls can effectively improve the energy absorption efficiency. Jusuf et al. [17] studied the impact resistance of single-walled, double-walled and multi-cell columns under dynamic axial loading by means of numerical analysis and experimental research. The results showed that adding internal ribs between the walls of double-walled columns is beneficial to improve the impact resistance of multi-cell columns. It was found that the multi-cell properties of thin-walled structures could improve their energy absorption. Moreover, the energy dissipation of thin-walled structures is mainly concentrated at the corners of thin-walled structures [1,18], and forming a 90° angle at corners can effectively improve the average crushing force and energy absorption [19]. Chen et al. [18] proposed simplified super folding element (SSFE) theory, and deduced the theoretical expressions of folding wavelength and mean crushing force of multi-cell columns.

Recently, some researchers found that there are many biological tissues in nature with outstanding mechanical properties and excellent crashworthiness, such as bamboo [20–25], beetle elytra [26–28], animal horns [29–31]. They used bio-inspired theory to optimize the design of thin-walled structures. At the same time, hierarchical designs inspired by bionic design [32–39] have been regarded as one of the effective design methods to improve the crashworthiness of thin-walled structures. For example, Zhang et al. [40,41] proposed a series of hierarchical designs of hexagonal and circular structures. The result revealed that hierarchical structures had higher energy absorption efficiency than single-walled structures. Yin et al. [42] compared the energy absorption of triangular hierarchical honeycomb and conventional honeycomb with the same thickness. The result showed that the hierarchical honeycomb has better axial crashworthiness. Wang et al. [43] investigated the crashworthiness of the vertex-based hierarchical square multi-cell tubes by means of numerical and theoretical analysis, and showed that the hierarchical design can make the deformation mode of multi-cell structures more stable. Zhang et al. [44] established a theoretical model and investigated the energy absorption of the hexagonal hierarchical structure, and found that hierarchical order is an important factor affecting the energy absorption efficiency.

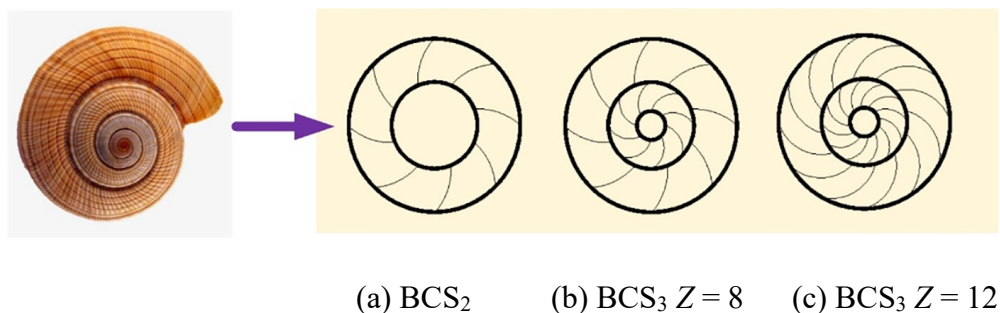
It is found that the multi-cell characteristics of thin-walled structures can enhance their energy absorption performances. The plastic strain and energy dissipation of the thin-walled structure mainly focus on the corner of the structure. In other words, the more corners there are, the more stable the

structure will be. How to properly distribute the corner elements in thin-walled structures? — Nature can give us the answer. In this study, novel thin-walled structures are inspired by the spiral hierarchy of the conch. A series of conch-like spiral multi-cell structures are formed by adding corner units of the multi-cell structure with regular lines. Based on the design of conch hierarchical structures, the bionic hierarchical energy-absorbing structures are developed. In addition, on the basis of the bionic conch design, a gradient design of gradual energy absorption was proposed to ensure the acceptable initial peak force and energy absorption efficiency. This design can reduce the initial peak force while ensuring the characteristics of efficient and gradual energy absorption, and effectively improve the safety performance of vehicles.

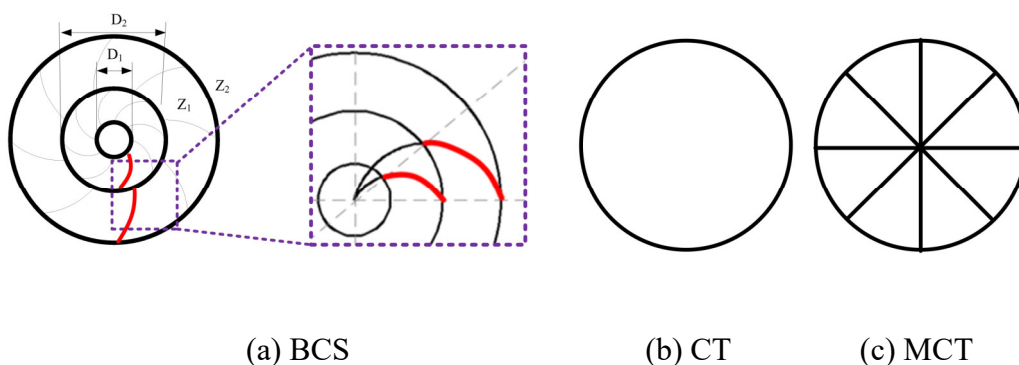
## 2. Numerical models, validation and comparative analysis

### 2.1. Geometry model

The novel bionic conch structures (BCS) are shown in Figure 1. The geometric cross section and geometric parameters of the bionic conch structures are shown in Figure 2(a), and the main geometric parameters including wall thickness  $T$ , inner ring diameter  $D_1$ , middle ring diameter  $D_2$ , the number of inner panels  $Z_1$ , and the number of outer panels  $Z_2$ . Figures 2(b) and 2(c) show the geometric cross-section of conventional thin-walled structures, in which Figure 2(b) shows the conventional single-cell tube (CT) and Figure 2(c) shows the conventional multi-cell tube (MCT). Among them, the outermost circle diameter of geometric sections of all thin-walled structures is 60 mm.



**Figure 1.** The hierarchical design of bionic conch.

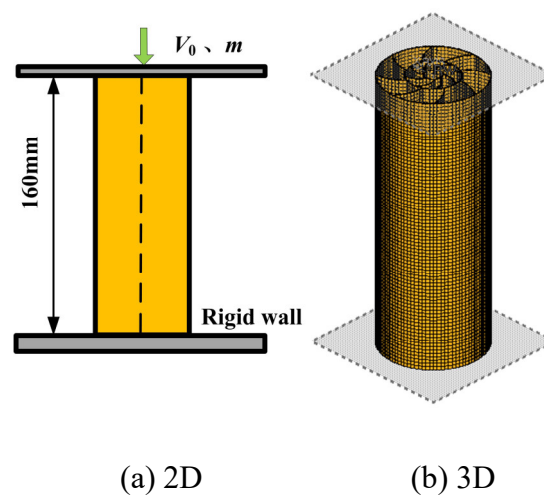


**Figure 2.** Geometric cross sections of three structures.

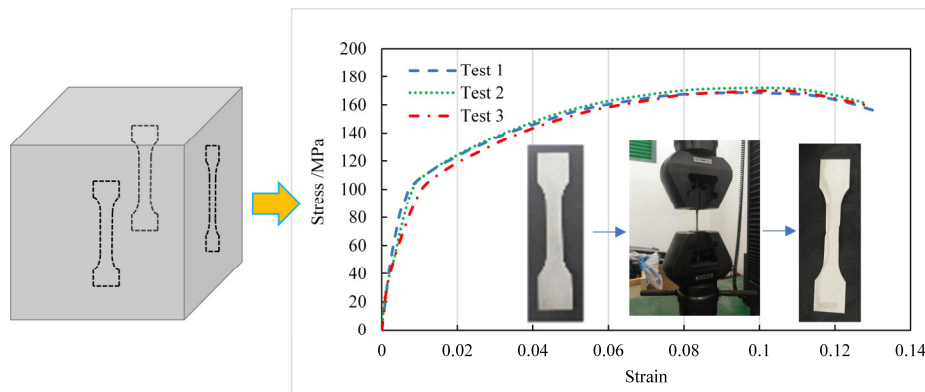
## 2.2. Finite element model (FEM)

The established finite element model of BCS is shown in Figure 3(b). The length of the model is 160 mm, and the bottom is connected with a rigid wall. The thin-walled structure is impacted with a mass of 500 kg and the initial velocity is 10 m/s. The grid size is discretized by BT four-node shell elements of  $1\text{ mm} \times 1\text{ mm}$ . The impact block and rigid wall are defined as rigid bodies, and the rigid support adopts MAT-20 rigid material model in LS-DYNA. Automatic point-surface contact is adopted between the thin-walled structure and the rigid support, and MAT-24 material model is adopted for the thin-walled structure, which is made of aluminum alloy AL6061-O. The basic material parameters of AL6061-O are as follows: density  $\rho = 2.7 \times 10^3\text{ kg/m}^3$ , Young's modulus  $E = 71.7\text{ GPa}$ , initial yield stress  $\sigma_y = 98.9\text{ MPa}$ , ultimate stress  $\sigma_u = 169\text{ MPa}$ , and Poisson's ratio  $\mu = 0.3$ . In this case, automatic single-sided contact is applied to the contact surface to ensure that contact penetration does not occur during compression.

The effective stress-strain curve of AL6061-O is shown in Figure 4. The static and dynamic friction coefficients of contact are 0.3 and 0.2, respectively. In addition, the strain rate effect is ignored in the numerical model because aluminum alloys are not sensitive to strain rate [45].



**Figure 3.** The impact diagram 2D & 3D.



**Figure 4.** Effective stress-strain curve of AL6061-O.

### 2.3. Crashworthiness indicators

The main crashworthiness indicators include Energy Absorption (EA), Specific Energy Absorption (SEA), Peak Crushing Force (PCF), and Crushing Load Efficiency (CLE).

SEA is the most critical indicator of energy absorption efficiency, which represents the energy absorption rate of thin-walled structures per unit mass, and can be expressed as:

$$SEA = \frac{EA}{m} \quad (1)$$

where  $m$  represents the mass of the structure, EA represents the total energy absorption of the structure in the process of plastic deformation, and its equation is:

$$EA = \int_0^{\delta} F(x) dx \quad (2)$$

where  $\delta$  represents the effective compression displacement. Generally, the effective compression displacement is 70% of the length of the model.  $F(x)$  is the instantaneous crushing force. The Peak Crushing Force (PCF) and Mean Crushing Force (MCF) of  $F(x)$  are closely related to the safety of passengers, because a high initial peak force will cause serious damage to passengers.

MCF can be expressed as:

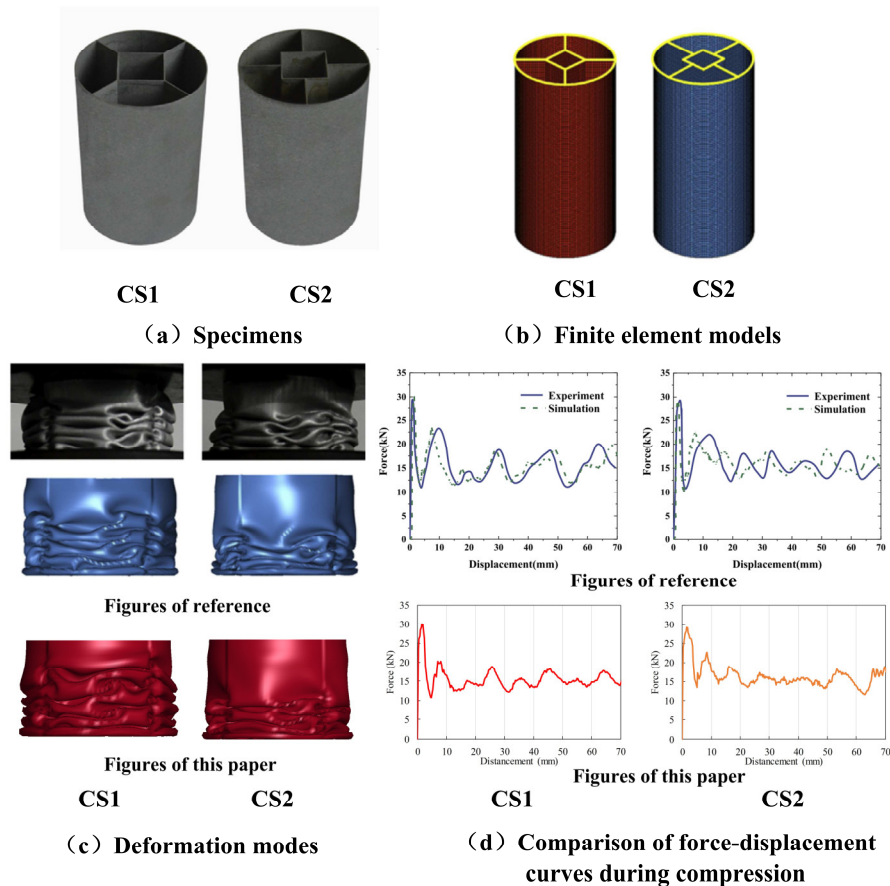
$$MCF = \frac{EA}{\delta} = \frac{\int_0^{\delta} F(x) dx}{\delta} \quad (3)$$

In addition, CLE can evaluate the stability of load in the impact process, and can be expressed as:

$$CLE = \frac{MCF}{PCF} \times 100\% \quad (4)$$

### 2.4. Validation of FE models

To verify the accuracy of the model, this paper compared the model built by the above method with the simulation results of references. The simulation models CS1 and CS2 established by Chen et al. [46] were highly consistent with the experimental results. Therefore, this paper used the same method to establish the finite element model for the corresponding simulation analysis. The comparison of the deformation modes with the reference and experimental results is shown in Figure 5. The test and simulation results are shown in Table 1, and the results show that the deformation modes, process curves, PCF and SEA results of the model established in this paper are in good consistency with the experimental results of the reference, and the error is less than 1%, which proves the accuracy of the model.



**Figure 5.** Comparison of deformation modes and process curves.

**Table 1.** Comparison of crashworthiness indicators.

Indicators	Structure	Test	Reference [46]	This paper	Error (%)
PCF/kN	CS1	29.65	30.14	30.06	-0.27
	CS2	29.58	29.39	29.16	-0.78
SEA/(kJ/kg)	CS1	9.74	9.29	9.22	-0.73
	CS2	9.55	9.35	9.34	-0.13

### 2.5. Comparison between BCS and conventional structures

To explore whether the hierarchical fractal of conch structures has obvious advantages in crashworthiness, simulations were carried out on four thin-walled structures of different masses. The relevant structural parameters of BCS2 are:  $D = 30$  mm,  $Z = 8$ ; The relevant structural parameters of BCS3 are:  $D1 = 10$  mm,  $D2 = 30$  mm,  $Z1 = Z2 = 8$ . The simulation results are shown in Table 2.

The comparison of SEA and CLE of four thin-walled structures (Figures 6 and 7) shows that BCS can absorb more energy and have higher energy absorption efficiency under the same mass conditions compared with other conventional structures. Moreover, with the increase of hierarchy order, the efficiency of BCS<sub>3</sub> is further enhanced than that of BCS<sub>2</sub>, and CLE also shows a similar trend, indicating that BCS<sub>3</sub> has better load stability. Among them, the SEA of BCS<sub>3</sub> ( $m = 0.110$  kg) increased by 30.6 and 22.2% respectively compared with CT and MCT of the same mass, and CLE

increased by 46.8 and 35.3% respectively. Figure 7 shows the deformation modes of the four structures after compression. Obviously, the deformation mode of BCS<sub>3</sub> is more orderly and the number of folded layers is more than that of other structures, which indicates that this structure has a more reasonable geometric layout and a higher material utilization rate. In addition, the growth rate of SEA and CLE gradually decreases with the increase of mass, so simply increasing the mass is not the optimum way to improve the crashworthiness of the structure.

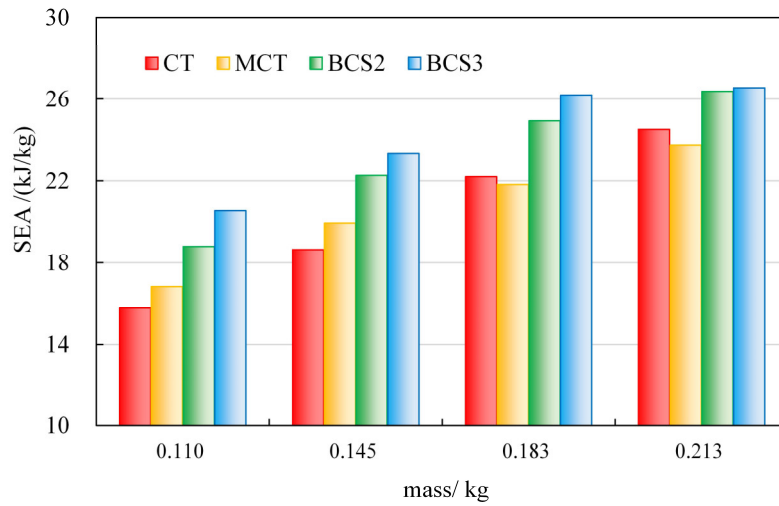
Figure 8 shows the force-displacement curves of the four thin-walled structures ( $m = 0.110$  kg). It can be seen from the figure that the MCF of BCS<sub>3</sub> is significantly higher than that of the other three structures. From this curve, the amplitude of BCS<sub>3</sub> is lower, and the energy absorption is more stable. At the same time, the local magnification shows that the PCF of BCS<sub>3</sub> is also the lowest among the four structures. Therefore, the CLE is higher and the energy absorption efficiency is better. In summary, BCS<sub>3</sub> has two important characteristics of high energy absorption structure.

In addition, it can be seen from Figure 9 (PCF of four thin-walled structures under four groups of the same mass conditions) that although the BCS brings a high absorption effect, it does not bring about a significant increase in PCF, but a certain decrease. The PCF of BCS<sub>3</sub> ( $m = 0.213$  kg) is 18.7 and 9.6% lower than that of CT and MCT of the same mass, respectively.

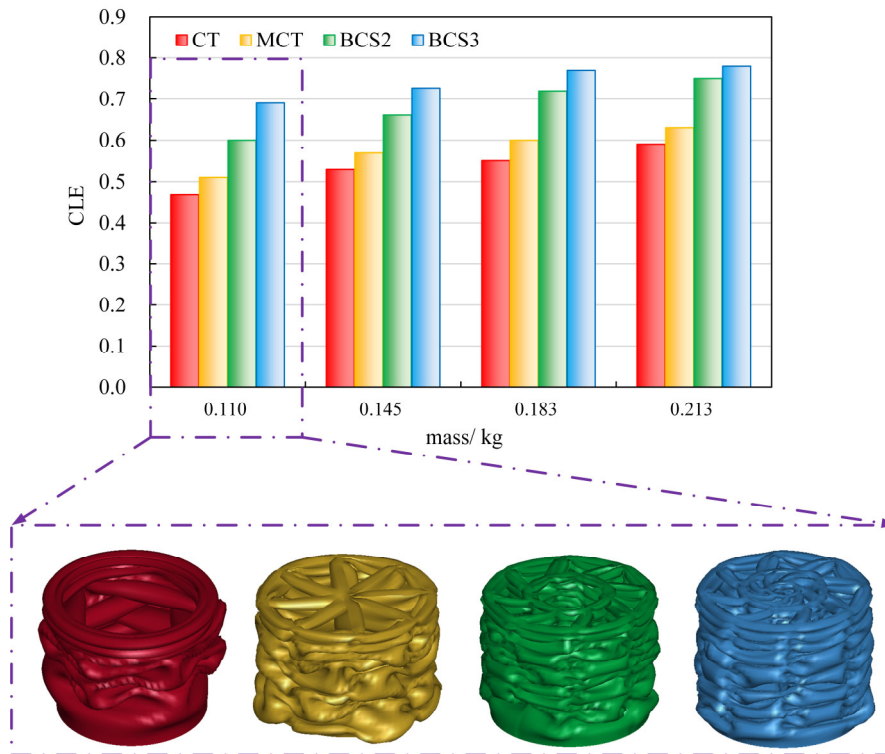
In conclusion, BCS is superior to the conventional thin-walled structures in energy absorption capacity, load stability and peak impact.

**Table 2.** Numerical results of three structures at different masses.

Structure	$m/\text{kg}$	$T/\text{mm}$	EA /kJ	PCF /kN	SEA/(kJ/kg)	CLE
CT	0.110	1.35	1.73	33.31	15.73	0.47
MCT	0.110	0.59	1.85	32.91	16.82	0.51
BCS <sub>2</sub>	0.110	0.60	2.07	31.21	18.82	0.60
BCS <sub>3</sub>	0.110	0.45	2.26	29.89	20.55	0.69
CT	0.145	1.80	2.70	46.45	18.62	0.53
MCT	0.145	0.79	2.89	46.16	19.93	0.57
BCS <sub>2</sub>	0.145	0.80	3.23	44.46	22.28	0.66
BCS <sub>3</sub>	0.145	0.60	3.38	42.33	23.31	0.73
CT	0.183	2.24	4.07	67.45	22.24	0.55
MCT	0.183	0.98	3.99	60.72	21.80	0.60
BCS <sub>2</sub>	0.183	0.99	4.57	58.07	24.97	0.72
BCS <sub>3</sub>	0.183	0.76	4.80	56.67	26.23	0.77
CT	0.213	2.65	5.23	81.05	24.55	0.59
MCT	0.213	1.14	5.06	72.88	23.76	0.63
BCS <sub>2</sub>	0.213	1.15	5.62	68.55	26.38	0.75
BCS <sub>3</sub>	0.213	0.80	5.66	65.91	26.57	0.78

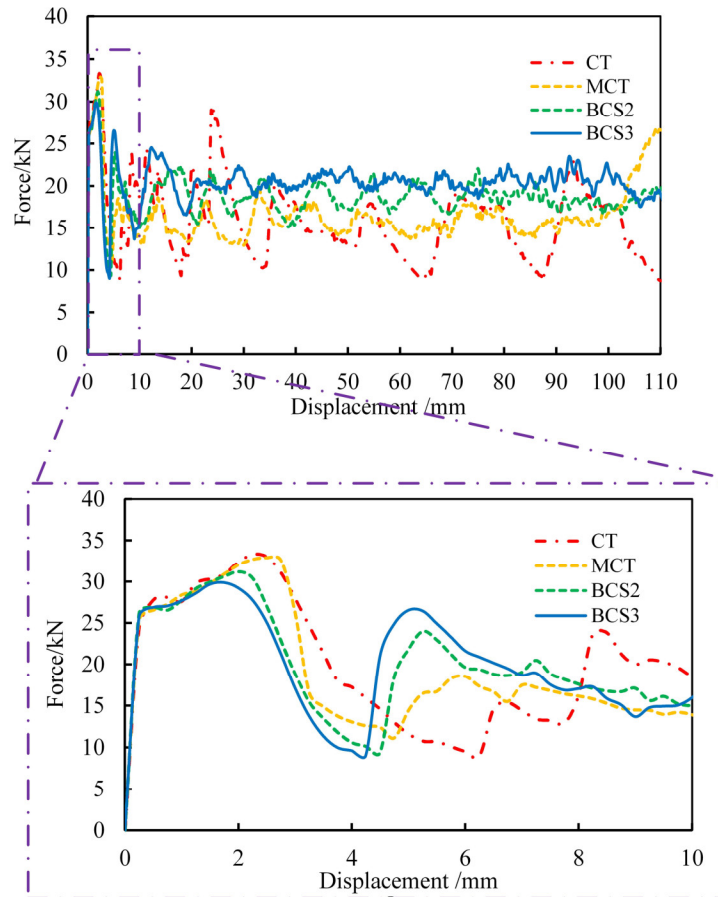


**Figure 6.** SEA of four multi-cell structures.

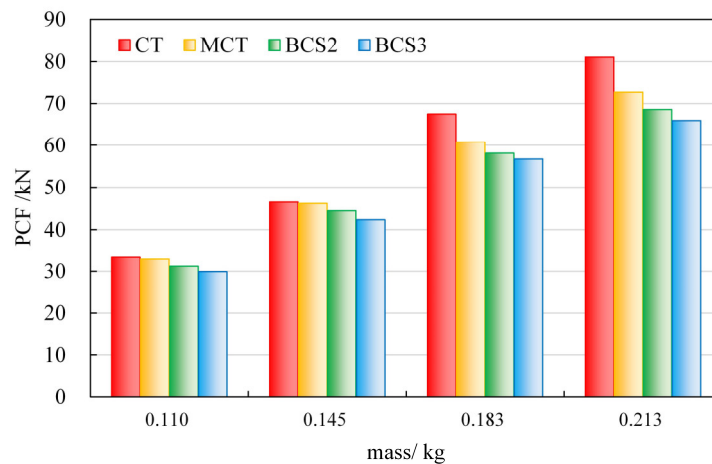


**Figure 7.** CLE of four multi-cell structures.





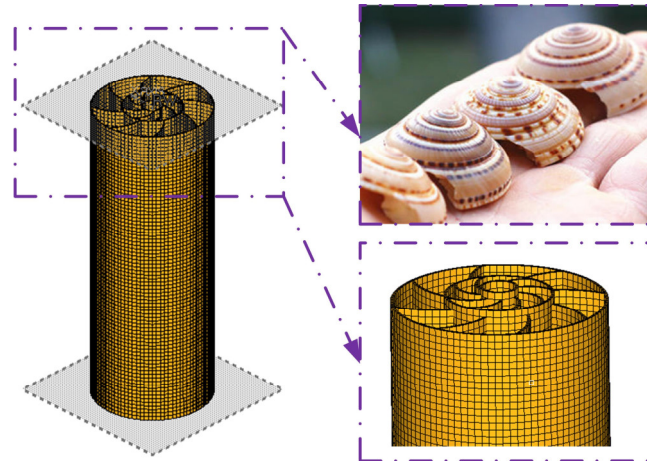
**Figure 8.** Force-displacement curves in the impacting process ( $m = 0.110$  kg).



**Figure 9.** PCF of four multi-cell structures.

Since the conch structures have hierarchical gradients in the axial direction, a bionic conch axial gradient design is established in this paper (the height of the inner ring is 2 mm higher than the secondary outer ring, and the secondary outer ring is 2 mm higher than the outermost ring), as shown in Figure 10. This design can play the role of progressive collapse, effectively reduce the initial peak

force, and further improve the impact efficiency of the structure.



**Figure 10.** Bionic conch axial gradient design.

Table 3 shows the comparison of crashworthiness between BCS<sub>3</sub> initial design and graded gradient design. It can be seen that CLE is increased by 13.04% at most, which proves the effectiveness of the design.

**Table 3.** Comparison of BCS<sub>3</sub> initial design and graded gradient design.

Structure	$m/kg$	$T/mm$	EA/kJ	CLE	CLE increase rate	EA decrease rate
BCS <sub>3</sub>	0.110	0.45	2.26	0.69	-	-
	0.145	0.60	3.38	0.73	-	-
	0.183	0.76	4.80	0.77	-	-
	0.213	0.80	5.66	0.78	-	-
Graded gradient design	0.110	0.45	2.20	0.78	13.04%	2.65%
	0.145	0.60	3.35	0.80	9.59%	0.89%
	0.183	0.76	4.68	0.81	5.19%	2.50%
	0.213	0.80	5.24	0.84	7.69%	7.42%

### 3. Influence of design parameters

From the above summary, it can be concluded that BCS can effectively improve the crashworthiness of the structure, and the energy absorption efficiency is further improved with the increase of the conch hierarchy. Further research shows that the crashworthiness of thin-walled structures is closely related to the geometric topological parameters of the section. The geometric parameters of BCS<sub>3</sub>, including wall thickness  $T$ , inner ring diameter  $D_1$ , middle ring diameter  $D_2$ , the number of inner panels  $Z_1$  and the number of outer panels  $Z_2$ , all have different degrees of influence on its energy absorption characteristics. To improve the energy absorption capacity of the structure as much as possible under the condition of limited mass, this section will analyze the influence of main geometric parameters on crashworthiness.

### 3.1. The influence of $D_1$ and $D_2$

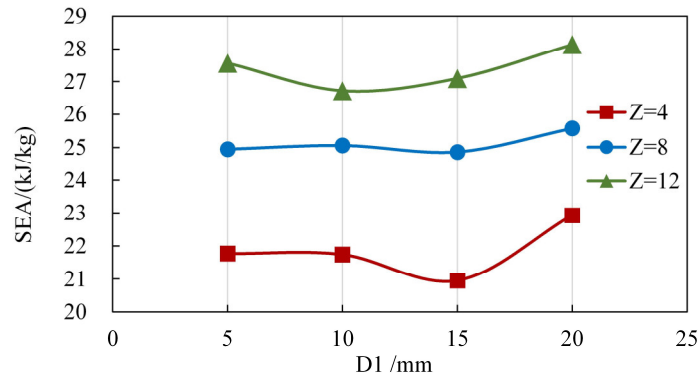
To study the influence of inner ring diameter  $D_1$  and middle ring diameter  $D_2$  on the crashworthiness of BCS, the corresponding simulation analysis was carried out. By changing  $D_1$  and  $D_2$ , the distribution of inner and outer diameters can be adjusted, thereby affecting the folding mode of the structure. Unreasonable structure distribution may lead to structural instability, global buckling, and low material utilization rate, which should be adjusted within a reasonable range.

Firstly, by controlling the variables, set  $D_2$  to 30 mm and the range of  $D_1$  to {5, 10, 15, 20} mm. To exclude the influence of the number of inner and outer panels and wall thickness, three levels of  $Z_1 = Z_2 = Z = \{4, 8, 12\}$  ( $T = 0.8$  mm) were set respectively. Table 4 lists the structural crashworthiness parameters and indicators corresponding to changing  $D_1$ .

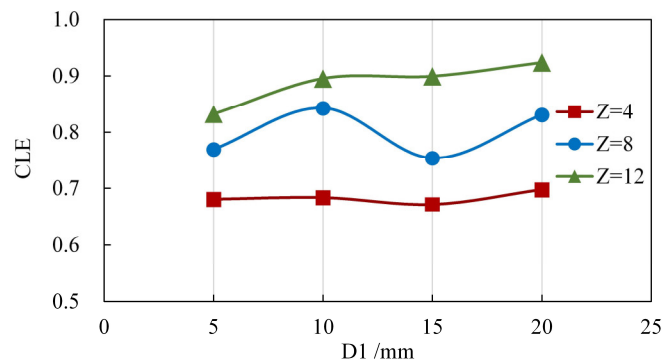
**Table 4.** Influence of  $D_1$  on crashworthiness of BCS.

$D_1$ /mm	$Z_1$	$Z_2$	EA /kJ	PCF /kN	SEA /(kJ/kg)	CLE
5	4	4	3.36	44.83	21.77	0.68
10	4	4	3.43	45.60	21.74	0.68
15	4	4	3.38	45.76	20.96	0.67
20	4	4	3.84	50.08	22.93	0.70
5	8	8	5.18	61.19	24.95	0.77
10	8	8	5.24	56.46	25.06	0.84
15	8	8	5.26	63.44	24.87	0.75
20	8	8	5.57	60.93	25.58	0.83
5	12	12	7.19	78.49	27.56	0.83
10	12	12	7.06	71.65	26.72	0.90
15	12	12	7.08	71.53	27.10	0.90
20	12	12	7.54	74.22	28.13	0.92

It can be seen from Figure 11 that the SEA of BCS increases significantly with the gradual increase of  $Z$ . This is because with the increase of  $Z$ , the number of corner elements of the BCS structure will increase, thus increasing the energy absorption concentration area, and SEA has an obvious growth trend. However, with the increase of  $D_1$ , SEA first decreased and then increased, but the trend was not obvious and fluctuated around  $\pm 1$ (kJ/kg). In addition, Figure 12 shows the change curve of CLE with  $D_1$  and  $Z$ , and the same conclusion can be drawn. With the increase of  $D_1$ , SEA and CLE of BCS showed an upward trend, but it was not obvious.



**Figure 11.** SEA with different D1 and Z.



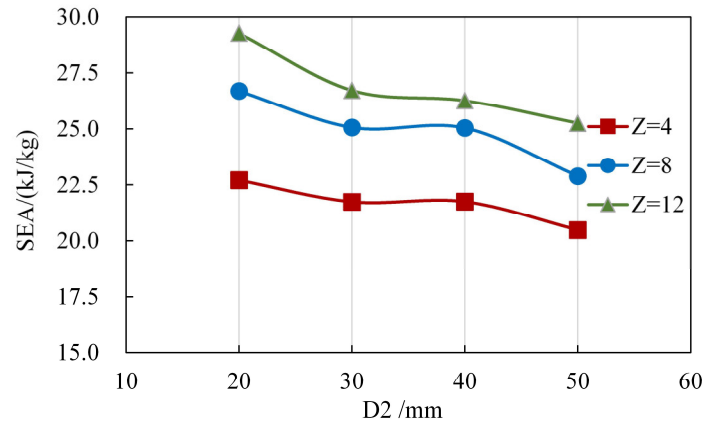
**Figure 12.** CLE with different D1 and Z.

Next, set  $D_1$  to 10mm and the range of  $D_2$  to  $\{20, 30, 40, 50\}$ mm using the same control variables method. To exclude the influence of the number of inner and outer panels and wall thickness,  $Z_1 = Z_2 = Z = \{4, 8, 12\}$  ( $T = 0.8$  mm) were set respectively. Table 5 lists the structural crashworthiness parameters and indicators corresponding to changing  $D_2$ .

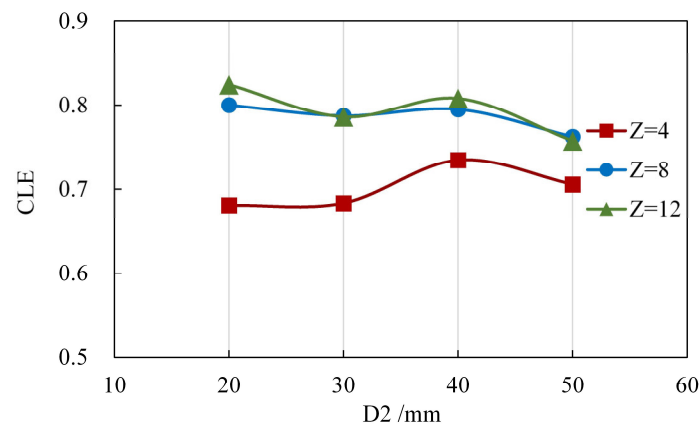
**Table 5.** Influence of  $D_2$  on crashworthiness of BCS.

$D_2$ /mm	$Z_1$	$Z_2$	EA /kJ	PCF /kN	SEA / (kJ/kg)	CLE
20	4	4	3.24	43.26	22.71	0.68
30	4	4	3.43	45.60	21.74	0.68
40	4	4	3.77	46.70	21.75	0.73
50	4	4	3.66	47.12	20.48	0.71
20	8	8	5.06	57.55	26.70	0.80
30	8	8	5.24	60.46	25.06	0.79
40	8	8	5.75	65.81	25.04	0.79
50	8	8	5.25	62.57	22.89	0.76
20	12	12	6.84	75.41	29.27	0.82
30	12	12	7.06	81.65	26.72	0.79
40	12	12	7.51	84.52	26.26	0.81
50	12	12	7.02	84.23	25.25	0.76

It can be seen from Figures 13 and 14 that the SEA of BCS gradually decreases with the increase of  $D_2$ , while CLE did not show the same trend. There was no significant difference between the CLE at  $Z = 8$  and the CLE at  $Z = 12$ , indicating that increasing  $Z$  is not the only factor to improve the load stability of the structure. In addition,  $D_2$  has a greater impact on the crashworthiness of BCS than  $D_1$ , so it can be expected that  $D_2$  will have a greater weight than  $D_1$  in the following structural optimization process.



**Figure 13.** The curve of SEA with  $D_2$  and  $Z$  change.



**Figure 14.** The curve of CLE with  $D_2$  and  $Z$  change.

### 3.2. The influence of $Z_1$ and $Z_2$

It is known that the crashworthiness of thin-walled structures is closely related to the distribution of mechanical materials, and the type and number of geometric corner elements also play an important role in the energy absorption capacity of structures. Changing the number of inner panels  $Z_1$  and the number of outer panels  $Z_2$  can change the morphology of the corner elements and effectively increase the number of corner elements. Therefore, it is of great significance to analyze the parameters of  $Z_1$  and  $Z_2$ .

First of all, to exclude the influence of ring diameters,  $Z_1 \{4, 6, 8, 10, 12\}$  and  $Z_2 \{4, 6, 8, 10, 12\}$

were set respectively on the basis of  $D_1 = 10$  mm and  $D_2 = 30$  mm to explore the influence of  $Z_1$  and  $Z_2$  changes. The corresponding results of crashworthiness indicators are listed in Table 6 ( $T = 0.8$  mm).

Figure 15 shows the changing trends of the SEA of BCS with  $Z_1$  and  $Z_2$ . It can be seen from the figure that as  $Z_1$  increases by one gradient, the SEA of BCS increases by 1.2–7.4% compared with the previous gradient, with an average increase of 4.1%. With the increase of  $Z_2$ , the SEA of BCS increased by -1.6–5.9% compared with the previous gradient under the same  $Z_1$  condition, with an average increase of 1.22%. It can be seen that  $Z_1$  can improve the crashworthiness of BCS more effectively than  $Z_2$ . In addition, when  $Z_1 = Z_2 = 12$ , an obvious inflection point appears in Figure 15. The deformation modes are shown in Figure 16. With the increase of  $Z_2$  ( $Z_2 \leq 10$ ), the folding modes of BCS become more and more regular, and the number of folds increases. When  $Z_2 = 12$ , the folding mode presents irregular buckling compared to  $Z_2 = 10$ . In this deformation mode, the effective folding area and the number of effective folding layers are reduced, so the SEA is significantly decreased.

The change of CLE has the same trend. With the increase of  $Z_1$  and  $Z_2$ , the CLE gradually increased, and with the increase of  $Z_2$ , the increase of BCS was more obvious in the early stage, but the growth in the later stage was relatively gentle.

**Table 6.** The corresponding results of crashworthiness indicators.

$Z_1$	$Z_2$	EA /kJ	PCF /kN	SEA / (kJ/kg)	CLE
4	4	3.43	45.60	21.74	0.68
4	6	4.01	52.22	23.04	0.70
4	8	4.35	54.44	22.81	0.73
4	10	4.88	60.00	23.55	0.74
4	12	5.31	65.40	23.73	0.74
6	4	3.78	49.08	22.68	0.70
6	6	4.28	54.74	23.34	0.74
6	8	4.71	57.56	23.57	0.74
6	10	5.34	64.39	24.70	0.75
6	12	5.68	68.70	24.38	0.75
8	4	4.28	49.84	24.37	0.78
8	6	4.70	56.50	24.44	0.76
8	8	5.24	60.46	25.06	0.84
8	10	5.75	65.74	25.53	0.80
8	12	6.18	71.02	25.55	0.79
10	4	4.69	54.94	25.36	0.78
10	6	5.13	60.98	25.46	0.76
10	8	5.53	63.99	25.36	0.79
10	10	6.09	68.02	25.99	0.81
10	12	6.62	74.83	26.37	0.80
12	4	5.21	56.61	26.88	0.84
12	6	5.69	62.69	27.01	0.82
12	8	6.15	66.00	27.09	0.85
12	10	6.61	70.97	27.15	0.85
12	12	7.06	76.65	26.72	0.84

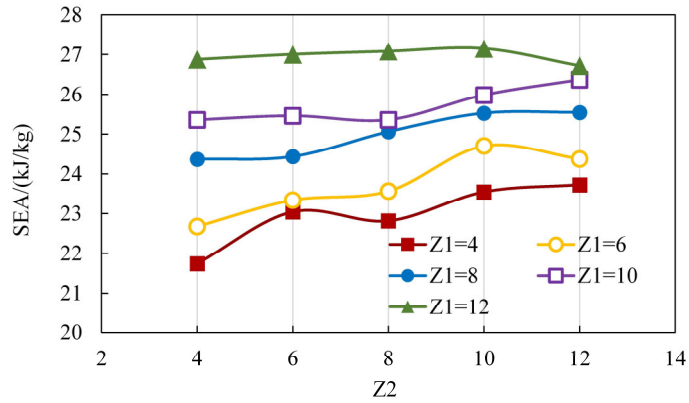


Figure 15. SEA with different  $Z_1$  and  $Z_2$ .

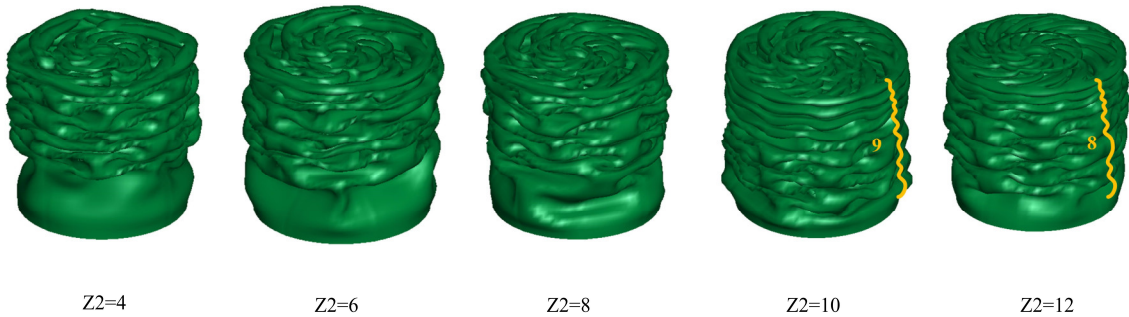


Figure 16. Deformation modes of BCS.

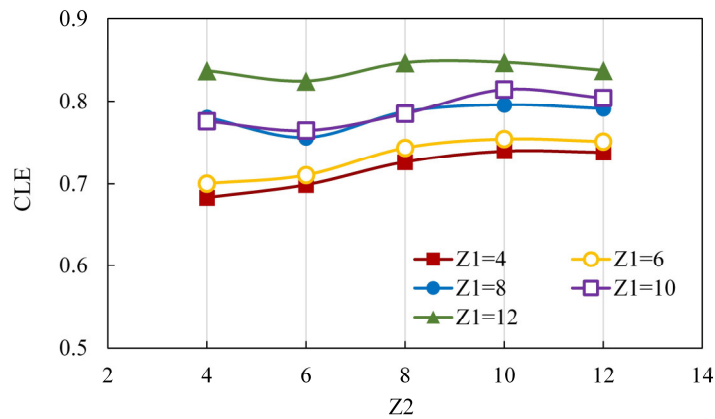


Figure 17. CLE with different  $Z_1$  and  $Z_2$ .

### 3.3. Parameter significance analysis

Based on the studies of a large number of scholars [13–15,18,41,44], it can be clearly concluded that the wall thickness  $T$  can effectively improve the total energy absorption of the structure, but it will increase the PCF of the structure. Therefore, this paper also verifies this conclusion by several groups

of simulations with different  $T$  (Table 7).

**Table 7.** Influence of different  $T$  on energy absorption capacity.

$D_1$ /mm	$D_2$ /mm	$Z_1$	$Z_2$	$T$	PCF /kN	SEA /(kJ/kg)	CLE
10	20	8	8	0.6	41.04	23.12	0.73
10	20	8	8	0.8	57.55	26.70	0.80
10	20	8	8	1	77.45	29.96	0.83
10	30	8	8	0.6	37.84	21.37	0.80
10	30	8	8	0.8	56.46	25.06	0.84
10	30	8	8	1	79.03	27.00	0.81
10	40	8	8	0.6	44.09	21.17	0.75
10	40	8	8	0.8	65.81	25.04	0.79
10	40	8	8	1	89.03	26.58	0.78
10	50	8	8	0.6	43.84	19.91	0.71
10	50	8	8	0.8	62.57	22.89	0.76
10	50	8	8	1	82.63	26.57	0.84

**Table 8.** Results of PCF significance analysis.

PCF	$p$ value	$t$ ratio
$T$	< 0.0001*	23.27
$Z_2$	< 0.0001*	17.06
$Z_1$	< 0.0001*	10.17
$D_2$	< 0.0001*	5.34
$D_2 * Z_1$	0.02425	2.32
$D_1$	0.80903	0.24

**Table 9.** Results of SEA significance analysis.

SEA	$p$ value	$t$ ratio
$T$	< 0.0001*	18.81
$Z_1$	< 0.0001*	18.81
$D_2$	< 0.0001*	-11.36
$Z_2$	< 0.0001*	6.15
$Z_1 * Z_2$	0.00012	-4.17
$D_2 * D_2$	0.00553	2.90
$D_1 * D_1$	0.03324	2.19
$D_2 * Z_1$	0.05482	-1.97
$D_1$	0.86509	-0.17

To further study the influence of five important geometric parameters  $D_1$ ,  $D_2$ ,  $Z_1$ ,  $Z_2$  and  $T$  on the crashworthiness of BCS, the significance parameters of PCF and SEA were analyzed by stepwise regression. Step regression is based on the principle of least square method. From one independent variable to all independent variables, each step analyzes whether the model is improved, so as to explore independent variables with significant contributions. After deleting the interaction parameters



with less influence, the analysis results are shown in Tables 8 and 9.

When the probability value  $p < 0.05$ , it indicates that the parameter has a significant effect on PCF and SEA. The absolute value of  $t$  ratio can be used to compare the significance of parameters. Therefore, the order of influence of geometric parameters on PCF is  $T > Z_2 > Z_1 > D_2 \gg D_1$ . The  $p$  value of  $D_1 > 0.05$  indicates that  $D_1$  has no significant effect on PCF. For SEA, the order is as follows:  $Z_1 \approx T > D_2 > Z_2 \gg D_1$ . The effect of  $D_1$  on SEA is also not significant.

Based on the validation of the parameter study and significance analysis, the following conclusions can be drawn:

- 1) With the increase of each geometric parameter, the PCF of BCS gradually increases. The order of influence degree of geometric parameters is:  $T > Z_2 > Z_1 > D_2 \gg D_1$ .
- 2) The SEA of BCS gradually increases with the increase of other geometric parameters except  $D_2$ . Therefore, reducing  $D_2$  can effectively improve SEA ( $t$  ratio = -11.36) and decrease PCF ( $t$  ratio = 5.34). The order of influence degree of geometric parameters is:  $T \approx Z_1 > D_2 > Z_2 \gg D_1$ .
- 3)  $D_1$  has no significant effect on SEA ( $t$  ratio = -0.17) and PCF ( $t$  ratio = 0.24), which can be ignored and fixed at 10 mm in the subsequent optimization analysis.
- 4) Increasing  $Z_2$  can increase SEA ( $t$  ratio = 6.15), but PCF ( $t$  ratio = 17.06) also increases significantly. Therefore, increasing  $Z_2$  cannot effectively improve the energy absorption efficiency of BCS.

#### 4. Multi-objective crashworthiness optimization

As an important energy-absorbing component of the front bumper, BCS aims to absorb as much energy as possible per unit mass. At the same time, the PCF of the structure is also a key indicator of vehicle safety. It is generally required to be limited within a safe range to reduce the impact acceleration and ensure the safety of passengers. Therefore, this section will further optimize the geometric parameter configuration of BCS through a multi-objective optimization design.

According to the conclusion of the previous section, the influence of  $D_1$  is negligible and is set to 10 mm. The minimum value of  $D_2$  is set to 15mm to ensure manufacturability. Therefore, the multi-objective optimization model expression of BCS can be described as:

$$\left\{ \begin{array}{l} \text{Min}\{-\text{SEA}(T, D_2, Z_1, Z_2), \text{PCF}(T, D_2, Z_1, Z_2)\} \\ \text{s. t. } \quad 0.6\text{mm} \leq T \leq 1.2 \text{ mm} \\ \quad \quad 15\text{mm} \leq D_2 \leq 55 \text{ mm} \\ \quad \quad 4 \leq Z_1 \leq 12 \\ \quad \quad 4 \leq Z_2 \leq 12 \end{array} \right. \quad (5)$$

##### 4.1. Approximation model

Establishing a high precision approximate model is an effective means for optimal design. According to the collected data, by fitting different approximate models, the relationship surface between variables and responses can be derived, which can effectively reduce the number of experiments and improve the optimization efficiency. There are many kinds of approximation models, such as: RSM (Response Surface Method) [47], RBF (Radial Basis Function) [48] and KRG (Kriging approximation model) [49]. Different approximation models have their own advantages and disadvantages. Therefore, this paper establishes RSM, KRG and RBF approximation models respectively, and verifies their respective accuracy.

The advantage of RSM model is that it can fit a small number of data results with algebraic formulas, and the calculation is simple and efficient. It has good robustness, strong practicability and wide application range. The mathematical expression of the third-order RSM model is as follows:

$$\begin{aligned} \tilde{y} = & \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \cdots + \beta_M x_M \\ & + \beta_{M+1} x_1^2 + \beta_{M+2} x_2^2 + \cdots + \beta_{2M} x_{2M}^2 \\ & + \beta_{2M+1} x_1^3 + \beta_{2M+2} x_2^3 + \cdots + \beta_{3M} x_{3M}^3 \\ & + \sum_{i \neq j} \beta_{ij} x_i x_j \end{aligned} \quad (6)$$

The minimum number of sample points to be input by the model is:  $(M + 1)(M + 2) / 2 + M$ , where  $M$  is the number of independent variables.

KRG model is an unbiased optimal estimation method of interval variables using spatial local interpolation. Its mathematical expression is as follows:

$$\tilde{y}(x_0) = \sum_{i=1}^N \lambda_i y(x_i) \quad (7)$$

where  $x_0$  represents the point to be estimated,  $x_i$  represents the  $i$ -th observation point around  $x_0$ , and  $y(x_i)$  represents the corresponding observation value.  $\lambda_i$  represents the undetermined weighting coefficient of the corresponding observed value.

The advantage of RBF model is that it has strong nonlinear function fitting ability and strong generalization ability. Occasional noise points have little influence on the whole approximate model. Its mathematical expression is as follows:

$$\hat{f}(x) = \sum_{i=1}^N \varphi_i \phi[r(x_i, x)] \quad (8)$$

where  $x_i$  represents the vector of design variables at the  $i$ -th design point.  $\varphi_i$  is the linear combination coefficient of  $m$  neurons.  $\phi$  can be represented as:

$$\phi[r(x_i, x)] = \sqrt{\|x_i - x\|^2 + c^2} \quad (9)$$

where  $\|x_i - x\|$  is the Euclidean distance and  $c$  is taken as 1 in this paper.

To evaluate the accuracy of different approximate models, three kinds of approximate models can be evaluated by  $R^2$  and RMSE (Root Mean Square Error). Where  $R^2$  is expressed as:

$$R^2 = \frac{\sum_{i=1}^N (f_i - \bar{f})^2 - \sum_{i=1}^N (f_i - f'_i)^2}{\sum_{i=1}^N (f_i - \bar{f})^2} \quad (10)$$

where  $f_i$  and  $f'_i$  represent the sample data and the approximate data corresponding to point  $i$  respectively,  $\bar{f}$  represents the mean value of the sample data, and  $N$  represents the number of sample points. The closer  $R^2$  is to 1, the more accurate the response surface.

The expression of RMSE is:

$$\text{RMSE} = \sqrt{\frac{\sum_{i=1}^N (f_i - f'_i)^2}{N}} \quad (11)$$

The RMSE result values less than 0.2 are considered acceptable accuracy. Therefore, according to the simulation data, RSM, RBF and KRG response surfaces were established respectively, and  $R^2$  and RMSE corresponding to the three approximation models are listed in Table 10.

According to the data,  $R^2$  of the third-order RSM is closer to 1, and RMSE is closer to 0, so the accuracy order of approximation models is  $RSM > RBF > KRG$ . In addition, the accuracy of RSM was verified by 10 random samplings, as shown in Table 11. The errors were all less than 10%, and the accuracy was acceptable.

**Table 10.** Accuracy comparison.

		RSM	KRG	RBF
PCF	$R^2$	0.968	0.930	0.933
	RMSE	0.061	0.083	0.081
SEA	$R^2$	0.976	0.874	0.935
	RMSE	0.052	0.099	0.073

**Table 11.** Accuracy analysis.

$D_1$	$D_2$	$Z_1$	$Z_2$	$T$	SEA-RSM	SEA-initial	error-SEA	PCF-RSM	PCF-initial	error-PCF
10	30	4	12	0.8	24.10	23.73	1.56%	67.38	65.40	3.03%
10	30	10	10	0.8	26.13	25.99	0.54%	67.28	68.02	-1.09%
10	40	8	8	0.6	21.14	21.17	-0.14%	45.88	44.09	4.06%
10	30	8	8	0.6	21.35	21.37	-0.09%	41.36	37.84	9.30%
10	50	4	4	0.8	20.78	20.48	1.46%	44.18	47.12	-6.24%
10	30	8	4	0.8	24.01	24.37	-1.48%	51.14	49.84	2.61%
10	30	4	4	0.8	21.59	21.74	-0.69%	45.12	45.60	-1.05%
10	40	8	8	0.8	24.54	25.04	-2.00%	65.78	65.81	-0.05%
10	30	12	4	0.8	26.65	26.88	-0.86%	58.07	56.61	2.58%
10	30	10	8	0.8	26.01	25.36	2.56%	63.01	63.99	-1.53%

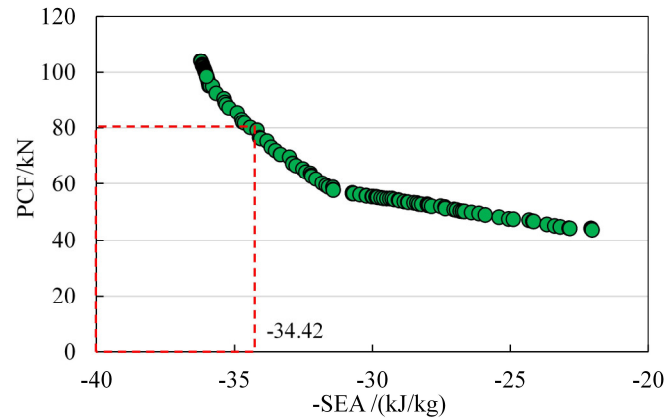
#### 4.2. Results and discussion of multi-objective optimization

After obtaining an accurate and reliable approximation model, the second step is to optimize and discussion based on RSM. Multi-objective particle swarm optimization (MOPSO) was used to obtain the corresponding optimization results.

MOPSO is a population intelligence algorithm, which is designed by simulating the predatory behavior of birds. The process of finding the optimal design point is much like the foraging activity of these creatures. PSO is a population-based search process, in which individuals (called particles) continuously change positions (called states) within the search area. In other words, the birds communicate their location throughout the search process to let other birds know where the food comes from. Eventually, the whole bird flock can gather around the food source, which is what we call the optimal solution, and the problem converges.

Figure 18 shows the Pareto diagram of SEA and PCF. According to the safety requirements, the PCF value was limited to 80 kN to obtain the optimum configuration after BCS optimization ( $D_1 = 10$

mm,  $D_2 = 15$  mm,  $Z_1 = 12$ ,  $Z_2 = 4$ ,  $T = 1.03$  mm). As shown in Table 12, the finite element analysis was carried out based on the corresponding optimization results and compared with the optimization results. The results show that the error between the predicted and actual values of the optimum structural PCF and SEA obtained by the RSM approximation model is less than 5%, with high accuracy and acceptability.



**Figure 18.** Pareto diagram.

**Table 12.** Error comparison between optimized predicted value and simulated actual value.

Indicator	Actual	Predict	Error
SEA/(kJ/kg)	33.60	34.42	-2.38%
PCF/kN	79.12	80.13	-1.26%

## 5. Conclusions

In this paper, a series of novel bionic conch structures (BCS) are proposed to find a more excellent crashworthiness design scheme in this study. The comparative analysis of crashworthiness, the study of parameter effects, and the multi-objective optimization design have been carried out successively. The following conclusions can be drawn:

- 1) By comparing and analyzing the energy absorption characteristics of bionic conch structures, conventional single-cell tubes, and multi-cell tubes under axial loading, the results show that the bionic conch structures have higher energy absorption efficiency than the other two structures with the same mass. Among them, the SEA of BCS<sub>3</sub> ( $m = 0.110$  kg) is increased by 30.6 and 22.2% compared with CT and MCT of the same mass, and CLE is increased by 46.8 and 35.3%. The PCF of BCS<sub>3</sub> ( $m = 0.213$  kg) is 18.7 and 9.6% lower than that of CT and MCT of the same mass, respectively.
- 2) Through parameter design and factor significance analysis, the contribution of key parameters of BCS (wall thickness, inner and outer ring diameter, number of inner and outer panels) to crashworthiness was analyzed. The results show that the order of influence of geometric parameters on PCF is  $T > Z_2 > Z_1 > D_2 \gg D_1$ ; The order of influence on SEA is  $Z_1 > T > D_2 > Z_2 \gg D_1$ .
- 3) Through the multi-objective optimization design, the approximation models (RSM, KRG, and RBF) and the multi-objective particle swarm optimization method were combined to find the optimum geometric configuration, and further optimize the crashworthiness of BCS to obtain the optimum

configuration ( $D_1 = 10$  mm,  $D_2 = 15$  mm,  $Z_1 = 12$ ,  $Z_2 = 4$ ,  $T = 1.03$  mm).

The research results of this paper have positive significance for the development of new lightweight thin-walled energy-absorbing structures.

## Acknowledgments

This work was supported by the Natural Science Foundation of Fujian Province (Grant No. 2021J011168), the Education Research Project for Young and Middle-aged Teachers of Fujian Province (Grant No. JAT200688), the Research Project for Young and Middle-aged Teachers of Ningde Normal University (Grant No. 2022ZQ109 and Grant No. 2022ZQ102) and the Collaborative Innovation Center of Ningde Normal University (Grant No. 2022ZX02).

## Conflict of interest

The authors declare there is no conflict of interest.

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