# THE JACOBI SPECTRAL COLLOCATION METHOD FOR FRACTIONAL INTEGRO-DIFFERENTIAL EQUATIONS WITH NON-SMOOTH SOLUTIONS

### Yin Yang\*

Hunan Key Laboratory for Computation and Simulation in Science and Engineering Key Laboratory of Intelligent Computing & Information Processing of Ministry of Education School of Mathematics and Computational Science, Xiangtan University Xiangtan, MO 411105, China

Sujuan Kang

Xiangtan University Xiangtan, MO 411105, China

### VASILIY I. VASIL'EV

Ammosov North-Eastern Federal University Yakutsk, MO 677000 , Russia

ABSTRACT. In recent years, many numerical methods have been extended to fractional integro-differential equations. But most of them ignore an important problem. Even if the input function is smooth, the solutions of these equations would exhibit some weak singularity, which leads to non-smooth solutions, and a deteriorate order of convergence. To overcome this problem, we first study in detail the singularity of the fractional integro-differential equation, and then eliminate the singularity by introducing some smoothing transformation. We can maximize the convergence rate by adjusting the parameters in the auxiliary transformation. We use the Jacobi spectral-collocation method with global and high precision characteristics to solve the transformed equation. A comprehensive and rigorous error estimation under the  $L^{\infty}$ - and  $L^2_{\omega^{\alpha,\beta}}$ -norms is derived. Finally, we give specific numerical examples to show the accuracy of the theoretical estimation and the feasibility and effectiveness of the proposed method.

1. Introduction. With more attention to integro-differential equations, the numerical calculation of fractional integro-differential equations has been also paid more attention by many scholars. Fractional integro-differential equations have a profound physical background and a rich connotation. For various phenomena in damping laws, diffusion process[31], earthquake model[13], fluid-dynamic traffic

<sup>2020</sup> Mathematics Subject Classification. 34A12, 74S25, 65L60, 65L70, 33C45.

Key words and phrases. The fractional integro-differential equation, non-smooth solution, smoothing transformation, spectral collocation method, convergence analysis.

Yin Yang was supported by National Natural Science Foundation of China Project (11671342, 11931003) and Project of Scientific Research Fund of Hunan Provincial Science and Technology Department (2020JJ2027); Sujuan Kang was supported by National Natural Science Foundation of China Project (11771369) and Key Project of Hunan Provincial Department of Education (17A210); Vasilev Vasilii Ivanovich was supported by Project of Scientific Research Fund of Hunan Provincial Science and Technology Department (2018WK4006, 2019YZ3003).

<sup>\*</sup> Corresponding author: Yin Yang.

model[14], mathematical physics and engineering[28, 37], chemistry, acoustics, fluid and continuum mechanics[8], psychology[1, 35] and other fields, fractional integrodifferential equations are suitable models.

In recent years, several numerical methods were proposed to solve the fractional integro-differential equation. The most common methods are the Adomian decomposition method [25], collocation method [33] and fractional differential transform method [2]. In [16], Huang proposed a method for solving linear fractional integro-differential equations by Taylor's expansion, including Fredholm type and Volterra type. Yang et al. [34] used the Laplace decomposition method to solve the fractional integro-differential equation. M. Jani et al. [17] proposed a numerical method for solving fractional integro-differential equations with nonlocal boundary conditions by using Bernstein polynomials.

The fractional differential operators are nonlocal and have weakly singular kernels. The fractional differential equations are more complicated than the integerorder counterparts. In recent years, many numerical methods have been extended to fractional integro-differential equations. Most of the analyses have some unreasonable limitations on solutions in order to achieve high accuracy. When these equations are transformed into the equivalent Volterra integral equations of the second kind with a weakly singular kernel, even if the input function is smooth, the solution of the equation usually exhibits a weak singularity at z = 0. Which leads to a non-smooth solution and a lower order of convergence.

So far, in order to solve the fractional differential equations and fractional integrodifferential equations with non-smooth solutions, several methods have been proposed. One method is to approximate the fractional derivative operators in the governing differential equation directly and then the corresponding collocation schemes are derived [3, 18]. Another method is to rewrite the governing differential equation in an equivalent integral equation, solved by the corresponding collocation method [22, 36, 21]. The integral collocation method is more stable than the differential collocation method. The reason is that numerical differentiation is sensitive to small perturbations in the input. But numerical integration is essentially stable [10]. Therefore, when using the differential collocation method to solve differential equations, we need to employ efficient integration preprocessing to overcome the illconditioning problem. It is necessary with increasing of the number of collocation nodes [15]. We would like to note that Hao proposed an efficient finite difference algorithm to solve fractional boundary value problems with non-smooth solutions in [12].

For many types of equations with non-smooth solutions, the idea of introducing suitable transformations has been considered. It would eliminate the singularity in the transformed equation, and lead to a high convergence order. For the second kind of Volterra integral equation, Chen and Tang [9] proposed a variable transformation to eliminate the singularity of the solution. With a strict error analysis, the method is shown to have a spectral convergence. Pedas [19] made a proper transformation, and used the piecewise polynomial collocation method to solve the resulting equation on a mildly graded grid or a uniform grid. Baratella and Orsi [7] used a variable transformation to turn the solution of the linear Volterra integral equation of the second kind smooth, and solved it by the standard product integration method. Tang [20] used a variable transformation and the Jacobi spectral collocation method to solve the Abel-Volterra integral equation of the second kind. For the linear Fredholm integral equation of the second kind, Monegato and Scuderi [26] proposed a non-linear transformation to eliminate the singularity of the equation. Ghoreishi [11] used a variable transformation and a spectral method to solve the multi-order fractional differential equation. Pedas et al. [27] regularized the solution of fractional initial and boundary value problems by a suitable smoothing transformation. They solved the transformed equation by a piecewise polynomial collocation method on a mildly graded grid and on a uniform grid. Zaky [38] used a smoothing transformation and the Jacobi spectral collocation method to solve the rational-order fractional terminal value problems with non-smooth solutions.

Based on the above works, we apply the smoothing transformation and the Jacobi spectral collocation method with high accuracy and global characteristics to the following fractional integro-differential equations.

$$D_z^{\alpha} \tilde{y}(z) = \tilde{y}(z) + \int_0^z \tilde{K}(z,\tau) \tilde{y}(\tau) d\tau + \tilde{g}(z), \quad z \in I = [0,T],$$
  
$$\tilde{y}(0) = \lambda, \tag{1}$$

where  $\tilde{g}(z)$  is the source function, and  $\tilde{K}(z,\tau)$  is the kernel function. The given function  $\tilde{g}(z)$  and  $\tilde{K}(z,\tau)$  are continuous on their respective domains  $0 \leq \tau \leq z \leq T$  and  $\Delta_T := \{(z,\tau) \in \mathbb{R}^2 : 0 \leq \tau \leq z \leq T\}, \lambda \in \mathbb{R}$ .  $D_z^{\alpha}$  is the Caputo fractional derivative of rational-order  $\alpha, 0 < \alpha < 1$ .

Let  $\Gamma(\cdot)$  denote the Gamma function. For any positive integer n with  $n-1 < \alpha < n$ , the Caputo derivative is defined as follows:

$$D_z^{\alpha}f(z) = \frac{1}{\Gamma(n-\alpha)} \int_a^z (z-\tau)^{n-\alpha-1} f^{(n)}(\tau) d\tau, \quad z \in [a,b].$$

In addition, the Riemann-Liouville fractional integral  $I_z^{\alpha}$  of order  $\alpha$  is defined by

$$I_z^{\alpha}f(z) = \frac{1}{\Gamma(\alpha)} \int_a^z (z-\tau)^{\alpha-1} f(\tau) d\tau, \quad z \in [a,b].$$

We note that,

$$I_{z}^{\alpha}(D_{z}^{\alpha}f(z)) = f(z) - \sum_{k=0}^{n-1} f^{(k)}(a) \frac{z^{k}}{k!}.$$
(2)

The layout of this paper as follows: In Section 2, we introduce the basic properties of Jacobi polynomials and Jacobi-Gauss interpolation. The fractional integral differential equation is transformed into an equivalent integral equation, in Section 3. A smoothing transformation of variable is defined for the new equation so that the solution is smooth, in Section 3. The Jacobi spectral-collocation method is defined in Section 4. The convergence analysis of the collocation method is derived in Section 5. In Section 6, we give several numerical examples verifying the accuracy of the theoretical estimation and the feasibility and effectiveness of the method. Finally, some concluding remarks are drawn in Section 7.

2. Some properties of Jacobi polynomials. In this section, we introduce some basic properties about Jacobi polynomials and Jacobi-Gauss interpolation that are related to spectral-collocation methods [30].

The Jacobi polynomials, denoted by  $\mathcal{P}_n^{\alpha,\beta}(x)$ , are orthogonal with the Jacobi weight function  $\omega^{\alpha,\beta}(x) = (1-x)^{\alpha}(1+x)^{\beta}$  over  $\Lambda = (-1,1)$ , namely,

$$\left(\mathcal{P}_{i}^{\alpha,\beta}(x),\mathcal{P}_{j}^{\alpha,\beta}(x)\right)_{\omega^{\alpha,\beta}} = \int_{-1}^{1} \mathcal{P}_{i}^{\alpha,\beta}(x)\mathcal{P}_{j}^{\alpha,\beta}(x)\omega^{\alpha,\beta}(x)dx = \gamma_{i}^{\alpha,\beta}\delta_{i,j},\tag{3}$$

where  $\delta_{i,j}$  is the Kronecker function and

$$\gamma_i^{\alpha,\beta} = \frac{(2)^{\alpha+\beta+1}\Gamma\left(i+\alpha+1\right)\Gamma\left(i+\beta+1\right)}{(2i+\alpha+\beta+1)\Gamma\left(i+1\right)\Gamma\left(i+\alpha+\beta+1\right)}.$$
(4)

For a given positive integer  $N \ge 0$ , let  $\mathcal{P}_N$  denote the space of all polynomials of degree not exceeding N. We denote by  $\{x_i^{\alpha,\beta}, \varpi_i^{\alpha,\beta}\}_{i=0}^N$  the set of quadrature nodes and weights of the Jacobi-Gauss integration. The Jacobi-Gauss integration formula has the form

$$\int_{\Lambda} \varphi(x) \omega^{\alpha,\beta}(x) dx \approx \sum_{i=0}^{N} \varphi(x_i) \overline{\omega}_i^{\alpha,\beta}.$$
(5)

The above quadrature formula (5) is exact for any  $\varphi(x) \in \mathcal{P}_{2N+1}$ . Hence, by (3),

$$\sum_{k=0}^{N} J_{i}^{\alpha,\beta}(x_{k}^{\alpha,\beta}) J_{j}^{\alpha,\beta}(x_{k}^{\alpha,\beta}) \overline{\omega}_{k}^{\alpha,\beta} = \gamma_{i}^{\alpha,\beta} \delta_{i,j}, \quad \forall \ 0 \le i+j \le 2N+1.$$
(6)

For any  $\mu \in C(\Lambda)$ , the Jacobi-Gauss interpolation operator  $I_{x,N}^{\alpha,\beta}: C(\Lambda) \to \mathcal{P}_N$  is determined uniquely by

$$I_{x,N}^{\alpha,\beta}\mu(x_j^{\alpha,\beta}) = \mu(x_j^{\alpha,\beta}), \quad 0 \le j \le N.$$
(7)

The interpolation condition (7) implies that  $I_{x,N}^{\alpha,\beta}\mu = \mu$  for all  $\mu \in \mathcal{P}_N$ . On the other hand, since  $I_{x,N}^{\alpha,\beta}\mu \in \mathcal{P}_N$ , we can write

$$I_{x,N}^{\alpha,\beta}\mu(x) = \sum_{i=0}^{N} \hat{\mu}_i^{\alpha,\beta} J_i^{\alpha,\beta}(x), \quad \hat{\mu}_i^{\alpha,\beta} = \frac{1}{\gamma_i^{\alpha,\beta}} \sum_{j=0}^{N} \mu(x_j) J_i^{\alpha,\beta}(x_j) \varpi_j^{\alpha,\beta}.$$
 (8)

In particular, for  $\beta = 0$ , the set of Jacobi polynomials is reduced to  $J_i^{\alpha}(x)$ . Therefore, we can also write  $x_j^{\alpha} = x_j^{\alpha,0}, \, \varpi_j^{\alpha} = \varpi_j^{\alpha,0}$  and  $I_{x,N}^{\alpha} = I_{x,N}^{\alpha,0}$ .

3. Setting the problem. In this section, we use the definition and related properties of Riemann-Liouville fractional integral and Caputo fractional derivative to transform the original fractional equation with initial conditions into the second kind of Volterra integral equation with weak singular kernel. We show the equation has a non-smooth solution. Then we apply the smoothing transformation to eliminate the singularity of the solution at the left endpoint.

First, we use (2) to transform the original equation (1) into an equivalent Volterra integral equation with weak singular kernel.

$$\begin{split} \tilde{y}(z) &= \lambda + \frac{1}{\Gamma(\alpha)} \int_0^z (z-s)^{\alpha-1} (\tilde{y}(s) + \tilde{g}(s)) ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_0^z (z-s)^{\alpha-1} \int_0^s \tilde{K}(s,\tau) \tilde{y}(\tau) d\tau ds \end{split}$$

Using Dirichlet's formula

$$\int_0^z \int_0^s \phi(s,\tau) d\tau ds = \int_0^z \int_\tau^z \phi(s,\tau) ds d\tau,$$

we derive

$$\tilde{y}(z) = \lambda + \frac{1}{\Gamma(\alpha)} \int_0^z (z-s)^{\alpha-1} \tilde{g}(s) ds + \frac{1}{\Gamma(\alpha)} \int_0^z \left( (z-s)^{\alpha-1} + \int_s^z (z-\tau)^{\alpha-1} \tilde{K}(\tau,s) d\tau \right) \tilde{y}(s) ds.$$
(9)

The equation (9) is transformed into the following Volterra integral equation of the second kind by the linear transformation  $w = \frac{\tau - s}{z - s}$ ,  $w \in [0, 1]$ ,

$$\tilde{y}(z) = f(z) + \int_0^z (z-s)^{\alpha-1} K(w(z-s)+s,s)\tilde{y}(s)ds,$$
(10)

where

$$\begin{split} f(z) &= \lambda + \frac{1}{\Gamma(\alpha)} \int_0^z (z-s)^{\alpha-1} \tilde{g}(s) ds, \\ K(w(z-s)+s,s) &= \frac{1}{\Gamma(\alpha)} \Big( 1 + \int_0^1 (z-s)(1-w)^{\alpha-1} \tilde{K}(w(z-s)+s,s) dw \Big). \end{split}$$

**Lemma 3.1.** The kernel function K(w(z - s) + s, s) in (10) is continuous and bounded.

Proof. We have

$$\begin{split} & K(w(z-s)+s,s) \\ &= \frac{1}{\Gamma(\alpha)} \Big( 1 + \int_0^1 (z-s)(1-w)^{\alpha-1} \tilde{K}(w(z-s)+s,s) dw \Big) \\ &= \frac{1}{\Gamma(\alpha)} \Big( 1 + \int_0^1 (z-s)(1-w)^{\alpha-1} w^0 \tilde{K}(w(z-s)+s,s) dw \Big) \end{split}$$

For  $z \in [0, T]$  and  $s \in [0, z]$ ,  $z - s \in [-z, T]$ . It is known that  $\tilde{K}(w(z - s) + s, s)$  is bounded and continuous on  $\Delta_T$ . Let  $\tilde{K}(w(z - s) + s, s)$  have the maximum and minimum values on  $\Delta_T$ ,  $\mathcal{Q}_{max}$  and  $\mathcal{Q}_{min}$ , respectively. There is

$$\frac{1}{\Gamma(\alpha)} \left( 1 - z \mathcal{Q}_{min} B(1, \alpha) \right) \leq K(w(z - s) + s, s) \\ \leq \frac{1}{\Gamma(\alpha)} \left( 1 + T \mathcal{Q}_{max} B(1, \alpha) \right),$$

where  $B(\cdot, \cdot)$  is the  $\beta$  function:  $B(\xi, \eta) = \int_0^1 s^{\xi-1} (1-s)^{\eta-1} d\xi$ . The lemma is proved.

We give some lemmas on smoothness of solution of the general Volterra integral equation of the second kind.

**Lemma 3.2.** [23] Consider the following general Volterra integral equation of the second kind:

$$y(z) = f(z) + \frac{1}{\Gamma(\gamma)} \int_0^z (z-s)^{\gamma} K(z,s,y(s)) ds, \quad z \in I = [0,T],$$
(11)

where  $\gamma > -1$ ,  $f: I \to \mathbb{R}^n$  is a continuous bounded function,  $K: S \times \mathbb{R}^n \to \mathbb{R}^n$  is a continuous bounded function, and  $\{S = (z, s) : 0 \le s \le z \le T\}$ .

1. If f(z) and K(z, s, y(s)) are differentiable, the integral equation has a unique solution y(z) that is also differentiable on (0,T];

2. If  $f(z) = F(z, z^{1+\gamma})$ ,  $F(z_1, z_2)$  and K(z, s, y(s)) are differentiable, the integral equation has a unique solution y(z) that satisfies

$$y(z) = Y(z, z^{1+\gamma}),$$

where  $Y(z_1, z_2)$  is differentiable at (0, 0).

We note that the solution of equation (14) is not smooth at z = 0 in general.

It can be obtained from the above lemma that the Eq.(10) has a unique solution y(z), which is differentiable on  $z \in (0, T]$  and is not necessarily smooth at z = 0. For  $0 < 1 - \alpha < 1$ , the equation has a singular term  $(z - s)^{\alpha - 1}$ . By the literature [5], for any positive integer m, if  $K(\tau(w(z - s)), s)$  and f(z) are continuous differentiable functions of order m in the corresponding area, there exists a function Y = Y(z, v) possessing continuous derivatives of order m, such that the solution of the Eq.(10) can be written as  $y(z) = Y(z, z^{\alpha})$ . This indicates that when  $z \to 0$ ,  $y^{(m)}(z) \sim z^{\alpha - m}$ , and thus  $y(z) \notin C^m[0, T]$ .

**Lemma 3.3.** [4] Let  $0 < \alpha < 1$ . We assume that  $f \in C^m(I)$ ,  $K \in C^m(D)$  for some  $m \ge 0$ .

1. If m = 0, the Volterra integral equation,

$$y(z) = f(z) + \int_0^z (z-s)^{-\mu} K(z,s) y(s) ds, \quad 1 > \mu > 0, z \in I,$$
(12)

possesses a unique solution  $y(z) \in C(I)$ . This solution has the representation

$$y(z) = f(z) + \int_0^z R_\mu(z,s) f(s) ds, \quad z \in I,$$

where the resolvent kernel  $R_{\mu}(z,s)$  of the kernel  $(z-s)^{-\mu}K(z,s)$  has the form

$$R_{\mu}(z,s) = (z-s)^{-\mu}Q_{\mu}(z,s).$$

Here,  $Q_{\mu}(z,s)$  is continuous on D.

2. If  $m \ge 1$ , every nontrivial solution has the property that  $y(z) \notin C^1(I)$ : as  $z \to 0^+$  the solution behaves like

$$y'(z) \sim C z^{-\mu}, \quad 0 < \mu < 1.$$

In earlier work, when  $0 < 1 - \alpha < 1$ , the general form of the exact solution of the Eq.(10) has been derived, in next lemma.

**Lemma 3.4.** [5] Assume that  $f \in C^m(I)$  with  $m \in N^+$ , and  $K(w(z-s)+s,s) \in C^m(I \times I)$  with  $K(w(z-s)+s, w(z-s)+s) \neq 0$  on I = [0,T]. Then, the regularity of the unique solution of the weakly singular Volterra integral equation (10) can be described by

$$y(z) \in C[0,T] \bigcap C^{m}(0,T], \quad | \ y(z) | \le C_{\mu} z^{-\mu}, \quad z \in (0,T],$$
(13)  
$$y(z) = \sum_{(j,k)_{\mu}} \gamma_{j,k}(\mu) z^{j+k(1-\mu)} + Y_{m}(z;\mu), \quad z \in I,$$

where  $(j,k)_{\mu} := \{(j,k) : j,k \in N^+ \cup 0, j + k(1-\mu) < m\}, \gamma_{j,k}(\mu)$  are some constants and  $Y_m(\cdot;\mu) \in C^m(I)$ .

**Lemma 3.5.** [6] Suppose that  $f \in C^m(I)$ ,  $K(w(z-s)+s,s) \in C^m(I \times I)$  on I = [0,T], and  $K(w(z-s)+s,s) \neq 0$  with  $m \geq 0$ . Let  $\mu = 1 - \alpha, 0 < \mu < 1$ .

The Volterra integral equation (10) has a unique solution  $y(z) \in C[0,T] \cap C^m(0,T]$ . Further, y(z) has the following form

$$y(z) = f(z) + \sum_{k=1}^{\infty} \psi_k(z) z^{k(1-\mu)}, \quad z \in I,$$

where  $\psi_k \in C^m(I), k \ge 1$ , and the series is absolutely uniformly convergent on I.

If  $\mu = \frac{p}{q}$  is rational (i.e.,  $p, q \in N$ , reduced to lowest terms), then the solution of the Eq.(10) can be expressed in the form

$$y(z) = f(z) + \sum_{s=1}^{q-1} \nu_s(z) z^{s(1-\mu)}, \quad z \in I,$$
(14)

where  $\nu_s \in C^m(I) (0 \le s \le q-1)$ .

From the above lemma,  $y(z) \notin C^m[0,T]$ . For the Eq.(13), Chen and Tang [9] proposed the function transformation  $\tilde{y}(t) = t^{u+m-1}[y(t) - y(0)]$  to remove a single term singularity like  $t^{1-u-m}$ . They used the spectral-collocation method and achieved excellent results. Our work has been inspired by their excellent results in [9, 32]. We apply the similar transformation mentioned above to (14), and obtain the following lemma. This result will be the starting point to the construction of the numerical method presented later.

**Lemma 3.6.** Using the following transformation for (14),

$$z = t^{\sigma}, \quad Y(t) = y(z), \quad t \in I' = [0, T^{\frac{1}{\sigma}}], \quad \sigma \in N^+,$$
 (15)

it is deduced that

- 1. if  $\sigma = q$  or a multiple of q, then  $Y(t) \in C^m(I')$ ;
- 2. if  $\sigma \geq \frac{q}{q-p}$ , then Y(t) is at least a first-order differentiable function.

*Proof.* Taking the above transformation (15) to (14), we obtain

$$y(t^{\sigma}) = f(t^{\sigma}) + \sum_{s=1}^{q-1} \nu_s(t^{\sigma}) t^{s\sigma(1-\mu)} = f(t^{\sigma}) + \sum_{s=1}^{q-1} \nu_s(t^{\sigma}) t^{s\sigma(\frac{q-p}{q})}.$$

Thus we deduce the two conclusions in the lemma.

By the Lemma 3.5, it follows that the solution of the Eq.(10) can be written in the form of  $\tilde{y}(z) = y_1(z) + y_2(z)$  where, for a fixed  $m, y_1(z) \in C^m(I)$  and  $y_2(z)$  is the non-smooth part of the solution.

Our first step is to replace  $\tilde{y}(z)$  by  $\tilde{y}(z) := y(z) + \lambda$ , where y(0) = 0. Hence, the Eq.(1) can be expressed in terms of y as

$$D_z^{\alpha} y(z) = \left( y(z) + \tilde{g}(z) + \lambda \right) + \int_0^z \tilde{K}(z,\tau) (y(\tau) + \lambda) d\tau, \quad z \in (0,T],$$
  
$$y(0) = 0.$$
(16)

An equivalent integral form of the above equation is

$$y(z) = \frac{1}{\Gamma(\alpha)} \int_0^z (z-s)^{\alpha-1} \Big( y(s) + \tilde{g}(s) + \lambda \Big) ds \qquad (17)$$
$$+ \frac{1}{\Gamma(\alpha)} \int_0^z (z-s)^{\alpha-1} \int_0^s \tilde{K}(s,\tau) (y(\tau) + \lambda) d\tau ds.$$

We apply the smoothing transformation

$$z = t^{\sigma} \quad s = \gamma^{\sigma}, \quad 1 < \sigma \in N,$$

reducing the problem (17) to the following integral equation whose solution does not involve anymore singularities in the first derivative.

$$y(t^{\sigma}) = \frac{1}{\Gamma(\alpha)} \int_0^t \sigma \gamma^{\sigma-1} (t^{\sigma} - \gamma^{\sigma})^{\alpha-1} \Big( y(\gamma^{\sigma}) + \tilde{g}(\gamma^{\sigma}) + \lambda \Big) d\gamma \qquad (18)$$
$$+ \frac{1}{\Gamma(\alpha)} \int_0^t \sigma \gamma^{\sigma-1} (t^{\sigma} - \gamma^{\sigma})^{\alpha-1} \int_0^{\gamma^{\sigma}} \tilde{K}(\gamma^{\sigma}, \tau) (y(\tau) + \lambda) d\tau d\gamma.$$

Moreover, using the linear transformation

$$\begin{split} t &= T^{\frac{1}{\sigma}}(\frac{x+1}{2}), \quad x \in \Lambda, \\ \gamma &= T^{\frac{1}{\sigma}}(\frac{\xi+1}{2}), \quad \xi \in (-1,x), \end{split}$$

the Eq.(18) becomes

$$y(T(\frac{x+1}{2})^{\sigma}) = \frac{1}{\Gamma(\alpha)} \int_{-1}^{x} \frac{\sigma T}{2} (\frac{\xi+1}{2})^{\sigma-1} \Big( T(\frac{x+1}{2})^{\sigma} - T(\frac{\xi+1}{2})^{\sigma} \Big)^{\alpha-1} \\ \times \Big( y(T(\frac{\xi+1}{2})^{\sigma}) + \tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda \Big) d\xi + \frac{1}{\Gamma(\alpha)} \\ \times \int_{-1}^{x} \frac{\sigma T}{2} (\frac{\xi+1}{2})^{\sigma-1} \Big( T(\frac{x+1}{2})^{\sigma} - T(\frac{\xi+1}{2})^{\sigma} \Big)^{\alpha-1} \\ \times \int_{0}^{T(\frac{\xi+1}{2})^{\sigma}} \tilde{K} \Big( T(\frac{\xi+1}{2})^{\sigma}, \tau \Big) (y(\tau) + \lambda) d\tau d\xi.$$
(19)

Furthermore, in order to transform the integral interval  $(0, T(\frac{\xi+1}{2})^{\sigma})$  into  $(-1, \xi)$ , we use the linear transformation  $\tau = T(\frac{\eta+1}{2})^{\sigma}, \eta \in \Lambda$ , we obtain

$$y(T(\frac{x+1}{2})^{\sigma}) = \frac{1}{\Gamma(\alpha)} \int_{-1}^{x} \frac{\sigma T}{2} (\frac{\xi+1}{2})^{\sigma-1} \Big( T(\frac{x+1}{2})^{\sigma} - T(\frac{\xi+1}{2})^{\sigma} \Big)^{\alpha-1} \\ \times \Big( y(T(\frac{\xi+1}{2})^{\sigma}) + \tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda \Big) d\xi + \frac{1}{\Gamma(\alpha)} \\ \times \int_{-1}^{x} (\frac{\sigma T}{2})^{2} (\frac{\xi+1}{2})^{\sigma-1} \Big( T(\frac{x+1}{2})^{\sigma} - T(\frac{\xi+1}{2})^{\sigma} \Big)^{\alpha-1} \\ \times \int_{-1}^{\xi} (\frac{\eta+1}{2})^{\sigma-1} \tilde{K} \Big( T(\frac{\xi+1}{2})^{\sigma}, T(\frac{\eta+1}{2})^{\sigma} \Big) \\ \times \Big( y(T(\frac{\eta+1}{2})^{\sigma}) + \lambda \Big) d\eta d\xi.$$
(20)

We use the following linear transformation to convert the integration interval  $(-1,\xi)$  to (-1,1).

$$\eta = \eta(\xi, \theta) = \frac{\xi + 1}{2}\theta + \frac{\xi - 1}{2}, \quad \theta \in \Lambda.$$

Equation (20) can be written as

$$y(T(\frac{x+1}{2})^{\sigma}) = \frac{1}{\Gamma(\alpha)} \int_{-1}^{x} \frac{\sigma T}{2} (\frac{\xi+1}{2})^{\sigma-1} \Big( T(\frac{x+1}{2})^{\sigma} - T(\frac{\xi+1}{2})^{\sigma} \Big)^{\alpha-1} \\ \times \Big( y(T(\frac{\xi+1}{2})^{\sigma}) + \tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda \Big) d\xi + \frac{1}{\Gamma(\alpha)} \\ \times \int_{-1}^{x} (\frac{\sigma T}{2})^{2} (\frac{\xi+1}{2})^{\sigma} \Big( T(\frac{x+1}{2})^{\sigma} - T(\frac{\xi+1}{2})^{\sigma} \Big)^{\alpha-1} \\ \times \int_{-1}^{1} (\frac{\eta+1}{2})^{\sigma-1} \tilde{K} \Big( T(\frac{\xi+1}{2})^{\sigma}, T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma} \Big) \\ \times \Big( y(T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma}) + \lambda \Big) d\theta d\xi.$$
(21)

Using the formula

$$a^{\sigma} - b^{\sigma} = (a - b) \sum_{i=0}^{\sigma-1} a^{i} b^{\sigma-i-1},$$

(21) becomes

$$y(T(\frac{x+1}{2})^{\sigma}) = \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)} \int_{-1}^{x} (x-\xi)^{\alpha-1}g(x,\xi) \left(y(T(\frac{\xi+1}{2})^{\sigma}) + \tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda\right) d\xi + \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)} \int_{-1}^{x} (x-\xi)^{\alpha-1} \\ \times \int_{-1}^{1} g(x,\xi,\theta) \tilde{K} \left(T(\frac{\xi+1}{2})^{\sigma}T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma}\right) \\ \times \left(y(T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma}) + \lambda\right) d\theta d\xi,$$
(22)

where

$$\begin{split} g(x,\xi) &= \sigma(\frac{\xi+1}{2})^{\sigma-1} \Big(\sum_{i=0}^{\sigma-1} (\frac{x+1}{2})^i (\frac{\xi+1}{2})^{\sigma-i-1} \Big)^{\alpha-1}, \\ g(x,\xi,\theta) &= \sigma^2 (\frac{\eta(\xi,\theta)+1}{2})^{\sigma-1} (\frac{\xi+1}{2})^{\sigma} \Big(\sum_{i=0}^{\sigma-1} (\frac{x+1}{2})^i (\frac{\xi+1}{2})^{\sigma-i-1} \Big)^{\alpha-1}. \end{split}$$

Finally, by the change of variable

$$\xi = \xi(x, v) = \frac{x+1}{2}v + \frac{x-1}{2}, \quad x, v \in \Lambda,$$

and setting

$$Y(x) = y(T(\frac{x+1}{2})^{\sigma}),$$

(22) is reduced to

$$Y(x) = \frac{T^{\alpha}}{4^{\alpha}\Gamma(\alpha)} \int_{-1}^{1} (x+1)^{\alpha} (1-v)^{\alpha-1} G(x,\xi(x,v)) dv,$$
  
+  $\frac{T^{\alpha+1}}{2^{2\alpha+1}\Gamma(\alpha)} \int_{-1}^{1} (x+1)^{\alpha} (1-v)^{\alpha-1}$ 

.

$$\times \int_{-1}^{1} K(\xi(x,v),\eta) \Big( Y(\eta) + \lambda \Big) d\theta dv, \tag{23}$$

where

$$\begin{aligned} &G(x,\xi(x,v)) &= g(x,\xi(x,v)) \Big( Y(\xi) + \tilde{g}(T(\frac{\xi(x,v)+1}{2})^{\sigma}) + \lambda \Big), \\ &K(\xi(x,v),\eta) &= g(x,\xi(x,v),\theta) \tilde{K} \Big( T(\frac{\xi(x,v)+1}{2})^{\sigma}, T(\frac{\eta(\xi(x,v),\theta)+1}{2})^{\sigma} \Big) \Big). \end{aligned}$$

4. The Jacobi spectral collocation method. In this section, we propose the Jacobi spectral-collocation method to (23). Solving Equation (23) by the Jacobi spectral-collocation method is to find  $Y_N(x) \in \mathcal{P}_N$ , such that

$$Y_{N}(x) = I_{x,N}^{\alpha-1} \frac{T^{\alpha}}{4^{\alpha} \Gamma(\alpha)} \int_{-1}^{1} I_{v,N}^{\alpha-1} (x+1)^{\alpha} (1-v)^{\alpha-1} G_{N}(x,\xi(x,v)) dv + I_{x,N}^{\alpha-1} \frac{T^{\alpha+1}}{2^{2\alpha+1} \Gamma(\alpha)} \int_{-1}^{1} I_{v,N}^{\alpha-1} (x+1)^{\alpha} (1-v)^{\alpha-1} \times \int_{-1}^{1} K_{N}(\xi(x,v),\eta) d\theta dv,$$
(24)

where

$$G_N(x,\xi(x,v)) = g(x,\xi(x,v)) \Big( Y_N(\xi) + \tilde{g}(T(\frac{\xi(x,v)+1}{2})^{\sigma}) + \lambda \Big), K_N(\xi(x,v),\eta) = K(\xi(x,v),\eta) \Big( Y_N(\eta) + \lambda \Big).$$

In order to implement the above basic algorithm more effectively, we set

$$Y_{N}(x) = \sum_{i=0}^{N} \mu_{i} J_{i}^{\alpha-1}(x),$$

$$I_{x,N}^{\alpha-1} I_{v,N}^{\alpha-1} \int_{-1}^{1} (x+1)^{\alpha} K_{N}(\xi(x,v),\eta) d\theta = \sum_{i=0}^{N} \sum_{j=0}^{N} d_{i,j} J_{i}^{\alpha-1}(x) J_{j}^{\alpha-1}(v),$$

$$I_{x,N}^{\alpha-1} I_{v,N}^{\alpha-1}(x+1)^{\alpha} G_{N}(x,\xi(x,v)) = \sum_{i=0}^{N} \sum_{j=0}^{N} b_{i,j} J_{i}^{\alpha-1}(x) J_{j}^{\alpha-1}(v).$$
(25)

Employing (25) and (3), we can directly calculate the result that

$$I_{x,N}^{\alpha-1} \frac{T^{\alpha+1}(x+1)^{\alpha}}{2^{2\alpha+1}\Gamma(\alpha)} I_{v,N}^{\alpha-1} \int_{-1}^{1} (1-v)^{\alpha-1} \int_{-1}^{1} K_N(\xi(x,v),\eta) d\theta dv$$
  
=  $\frac{T^{\alpha+1}}{2^{2\alpha+1}\Gamma(\alpha)} \sum_{i=0}^{N} \sum_{j=0}^{N} d_{i,j} J_i^{\alpha-1}(x) \int_{-1}^{1} (1-v)^{\alpha-1} J_j^{\alpha-1}(v) dv$   
=  $\frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha+1)} \sum_{i=0}^{N} d_{i,0} J_i^{\alpha-1}(x).$  (26)

Using (26), (5) and (8) it yields

$$d_{i,0} = \frac{\alpha(2i+\alpha)}{4^{\alpha}} \sum_{j=0}^{N} \sum_{m=0}^{N} \sum_{k=0}^{N} (x_j+1)^{\alpha} \hat{K}_N(\xi(x,v),\eta) \\ \cdot J_i^{\alpha-1}(x_j) \omega_j^{\alpha-1} \omega_m^{\alpha-1} \omega_k^{0,0},$$
(27)

where

$$\hat{K}_N(\xi(x,v),\eta) = K\Big(\xi(x_j,v_m),\eta(\xi(x_j,v_m),\theta_k)\Big)\Big(Y_N(\eta(\xi(x_j,v_m),\theta_k)) + \lambda\Big).$$

Similarly, by Eqs. (3) and (25), we conclude that

$$I_{x,N}^{\alpha-1} \frac{T^{\alpha}(x+1)^{\alpha}}{4^{\alpha}\Gamma(\alpha)} I_{v,N}^{\alpha-1} \int_{-1}^{1} (1-v)^{\alpha-1} G_N(x,\xi(x,v)) dv$$
  
=  $\frac{T^{\alpha}}{4^{\alpha}\Gamma(\alpha)} \sum_{i=0}^{N} \sum_{j=0}^{N} b_{i,j} J_i^{\alpha-1}(x) \int_{-1}^{1} (1-v)^{\alpha-1} J_j^{\alpha-1}(v) dv$   
=  $\frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha+1)} \sum_{i=0}^{N} b_{i,0} J_i^{\alpha-1}(x).$  (28)

Using (28), (5) and (8), we obtain

$$b_{i,0} = \frac{\alpha(2i+\alpha)}{4^{\alpha}} \sum_{j=0}^{N} \sum_{m=0}^{N} (x_j+1)^{\alpha} \hat{G}_N(x,\xi(x,v)) J_i^{\alpha-1}(x_j) \omega_j^{\alpha-1} \omega_m^{\alpha-1},$$
(29)

where

$$\hat{G}_N(x,\xi(x,v)) = g(x_j,\xi(x_j,v_m)) \Big( Y_N(\xi(x_j,v_m)) + \tilde{g}(T(\frac{\xi(x_j,v_m)+1}{2})^{\sigma}) + \lambda \Big).$$

In summary, by (25)-(29), we deduce that

$$\sum_{i=0}^{N} \mu_i J_i^{\alpha-1}(x)$$
  
=  $\frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha+1)} \sum_{i=0}^{N} d_{i,0} J_i^{\alpha-1}(x) + \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha+1)} \sum_{i=0}^{N} b_{i,0} J_i^{\alpha-1}(x).$  (30)

Finally, using (3) it yields

$$\mu_{i} = \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha+1)}d_{i,0} + \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha+1)}b_{i,0}, \quad 0 \le i \le N.$$
(31)

The numerical solution can be obtained by solving the equations.

5. Error analysis. In this section, we estimate the error of the numerical solution. We bound the error in the  $L^{\infty}$  and  $L^2_{\omega^{\alpha,\beta}}$  norms. In order to give the subsequent lemmas conveniently, we first introduce some spaces.

Let the region  $\Lambda \subset \mathbb{R}^n$  be a non-empty Lebesgue measurable set, u(x) is a real value Lebesgue measurable function defined on  $\Lambda$ .  $L^p(\Lambda)$  is defined as

$$L^{p}(\Lambda) = \left\{ u: \ \left\| u \right\|_{L^{p}(\Lambda)} < \infty, \ 1 \le p \le \infty \right\},$$

equipped with the norm,

$$\begin{split} \left\| u \right\|_{L^{p}(\Lambda)} &= \left( \int_{\Lambda} \left| u(x) \right|^{p} dx \right)^{\frac{1}{p}}, \ 1 \leq p < \infty, \\ \left\| u \right\|_{L^{\infty}(\Lambda)} &= \operatorname{esssup}_{x \in (\Lambda)} |u(x)|. \end{split}$$

For a non-negative integer l, and  $1 \le p \le \infty$ , the Sobolev space is defined as:

$$H^{l,p}(\Lambda) = \left\{ u \in L^p(\Lambda) : \partial^{\alpha} u \in L^p(\Lambda), \ \forall \ \left| \alpha \right| \le l \right\}.$$

If p = 2, we record  $H^{l,2}(\Lambda)$  as  $H^{l}(\Lambda)$ , which is a separable Hilbert Space. If l = 0,  $H^{l,p}(\Lambda)$  is  $L^{p}(\Lambda)$  space.

Then we introduce the weighted  $L^2_{\omega^{\alpha,\beta}}(\Lambda)$  space. Assume that the weight function  $\omega^{\alpha,\beta}(x) = (1-x)^{\alpha}(1+x)^{\beta}$  with  $\alpha,\beta > -1$ , then

 $L^2_{\omega^{\alpha,\beta}}(\Lambda) = \{ u : u \text{ is measurable and } \|u\|_{\omega^{\alpha,\beta}} < \infty \},$ 

endowed with the norm and inner product

$$\begin{aligned} \|u\|_{\omega^{\alpha,\beta}} &= \left(\int_{\Lambda} |u(x)|^2 \omega^{\alpha,\beta}(x) \,\mathrm{d}x\right)^{\frac{1}{2}}, \\ (u,v)_{\omega^{\alpha,\beta}} &= \int_{\Lambda} u(x)v(x)\omega^{\alpha,\beta}(x) \,\mathrm{d}x, \quad \forall \ u,v \in L^2_{\omega^{\alpha,\beta}}(\Lambda). \end{aligned}$$

The weighted Hilbert space is defined as follows

$$H^l_{\omega^{\alpha,\beta}}(\Lambda):=\{u:\partial^m_x u\in L^2_{\omega^{\alpha,\beta}}(\Lambda),\ 0\leq m\leq l\},$$

equipped with the norm, semi-norm and inner product

$$\begin{split} \|u\|_{l,\omega^{\alpha,\beta}} &= \left(\sum_{m=0}^{l} \|\partial^{m}u\|_{\omega^{\alpha,\beta}}^{2}\right)^{\frac{1}{2}}, \quad |u|_{l,\omega^{\alpha,\beta}} = \|\partial^{l}u\|_{\omega^{\alpha,\beta}}\\ (u,v)_{l,\omega^{\alpha,\beta}} &= \sum_{m=0}^{l} \int_{\Lambda} \partial_{x}^{m}u(x)\partial_{x}^{m}v(x)\omega^{\alpha,\beta}dx. \end{split}$$

For a non-negative integer l, we introduce the non-uniformly Jacobi-weighted Sobolev space

$$B^{l}_{\omega^{\alpha,\beta}}(\Lambda) := \{ u : \partial_{x}^{m} u \in L^{2}_{\omega^{\alpha+m,\beta+m}}(\Lambda), \ 0 \le m \le l \},$$

endowed with the norm, semi-norm and inner product

$$\begin{aligned} \|u\|_{B^{l}_{\omega^{\alpha,\beta}}} &= (u,u)^{1/2}_{B^{l}_{\omega^{\alpha,\beta}}}, \quad \|u\|_{B^{l}_{\omega^{\alpha,\beta}}} &= \|\partial^{l}_{x}u\|_{\omega^{\alpha+l,\beta+l}}, \\ (u,v)_{B^{l}_{\omega^{\alpha,\beta}}} &= \sum_{m=0}^{l} (\partial^{m}_{x}u,\partial^{m}_{x}v)_{\omega^{\alpha+m,\beta+m}}, \end{aligned}$$

where  $\|u\|_{\omega^{\alpha,\beta}}$  is the norm of  $L^2_{\omega^{\alpha,\beta}}(\Lambda)$ . Especially,  $L^2(\Lambda) = B^0_{\omega^{0,0}}$ ,  $\|\cdot\| = \|\cdot\|_{L^2(\Lambda)}$ and  $\|\cdot\|_{\infty} = \|\cdot\|_{L^{\infty}(\Lambda)}$ . The non-uniform Jacobi-weighted Sobolev space distinguishes itself from the usual weighted Sobolev space  $H^l_{\omega^{\alpha,\beta}}$  by involving different weight functions for derivatives of different orders. It is clear that  $H^l_{\omega^{\alpha,\beta}}$  is a subspace of  $B^l_{\omega^{\alpha,\beta}}$ , that is  $\|u\|_{B^l_{\omega^{\alpha,\beta}}} \leq c \|u\|_{H^l_{\omega^{\alpha,\beta}}}$ . The space  $L^{\infty}(\Lambda)$  is the Banach space of the measurable functions u that are

The space  $L^{\infty}(\Lambda)$  is the Banach space of the measurable functions u that are bounded outside a set of measure zero, equipped the norm

$$\|u\|_{\infty} = \operatorname{esssup}_{x \in (\Lambda)} |u(x)|.$$

We denote by  $C^m(\Lambda)$  the space of m-times continuously differentiable functions on the interval  $\Lambda$ .

**Lemma 5.1.** [24] Let  $F_j(x)_{j=0}^N$  be the Nth Lagrange interpolation polynomials associated with the N + 1 Gauss points of the Jacobi polynomials. Then

$$\|I_N^{\alpha,\beta}\|_{L^{\infty}(I)} = \max_{x \in [-1,1]} \sum_{j=0}^N |F_j(x)| = \begin{cases} \mathscr{O}(\log N), \ -1 \le \alpha, \beta \le -\frac{1}{2}, \\ \mathscr{O}(N^{\epsilon+\frac{1}{2}}), \ \epsilon = \max(\alpha, \beta), otherwise. \end{cases}$$

**Lemma 5.2.** [29] For  $\alpha, \beta > -1$ , and any  $u \in B^l_{\omega^{\alpha,\beta}}$  with  $l \ge 1$ , and integers  $0 \le m \le l \le N+1$ ,

$$\|\partial_x^m (u - I_{x,N}^{\alpha,\beta} u)\|_{\omega^{\alpha+m,\beta+m}} \le c N^{m-l} \|\partial_x^l u\|_{\omega^{\alpha+l,\beta+l}}.$$

Moreover, for any  $u \in H^l_{\omega^{-1/2,-1/2}}$  with  $1 \le l \le N+1$ ,

$$||u - I_{x,N}^{-1/2,-1/2}u||_{\infty} \le cN^{1/2-l}||u||_{\omega^{-1/2,-1/2}},$$

where c is a positive constant independent of l, N and u.

**Lemma 5.3.** [38] Let  $v_i^{\alpha-1}$  be the Jacobi-Gauss nodes in  $\Lambda$  and  $\xi_i^{\alpha-1} = \xi(x, v_i^{\alpha-1})$ . The mapped Jacobi-Guass interpolation operator  ${}_xI_{\xi,N}^{\alpha-1} : C(-1,x) \to P_N(-1,x)$  is defined by

$${}_{x}I_{\xi,N}^{\alpha-1}u(\xi_{i}^{\alpha-1}) = u(\xi_{i}^{\alpha-1}), \quad 0 \le i \le N.$$

Hence

$${}_{x}I^{\alpha-1}_{\xi,N}u(\xi^{\alpha-1}_{i}) = u(\xi^{\alpha-1}_{i}) = u(\xi(x,v^{\alpha-1}_{i})) = I^{\alpha-1}_{v,N}u(\xi(x,v^{\alpha-1}_{i})),$$

and

$${}_{x}I^{\alpha-1}_{\xi,N}u(\xi) = I^{\alpha-1}_{v,N}u(\xi(x,v)) \mid_{v=\frac{2\xi}{x+1}+\frac{1-x}{x+1}}.$$

From the above formula, we can derive the following results

$$\begin{split} \int_{-1}^{x} (x-\xi)^{\alpha-1} {}_{x}I_{\xi,N}^{\alpha-1} u(\xi) d\xi &= \left(\frac{1+x}{2}\right)^{\alpha} \int_{-1}^{1} (1-v)^{\alpha-1} I_{v,N}^{\alpha-1} u(\xi(x,v)) dv \\ &= \left(\frac{1+x}{2}\right)^{\alpha} \sum_{i=0}^{N} \omega_{i}^{\alpha-1} u(\xi_{i}^{\alpha-1}), \\ \int_{-1}^{x} (x-\xi)^{\alpha-1} ({}_{x}I_{\xi,N}^{\alpha-1} u(\xi))^{2} d\xi &= \left(\frac{1+x}{2}\right)^{\alpha} \sum_{i=0}^{N} \omega_{i}^{\alpha-1} u^{2}(\xi_{i}^{\alpha-1}). \end{split}$$

Moreover, if we denote I as the identity operator, for any  $1 \leq l \leq N+1,$  we have that

$$\begin{split} & \int_{-1}^{x} (x-\xi)^{\alpha-1} \mid (I - {}_{x}I^{\alpha-1}_{\xi,N})u(\xi) \mid^{2} d\xi \\ & = (\frac{1+x}{2})^{\alpha} \int_{-1}^{1} (1-v)^{\alpha-1} \mid (I - I^{\alpha-1}_{v,N})u(\xi(x,v)) \mid^{2} dv \\ & \leq cN^{-2l} (\frac{1+x}{2})^{\alpha} \int_{-1}^{1} (1-v)^{\alpha+l-1} (1+v)^{l} \mid \partial_{v}^{l}u(\xi(x,v)) \mid^{2} dv \\ & = cN^{-2l} \int_{-1}^{x} (x-\xi)^{\alpha+l-1} (1+\xi)^{l} \mid \partial_{\xi}^{l}u(\xi) \mid^{2} d\xi. \end{split}$$

Now, we are ready to prove the following convergence results.

## 5.1. Error analysis in $L^2_{\omega^{\alpha-1,0}}(\Lambda)$ .

**Theorem 5.4.** Let Y be the exact solution of the original equation (16). Let  $Y_N$  be the numerical solution obtained by the discrete scheme (25) combined with the

approximate Eq. (24). Let  $e_N = Y - Y_N$ .

$$\|e_N\|_{\omega^{\alpha-1,0}} \leq \|Y(x) - I_{x,N}^{\alpha-1}Y(x)\|_{\omega^{\alpha-1,0}} + \|I_{x,N}^{\alpha-1}Y - Y_N\|_{\omega^{\alpha-1,0}}$$
  
$$\leq \sum_{i=1}^5 \|E_i\|_{\omega^{\alpha-1,0}},$$
(32)

where

$$E_{1} = Y(x) - I_{x,N}^{\alpha-1} Y(x),$$

$$E_{2} = \frac{T^{\alpha}}{2^{\alpha} \Gamma(\alpha)} I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} (I - {}_{x}I_{\xi,N}^{\alpha-1}) G(x,\xi) d\xi,$$

$$E_{3} = \frac{T^{\alpha}}{2^{\alpha} \Gamma(\alpha)} I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} {}_{x}I_{\xi,N}^{\alpha-1} \hat{G}(x,\xi) (Y - Y_{N}) d\xi,$$

$$E_{4} = \frac{T^{\alpha+1}}{2^{\alpha+1} \Gamma(\alpha)} I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} (I - {}_{x}I_{\xi,N}^{\alpha-1}) K(x,\xi,\eta) d\theta d\xi,$$

$$E_{5} = \frac{T^{\alpha+1}}{2^{\alpha+1} \Gamma(\alpha)} I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} {}_{x}I_{\xi,N}^{\alpha-1} \hat{K}(x,\xi,\eta) (Y - Y_{N}) d\theta d\xi.$$
(33)

Here

$$\begin{split} G(x,\xi) &= g(x,\xi) \Big( Y(\xi) + \tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda \Big), \\ \hat{G}(x,\xi)(Y-Y_N) &= g(x,\xi) \Big( Y(\xi) - Y_N(\xi) \Big), \\ K(x,\xi,\eta) &= g(x,\xi,\theta) \tilde{K} \Big( T(\frac{\xi+1}{2})^{\sigma}, T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma} \Big) \\ &\cdot \Big( Y(\eta(\xi,\theta)) + \lambda \Big), \\ \hat{K}(x,\xi,\eta)(Y-Y_N) &= g(x,\xi,\theta) \tilde{K} \Big( T(\frac{\xi+1}{2})^{\sigma}, T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma} \Big) \\ &\cdot \Big( Y(\eta(\xi,\theta)) - Y_N(\eta(\xi,\theta)) \Big). \end{split}$$

*Proof.* It follows from (22) that

$$I_{x,N}^{\alpha-1}Y(x) = \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)}I_{x,N}^{\alpha-1}\int_{-1}^{x}(x-\xi)^{\alpha-1}G(x,\xi)d\xi +\frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)}I_{x,N}^{\alpha-1}\int_{-1}^{x}(x-\xi)^{\alpha-1}\int_{-1}^{1}K(x,\xi,\eta)d\theta d\xi, Y_{N}(x) = \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)}I_{x,N}^{\alpha-1}\int_{-1}^{x}(x-\xi)^{\alpha-1}{}_{x}I_{\xi,N}^{\alpha-1}G_{N}(x,\xi)d\xi +\frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)}I_{x,N}^{\alpha-1}\int_{-1}^{x}(x-\xi)^{\alpha-1}\int_{-1}^{1}{}_{x}I_{\xi,N}^{\alpha-1}K_{N}(x,\xi,\eta)d\theta d\xi,$$
(34)

where  ${}_{x}I^{\alpha-1}_{\xi,N}$  is defined in Lemma 5.3, and

$$\begin{aligned} G(x,\xi) &= g(x,\xi) \Big( Y(\xi) + \tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda \Big), \\ G_N(x,\xi) &= g(x,\xi) \Big( Y_N(\xi) + \tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda \Big), \\ K(x,\xi,\eta) &= g(x,\xi,\theta) \tilde{K} \Big( T(\frac{\xi+1}{2})^{\sigma}, T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma} \Big) \Big( Y(\eta(\xi,\theta)) + \lambda \Big), \end{aligned}$$

$$K_N(x,\xi,\eta) = g(x,\xi,\theta)\tilde{K}\Big(T(\frac{\xi+1}{2})^{\sigma}, T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma}\Big)\Big(Y_N(\eta(\xi,\theta))+\lambda\Big).$$

By (34), we obtain

$$I_{x,N}^{\alpha-1}Y - Y_{N}$$

$$= \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)}I_{x,N}^{\alpha-1}\int_{-1}^{x}(x-\xi)^{\alpha-1}(I-{}_{x}I_{\xi,N}^{\alpha-1})G(x,\xi)d\xi$$

$$+ \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)}I_{x,N}^{\alpha-1}\int_{-1}^{x}(x-\xi)^{\alpha-1}{}_{x}I_{\xi,N}^{\alpha-1}\hat{G}(x,\xi)(Y-Y_{N})d\xi \qquad (35)$$

$$+ \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)}I_{x,N}^{\alpha-1}\int_{-1}^{x}(x-\xi)^{\alpha-1}\int_{-1}^{1}(I-{}_{x}I_{\xi,N}^{\alpha-1})K(x,\xi,\eta)d\theta d\xi$$

$$+ \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)}I_{x,N}^{\alpha-1}\int_{-1}^{x}(x-\xi)^{\alpha-1}\int_{-1}^{1}{}_{x}I_{\xi,N}^{\alpha-1}\hat{K}(x,\xi,\eta)(Y-Y_{N})d\theta d\xi,$$

where

$$\hat{G}(x,\xi)(Y-Y_N) = g(x,\xi)\Big(Y(\xi) - Y_N(\xi)\Big),$$
  

$$\hat{K}(x,\xi,\eta)(Y-Y_N) = g(x,\xi,\theta)\tilde{K}\Big(T(\frac{\xi+1}{2})^{\sigma},T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma}\Big)$$
  

$$\cdot\Big(Y(\eta(\xi,\theta)) - Y_N(\eta(\xi,\theta))\Big).$$

The theorem is proved.

**Theorem 5.5.** Let Y be the exact solution of the original equation (16). Let  $Y_N$  is the numerical solution obtained by the discrete scheme (25) combined with the approximate equation (24). Let  $\alpha \in (0,1)$ . Assume that  $Y \in B^l_{\omega^{\alpha-1,0}}(\Lambda)$  with  $1 \leq l \leq N+1$ . We conclude the error estimate:

$$\begin{aligned} \|e_{N}\|_{\omega^{\alpha-1,0}} \\ &\leq cN^{-l}G^{*} \|\partial_{\xi}^{l} \left(Y+g\right)\|_{\omega^{\alpha+l-1,l}} + c(N^{1-l}+N^{-l})K^{*} \|\partial_{\xi}^{l}Y\|_{\omega^{\alpha+l-1,l}} \\ &+ cN^{-l}(1+NK^{*}+K^{*}+G^{*}) \|\partial_{x}^{l}Y\|_{\omega^{\alpha+l-1,l}}, \end{aligned}$$
(36)

where

$$G^* = \max_{i \in [0,N]} \max_{\xi \in [-1,x]} g(x_i,\xi),$$
  

$$K^* = \max_{i \in [0,N]} \max_{k \in [0,N]} \max_{\xi \in [-1,x]} g(x_i,\xi,\theta_k) K(\xi,\eta(\xi,\theta_k)).$$

Proof. By Lemma 5.2,

$$\left\| E_1 \right\|_{\omega^{\alpha-1,0}} = \left\| Y(x) - I_{x,N}^{\alpha-1} Y(x) \right\|_{\omega^{\alpha-1,0}} \le c N^{-l} \left\| \partial_x^l Y \right\|_{\omega^{\alpha+l-1,l}}.$$
(37)

Using (5), we get

$$\begin{aligned} & \left\| E_2 \right\|_{\omega^{\alpha-1,0}} \\ &= \frac{T^{\alpha}}{2^{\alpha} \Gamma(\alpha)} \left\| I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} (I - {}_x I_{\xi,N}^{\alpha-1}) G(x,\xi) d\xi \right\|_{\omega^{\alpha-1,0}} \\ &= \frac{T^{\alpha}}{2^{\alpha} \Gamma(\alpha)} \left[ \sum_{i=0}^{N} \omega_i \Big( \int_{-1}^{x_i} (x_i - \xi)^{\alpha-1} (I - {}_{x_i} I_{\xi,N}^{\alpha-1}) G(x_i,\xi) d\xi \Big)^2 \right]^{1/2}. \end{aligned}$$
(38)

Apply the Cauchy-Schwarz inequality,

$$\left|\int_{-1}^{x_{i}} a(\xi)b(\xi)d\xi\right|^{2} \leq \int_{-1}^{x_{i}} |a(\xi)|^{2} d\xi \int_{-1}^{x_{i}} |b(\xi)|^{2} d\xi,$$
(39)

where

$$a(\xi) = (x_i - \xi)^{\frac{\alpha - 1}{2}},$$
  

$$b(\xi) = (x_i - \xi)^{\frac{\alpha - 1}{2}} (I - x_i I_{\xi,N}^{\alpha - 1}) G(x_i, \xi),$$

and Lemma 5.3, we derive

$$\begin{aligned} |E_{2}||_{\omega^{\alpha-1,0}} &= \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)} \left[ \sum_{i=0}^{N} \omega_{i} \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} d\xi \\ &\times \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} | (I-x_{i}I_{\xi,N}^{\alpha-1})G(x_{i},\xi)d\xi |^{2} \right]^{1/2} \\ &\leq \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha+1)} \left[ \sum_{i=0}^{N} \omega_{i}\alpha(x_{i}+1)^{\alpha} \right. \end{aligned}$$
(40)  
$$&\times \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} | (I-x_{i}I_{\xi,N}^{\alpha-1})G(x_{i},\xi)d\xi |^{2} \right]^{1/2} \\ &\leq cN^{-l}G^{*} \Big( \sum_{i=0}^{N} \omega_{i}\alpha(x_{i}+1)^{\alpha} \Big)^{1/2} \max_{i\in[0,N]} \\ &\times \Big( \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha+l-1} (1+\xi)^{l} | \partial_{\xi}^{l} \Big( Y(\xi) + g(\xi) \Big) |^{2} d\xi \Big)^{1/2}, \end{aligned}$$

where

$$g(\xi) = \left(\tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda\right), \quad G^* = \max_{i \in [0,N]} \max_{\xi \in [-1,x]} g(x_i,\xi).$$

For any  $x_i \in (-1, 1)$ , and  $\alpha \in (0, 1)$ ,

$$\sum_{i=0}^{N} \omega_i \alpha (x_i + 1)^{\alpha} \le 2.$$

$$\tag{41}$$

Hence

$$\left\|E_{2}\right\|_{\omega^{\alpha-1,0}} \leq cN^{-l}G^{*}\left\|\partial_{\xi}^{l}\left(Y(\cdot)+g(\cdot)\right)\right\|_{\omega^{\alpha+l-1,l}}.$$
(42)

In the same way, by the Cauchy-Schwarz inequality, we deduce that

$$\begin{split} & \left\| E_{3} \right\|_{\omega^{\alpha-1,0}} \\ &= \frac{T^{\alpha}}{2^{\alpha} \Gamma(\alpha)} \left\| I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} {}_{x} I_{\xi,N}^{\alpha-1} \left( \hat{G}(x,\xi)(Y-Y_{N}) \right) d\xi \right\|_{\omega^{\alpha-1,0}} \\ &= \frac{T^{\alpha}}{2^{\alpha} \Gamma(\alpha)} \left[ \sum_{i=0}^{N} \omega_{i} \left( \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} {}_{x_{i}} I_{\xi,N}^{\alpha-1} \left( \hat{G}(x_{i},\xi)(Y-Y_{N}) \right) d\xi \right)^{2} \right]^{1/2} \\ &\leq \frac{T^{\alpha} G^{*}}{2^{\alpha} \Gamma(\alpha)} \left[ \sum_{i=0}^{N} \omega_{i} \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} d\xi \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} \\ &\times |_{x_{i}} I_{\xi,N}^{\alpha-1} \left( Y(\xi) - Y_{N}(\xi) \right) |^{2} d\xi \right]^{1/2}. \end{split}$$

$$(43)$$

Using Lemma 5.3 yields

$$\begin{split} \|E_{3}\|_{\omega^{\alpha-1,0}} &\leq \frac{G^{*}T^{\alpha}}{2^{\alpha}\Gamma(\alpha)} \Big(\sum_{i=0}^{N} \omega_{i}\alpha(x_{i}+1)^{\alpha}\Big)^{1/2} \max_{i\in[0,N]} \Big(\int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} |_{x_{i}} I_{\xi,N}^{\alpha-1} \\ &\times \Big(Y(\xi) - Y_{N}(\xi)\Big) |^{2} d\xi\Big)^{1/2} \\ &\leq \frac{G^{*}T^{\alpha}}{2^{\alpha-1/2}\Gamma(\alpha)} \max_{i\in[0,N]} \Big(\Big(\int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} |_{x_{i}} I_{\xi,N}^{\alpha-1}Y(\xi) - Y(\xi) |^{2} d\xi\Big)^{1/2} \\ &+ \Big(\int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} |Y(\xi) - Y_{N}(\xi)|^{2} d\xi\Big)^{1/2}\Big) \\ &\leq cG^{*}N^{-l} \max_{i\in[0,N]} \Big(\int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha+l-1} (1+\xi)^{l} |\partial_{\xi}^{l}Y|^{2} d\xi\Big)^{1/2} \\ &+ \frac{G^{*}T^{\alpha}}{2^{\alpha+1/2}\Gamma(\alpha)} \max_{i\in[0,N]} \Big(\int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} |Y(\xi) - Y_{N}(\xi)|^{2} d\xi\Big)^{1/2} \\ &\leq cG^{*}N^{-l} \|\partial_{x}^{l}Y\|_{\omega^{\alpha+l-1,l}} + cG^{*} \|e_{N}\|_{\omega^{\alpha-1,0}}. \end{split}$$

Similarly, by (5), we obtain that

$$\begin{aligned} & \left\| E_4 \right\|_{\omega^{\alpha-1,0}} \\ &= \frac{T^{\alpha+1}}{2^{\alpha+1} \Gamma(\alpha)} \left\| I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} (I - {}_x I_{\xi,N}^{\alpha-1}) K(x,\xi,\eta) d\theta d\xi \right\|_{\omega^{\alpha-1,0}} \\ &= \frac{T^{\alpha+1}}{2^{\alpha+1} \Gamma(\alpha)} \left[ \sum_{i=0}^{N} \omega_i \Big( \int_{-1}^{x_i} (x_i - \xi)^{\alpha-1} \int_{-1}^{1} (1 - {}_x I_{\xi,N}^{\alpha-1}) K(x_i,\xi,\eta) d\theta d\xi \Big]_{-1}^{2} \right]_{-1}^{1/2} \\ & \times (I - {}_{x_i} I_{\xi,N}^{\alpha-1}) K(x_i,\xi,\eta) d\theta d\xi \Big]_{-1}^{2} \end{aligned}$$

$$(45)$$

By the Cauchy-Schwarz inequality, we further get

$$\begin{aligned} \|E_4\|_{\omega^{\alpha-1,0}} &= \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)} \left[ \sum_{i=0}^{N} \omega_i \int_{-1}^{x_i} (x_i - \xi)^{\alpha-1} d\xi \int_{-1}^{x_i} (x_i - \xi)^{\alpha-1} \\ &\times |\int_{-1}^{1} (I - x_i I_{\xi,N}^{\alpha-1}) K(x_i,\xi,\eta) d\theta |^2 d\xi \right]^{1/2} \\ &\leq \frac{T^{\alpha+1} K^*}{2^{\alpha+1}\Gamma(\alpha+1)} \Big( \sum_{i=0}^{N} \omega_i \alpha(x_i + 1)^{\alpha} \Big)^{1/2} \left[ \int_{-1}^{x_i} (x_i - \xi)^{\alpha-1} \\ &\times |\sum_{k=0}^{N} (I - x_i I_{\xi,N}^{\alpha-1}) \Big( Y(\eta(\xi,\theta_k)) + \lambda \Big) |^2 d\xi \right]^{1/2}, \end{aligned}$$
(46)

where

$$K(\xi, \eta(\xi, \theta)) = \tilde{K}\Big(T(\frac{\xi+1}{2})^{\sigma}, T(\frac{\eta(\xi, \theta)+1}{2})^{\sigma}\Big),$$
  
$$K^* = \max_{i \in [0,N]} \max_{k \in [0,N]} \max_{\xi \in [-1,x]} g(x_i, \xi, \theta_k) K(\xi, \eta(\xi, \theta_k)).$$

Applying Lemma 5.3 leads to

$$\begin{aligned} \|E_4\|_{\omega^{\alpha-1,0}} &\leq c(N^{1-l}+N^{-l})K^* \Big(\sum_{i=0}^N \omega_i \alpha(x_i+1)^{\alpha}\Big)^{1/2} \max_{i\in[0,N]} \max_{k\in[0,N]} \\ &\times \Big(\int_{-1}^{x_i} (x_i-\xi)^{\alpha+l-1} (1+\xi)^l \mid \partial_{\xi}^l \Big(Y(\eta(\xi,\theta_k))+\lambda\Big) \mid^2 d\xi\Big)^{1/2} \\ &\leq c(N^{1-l}+N^{-l})K^* \Big(\sum_{i=0}^N \omega_i \alpha(x_i+1)^{\alpha}\Big)^{1/2} \max_{i\in[0,N]} \max_{k\in[0,N]} \\ &\times \Big(\int_{-1}^{x_i} (x_i-\xi)^{\alpha+l-1} (1+\xi)^l \mid \partial_{\xi}^l Y(\eta(\xi,\theta_k)) \mid^2 d\xi\Big)^{1/2}. \end{aligned}$$
(47)

By (**41**),

$$\left\| E_4 \right\|_{\omega^{\alpha-1,0}} \le c(N^{1-l} + N^{-l})K^* \left\| \partial_{\xi}^l Y(\cdot) \right\|_{\omega^{\alpha+l-1,l}}.$$
(48)

Similarly, using the Cauchy-Schwarz inequality, we further get

$$\begin{aligned} \|E_{5}\|_{\omega^{\alpha-1,0}} &= \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)} \|I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} {}_{x} I_{\xi,N}^{\alpha-1} \hat{K}(x,\xi,\eta) (Y-Y_{N}) d\theta d\xi \|_{\omega^{\alpha-1,0}} \\ &= \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)} \left[ \sum_{i=0}^{N} \omega_{i} \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} d\xi \int_{-1}^{x_{i}} (x-\xi)^{\alpha-1} |\sum_{k=0}^{N} {}_{x_{i}} I_{\xi,N}^{\alpha-1} \right] \\ &\times \hat{K}(x,\xi,\eta(\xi,\theta_{k})) (Y-Y_{N}) |^{2} d\xi \end{aligned}$$

From the above formula, we can get

$$\begin{aligned} \left\| E_{5} \right\|_{\omega^{\alpha-1,0}} &\leq \frac{T^{\alpha+1}K^{*}}{2^{\alpha+1}\Gamma(\alpha)} \left[ \sum_{i=0}^{N} \omega_{i} \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} d\xi \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} |\sum_{k=0}^{N} x_{i} I_{\xi,N}^{\alpha-1} \\ &\times Y(\eta(\xi,\theta_{k})) - Y(\eta(\xi,\theta_{k})) + Y(\eta(\xi,\theta_{k})) - Y_{N}(\eta(\xi,\theta_{k})) |^{2} d\xi \right]^{1/2} \\ &\leq \frac{T^{\alpha+1}K^{*}}{2^{\alpha+1}\Gamma(\alpha+1)} \left( \sum_{i=0}^{N} \omega_{i} \alpha(x_{i}+1)^{\alpha} \right)^{1/2} \max_{i\in[0,N]} \max_{k\in[0,N]} \\ &\left[ \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} |\sum_{k=0}^{N} x_{i} I_{\xi,N}^{\alpha-1} Y(\eta(\xi,\theta_{k})) - Y(\eta(\xi,\theta_{k})) |^{2} d\xi \right]^{1/2} \\ &+ \frac{cT^{\alpha+1}K^{*}}{2^{\alpha+1}\Gamma(\alpha+1)} \left( \sum_{i=0}^{N} \omega_{i} \alpha(x_{i}+1)^{\alpha} \right)^{1/2} \max_{i\in[0,N]} \max_{k\in[0,N]} \\ &\left[ \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} |\sum_{k=0}^{N} (Y(\eta(\xi,\theta_{k})) - Y_{N}(\eta(\xi,\theta_{k}))) |^{2} d\xi \right]^{1/2}. \end{aligned}$$

$$(50)$$

Also using Lemma 5.3 and (41), we obtain

$$\|E_5\|_{\omega^{\alpha-1,0}} \le c(N^{1-l}+N^{-l})K^* \max_{i\in[0,N]} \max_{k\in[0,N]} \left(\int_{-1}^{x_i} (x_i-\xi)^{\alpha+l-1}(1+\xi)^l \right)^{1/2}$$

$$\times |\partial_{\xi}^{l} Y(\eta(\xi,\theta_{k}))|^{2} d\xi \Big)^{1/2} + c(N+1)K^{*}$$

$$\times \max_{i \in [0,N]} \max_{k \in [0,N]} \left( \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} |Y(\eta(\xi,\theta_{k})) - Y_{N}(\eta(\xi,\theta_{k}))|^{2} d\xi \right)^{1/2}.$$

Drawn by the above formula,

$$\|E_5\|_{\omega^{\alpha-1,0}} \le c(N^{1-l} + N^{-l})K^* \|\partial_x^l Y\|_{\omega^{\alpha+l-1,l}} + c(N+1)K^* \|e_N\|_{\omega^{\alpha-1,0}}.$$
(51)

In summary,

$$\begin{aligned} \|e_{N}\|_{\omega^{\alpha-1,0}} \\ &\leq c(N^{1-l}+N^{-l})K^{*}\|\partial_{\xi}^{l}Y\|_{\omega^{\alpha+l-1,l}} + cN^{-l}G^{*}\|\partial_{\xi}^{l}\left(Y+g\right)\|_{\omega^{\alpha+l-1,l}} \\ &+ cN^{-l}(1+NK^{*}+K^{*}+G^{*})\|\partial_{x}^{l}Y\|_{\omega^{\alpha+l-1,l}}. \end{aligned}$$
(52)

## 5.2. Error analysis in $L^{\infty}(\Lambda)$ .

**Theorem 5.6.** Let Y be the exact solution of the original equation (16).  $Y_N$  is the numerical solution obtained by the discrete scheme (25) combined with the approximate equation (24). Let  $\alpha \in (0, 1)$ . Suppose that  $Y \in H^l_{\omega^{\alpha-1,0}}(\Lambda) \cap H^l_{w^{-1/2,-1/2}}(\Lambda)$  with  $1 \leq l \leq N+1$ , we conclude the following error estimate:

$$\begin{aligned} \left\| e_N \right\|_{\infty} &\leq c G^{**} N^{1/2-l} \left\| \partial_{\xi}^l \Big( Y(\xi) + g(\xi) \Big) \right\|_{\omega^{\alpha+l-1,l}} + c N^{1-l} \left\| Y \right\|_{\omega^{-1/2,-1/2}} \\ &+ c (G^{**} + NK^{**} + K^{**}) N^{1/2-l} \left\| \partial_x^l Y \right\|_{\omega^{\alpha+l-1,l}} \\ &+ c K^{**} (N^{3/2-l} + N^{1/2-l}) \left\| \partial_{\xi}^l Y \right\|_{\omega^{\alpha+l-1,l}}, \end{aligned}$$

where

$$\begin{array}{lll} G^{**} & = & \max_{x \in [-1,1]} \max_{\xi \in [-1,x]} g(x,\xi), \\ K^{**} & = & \max_{x \in [-1,1]} \max_{\theta_k \in [-1,1]} \max_{\xi \in [-1,x]} g(x,\xi,\theta_k) K(\xi,\eta(\xi,\theta_k)). \end{array}$$

*Proof.* According to (32),

$$\|e_N\|_{\infty} \le \|Y - I_{x,N}^{\alpha - 1}Y\|_{\infty} + \|I_{x,N}^{\alpha - 1}Y - Y_N\|_{\infty} \le \sum_{i=1}^5 \|E_i\|_{\infty}.$$
 (53)

By (5.1) and (5.2), we deduce that

$$\begin{aligned} \|E_1\|_{\infty} &= \|Y - I_{x,N}^{\alpha-1}Y\|_{\infty} = \|Y - I_{x,N}^{-1/2}Y + I_{x,N}^{\alpha-1}I_{x,N}^{-1/2}Y - I_{x,N}^{\alpha-1}Y\|_{\infty} \\ &\leq (1 + \|I_{x,N}^{\alpha-1}\|_{\infty})\|Y - I_{x,N}^{-1/2}Y\|_{\infty} \\ &\leq cN^{1-l}\|Y\|_{\omega^{-1/2,-1/2}}. \end{aligned}$$
(54)

The Cauchy-Schwarz inequality, along with Lemmas 5.1 and 5.3, lead to

$$|E_{2}| = \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)} |I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} (I - {}_{x}I_{\xi,N}^{\alpha-1}) G(x,\xi) d\xi |$$
  
$$\leq \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)} ||I_{x,N}^{\alpha-1}||_{\infty} \max_{x \in [-1,1]} |\int_{-1}^{x} (x-\xi)^{\alpha-1} (I - {}_{x}I_{\xi,N}^{\alpha-1}) G(x,\xi) d\xi |$$

YIN YANG, SUJUAN KANG AND VASILIY I. VASIL'EV

$$\leq cN^{1/2} \max_{x \in [-1,1]} \left| \int_{-1}^{x} (x-\xi)^{\alpha-1} (I - {}_{x}I^{\alpha-1}_{\xi,N}) G(x,\xi) d\xi \right|$$

$$\leq cN^{1/2} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} (x-\xi)^{\alpha-1} d\xi \int_{-1}^{x} (x-\xi)^{\alpha-1} (I - {}_{x}I^{\alpha-1}_{\xi,N}) \right] \\ \times \left| G(x,\xi) \right|^{2} d\xi \right]^{1/2}$$

$$\leq cG^{**} N^{1/2-l} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} (x-\xi)^{\alpha-1} (1+\xi)^{l} \left| \partial_{\xi}^{l} \left( Y(\xi) + g(\xi) \right) \right|^{2} d\xi \right]^{1/2}$$

$$\leq cG^{**} N^{1/2-l} \left\| \partial_{\xi}^{l} \left( Y(\xi) + g(\xi) \right) \right\|_{\omega^{\alpha+l-1,l}},$$

$$(55)$$

where

$$g(\xi) = \left(\tilde{g}(T(\frac{\xi+1}{2})^{\sigma}) + \lambda\right), \quad G^{**} = \max_{x \in [-1,1]} \max_{\xi \in [-1,x]} g(x,\xi).$$

Similarly, by Lemma 5.1 and the Cauchy-Schwarz inequality, we obtain

$$|E_{3}| = \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)} |I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} {}_{x} I_{\xi,N}^{\alpha-1} \Big( \hat{G}(x,\xi)(Y-Y_{N}) \Big) \Big) d\xi |$$
  

$$\leq \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)} \|I_{x,N}^{\alpha-1}\|_{\infty} \max_{x \in [-1,1]} |\int_{-1}^{x} (x-\xi)^{\alpha-1} {}_{x} I_{\xi,N}^{\alpha-1} \Big( \hat{G}(x,\xi)(Y-Y_{N}) \Big) \Big) d\xi |$$
  

$$\leq \frac{T^{\alpha}}{2^{\alpha}\Gamma(\alpha)} N^{1/2} \max_{x \in [-1,1]} \Big( \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} d\xi \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} d\xi \int_{-1}^{x_{i}} (x_{i}-\xi)^{\alpha-1} | {}_{x} I_{\xi,N}^{\alpha-1} \Big( \hat{G}(x,\xi)(Y-Y_{N}) \Big) \Big) |^{2} d\xi \Big)^{1/2}.$$
(56)

Using the Lemma 5.3 yields

$$|E_{3}| \leq cN^{1/2} \max_{x \in [-1,1]} \left( \int_{-1}^{x_{i}} (x_{i} - \xi)^{\alpha - 1} |_{x} I_{\xi,N}^{\alpha - 1} \left( \hat{G}(x,\xi)(Y - Y_{N}) \right) |^{2} d\xi \right)^{1/2} \leq cG^{**} N^{1/2} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} (x - \xi)^{\alpha - 1} |_{x} I_{\xi,N}^{\alpha - 1} Y(\xi) - Y(\xi) |^{2} + |Y(\xi) - Y_{N}(\xi)|^{2} d\xi \right]^{1/2} \leq cG^{**} N^{1/2 - l} \|\partial_{x}^{l} Y\|_{\omega^{\alpha + l - 1, l}} + cG^{**} N^{1/2} \|e_{N}\|_{\omega^{\alpha - 1, 0}}.$$
(57)

By Lemma 5.1,

$$|E_{4}|$$

$$= \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)} |I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} (I-{}_{x}I_{\xi,N}^{\alpha-1}) K(x,\xi,\eta) d\theta d\xi |$$

$$\leq \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)} ||I_{x,N}^{\alpha-1}||_{\infty} \max_{x\in[-1,1]} |\int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} (I-{}_{x}I_{\xi,N}^{\alpha-1}) K(x,\xi,\eta) d\theta d\xi |$$

$$\leq cN^{1/2} \max_{x\in[-1,1]} |\int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} (I-{}_{x}I_{\xi,N}^{\alpha-1}) K(x,\xi,\eta) d\theta d\xi |.$$
(58)

We obtain from the Cauchy-Schwarz inequality that

$$|E_{4}|$$

$$\leq cN^{1/2} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} (x-\xi)^{\alpha-1} | \int_{-1}^{1} (I - xI_{\xi,N}^{\alpha-1}) K(x,\xi,\eta) |^{2} d\theta d\xi \right]^{1/2}$$

$$\leq cN^{1/2} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} (x-\xi)^{\alpha-1} | \sum_{k=0}^{N} (I - xI_{\xi,N}^{\alpha-1}) K(x,\xi,\eta) |^{2} d\xi \right]^{1/2}$$

$$\leq cK^{**} (N^{3/2-l} + N^{1/2-l}) \max_{x \in [-1,1]} \max_{\theta_{k} \in [-1,1]} \left[ \int_{-1}^{x} (x-\xi)^{\alpha+l-1} \times (1+\xi)^{l} | \partial_{\xi}^{l} \left( Y(\eta(\xi,\theta_{k})) + \lambda \right) |^{2} d\xi \right]^{1/2}$$

$$\leq cK^{**} (N^{3/2-l} + N^{1/2-l}) \| \partial_{\xi}^{l} Y \|_{\omega^{\alpha+l-1,l}}, \qquad (59)$$

where

$$\begin{split} K(\xi,\eta(\xi,\theta)) &= \tilde{K}\Big(T(\frac{\xi+1}{2})^{\sigma}, T(\frac{\eta(\xi,\theta)+1}{2})^{\sigma}\Big),\\ K^{**} &= \max_{x\in[-1,1]}\max_{\theta_k\in[-1,1]}\max_{\xi\in[-1,x]}g(x,\xi,\theta_k)K(\xi,\eta(\xi,\theta_k)). \end{split}$$

By Lemma 5.1 and 5.3,

$$|E_{5}| = \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)} |I_{x,N}^{\alpha-1} \int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} {}_{x}I_{\xi,N}^{\alpha-1} \hat{K}(x,\xi,\eta)(Y-Y_{N})d\theta d\xi |$$
  

$$\leq \frac{T^{\alpha+1}}{2^{\alpha+1}\Gamma(\alpha)} ||I_{x,N}^{\alpha-1}||_{\infty} \max_{x\in[-1,1]} |\int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} {}_{x}I_{\xi,N}^{\alpha-1} \times \hat{K}(x,\xi,\eta)(Y-Y_{N})d\theta d\xi |$$

$$\leq cN^{1/2} \max_{x\in[-1,1]} |\int_{-1}^{x} (x-\xi)^{\alpha-1} \int_{-1}^{1} {}_{x}I_{\xi,N}^{\alpha-1} \hat{K}(x,\xi,\eta)(Y-Y_{N})d\theta d\xi |.$$
(60)

We further get from the Cauchy-Schwarz inequality that

$$|E_{5}|$$

$$\leq cN^{1/2} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} (x-\xi)^{\alpha-1} d\xi \int_{-1}^{x} (x-\xi)^{\alpha-1} |\int_{-1}^{1} x I_{\xi,N}^{\alpha-1} \hat{K}(x,\xi,\eta) \times (Y-Y_{N}) d\theta |^{2} d\xi \right]^{1/2}$$

$$\leq cN^{1/2} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} (x-\xi)^{\alpha-1} |\int_{-1}^{1} x I_{\xi,N}^{\alpha-1} \hat{K}(x,\xi,\eta) (Y-Y_{N}) d\theta |^{2} d\xi \right]^{1/2}$$

$$\leq cK^{**} N^{1/2} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} x I_{\xi,N}^{\alpha-1} \left( Y(\eta(\xi,\theta_{k})) - Y_{N}(\eta(\xi,\theta_{k})) \right) \right]^{2} d\xi \right]^{1/2}$$

$$\leq c(N^{3/2} + N^{1/2}) K^{**} \max_{x \in [-1,1]} \max_{x \in [-1,1]} \max_{x \in [-1,1]} \max_{x \in [-1,1]} \left[ \int_{-1}^{x} (x-\xi)^{\alpha-1} |x I_{\xi,N}^{\alpha-1} Y(\eta(\xi,\theta_{k})) - Y(\eta(\xi,\theta_{k})) \right]^{1/2} d\xi \right]^{1/2}$$

$$+c(N^{3/2}+N^{1/2})K^{**}\max_{x\in[-1,1]}\max_{\theta_k\in[-1,1]} \left(\sum_{j=1}^{x}(x-\xi)^{\alpha-1} |Y(\eta(\xi,\theta_k))-Y_N(\eta(\xi,\theta_k))|^2 d\xi\right]^{1/2}.$$
 (61)

It follows from Lemma 5.3 that

$$|E_{5}| \leq (N^{3/2} + N^{1/2}) K^{**} \max_{x \in [-1,1]} \max_{\theta_{k} \in [-1,1]} \left[ \int_{-1}^{x} (x - \xi)^{\alpha + l - 1, l} (1 + \xi)^{l} \\ \times |\partial_{\xi}^{l} Y(\eta(\xi, \theta_{k}))|^{2} d\xi \right]^{1/2} + c(N^{3/2 - l} + N^{1/2 - l}) K^{**} \max_{x \in [-1,1]} \\ \times \max_{\theta_{k} \in [-1,1]} \left[ \int_{-1}^{x} (x - \xi)^{\alpha - 1} |e_{N}(\eta(\xi, \theta_{k}))|^{2} d\xi \right]^{1/2}$$

$$\leq c(N^{3/2 - l} + N^{1/2 - l}) K^{**} \|\partial_{x}^{l} Y\|_{\omega^{\alpha + l - 1, l}} \\ + c(N^{3/2} + N^{1/2}) K^{**} \|e_{N}\|_{\omega^{\alpha - 1, 0}}.$$
(62)

In summary, we get

$$\begin{aligned} \|e_N\|_{\infty} \\ &\leq cG^{**}N^{1/2-l} \|\partial_{\xi}^{l} \Big( Y(\xi) + g(\xi) \Big) \|_{\omega^{\alpha+l-1,l}} + cN^{1-l} \|Y\|_{\omega^{-1/2,-1/2}} \\ &+ c(G^{**} + NK^{**} + K^{**})N^{1/2-l} \|\partial_{x}^{l}Y\|_{\omega^{\alpha+l-1,l}} \\ &+ cK^{**} (N^{3/2-l} + N^{1/2-l}) \|\partial_{\xi}^{l}Y\|_{\omega^{\alpha+l-1,l}}. \end{aligned}$$

$$(63)$$

The theorem is proved.

6. **Numerical tests.** In this section, we give numerical examples to illustrate the feasibility and efficiency of the method.

6.1. Example 1. We consider the following fractional integro-differential equation:

$${}_{0}^{c}D_{t}^{\frac{2}{3}}y(t) = \Gamma(\frac{5}{3}) - t^{\frac{8}{3}} - \beta(1,\frac{5}{3})t^{\frac{5}{3}} - t^{2}y(t) + \int_{0}^{t}y(\tau)d\tau,$$
  

$$y_{0} = 0, \quad t \in [0,1].$$
(64)

The exact solution is  $t^{\frac{2}{3}}$ .

In the table 1, we list  $L^{\infty}$ - and  $L^2_{\omega^{\alpha-1,0}}$ -error with N = 10 and  $\sigma$  takes values of 1-9. As can be seen from the table, for  $\sigma$  takes values of 3, 6 and 9, which are multiples of 3, the error decreases faster and the convergence is better. Through a lot of numerical experiments, we conclude that not for all  $\sigma$  taking multiple value of 3, the convergence is better. One cannot predict that the greater the value of  $\sigma$  is, the better the convergence is. There is a critical point, which is the value of 27. For  $\sigma$  takes values of 2 to 27, the error convergence is better than that without smoothing transformation. To be more intuitive, we give a comparison of the exact solution and numerical solution with N = 10 and  $\sigma = 1$ , 3, 6, and 9 in Figures 1 and 2. And in Figure 3, we give  $L^{\infty}$ - and  $L^2_{\omega^{\alpha-1,0}}$ -error between the exact solution and the numerical solution with N = 10 and  $\sigma = 1$  to 9 and 28. Obviously, the error deceases faster when the value of 3, 6 and 9, which is the multiple of 3. Moreover, at the value of 28, the error convergence effect does not work well without smoothing transformation.

Ν	$\sigma = 1$		$\sigma=2$		$\sigma=3$	
	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$
2	4.31E-03	4.31E-03	4.12E-04	5.06E-04	3.21E-05	3.14E-05
4	7.92E-04	7.07E-04	2.76E-05	2.84E-05	2.34E-08	1.87E-08
6	2.63E-04	2.32E-04	5.37E-06	4.37E-06	1.44E-11	1.05E-11
8	1.15E-04	1.01E-04	1.32E-06	1.05E-06	3.00E-15	1.76E-15
10	6.01E-05	5.26E-05	4.08E-07	3.32E-07	2.33E-15	1.20E-15

TABLE 1. The  $L^{\infty}$ - and  $L^2_{\omega^{\alpha-1,0}}$ -error for N = 10 and  $\sigma$  takes values of 1-9.

N	$\sigma = 4$		$\sigma=5$		$\sigma=6$	
	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$
2	6.47E-03	6.21E-03	1.30E-02	1.24E-02	1.72E-02	1.65E-02
4	1.70E-05	1.29E-05	2.40E-05	1.75E-05	6.46E-09	4.82E-09
6	7.51E-07	5.35E-07	4.86E-07	3.18E-07	8.14E-10	5.29E-10
8	7.42E-08	5.85E-08	3.20E-08	2.20E-08	5.97E-12	3.60E-12
10	1.46E-08	1.05E-08	4.08E-09	2.89E-09	3.76E-14	1.94E-14

Ν	$\sigma = 7$		$\sigma = 8$		$\sigma=9$	
	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$
2	1.84E-02	1.77E-02	1.68E-02	1.61E-02	1.27E-02	1.21E-02
4	0.31E-03	0.22E-03	1.03E-03	0.73E-03	2.13E-03	1.52E-03
6	5.14E-07	3.09E-07	8.26E-07	4.92E-07	3.70E-07	2.28E-07
8	1.20E-08	6.94E-09	1.11E-08	5.96E-09	9.08E-10	5.12E-10
10	7.20E-10	4.42E-10	4.26E-10	2.40E-10	3.16E-11	1.68E-11



FIGURE 1. The exact solution and numerical solution for N = 10 and  $\sigma = 1$  and 3.



FIGURE 2. The exact solution and numerical solution for N = 10 and  $\sigma = 6$  and 9.



FIGURE 3. For N = 10,  $\sigma$  takes values of 1-9 and 28, the error of  $L^{\infty}$  and  $L^{2}_{\omega^{\alpha-1,0}}$  changes as the collocation point N increases.

### 6.2. Example 2. Consider

$${}_{0}^{c}D_{t}^{\frac{1}{2}}y(t) = f(t) + \int_{0}^{t} t\tau y(\tau)d\tau, \quad t \in [0,1],$$

$$y_{0} = 0,$$
(65)
where  $f(t) = \frac{\sqrt{\pi}}{2}BesselJ[0,\sqrt{t}] - t\Big(-2(-6+t)\sqrt{t}cos\sqrt{t} + 6(-2+t)sin\sqrt{t}\Big).$ 

The exact solution is  $\sin\sqrt{t}$ .

We list the  $L^{\infty}$ - and  $L^2_{\omega^{\alpha-1,0}}$ -error with N = 10 and  $\sigma$  takes values of 1-6 in Table 2. From the table, we can also see that when  $\sigma$  takes values of 2 and 4, which is the multiple of 2, the error decreases faster. And through a large number of numerical experiments, we get a critical point of  $\sigma$ , which is the value of 14. When  $\sigma$  takes values of 2-13, the error convergence is better than that without smoothing transformation. For the sake of intuition, we give a comparison when N = 10 and  $\sigma$  takes values of 1, 2 and 4 in Figure 4. In Figures 5, the  $L^{\infty}$ - and  $L^2_{\omega^{\alpha-1,0}}$ -error between the exact solution and the numerical solution are given when N = 10 and  $\sigma$  takes values 1-6 and 14. It clear that when  $\sigma$  takes values of 2 and 4, which are multiples of 2, the error is smaller. While  $\sigma$  takes the value of 14, the error is worse than that without smoothing transformation.

TABLE 2. The  $L^{\infty}$ - and  $L^2_{\omega^{\alpha-1,0}}$ -error for N=10 and  $\sigma$  takes values of 1-6.

N	$\sigma=1$		$\sigma=2$		$\sigma=3$	
	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$
2	3.13E-04	4.55E-04	2.79E-04	3.21E-04	1.86E-03	2.14E-03
4	2.30E-05	2.85E-05	2.11E-07	1.85E-07	3.37E-06	3.58E-06
6	4.27E-06	5.23E-06	1.62E-10	1.54E-10	5.11E-07	4.18E-07
8	1.38E-06	1.51E-06	1.01E-13	8.56E-14	6.87E-08	6.62E-08
10	5.29E-07	5.61E-07	4.77E-15	4.36E-15	1.88E-08	1.57E-08

N	$\sigma=4$		$\sigma=5$		$\sigma=6$	
	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$
2	3.94E-03	4.53E-03	5.31E-03	6.11E-03	3.86E-03	4.44E-03
4	2.70E-05	2.51E-05	1.38E-04	1.27E-04	4.51E-04	4.12E-04
6	3.23E-07	2.62E-07	8.69E-07	7.52E-07	1.09E-06	$9.15 \text{E}{-}07$
8	1.44E-09	1.12E-09	5.54E-08	3.90E-08	1.67E-07	1.18E-07
10	3.14E-11	2.70E-11	2.06E-09	1.61E-09	3.68E-09	2.52E-09



FIGURE 4. The exact solution and numerical solution for N=10 and  $\sigma{=}1,\,2$  and 4.



FIGURE 5. For N = 10 and  $\sigma$  takes values of 1-6 and 14, the error of  $L^{\infty}$  and  $L^{2}_{\omega^{\alpha-1,0}}$  changes as the collocation point N increases.

6.3. Example 3. Consider the following equation

$${}_{0}^{c}D_{t}^{\frac{1}{4}}y(t) = f(t) + \int_{0}^{t} te^{\tau}y(\tau)d\tau, \quad t \in [0,1],$$
  
$$y_{0} = 0,$$
 (66)

where  $f(t) = \frac{t}{4} \Big( 2e^t (3-2t)\sqrt{t} - 3\sqrt{\pi} Erfi[\sqrt{t}] + \frac{3\sqrt{\pi}t^{\frac{1}{4}}}{\Gamma(\frac{9}{4})} \Big).$ 

The exact solution is  $y(t) = t\sqrt{t}$ .

10

2.09E-10

2.73E-10

In Table 3, We list the  $L^{\infty}$ - and  $L^2_{\omega^{\alpha-1,0}}$ -error when N = 10 and  $\sigma$  takes values of 1-6. From the table, when  $\sigma$  takes the value of 4, which is the multiple of 4, the error decreases faster and the convergence is better. Through a lot of numerical experiments, we derive a critical point of the  $\sigma$ , which is the value of 8. When  $\sigma$  takes values of 2-7, the error is better than the situation that the smoothing transformation is not performed. We give a comparison when N = 10 and  $\sigma$  takes values of 1, 2 and 4 in Figures 6. In Figure 7, the  $L^{\infty}$ - and  $L^2_{\omega^{\alpha-1,0}}$ -error are given when N = 10 and  $\sigma$  takes values of 1-6 and 8. Obviously, when  $\sigma$  takes multiples of 4, the error decreases faster. However, when  $\sigma$  takes the value of 8, the error is not good without smoothing transformation.

TABLE 3. The  $L^{\infty}$ -and  $L^{2}_{\omega^{\alpha-1,0}}$ -error for N = 10 and  $\sigma$  takes values of 1-6.

N	$\sigma=1$		$\sigma=2$		$\sigma=3$	
	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$
2	3.34E-04	6.18E-04	3.65E-03	6.78E-03	3.94E-02	6.96E-02
4	5.68E-05	9.69E-05	3.54E-06	5.57E-06	1.79E-04	2.87E-04
6	1.17E-05	1.97E-05	1.77E-08	2.78E-08	5.01E-07	7.54E-07
8	3.58E-06	6.02E-06	1.66E-09	2.60E-09	3.82E-09	4.57E-09
10	1.39E-06	2.33E-06	2.68E-10	4.17E-10	2.67E-10	2.90E-10
Ν	$\sigma=4$		$\sigma=5$		$\sigma = 6$	
	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$	$  u - U  _{L^{\infty}}$	$  u - U  _{L^2}$
2	7.75E-02	1.37E-01	9.07E-02	1.60E-01	8.04E-02	1.42E-01
4	7.27E-04	1.25E-03	1.02E-03	1.21E-03	2.33E-03	3.89E-03
6	1.27E-05	1.84E-05	1.00E-04	1.47E-04	3.62E-04	5.36E-04
8	6 24E-08	8 53E-08	1 10E-06	1 50E-06	8 27E-06	$1.13E_{-}05$

8.63E-09

1.13E-08

1.15E-07

1.50E-07



FIGURE 6. The exact solution and numerical solution for N = 10 and  $\sigma = 1$ , 2 and 4.



FIGURE 7. For N = 10 and  $\sigma$  takes values of 1-6 and 8, the error of  $L^{\infty}$  and  $L^{2}_{\omega^{\alpha-1,0}}$  changes as the collocation point N increases.

7. Conclusion. In this paper, we first study in detail the reason why the fractional integro-differential equation has non-smooth solution. We eliminate the singularity of the solution by introducing a smooth transformation. Then we use the Jacobi spectral-collocation method with global and high precision characteristics to solve the transformed equation. Particularly, we have proved that the convergence rate for non-smooth solutions can be enhanced by using a suitable smoothing transformation, which allows us to adjust a parameter in the solution in view of a priori known regularity of the given data. The proposed scheme has many advantages, including (i) ease of implementation, (ii) lower computational cost, and (iii) exponential accuracy. In addition, we give a theoretical proof of the convergence of

collocation method, in both  $L^{\infty}$ -norm and  $L^2_{\omega^{\alpha,\beta}}$ -norm. Finally, we give some specific numerical examples. The numerical results confirm the validity of scheme and the correctness of the conclusions for solving the fractional integro-differential equation. This indicates that the proposed scheme possesses a good prospect in solving fractional integro-differential equations with non-smooth solutions. Next, we will apply the methods in this paper to solve the nonlinear fractional integro-differential equations.

Acknowledgments. This work was supported by National Natural Science Foundation of China Project (11671342, 11771369, and 11931003), the Project of Scientic Research Fund of the Hunan Provincial Science and Technology Department (2020JJ2027, 2018WK4006, and 2019YZ3003), and the Key Project of Hunan Provincial Department of Education (17A210).

#### REFERENCES

- W. M. Ahmad and R. EL-Khazali, Fractional-order dynamical models of love, Chaos Solitons Fractals, 33 (2007), 1367–1375.
- [2] A. Arikoglu and I. Ozkol, Solution of fractional integro-differential equations by using fractional differential transform method, *Chaos Solitons Fractals*, 40 (2009), 521–529.
- [3] A. H. Bhrawy and M. A. Zaky, Shifted fractional-order Jacobi orthogonal functions: Application to a system of fractional differential equations, Appl. Math. Model., 40 (2016), 832–845.
- [4] H. Brunner, Theory and Numerical Solution of Volterra Functional Integral Equations, HIT Summer Seminar, 2010.
- [5] H. Brunner, Collocation Methods for Volterra Integral and Related Functional Differential Equations, Cambridge University Press, 2004.
- [6] H. Brunner, Nonpolynomial spline collocation for Volterra equations with weakly singular kernel, SIAM J. Numer. Anal., 20 (1983), 1106–1119.
- [7] P. Baratella and A. P. Orsi, A new approach to the numerical solution of weakly singular Volterra integral equations, J. Comput. Appl. Math., 163 (2004), 401–418.
- [8] A. Carpinteri and F. Mainardi, Fractals and Fractional Calculus in Continuum Mechanics, Springer Verlag, 1997.
- [9] Y. Chen and T. Tang, Convergence analysis of the Jacobi spectral-collocation methods for Volterra integral equationS with a weakly singular kernel, Math. Comp., 79 (2010), 147–167.
- [10] K. Du, On well-conditioned spectral collocation and spectral methods by the integral reformulation, SIAM J. Sci. Comput., 38 (2016), A3247–A3263.
- [11] F. Ghoreishi and P. Mokhtary, Spectral collocation method for multi-order fractional differential equations, Int. J. Comput. Methods, 11 (2014), 1350072, 23 pp.
- [12] Z. Hao and W. Cao, An improved algorithm based on finite difference schemes for fractional Boundary Value Problems with nonsmooth solution, J. Sci. Comput., 73 (2017), 395–415.
- [13] J. H. He, Nonlinear Oscillation with Fractional Derivative and its Cahpinpalications, International Conference on Vibrating Engineering98, 1998.
- [14] J. H. He, Some applications of nonlinear fractional differential equations and therir approximations, Bulletin of Science Technology and Society, 15 (1999), 86–90.
- [15] C. Huang, Y. J. Jiao, L. L. Wang and Z. M. Zhang, Optimal fractional integration preconditioning and error analysis of fractional collocation method using nodal generalized Jacobi functions, SIAM J. Numer. Anal., 54 (2016), 3357–3387.
- [16] L. Huang, X. F. Li, Y. L. Zhao and X. Y. Duan, Approximate solution of fractional integrodifferential equations by Taylor expansion method, *Comput. Math. Appl.*, **62** (2011), 1127– 1134.
- [17] M. Jani, D. Bhatta and S. Javadi, Numerical solution of fractional integro-differential equations with nonlocal conditions, Appl. Appl. Math., 12 (2017), 98–111.
- [18] Y. J. Jiao, L. L. Wang and C. Huang, Well-conditioned fractional collocation methods using fractional Birkhoff interpolation basis, J. Comput. Phys., 305 (2016), 1–28.
- [19] M. Kolk and A. Pedas, Smoothing transformation and piecewise polynomial collocation for weakly singular Volterra integro-differential equations with weakly singular kernels, WSEAS Trans. Math., 6 (2007), 537-544. http://www.crm.umontreal.ca/AARMS07/pdf/pedas.pdf

- [20] X. Li and T. Tang, Convergence analysis of Jacobi spectral collocation methods for Abel-CVolterra integral equations of second kind, Front. Math. China, 7 (2012), 69–84.
- [21] X. Li and C. Xu, A space-time spectral method for the time fractional diffusion equation, SIAM J. Numer. Anal., 47 (2009), 2108–2131.
- [22] H. Liang and M. Stynes, Collocation methods for general caputo two-point boundary value problems, J. Sci. Comput., 76 (2018), 390–425.
- [23] Ch. Lubich, Runge-Kutta theory for Volterra and Abel integral equations of the second kind, Math. Comp., 41 (1983), 87–102.
- [24] G. Mastroianni and D. Occorsio, Optimal systems of nodes for Lagrange interpolation on bounded intervals. A survey., J. Comput. Appl. Math., 134 (2001), 325–341.
- [25] S. Momani and R. Qaralleh, An efficient method for solving systems of fractional integrodifferential equations, Comput. Math. Appl., 52 (2006), 459–470.
- [26] G. Monegato and L. Scuderi, High order methods for weakly singular integral equations with nonsmooth input functions, *Math. Comp.*, 67 (1998), 1493–1515.
- [27] A. Pedas, E. Tamme and M. Vikerpuur, Smoothing transformation and spline collocation for nonlinear fractional initial and boundary value problems, J. Comput. Appl. Math., 317 (2017), 1–16.
- [28] I. Podlubny, Fractional Differential Equations, Academic Press, Inc., San Diego, CA, 1999.
- [29] J. Shen, T. Tang and L. L. Wang, Spectral Methods. Algorithms, Analysis and Applications, Springer Series in Computational Mathematics, 2011.
- [30] Y. Yang, Y. Chen and Y. Huang, Spectral-collocation method for fractional Fredholm integrodifferential equations, J. Korean Math. Soc., 51 (2014), 203–224.
- [31] Y. Yang, Y. Chen, Y. Huang and H. Wei, Spectral collocation method for the time-fractional diffusion-wave equation and convergence analysis, J. Comput. Appl. Math., 73 (2017), 1218– 1232.
- [32] Y. Yang, W. Qiao, J. Wang and S. Zhang, Spectral collocation methods for nonlinear coupled time fractional Nernest-Planck equations in two dimensions and its convergence analysis, *Comput. Math. Appl.*, 78 (2019), 1431–1449.
- [33] Y. Yang, Y. Chen and Y. Huang, Convergence analysis of the Jacobi spectral-collocation method for fractional integro-differential equations, Acta Math. Sci. Ser. B (Engl. Ed.), 34 (2014), 673–690.
- [34] C. Yang and J. Hou, Numerical solution of Volterra integro-differential equations of fractional order by Laplace decomposition method, International Journal of Mathematical, Computational, Natural and Physical Engineering, 7 (2013), 549–553.
- [35] Y. Yang, Y. Huang and Y. Zhou, Numerical solutions for solving time fractional Fokker-Planck equations based on spectral collocation methods, J. Comput. Appl. Math., 339 (2018), 389– 404.
- [36] Y. Yang, Y. Huang and Y. Zhou, Numerical simulation of time fractional Cable equations and convergence analysis, Numer. Methods Partial Differential Equations, 34 (2018), 1556–1576.
- [37] Y. Yang and E. Tohidi, Numerical solution of multi-Pantograph delay boundary value problems via an efficient approach with the convergence analysis, *Comput. Appl. Math.*, 38 (2019), Paper No. 127, 14 pp.
- [38] M. A. Zaky, Recovery of high order accuracy in Jacobi spectral collocation methods for fractional terminal value problems with non-smooth solutions, J. Comput. Appl. Math., 357 (2019), 103–122.

Received March 2020; revised May 2020.

*E-mail address*: yangyinxtu@xtu.edu.cn *E-mail address*: 15773266037@163.com *E-mail address*: vasvasil@mail.ru