

*Research article***Simplified thermoelectric generator (TEG) with heatsinks modeling and simulation using Matlab and Simulink based-on dimensional analysis****Nganyang Paul Bayendang\*, Mohamed Tariq Kahn and Vipin Balyan**

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**Abstract:** Energy sustainability is becoming paramount today with the focus being on renewable and alternative energy. This manuscript therefore embarks on clean alternative energy rooted in thermoelectricity with focus on thermoelectric generator (TEG). However, a TEG do practically needs heat-exchangers or heatsinks to properly and reliably work but heatsinks present another problem—thermal resistance, which affects a TEG power output and efficiency and thus, must be addressed. Consequently, we investigate a TEG with heatsinks model based-on dimensional analysis using Matlab and Simulink. Our research has three unique contributions. Firstly, we derived the analytical formulas for direct calculations of TEG dimensionless hot and cold sides temperature and by introducing and applying a new dimensionless parameter, the dimensionless temperature difference ( $DT_s$ ). Secondly, we simplified further the new TEG dimensionless hot and cold sides temperature analytical formulas to obtain simpler and simplest forms. Thirdly, we implemented a TEG with heatsinks Matlab/Simulink theoretical model, that employs the simplified dimensional analysis, in which a TEG with heatsinks parameters of interest can be simulated to variously determine the analytical, numerical and graphical results with various optimal options to opt for, before doing a practical design.

**Keywords:** alternative energy; dimensional analysis; energy harvesting; TEG with heatsinks; thermoelectricity

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**Abbreviations and Symbols:**  $a$ : TEG p-n junction thermocouple area in  $m^2$ ;  $A_1$ : TEG hot side heatsink1 total surface area in  $m^2$ ;  $A_2$ : TEG cold side heatsink2 total surface area in  $m^2$ ;  $A_b$ : Heatsink base area in  $m^2$ ;  $\Delta T$ : TEG(s) temperature difference ( $T_h - T_c$ ) in  $^\circ C$  or kelvin;  $DT_s$ : TEG dimensionless

temperature difference;  $\text{Eff}^*$ : TEG dimensionless conversion efficiency;  $h_1$ : TEG hot side heatsink1 convection coefficient;  $h_2$ : TEG cold side heatsink2 convection coefficient; HFD: TEG heat flux density in  $\text{W}/\text{m}^2$ ; HS: Heatsinks; I: TEGs output current in ampere through the TEG;  $k$ : TEG/TEC effective thermal conductivity in  $\text{W}/\text{mK}$ ;  $K$ : TEG/TEC thermal conductance in  $(\text{W}/\text{K})$ ;  $K_1$ : TEG hot side heatsink1 thermal conductance;  $K_2$ : TEG cold side heatsink2 thermal conductance;  $L$ : TEG/TEC p-n junction thermocouple length in meter; LHS: Left Hand Side;  $n$ : TEG/TEC manufacturer p-n thermocouples amount used in a TEG/TEC;  $N$ : TEG number of modules required;  $N_h$ : TEG dimensionless convection conductance;  $N_i$ : TEG-HS dimensionless output current;  $N_k$ : TEG dimensionless thermal conductance;  $N_v$ : TEG-HS dimensionless output voltage ( $V_{os}$ );  $\eta$ : TEG thermal/electrical/conversion efficiency;  $\eta_1$ : TEG hot side heatsink1 fin efficiency;  $\eta_2$ : TEG cold side heatsink2 fin efficiency;  $\eta_h A$ : TEG convection conductance;  $\eta_1 h_1 A_1$ : TEG hot side heatsink1 convection conductance;  $\eta_2 h_2 A_2$ : TEG cold side heatsink2 convection conductance;  $\rho$ : TEG/TEC electrical resistivity in  $\Omega\text{m}$ ;  $\rho_e$ : TEG/TEC effective electrical resistivity in  $\Omega\text{m}$ ;  $P_n$ : TEG normalized output power;  $P_o$ : TEG output power in watt, is the difference between  $Q_h$  and  $Q_c$ ;  $P_{os}$ : TEG dimensionless output power, is the difference between  $Q_h^*(Q_{s1})$  and  $Q_c^*(Q_{s2})$ ;  $Q_c$ : TEG heat emitted on its cold side in watt;  $Q_h$ : TEG heat absorbed on its hot side in watt;  $Q_{s1}$ : TEG hot side dimensionless heat absorbed ( $Q_h^*$ );  $Q_{s2}$ : TEG cold side dimensionless heat released ( $Q_c^*$ );  $r$ : TEG/TEC thermocouples p-n junction unit resistance in ohm; RHS: Right Hand Side;  $R_L$ : TEG electrical load resistance in  $\Omega$  connected to the TEG output;  $R_i$ : TEG/TEC module internal resistance in ohm—also denoted as  $R_R$  in Figure 2;  $r_f$ : TEG dimensionless internal electrical resistance—also denoted as  $r_r$  in Figure 2;  $S$ : TE device Seebeck coefficient in  $\text{V}/\text{K}$ ;  $S_e$ : TEG/TEC effective Seebeck coefficient in  $\text{V}/\text{K}$ ;  $\bar{T}$ : TE device average temperature  $(T_h + T_c)/2$  in K or  $^\circ\text{C}$ ;  $T_1$ : TEG hot side temperature ( $T_h$ );  $T_2$ : TEG cold side temperature ( $T_c$ ); TE: Thermoelectric; TEC: Thermoelectric cooler; TEG: Thermoelectric generator;  $T_i$ : TEG heatsinks fluid dimensionless temperatures ( $T_{is}$ );  $T_{i1}$ : TEG hot side heatsink1 fluid dimensionless temperature;  $T_{i2}$ : TEG cold side heatsink2 fluid dimensionless temperature;  $T_{s1}$ : TEG hot side dimensionless temperature;  $T_{s2}$ : TEG cold side dimensionless temperature;  $T_c$ : Temperature on TEG/TEC cold side in  $^\circ\text{C}$ ;  $T_h$ : Temperature on TEG/TEC hot side in  $^\circ\text{C}$ ;  $T_p$ : TEG/TEC modules quantity in parallel;  $T_s$ : TEG/TEC modules quantity in series;  $V_o$ : TEG module output voltage in volt;  $V_{oc}$ : TEG ideal or open circuit output voltage (consider it as EMF = electromotive force) in volt;  $V_{os}$ : TEG dimensionless output voltage ( $N_v$ );  $V_n$ : TEG normalized output voltage;  $Z$ : TE device figure of merit in per K;  $Z_e$ : TEG/TEC effective figure of merit in per K;  $Z\bar{T}$ : TE device average dimensionless figure of merit;  $ZT_{i2}$ : TEG dimensionless figure of merit at temperature  $T_{i2}$ ;  $ZTA$ : TEG dimensionless figure of merit at temperature  $T_A$  ( $\bar{T}$ )

## 1. Introduction

Indicated in [1], South Africa has pledged its commitments to become a carbon reduced and green economic system, by considering a mixture of energy sources to secure energy sustainability. Upon ratifying the Paris agreement on climate change, renewable energy and energy efficiency frameworks as well as the regulatory policies have been developed and continuously fine-tuned taking into cognizance the current energy dynamics. In this regard, there is necessity and increasing demand for renewable energy to supplement and stabilize the unstable national grid, as well as for private use. These circumstances, warrant our research for an alternative energy rooted in thermoelectricity, with focus on basic residential energy sources and energy efficient loads. Basically, TEGs convert heat to DC power, whereas their dual thermoelectric coolers (TECs), reversibly converts DC power to cold and heat depending on the applied voltage polarity. If TEGs and TECs are properly designed, both can

be relatively energy efficient and helpful for essential domestic energy use such as low-voltage DC power, lighting, heating and cooling. Theoretical frameworks and applications of both TEG and TEC were comprehensively presented in [2–5]; however, they fell short of some practical aspects—which this article seeks to advance as articulated next.

In [4–9], thermoelectricity or thermoelectric (TE) devices (TEGs and TECs), require heatsinks or heat-exchangers to physically and reliably function and maintain a working temperature difference on the TEG and TEC hot and cold sides and most significantly to discharge the internal heat resulting from Joule (Ohmic) heating caused by the current flowing through the TEG/TEC. This Ohmic heating is irreversible and will become excessive if not properly managed and consequently, will cause drop in the output/cooling powers and inefficiency (change in entropy-heat flow will change direction due to increase in the cold side junction temperature). This can as well damage the TEG and TEC as a result of over-heating exceeding the hot and cold sides maximum temperature limit—which will melt the thermoelectric devices p-n junction thermocouples solder joints. The inclusion of heatsinks as a solution to alleviate this over-heating practical limitations in thermoelectric devices, unfortunately as well add/increase the TEGs and TECs hot and cold sides thermal resistances, which then oppose the ideal heat flow, hence making the TE devices inefficient.

To circumvent this thermal resistance problem resulting from adding heatsinks/heat-exchangers, various approaches have been investigated and some are stated briefly as follows. Simplified in [6] is a dimensional analysis by converting thermal resistance to convection conductance when using TEC with heatsinks—which was researched originally in [7]; however, the presentation lacks key analytical formulas. In [8], a TEG with heatsink for waste energy harvesting was analysed and optimised as a Thevenin equivalent circuit and investigated in [9] is a dimensionless model of a TEC functioning at real heat transfer state. Examined in [10], a multi-physics simulations were conducted to examine the thermal and electrical performances of a TEG module sandwiched between hot and cold blocks, whereas in [11], a parametric thermal analysis of TEG performance was done using dimensional analysis and presented in [12] is a numerical simulation and performance analysis of a TEC based on the lattice Boltzmann method. Studied in [13] is a multi-parameters analysis and optimization of a typical TEC using dimensional analysis. Proposed in [14] is a thermal resistance matching for TEC systems whereas examined in [15], is an optimal design of a multi-couple TEG, meanwhile [16] employed a graphical approach to design TEC systems. Demonstrated in [17] is an electron-transparent TEC using nano-particles and condensation thermometry and investigated in [18] is an optimal heat-exchanger in different automobile exhaust temperatures for TEG system using dimensional analysis. From the reviewed studies, the dimensional analysis technique, especially the unique and practical approach presented in [7] to improve TE devices efficiency when used with heatsinks, is of interest. This paper with keen focus on TEG as exemplified in Figure 1, further develops the dimensional analysis, by now employing a simplified Matlab implementation to derive novel analytical formulas to directly calculate a TEG hot and cold sides dimensionless temperature.

Our study was structured around the following points. We begin with the TEG with heatsinks applicable maths developed from [6,7] with now emphasis on the new additional analytical formulas. We derived the TEG hot and cold sides dimensionless temperature, as well as the further optimal simplifications contributed relative to the shortcomings of the formulas/approach used in [7]. In a next step, we depict the TEG with heatsinks simulator easy user interface modeled with Matlab/Simulink. The presentation of our results is followed by discussions as well as validations and lastly we conclude our study with a summary.

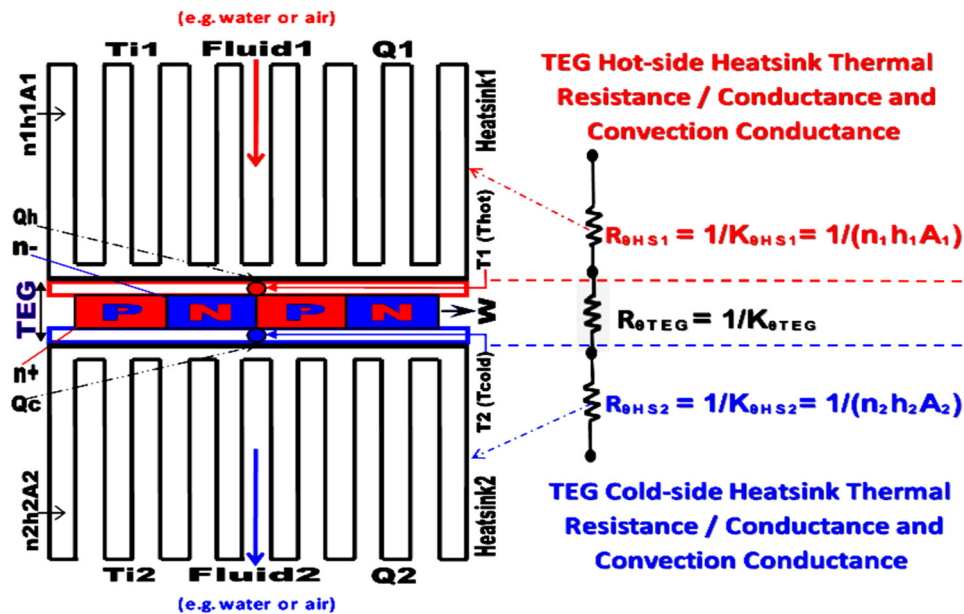


Figure 1. TEG with heatsinks on its hot and cold sides.

## 2. Dimensional analysis mathematics

The relevant mathematics for a TEG with heatsinks is expressed herein and we then introduce the new dimensionless temperature difference (DTs)—which is employed to simplify the apt approach given by [7]. Dimensional analysis is a technique that enables parameters with the same unit to be normalized within a minimum and maximum value, thus making them dimensionless and easier to work with, without worrying about their dimensions or unit of measurement. Nonetheless, novel in [7] is the conversion of TEG heatsinks thermal resistance to their convection conductance. This optimization technique gets rid of the TEG heatsinks thermal resistance which are harder to work with, in favour of the TEG heatsinks fluid convection conductance which are related to the TEG heatsinks fluid temperature and physically simpler to work with. This approach is pragmatic and the mathematical analysis is articulated in what follows.

TEG with heatsinks general heat flow equations:

Herein, the TEG heat flow equations, the heatsinks thermal resistance, their corresponding thermal conductance and convection conductance relationships developed from [6] are constituted as follows:

$$Q_1 = K_1(T_{i1} - T_1) \quad (\text{W}) \quad (1)$$

$$Q_2 = K_2(T_2 - T_{i2}) \quad (\text{W}) \quad (2)$$

With  $Q_1$  and  $Q_2$  being respectively the heat flow rates on the TEG heatsinks hot and cold sides,  $K_1$  and  $K_2$  are respectively the TEG hot and cold sides heatsinks thermal conductance,  $T_{i1}$  and  $T_{i2}$  are respectively the temperatures of the heatsinks fluid on the TEG hot and cold sides and lastly  $T_1$  and  $T_2$  are respectively the TEG hot and cold sides p-n junction temperatures. It is worthy of note that thermal resistance is the reciprocal of thermal conductance  $K$ —which corresponds to the convection conductance ( $hA$ ) and thus, Eqs 1 and 2 in respect of the convection conductance, can be re-written as:

$$Q_1 = \eta_1 h_1 A_1 (T_{i1} - T_1) \quad (\text{W}) \quad (3)$$

$$Q_2 = \eta_2 h_2 A_2 (T_2 - T_{i2}) \quad (\text{W}) \quad (4)$$

With  $\eta_1$  being the fin efficiency of heatsink1 (on the TEG hot-side),  $h_1$  is the convection coefficient of heatsink1 and  $A_1$  is the total surface area of heatsink1. Similarly,  $\eta_2$  is the fin efficiency of heatsink2 (on the TEG cold-side),  $h_2$  is the convection coefficient of heatsink2 and lastly  $A_2$  is the total surface area of heatsink2.

The TEG standard ideal heat flow equations are defined as:

$$Q_h = n[(SIT_1) + (K\Delta T)] - 0.5I^2R \quad (\text{W}) \quad (5)$$

$$Q_c = n[(SIT_2) + (K\Delta T)] + 0.5I^2R \quad (\text{W}) \quad (6)$$

where  $Q_h$  is the heat absorbed on the TEG hot side,  $n$  is the number of p-n junction thermocouples used in the TEG,  $S$  being the Seebeck coefficient,  $I$  being the output current from the TEG,  $K$  is the thermal conductance (computed as  $ak/L$ , with  $a$  being the area of the TEG p-n junction thermocouple,  $k$  is the TEG thermocouple p-n junction thermal conductivity and  $L$  is the TEG thermocouple p-n junction length).  $\Delta T = T_1 - T_2$  is the temperature difference between the TEG hot and cold sides,  $R = nr$  is the TEG module resistance, with  $r$  being the resistance of the TEG thermocouple p-n junction and  $Q_c$  is the heat released on the TEG cold side. The three terms on the right side of Eqs 5 and 6 are the Seebeck, Fourier and Ohmic terms respectively; with  $S$ ,  $K$  and  $R$  considered as temperature invariant. Now, taking into account the energy balance of the TEG with heatsinks system, Eqs 1, 3 and 5 are respectively equivalent now to Eqs 2, 4 and 6—which boils down to (with parameters  $T_1$ ,  $T_2$  and  $I$  being the unknowns):

$$Q_1 = Q_h = K_1(T_{i1} - T_1) = \eta_1 h_1 A_1 (T_{i1} - T_1) = n[(SIT_1) + (K\Delta T)] - 0.5I^2R \quad (\text{W}) \quad (7)$$

$$Q_2 = Q_c = K_2(T_2 - T_{i2}) = \eta_2 h_2 A_2 (T_2 - T_{i2}) = n[(SIT_2) + (K\Delta T)] + 0.5I^2R \quad (\text{W}) \quad (8)$$

With recognition to [7], TEG with heatsinks (HS) is optimised by defining the dimensionless parameters with regards to fluid 2 (water or air on the TEG cold side of heatsink2) and because the optimization is rendered dimensionless relative to fluid 2, fluid 2 temperature ( $T_{i2}$ ) and convection conductance must be given initially. The following dimensionless maths is developed further from [6,7] as:

TEG-HS dimensionless thermal conductance ( $N_k$ ):

This is the ratio of the thermal conductance  $K$  and the convection conductance  $\eta h A$  in fluid 2, deduced as:

$$N_k = K/\eta h A = (ak/l)/\eta_2 h_2 A_2 \quad (9)$$

TEG-HS dimensionless convection ( $N_h$ ):

This is the ratio of fluid 1 and fluid 2 convection conductances, denoted as:

$$N_h = \eta_1 h_1 A_1 / \eta_2 h_2 A_2 \quad (10)$$

TEG-HS dimensionless current ( $N_i$ ):

$$N_i = SI/K = SI/(ak/l) = ZT_{i2} (T_{s1} - T_{s2})/(R_r + 1) \quad (11)$$

TEG dimensionless temperatures ( $T_{s1}$ ,  $T_{s2}$ ,  $T_i$  and  $DT_s$ ):

TEG dimensionless temperatures are presented as:

$$T_1 \text{ dimensionless temperature: } T_{s1} = T_1/T_{i2} \quad (12)$$

$$T_2 \text{ dimensionless temperature: } T_{s2} = T_2/T_{i2} \quad (13)$$

$$\text{Fluids dimensionless temperature: } T_i (T_{is}) = T_{i1}/T_{i2} \quad (14)$$

$$\text{Dimensionless temperature difference } DT_s = T_{s1} - T_{s2} = \Delta T/T_{i2} \quad (15)$$

TEG-HS dimensionless heat absorbed ( $Q_{s1}$ ):

$$Q_{s1} = Q_1/\eta_2 h_2 A_2 T_{i2} \quad (16)$$

TEG-HS dimensionless heat released ( $Q_{s2}$ ):

$$Q_{s2} = Q_2/\eta_2 h_2 A_2 T_{i2} \quad (17)$$

TEG dimensionless output power ( $P_{out^*}$  or  $P_{os}$ ):

$$P_{out^*} = P_{out}/\eta_2 h_2 A_2 T_{i2} \quad (18)$$

$$P_{os} = P_{out^*} = Q_{s1} - Q_{s2} \quad (19)$$

where  $P_{out}$  is the TEG output power (power delivered to the electrical load)

TEG dimensionless output voltage ( $V_{os}$  or  $N_v$ ):

$$N_v = V/nST_{i2} \quad (20)$$

$$N_v = V_{os} = P_{os}/N_i N_k \quad (21)$$

TEG dimensionless conversion efficiency ( $Eff^*$ ):

$$Eff^* = P_{os}/Q_{s1} \quad (22)$$

NB: TEG conversion efficiency by default is dimensionless. The mentioned of dimensionless in front conversion efficiency is just for emphasis on the dimensionless analysis technique used.

TEG-HS dimensionless heat absorbed ( $Q_{s1}$ ) in terms of  $T_{s1}$ :

$$Q_{s1} = N_h (T_i - T_{s1}) \quad (23)$$

TEG-HS dimensionless heat released ( $Q_{s2}$ ) in terms of  $T_{s2}$ :

$$Q_{s2} = T_{s2} - 1 \quad (24)$$

TEG-HS dimensionless internal electrical resistance ( $R_r$ ):

$$R_r = R_L/R_t \quad (25)$$

where  $R_L$  is the electrical load connected to the TEG output and  $R_t$  is the TEG module internal electrical resistance. NB:  $R_r$  is denoted as  $rr$  in the TEG-HS simulator in Figure 2.

As per [7], using the dimensionless Eqs 9–14, Eqs 3–6 reduce to the following two expressions (26) and (27) having five unknowns that must be found for  $T_{s1}$  and  $T_{s2}$  in terms of five independent dimensionless parameters of  $ZT_{i2}$  (dimensionless figure of merit at  $T_{i2}$ ),  $T_i$ ,  $N_h$ ,  $N_k$  and  $R_r$ .

$$N_h(T_i - T_{s1})/N_k = ((ZT_{i2}(T_{s1} - T_{s2})T_{s1})/(R_r + 1)) - (((ZT_{i2}(T_{s1} - T_{s2})^2))/(2(R_r + 1)^2)) + (T_{s1} - T_{s2}) \quad (26)$$

$$(T_{s2} - 1)/N_k = ((ZT_{i2}(T_{s1} - T_{s2})T_{s2})/(R_r + 1)) + (((ZT_{i2}(T_{s1} - T_{s2})^2)/(2(R_r + 1)^2)) + (T_{s1} - T_{s2})) \quad (27)$$

As noticeable, Eqs 26 and 27 are cumbersome and unsolved further in [7] in terms of  $T_{s1}$  and  $T_{s2}$ ; therefore, there are no exact analytical equations to directly compute  $T_{s1}$  and  $T_{s2}$ . Eqs 26 and 27 are awkward closed-form expressions of  $T_{s1}$  and  $T_{s2}$ , which can only be solved by using numerical analysis; as a result, a numerical method using iterations, tables, graphs and approximations were employed by [7], as well as using a computer programme (NEDO) was further recommended. Consequently, because Eqs 26 and 27 could not be simplified further by [7],  $T_{s1}$  and  $T_{s2}$  could only be expressed as in Eqs 28 and 29 as functions of  $ZT_{i2}$ ,  $T_i$ ,  $N_h$ ,  $N_k$  and  $R_r$  for solving numerically.

$$T_{s1} = f(ZT_{i2}, T_i, N_h, N_k, R_r) \quad (28)$$

$$T_{s2} = f(ZT_{i2}, T_i, N_h, N_k, R_r) \quad (29)$$

This entire numerical process is tedious to determine  $T_{s1}$  and  $T_{s2}$ ; thus, this limitation motivated our study to seek for a direct analytical and better solution(s) which are asserted next.

We now introduce Eq 15—the dimensionless temperature difference  $DT_s$ , which is used to replace  $T_{s1} - T_{s2}$  in Eqs 26 and 27 to give Eqs 30 and 31 as:

$$N_h(T_i - T_{s1})/N_k = ((ZT_{i2}(DT_s)T_{s1})/(R_r + 1)) - (((ZT_{i2}(DT_s)^2)/(2(R_r + 1)^2)) + (DT_s)) \quad (30)$$

$$(T_{s2} - 1)/N_k = ((ZT_{i2}(DT_s)T_{s2})/(R_r + 1)) + (((ZT_{i2}(DT_s)^2)/(2(R_r + 1)^2)) + (DT_s)) \quad (31)$$

As instantly apparent, Eqs 30 and 31 can respectively and directly be solved for  $T_{s1}$  and  $T_{s2}$  independently in terms of the five dimensionless parameters  $ZT_{i2}$ ,  $T_i$ ,  $N_h$ ,  $N_k$  and  $R_r$ . Now, making  $T_{s1}$  and  $T_{s2}$  subjects of their respective Eqs 30 and 31, we derived new analytical equations for  $T_{s1}$  and  $T_{s2}$  as given in Eqs 32 and 33 as:

$$T_{s1} = (N_k ZT_{i2} DT_s^2 - 2N_k DT_s R_r^2 - 4N_k DT_s R_r - 2N_k DT_s + 2N_h T_i R_r^2 + 4N_h T_i R_r + 2N_h T_i) / (2(R_r + 1)(N_h + N_h R_r + DT_s ZT_{i2} N_k)) \quad (32)$$

$$T_{s2} = (N_k ZT_{i2} DT_s^2 + 2N_k DT_s R_r^2 + 4N_k DT_s R_r + 2N_k DT_s + 2R_r^2 + 4R_r + 2) / (2(R_r + 1)(R_r - DT_s N_k ZT_{i2} + 1)) \quad (33)$$

Furthermore, by adding Eqs 26 and 27 or Eqs 30 and 31; we can easily get rid of the nonlinear quadratic terms as shown in Eqs 34 and 35 and by re-arranging and solving for  $T_{s1}$  and  $T_{s2}$ , we can further derive a simpler  $T_{s1}$  and  $T_{s2}$  novel analytical formula as shown in Eqs 36 and 37.

$$N_h(T_i - T_{s1})/N_k + (T_{s2} - 1)/N_k = (ZT_{i2} DT_s T_{s1})/(R_r + 1) + (ZT_{i2} DT_s T_{s2})/(R_r + 1) + DT_s + DT_s \quad (34)$$

$$N_h(T_i - T_{s1})/N_k - ((ZT_{i2} DT_s T_{s1})/(R_r + 1)) - DT_s = ((ZT_{i2} DT_s T_{s2})/(R_r + 1)) + (T_{s2} - 1)/N_k + DT_s \quad (35)$$

Equation (34) was re-arranged to give Eq 35, such that the left hand side (LHS) of Eq (35) constitutes  $T_{s1}$  without  $T_{s2}$  and the right hand side (RHS) of Eq 35 constitutes  $T_{s2}$  without  $T_{s1}$ . Finally, the LHS and RHS were both solved independently by equating each to zero, to easily obtain  $T_{s1}$  in terms of  $ZT_{i2}$ ,  $T_i$ ,  $N_h$ ,  $N_k$ ,  $R_r$  and  $DT_s$  (NB: now six unknown parameters) and similarly to obtain  $T_{s2}$  in terms of  $ZT_{i2}$ ,  $N_k$ ,  $R_r$  and  $DT_s$  (NB: now four unknown parameters) to respectively give Eqs 36 and 37 expressed as:

$$T_{s1} = (N_h T_i - DT_s N_k)(R_r + 1)/(N_h + N_h R_r + DT_s N_k ZT_{i2}) \quad (36)$$

$$T_{s2} = (DT_s N_k + 1)(R_r + 1)/(R_r - DT_s N_k ZT_{i2} + 1) \quad (37)$$

As seen,  $T_i$  and  $N_h$  are absent in Eqs 33 and 37, meaning these two dimensionless parameters, don't directly affects  $T_{s2}$  or affects  $T_{s2}$  indirectly through  $T_{s1}$  and  $DT_s$ ; thus, making these equations insightful.

Finally, we furthermore obtained the simplest optimal analytical relationship to calculate  $T_{s1}$  and  $T_{s2}$  by utilizing a set of optimal numerical values given in [7] as:  $ZT_{i2} = 1$ ,  $T_i = 2.6$ ,  $N_h = 1$ ,  $N_k = 0.3$ ,  $R_r = 1.7$  and  $DT_s = 0.8$  and by substituting these values in Eq 35 and solving further, we obtain Eqs 38 and 39 as:

$$T_{s1} = 41T_{s2}/49 + (36/35) \quad (38)$$

$$T_{s2} = 49(T_{s1} - (36/35))/41 \quad (39)$$

It should be noted that, the  $ZT_{i2} = 1$ ,  $T_i = 2.6$ ,  $N_h = 1$ , at  $N_k = 0.3$ ,  $R_r = 1.7$  and now  $DT_s = 0.8$  optimal values set are not arbitrarily chosen but specifically deduced optimal values, that are inter-linked to each other and obtained under the same specified operating conditions. Furthermore, parameters  $ZT_{i2}$ ,  $T_i$  and  $N_h$  are initially provided or can be calculated from a chosen TEG-HS operating parameters and finally the optimal combinations of  $N_k$ ,  $R_r$  and now  $DT_s$ , can all be established from the above specified dimensionless equations. NB: other optimal values set can be used in Eq 35 to get new Eqs 38 and 39 also.

Now, to validate our new  $T_{s1}$  and  $T_{s2}$  formulas, we substitute this the same chosen set of optimal values (given in [7]) of  $ZT_{i2} = 1$ ,  $T_i = 2.6$ ,  $N_h = 1$ ,  $N_k = 0.3$ ,  $R_r = 1.7$  and  $DT_s = 0.8$  to finally determine, compare and verify the  $T_{s1}$  and  $T_{s2}$  values by using our newly derived simple, simpler and simplest analytical formulas; respectively using Eqs 32 and 33, Eqs 36 and 37 and Eqs 38 and 39 as follows:

Using the now simple formulas (Eqs 32 and 33),  $T_{s1}$  and  $T_{s2}$  are optimally directly computed as:

$$T_{s1} = 2.1794$$

$$T_{s2} = 1.3754$$

Using the now simpler formulas (Eqs 36 and 37),  $T_{s1}$  and  $T_{s2}$  are optimally directly deduced as:

$$T_{s1} = 2.1673$$

$$T_{s2} = 1.3610$$

As seen, both these new simple and simpler optimal solutions are approximately the same. We can then also easily verify both with Eqs 38 and 39 to get the simplest solution, by substituting  $T_{s2}$  to calculate  $T_{s1}$  or vice versa. We've now introduced three new analytical sets of formulas to easily compute  $T_{s1}$  and  $T_{s2}$  without going through the cumbersome numerical process. With  $T_{s1}$  and  $T_{s2}$  easily deduced, the other dimensionless parameters and ultimately all their physical dimensional parameters, can then be worked out using Eqs 1–25.

### 3. Model simulator

The relevant TEG with heatsinks mathematics based on dimensional analysis was articulated in Section 2 and the formulas for  $T_{s1}$  and  $T_{s2}$  were developed and expressed analytically in respect of



the now six independent parameters  $ZT_{i2}$ ,  $T_i$ ,  $N_k$ ,  $N_h$ ,  $R_r$  and  $DT_s$ . Furthermore,  $T_{s1}$  and  $T_{s2}$  were optimally simplified and validated in terms of  $T_{s1}$  and  $T_{s2}$  using Eqs 38 and 39. As apparent, the entire numerical as well as analytical procedures could be very tedious and as well subject to errors if manually done. In view of this, a Matlab and Simulink TEG model with heatsinks on both the TEG hot and cold sides, was then implemented using the formulas asserted in Section 2. Enclosed in the simulated TEG with heatsinks model, are the followings: i) The TEG parameters analysed in Section 2, which include;  $S$  the Seebeck coefficient,  $273.15$  the absolute temperature in kelvin,  $T_{i1}$  fluid temperature of heatsink1,  $T_{i2}$  fluid temperature of heatsink2, if required the TEG configuration in series  $T_s$  and or in parallel  $T_p$ ,  $r$  the TEG thermocouple p-n junction resistance,  $k$  the TEG thermocouple p-n junction thermal conductivity,  $P$  the TEG thermocouple p-n junction electrical resistivity,  $a$  the TEG thermocouple p-n junction area,  $L$  the TEG thermocouple p-n junction length and  $P_{req}$  the TEG total output power required. ii) The heatsinks parameters, which include;  $Ab$  the heatsink base area,  $n_1$  fins efficiency of heatsink1,  $h_1$  convection coefficient of heatsink1 fluid,  $A_1$  total area of heatsink1 with fins sides,  $n_2$  fins efficiency of heatsink2,  $h_2$  convection coefficient of heatsink2 fluid and  $A_2$  total area of heatsink2 with fins sides. All these parameters can easily be input in the model simulator and the TEG optimal parameters value computed as depicted in Figure 2.

Additionally, the TEG dimensionless parameters such as;  $N_i$  the dimensionless output current,  $N_k$  the dimensionless thermal conductance,  $Eff^*(n_{th})$  the conversion efficiency,  $P_{os}$  ( $W_{s1}$ ) the dimensionless output power,  $T_{s1}$  the TEG hot-side dimensionless temperature,  $T_{s2}$  the TEG cold-side dimensionless temperature and  $N_v$  the dimensionless output voltage, can all be either manually entered (as depicted in Figure 2 on the left side of the TEG with heatsinks model) or computed automatically. They're then used to finally calculate the TEG practical parameters values in SI units (as shown in Figure 2 on the right side of the TEG with heatsinks model). Some of the TEG physical parameters of interest that are computed include;  $Z$  the TEG figure of merit,  $n$  the TEG amount of p-n junction thermocouples,  $Q_h$  ( $Q_1$ ) the TEG hot side heat absorbed,  $Q_c$  ( $Q_2$ ) the TEG cold side heat released,  $P_o$  the TEG output power,  $T_1$  ( $T_h$ ) the TEG hot side temperature,  $T_2$  ( $T_c$ ) the TEG cold side temperature,  $R_R$  ( $R_i$ ) the TEG internal resistance,  $V_o$  the TEG output voltage,  $V_{oc}$  is the TEG ideal output voltage,  $I$  the TEG output current,  $N$  the total amount of TEG modules required,  $DT$  or  $\Delta T$  the TEG temperature difference and  $QPD$  is TEG with heatsinks heat flux density. The computed heatsinks parameters are:  $nhA$  the dimensionless convection conductance of heatsinks 1 or 2 fluid,  $T_{i1}$  and  $T_{i2}$  are fluids 1 and 2 hot and cold temperatures respectively,  $T_i$  the dimensionless fluid temperature,  $N_h$  the dimensionless convection conductance,  $ZT_{i2}$  the dimensionless figure of merit at  $T_{i2}$ ,  $ZTA$  the TEG dimensionless figure of merit at  $TA$ . The TEG with heatsinks normalised, maximum and effective parameters are also computed.

In terms of the aesthetics, the TEG-HS output and inputs parameters were sorted together based on their commonalities, as well as labeled and colour coded accordingly to make the TEG with heatsinks model simple to comprehend and as well user friendly as shown in Figure 2.

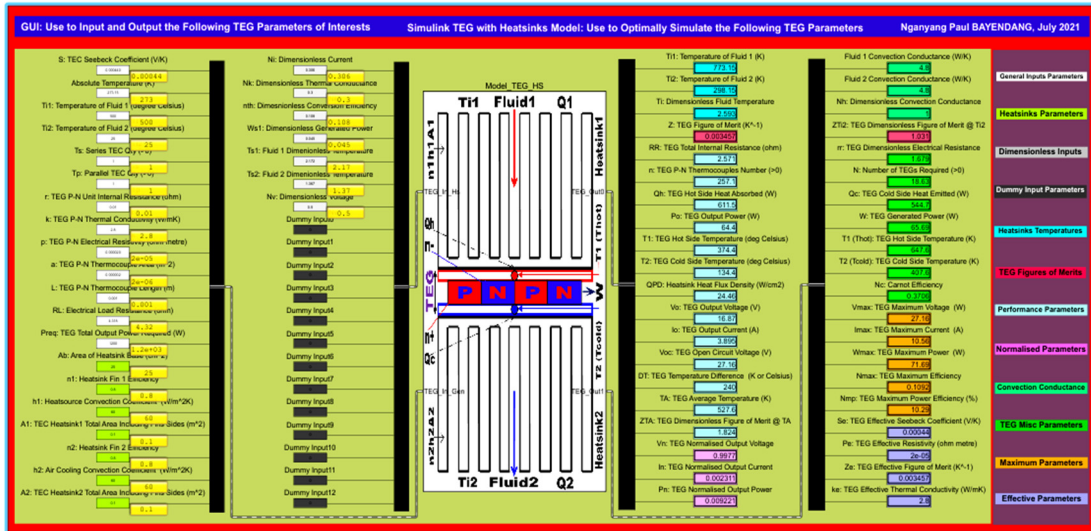


Figure 2. TEG with heatsinks model simulator.

Finally, in addition to the TEG with heatsinks numeric model computations, miscellaneous characteristics curves of some of the TEG crucial parameters of interest such as  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $Eff^*$ ,  $T_{s1}$  and  $T_{s2}$ ; were plotted against  $N_k$ ,  $R_r$  and  $DT_s$  to graphically calculate  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $Eff^*$ ,  $T_{s1}$  and  $T_{s2}$  different optimal values for  $ZT_{i2} = 1$ ,  $N_h = 1$ ,  $T_i = 2.6$ ,  $N_k = 0.1 - 0.4$ ,  $R_r = 0.5 - 2$  and  $DT_s = 0.1 - 1$ . These graphical results are in details, variously demonstrated next in Figures 3 to 6 and with the highlights summarised in Table 1.

Table 1. Summary of the study comparing the “simple” and “simpler” equations results in Figures 3–6.

	$R_r$	$N_k$	$DT_s$	$T_{s1}-T_{s2}$	$Q_{s1}$	$Q_{s2}$	$P_{os}$	$Eff^*$	$T_{s1}$	$T_{s2}$
Using “Simple” Eqs 32 and 33	2	0.3	0.8	0.83564	0.404938	0.35942	0.045518	0.112407	2.19506	1.35942
	1.7	0.3	0.8	0.80401	0.420599	0.375429	0.0451302	0.10731	2.17944	1.37543
	1.1	0.3	0.8	0.7129	0.462515	0.424578	0.0379377	0.0820247	2.13748	1.42458
	1	0.3	0.8	0.69221	0.471429	0.436364	0.0350649	0.0743802	2.12857	1.43636
	0.5	0.3	0.8	0.54428	0.528736	0.526984	0.00175151	0.00331263	2.07126	1.52698
Using “Simpler” Eqs 36 and 37	2	0.3	0.8	0.83736	0.414815	0.347826	0.0669887	0.161491	2.18519	1.34783
	1.7	0.3	0.8	0.80637	0.432653	0.360976	0.0716775	0.16567	2.16735	1.36098
	1.1	0.3	0.8	0.71795	0.482051	0.4	0.0820513	0.170213	2.11795	1.4
	1	0.3	0.8	0.69805	0.492857	0.409091	0.0837662	0.16996	2.10714	1.40909
	0.5	0.3	0.8	0.55829	0.565517	0.47619	0.0893268	0.157956	2.03448	1.47619

#### 4. Simulation results, discussions and validation

In Section 3, the TEG with heatsinks simulated model was presented with highlights on its various parameters and the numeric results, as exemplified in Figure 2 and summarised in Table 2. These results as well as the numerous graphical results displayed extensively next, are based on the new simple and simpler analytical  $T_{s1}$  and  $T_{s2}$  formulas derived in Section 2. These are comparatively engaged and displayed next and various comparisons of  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  with different combinations of  $ZT_{i2}$ ,  $N_h$ ,  $T_i$ ,  $N_k$ ,  $R_r$  and  $DT_s$  using the simple Eqs 32 and 33 as well as using the simpler Eqs 36 and 37 are shown and organised as follows. i) all the figures on the left are based on using the simple Eqs 32 and 33  $T_{s1}$  and  $T_{s2}$  values, whereas all the figures on the right are based on using the simpler Eqs 36 and 37  $T_{s1}$  and  $T_{s2}$  values. ii) Figure 3 graphs depict  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$

and  $Eff^*$  results using  $ZT_{i2} = 1, N_h = 1, T_i = 2.6, N_k = 0.1 - 0.4, R_r = 0 - 6$  and  $DT_S = 0.8$ . iii) Figure 4 graphs depict  $Q_{s1}, Q_{s2}, P_{os}, T_{s1}, T_{s2}$  and  $Eff^*$  results using  $ZT_{i2} = 1, N_h = 1, T_i = 2.6, N_k = 0.05 - 0.5, R_r = 0.5 - 2$  and  $DT_S = 0.8$ . iv) Figure 5 graphs depict in 3D  $Q_{s1}, Q_{s2}, P_{os}, T_{s1}, T_{s2}$  and  $Eff^*$  results with  $ZT_{i2} = 1, N_h = 1, T_i = 2.6, N_k = 0.3, R_r = 0.2 - 3.2$  and  $DT_S = 0.1 - 1$ . v) Figure 6 graphs depict in 3D  $Q_{s1}, Q_{s2}, P_{os}, T_{s1}, T_{s2}$  and  $Eff^*$  results using  $ZT_{i2} = 1, N_h = 1, T_i = 2.6, N_k = 0.05 - 0.5, R_r = 1.7$  and  $DT_S = 0.1 - 1$ . Table 1 summarises the comparison of the simple Eqs 32 and 33 results and the simpler Eqs 36 and 37 results. Figures 2–6 results are also provided as supplementary picture files to enable every aspect of our findings to be viewed clearly in high quality without ambiguities.

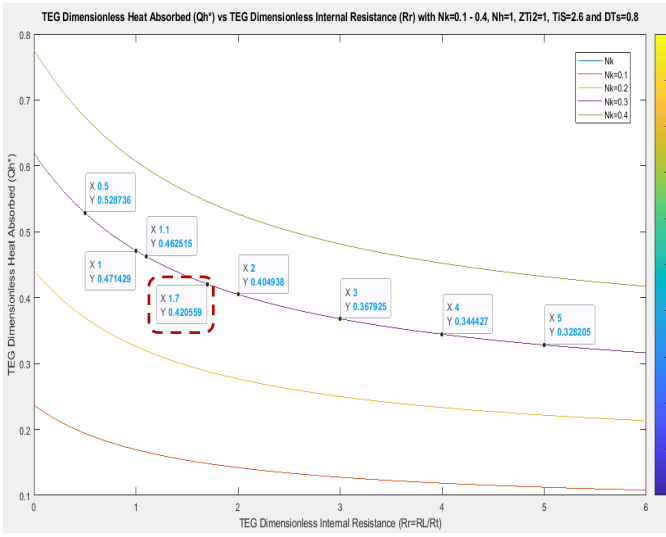
**Table 2.** Summary of Figure 2 (TEG-HS model simulator) simulation results.

Input Parameters				Output Parameters			
TEG Parameters		Heatsinks Parameters		Heatsink Fluids Temps		Convection Conductances	
$S$ (V/K)	0.00044	$Ab$ (W/cm <sup>2</sup> )	25	$T_{i1}$ (K)	773.15	$\eta_1 h_1 A_1$ (W/K)	4.8
Absolute T (K)	273.15	$n_1$	0.8	$T_{i2}$ (K)	298.15	$\eta_2 h_2 A_2$ (W/K)	4.8
$T_{i1}$ (°C)	500	$h_1$ (W/m <sup>2</sup> K)	60	$T_i$	2.593	$N_h$	1
$T_{i2}$ (°C)	25	$A_1$ (m <sup>2</sup> )	0.1	Figures of Merit		Dimensionless Heat Flows	
$T_s$	1	$n_2$	0.8	$Z$ (K <sup>-1</sup> )	0.003457	$Q_{s1}$	0.420599
$T_p$	1	$h_2$ (W/m <sup>2</sup> K)	60	$ZT_{i2}$	1.031	$Q_{s2}$	0.375429
$R$ (Ω)	0.01	$A_2$ (m <sup>2</sup> )	0.1	TEG Practical Performance Parameters			
$k$ (W/mK)	2.8	Dimensionless Parameters		RR (Ω)	2.571	$R_r$ (rr)	1.679
$P$ (Ωm)	0.00002	$N_i$	0.306	$n$	257.1	$N$	18.63
$a$ (m <sup>2</sup> )	0.000002	$N_k$	0.3	$Q_h$ ( $Q_1$ ) (W)	611.5	$Q_c$ ( $Q_2$ ) (W)	544.7
$L$ (m)	0.001	$n_{ih}$ ( $Eff^*$ )	0.108	$P_o$ (W)	64.4	$W_n$ (W)	65.69
$R_L$ (Ω)	4.32	$W_{s1}$ ( $Pos$ )	0.045	$T_1$ ( $T_h$ ) (°C)	374.4	$T_1$ ( $T_h$ ) (K)	647.6
$P_{req}$ (W)	1200	$T_{s1}$	2.172	$T_2$ ( $T_c$ ) (°C)	134.4	$T_2$ ( $T_c$ ) (K)	407.6
		$T_{s1}$	1.367	QPD (W/cm <sup>2</sup> )	24.46	$N_c$	0.3706
		$N_v$	0.5	$V_o$ (V)	16.87	$V_{max}$ (V)	27.16
		$DT_S$	0.8	$I_o$ (A)	3.896	$I_{max}$ (A)	10.56
		NB: the dimensionless parameters here can both be inputs and outputs		$V_{oc}$ (V)	27.16	$W_{max}$ (W)	71.69
				$\Delta T$ (°C)	240	$N_{max}$	0.1092
				TA (°C)	527.6	$Nmp_{max}$ (%)	10.29
				ZTA (°C)	1.824	$\Delta T$ (K)	240

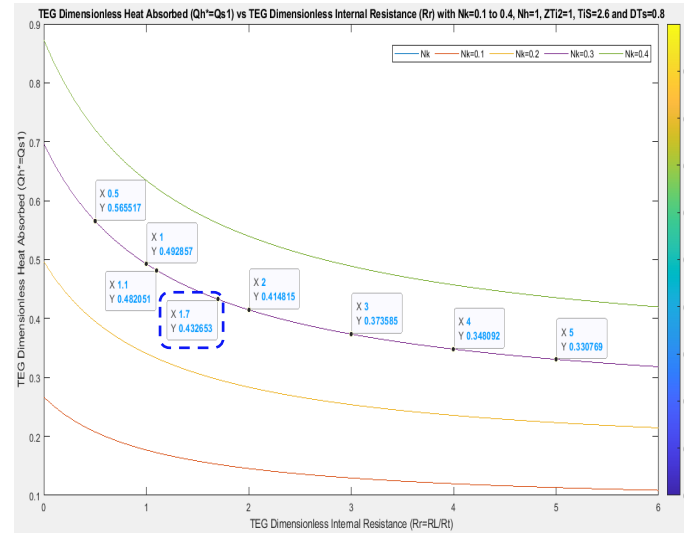
Figure 3 graphs depict  $Q_{s1}, Q_{s2}, P_{os}, T_{s1}, T_{s2}$  and  $Eff^*$  results using  $ZT_{i2} = 1, N_h = 1, T_i = 2.6, N_k = 0.1 - 0.4, R_r = 0 - 6$  and  $DT_S = 0.8$ . It also compares the newly introduced simple vs simpler equations results.

$N_k = 0.1 - 0.4$ : Using “simple” Eqs 32 and 33

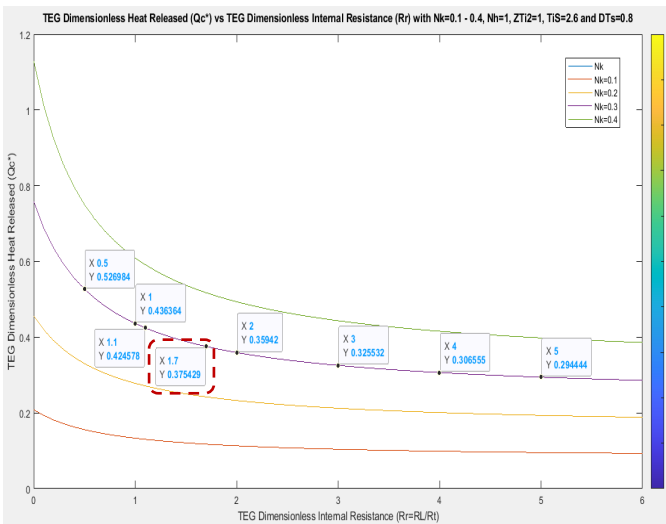
$N_k = 0.1 - 0.4$ : Using “simpler” Eqs 36 and 37



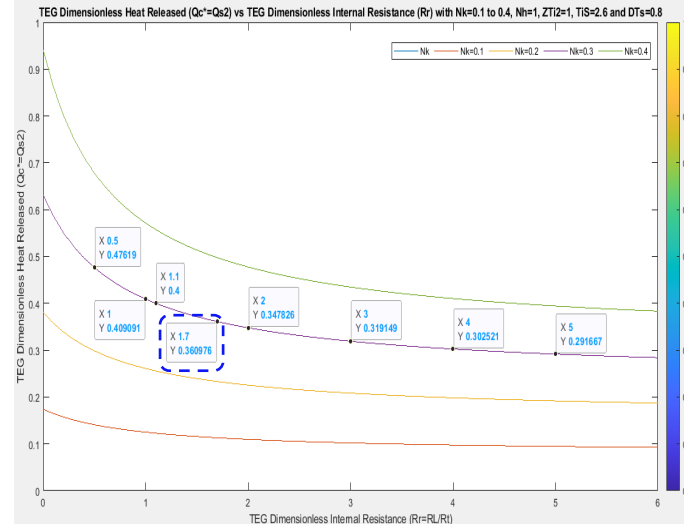
(a)



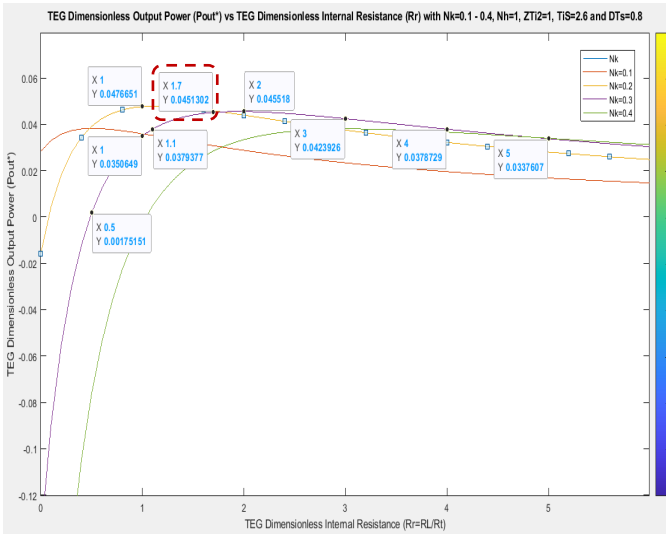
(g)



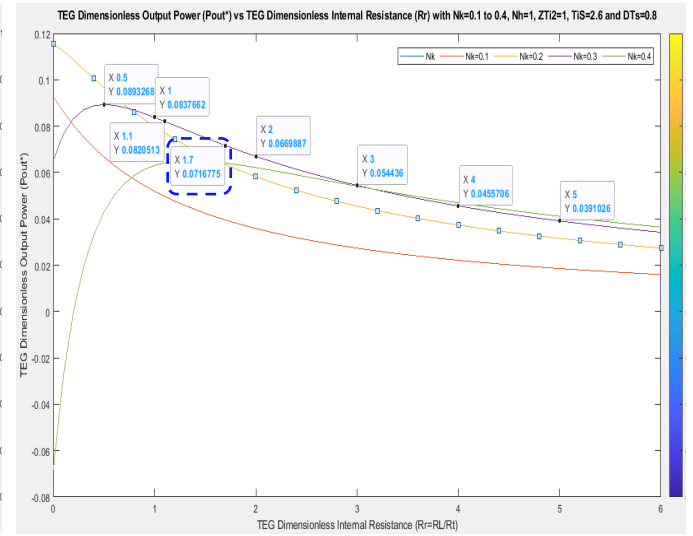
(b)



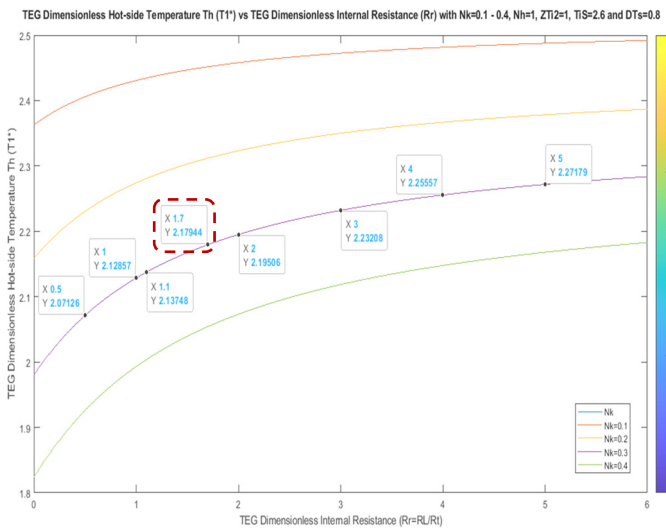
(h)



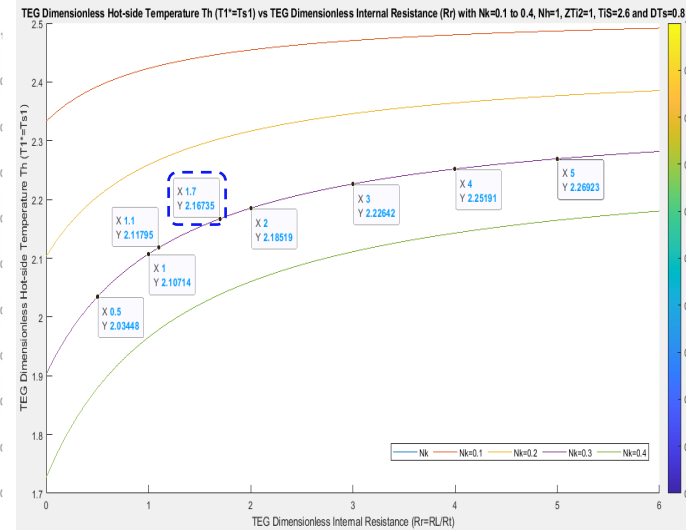
(c)



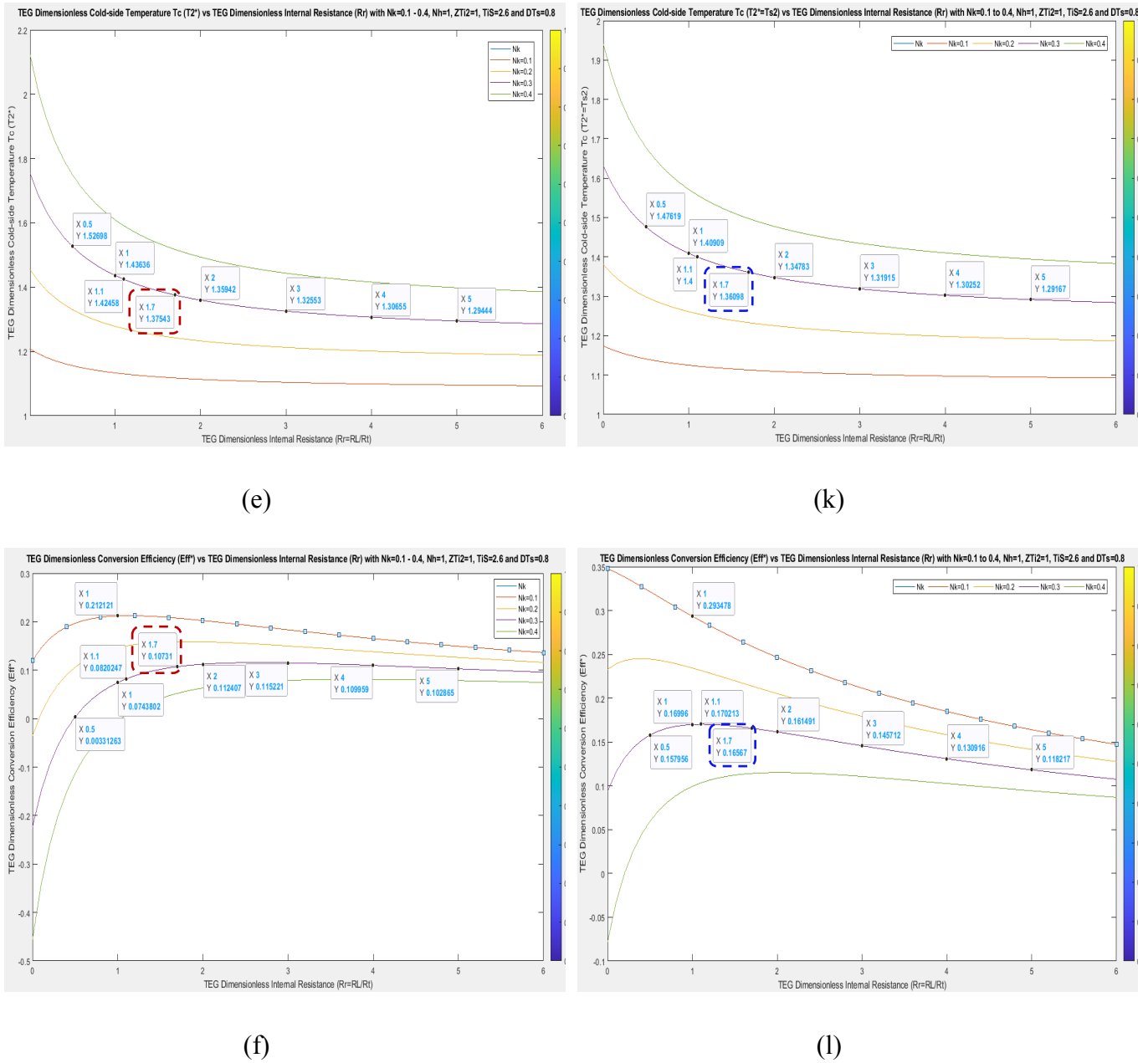
(i)



(d)



(j)

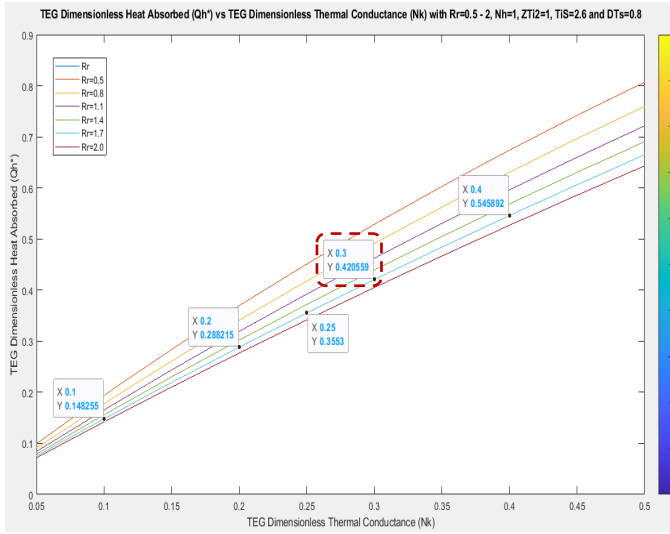


**Figure 3.** Performance and comparison plots of the: i) simple Eqs 32 and 33; (a)  $Q_{s1}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (b)  $Q_{s2}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (c)  $P_{os}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (d)  $T_{s1}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (e)  $T_{s2}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (f)  $Eff^*$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; ii) versus simpler Eqs 36 and 37; (g)  $Q_{s1}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (h)  $Q_{s2}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (i)  $P_{os}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (j)  $T_{s1}$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ ; (k)  $T_{s2}$  vs  $R_r$  @  $N_k = 0.3$ ; (l)  $Eff^*$  vs  $R_r$  @  $N_k = 0.1 - 0.4$ .

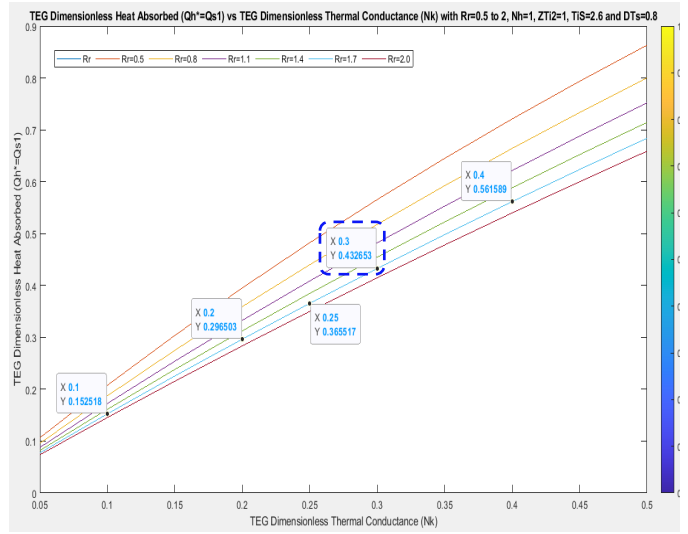
Figure 4 graphs depict  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  results using  $ZT_{i2} = 1$ ,  $N_h = 1$ ,  $T_i = 2.6$ ,  $N_k = 0.05 - 0.5$ ,  $R_r = 0.5 - 2$  and  $DT_S = 0.8$ . It also compares the newly introduced simple vs simpler formulas results.

$R_r = 0.5 - 2$ : Using “simple” Eqs 32 and 33

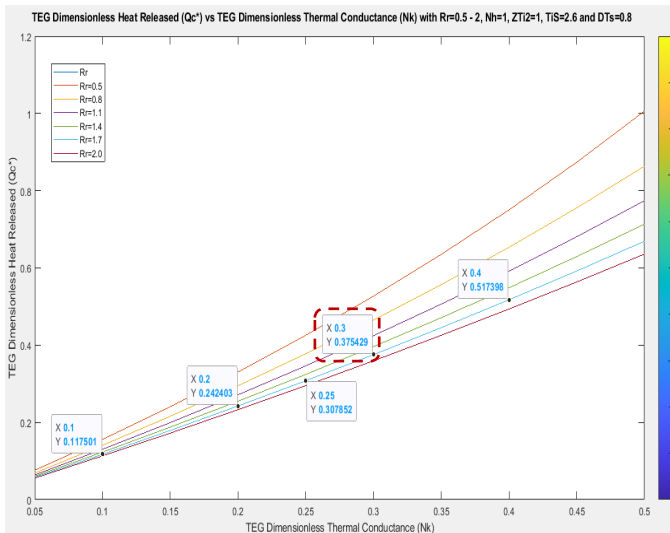
$R_r = 0.5 - 2$ : Using “simpler” Eqs 36 and 37



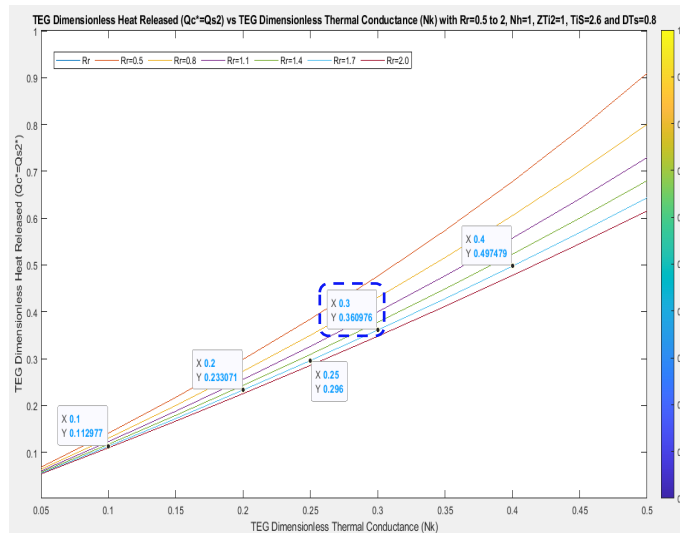
(a)



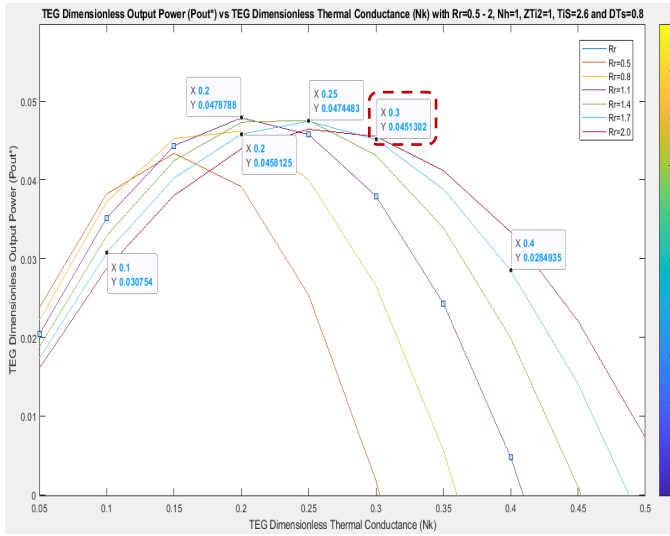
(g)



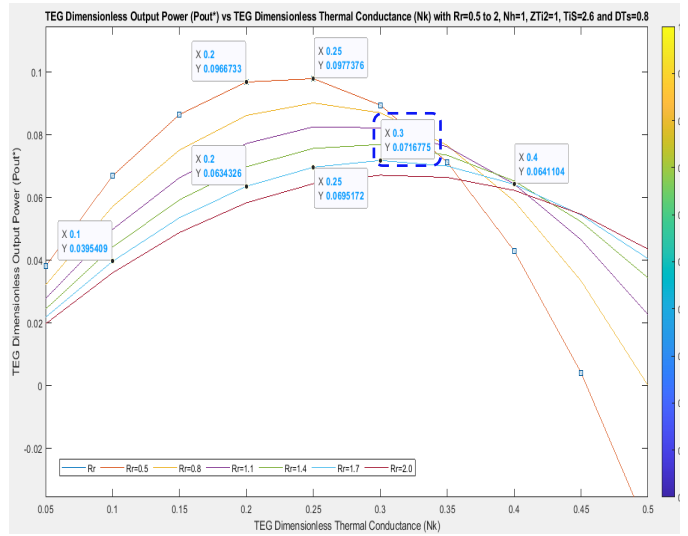
(b)



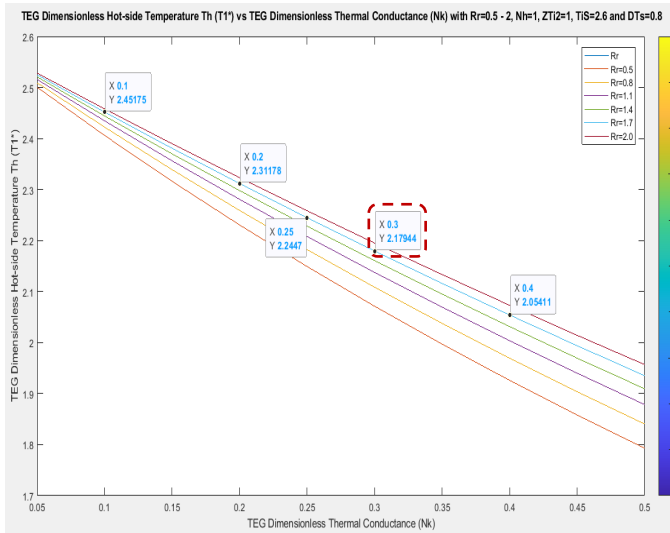
(h)



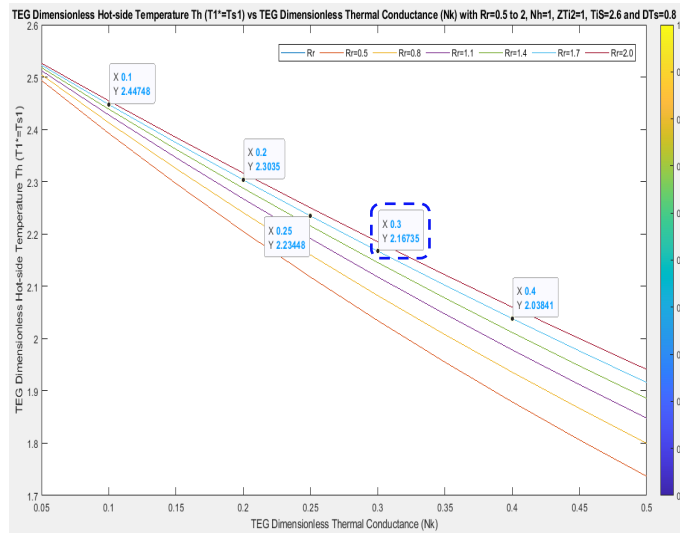
(c)



(i)

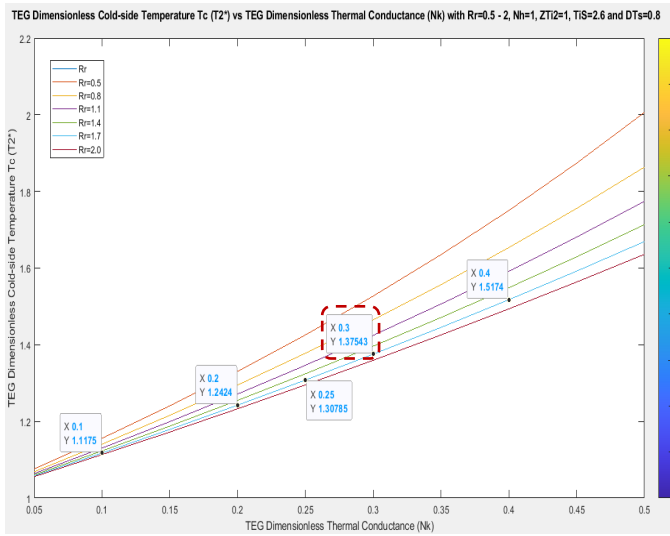


(d)

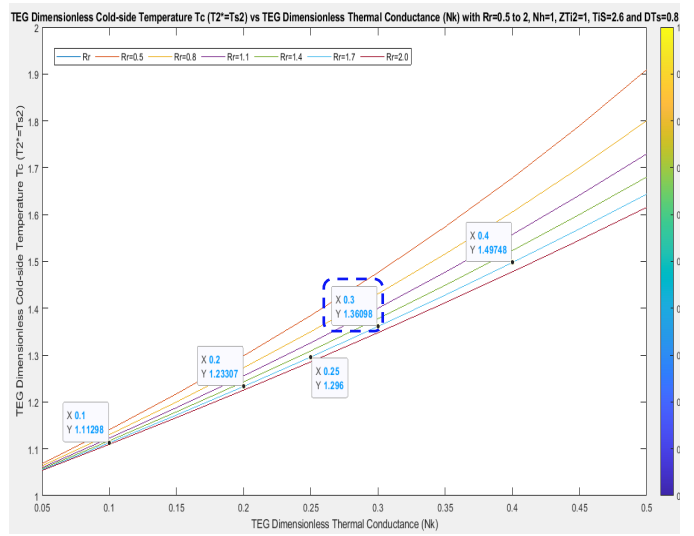


(j)

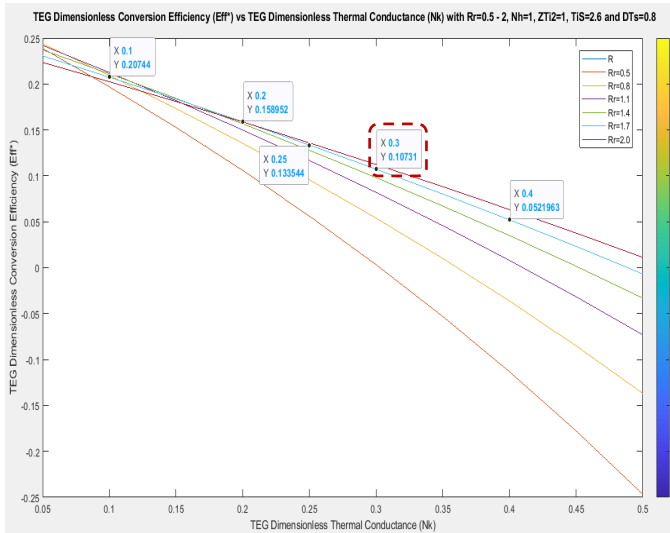




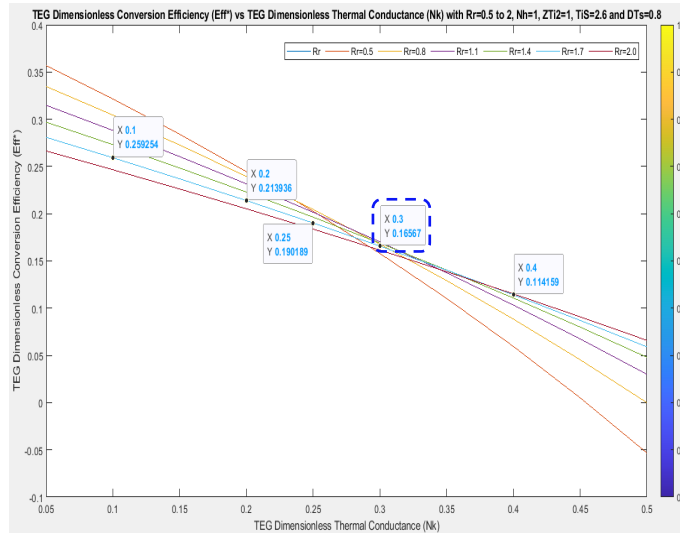
(e)



(k)



(f)



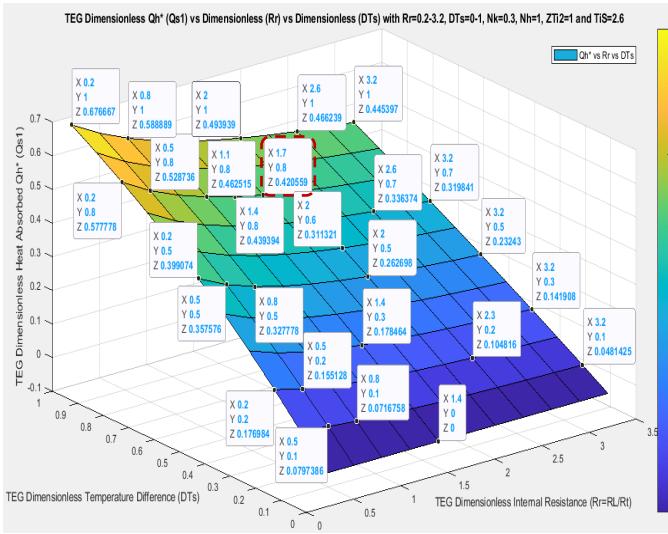
(l)

**Figure 4.** Performance and comparison plots of the: i) simple Eqs 32 and 33; (a)  $Q_{s1}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (b)  $Q_{s2}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (c)  $P_{os}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (d)  $T_{s1}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (e)  $T_{s2}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (f)  $Eff^*$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; versus ii) simpler Eqs 36 and 37; (g)  $Q_{s1}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (h)  $Q_{s2}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (i)  $P_{os}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (j)  $T_{s1}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (k)  $T_{s2}$  vs  $N_k$  @  $R_r = 0.5 - 2$ ; (l)  $Eff^*$  vs  $N_k$  @  $R_r = 0.5 - 2$ .

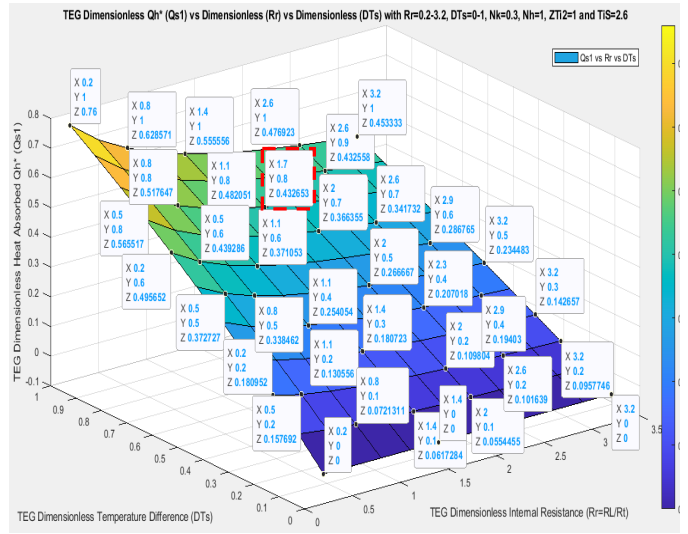
Figure 5 graphs depict in 3D  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  results with  $ZT_{i2} = 1$ ,  $N_h = 1$ ,  $T_i = 2.6$ ,  $N_k = 0.3$ ,  $R_r = 0.2 - 3.2$  and  $DT_s = 0.1 - 1$ . The newly introduced simple vs simpler equations results are also correlated.

$R_r$  vs  $DT_s$ : Using “simple” Eqs 32 and 33

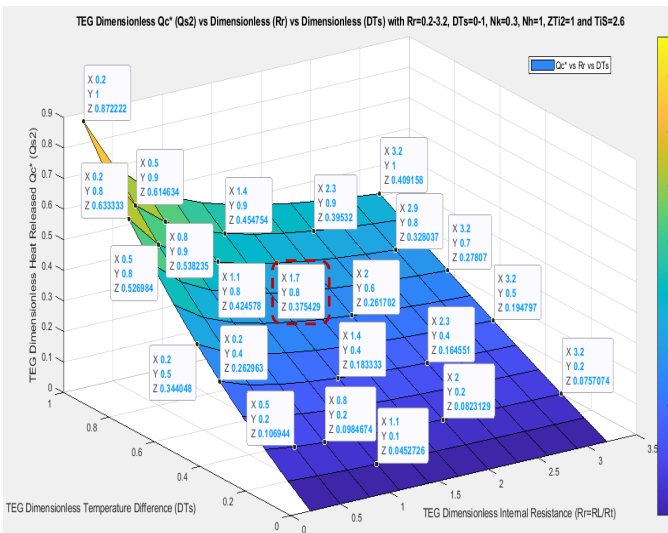
$R_r$  vs  $DT_s$ : Using “simpler” Eqs 36 and 37



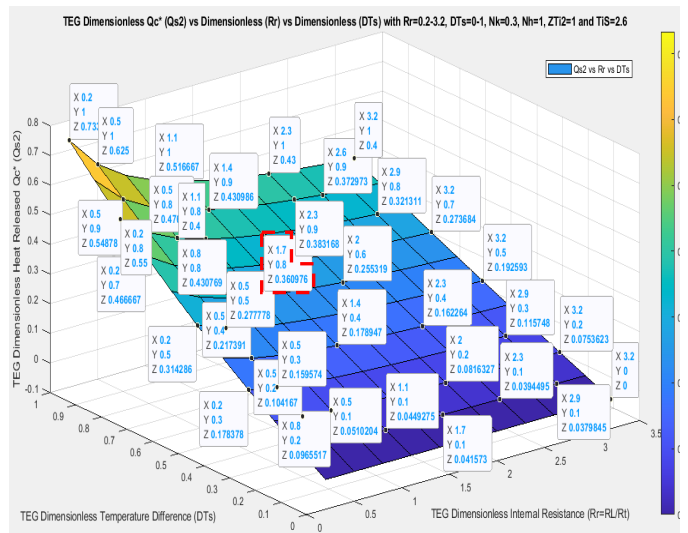
(a)



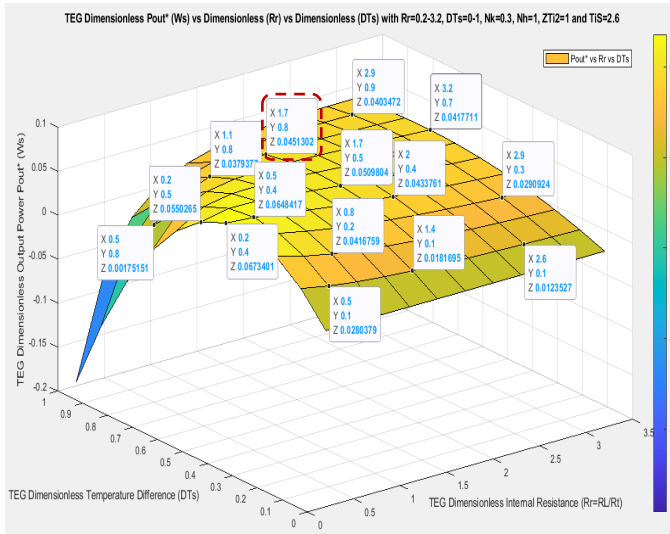
(g)



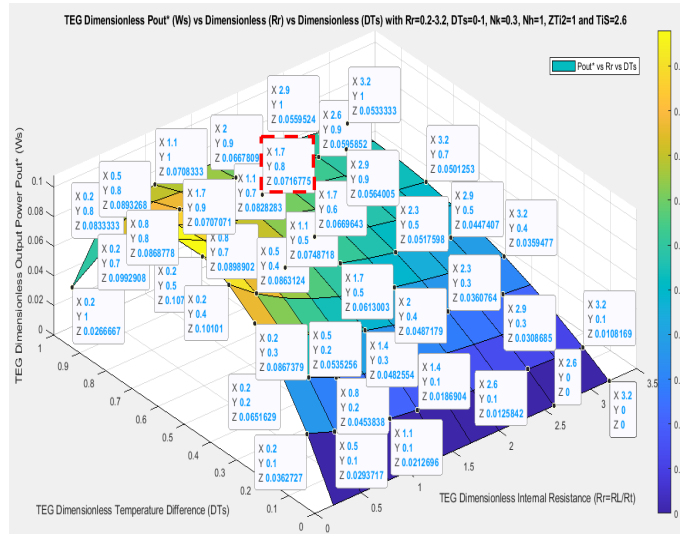
(b)



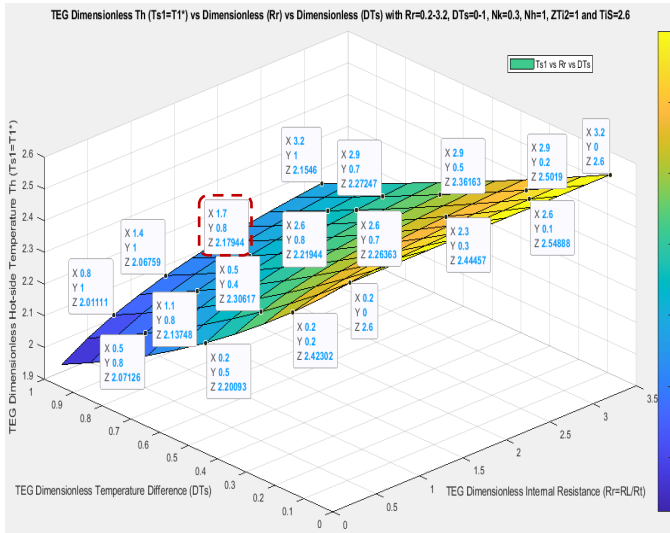
(h)



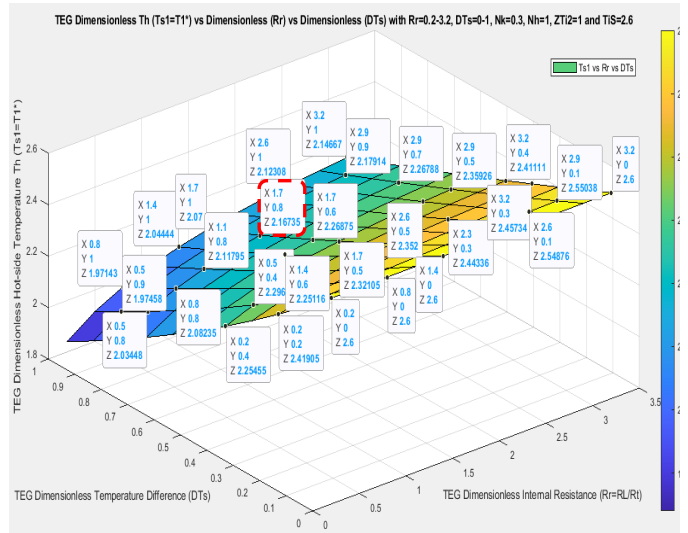
(c)



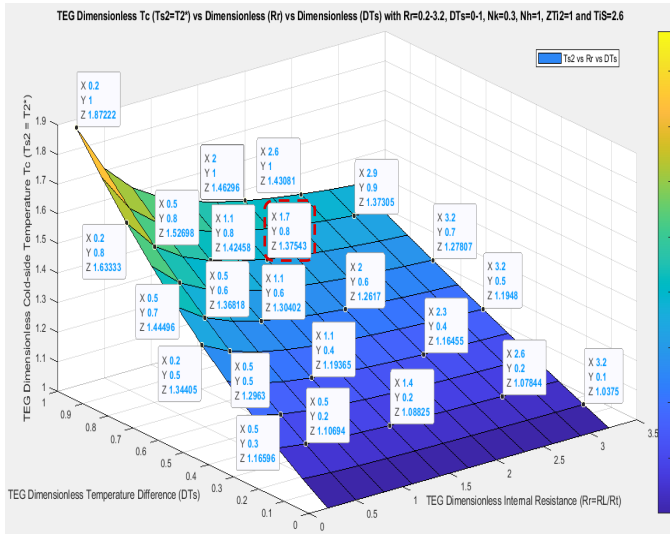
(i)



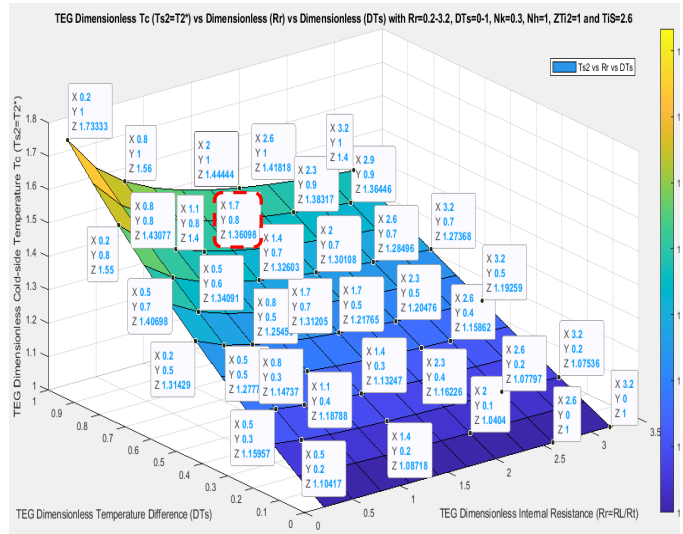
(d)



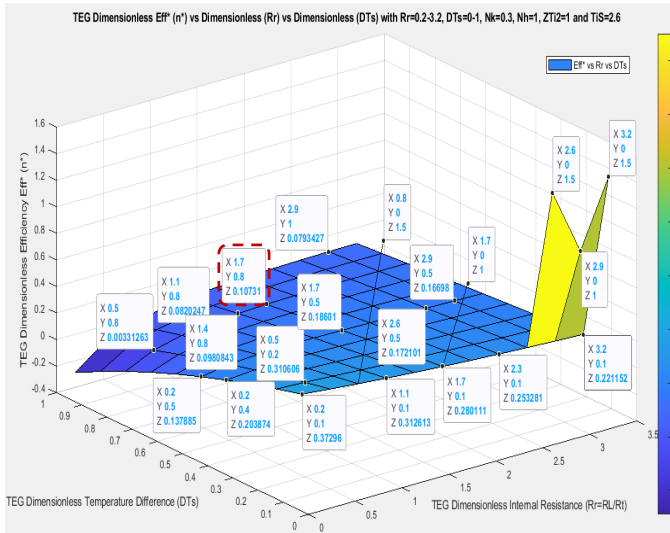
(j)



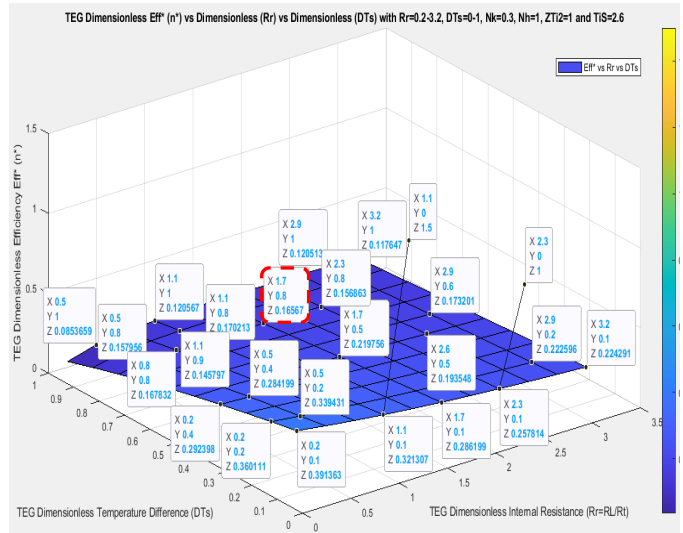
(e)



(k)



(f)



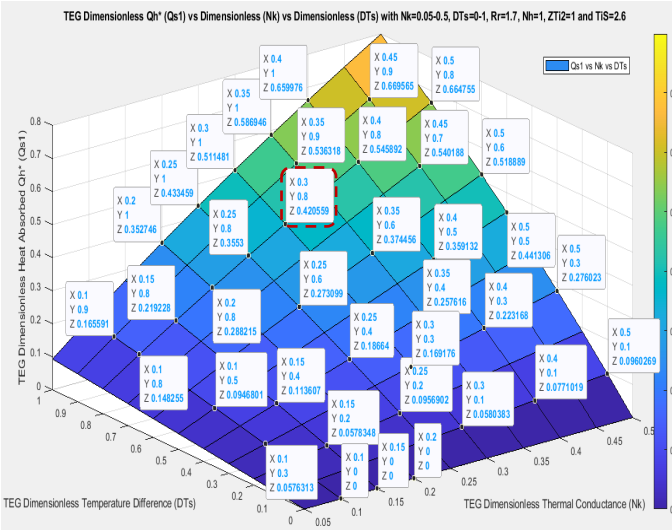
(l)

**Figure 5.** Performance and comparison plots of the: i) simple Eqs 32 and 33; (a)  $Q_{s1}$  vs  $R_r$  vs  $DT_s$ ; (b)  $Q_{s2}$  vs  $R_r$  vs  $DT_s$ ; (c)  $P_{os}$  vs  $R_r$  vs  $DT_s$ ; (d)  $T_{s1}$  vs  $R_r$  vs  $DT_s$ ; (e)  $T_{s2}$  vs  $R_r$  vs  $DT_s$ ; (f)  $Eff^*$  vs  $R_r$  vs  $DT_s$ ; versus ii) simpler Eqs 36 and 37; (g)  $Q_{s1}$  vs  $R_r$  vs  $DT_s$ ; (h)  $Q_{s2}$  vs  $R_r$  vs  $DT_s$ ; (i)  $P_{os}$  vs  $R_r$  vs  $DT_s$ ; (j)  $T_{s1}$  vs  $R_r$  vs  $DT_s$ ; (k)  $T_{s2}$  vs  $R_r$  vs  $DT_s$ ; (l)  $Eff^*$  vs  $R_r$  vs  $DT_s$ .

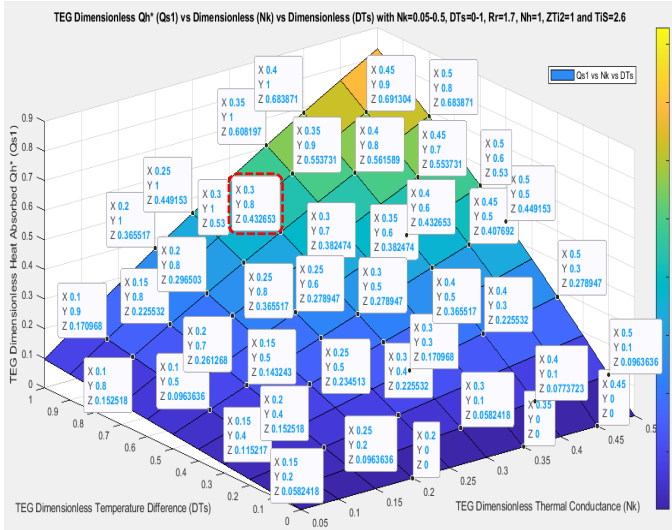
Figure 6 graphs depict in 3D  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  results using  $ZT_{i2} = 1$ ,  $N_h = 1$ ,  $T_i = 2.6$ ,  $N_k = 0.05 - 0.5$ ,  $R_r = 1.7$  and  $DT_s = 0.1 - 1$ . The newly introduced simple vs simpler formulas results are compared.

$N_k$  vs  $DT_s$ : Using “simple” Eqs 32 and 33

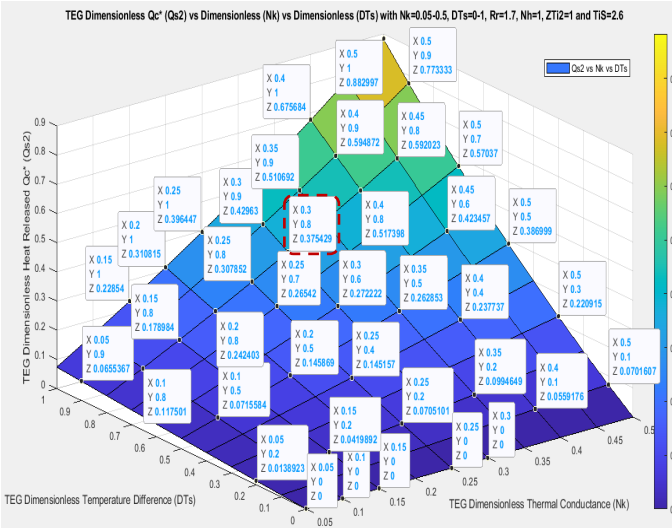
$N_k$  vs  $DT_s$ : Using “simpler” Eqs 36 and 37



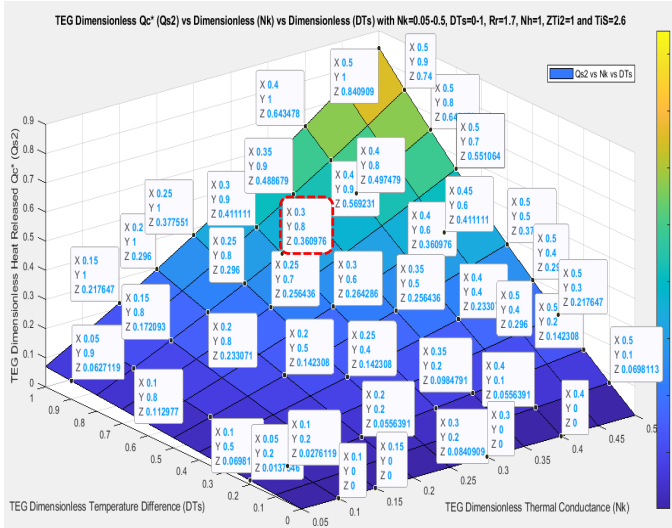
(a)



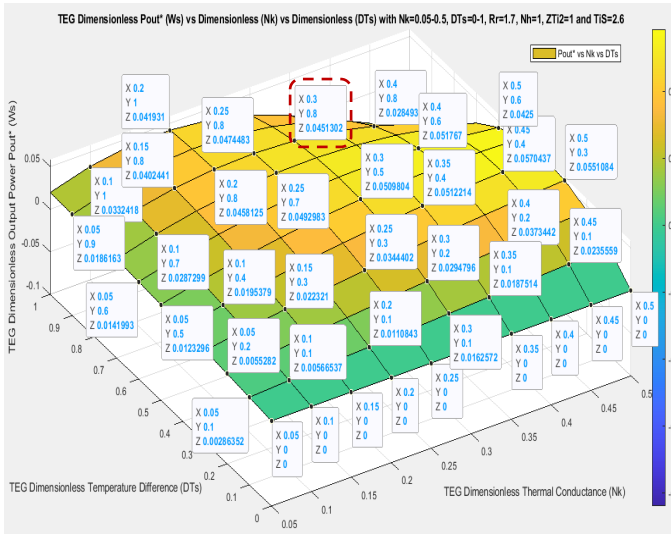
(g)



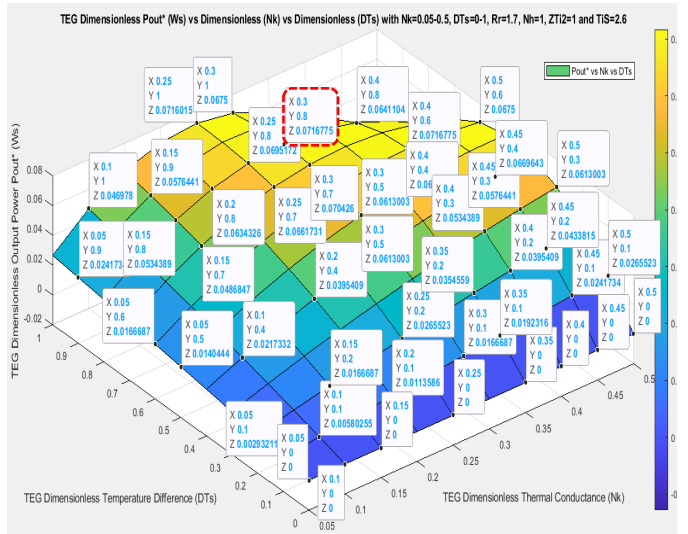
(b)



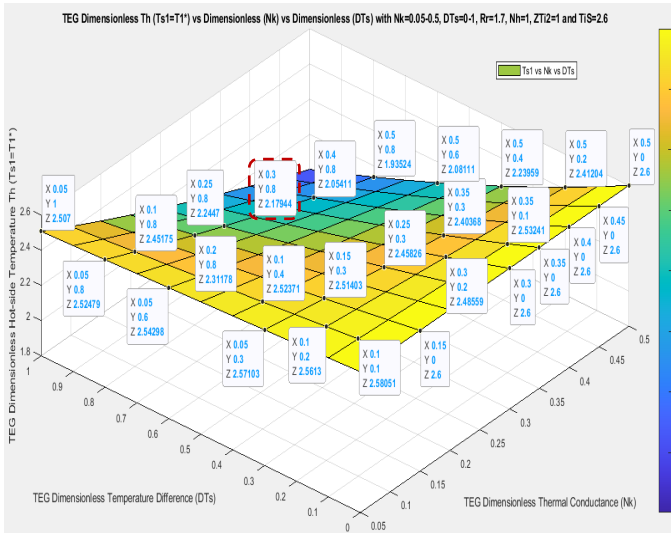
(h)



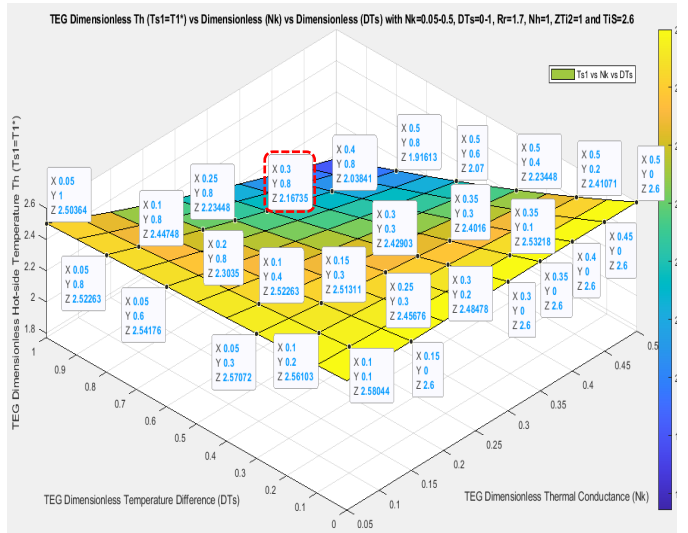
(c)



(i)

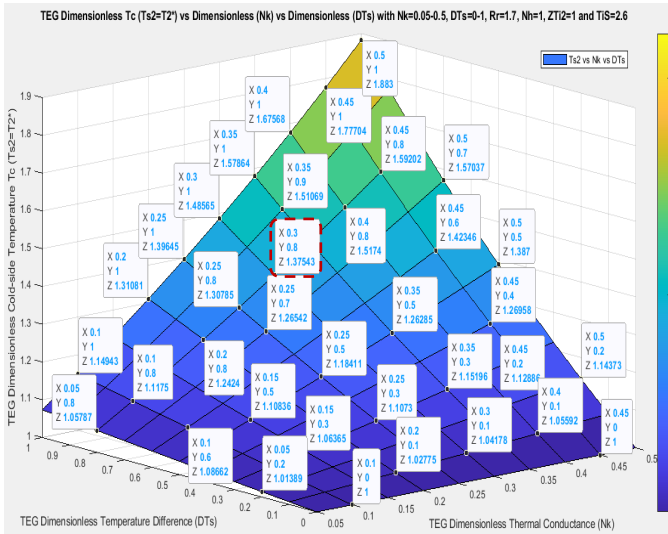


(d)

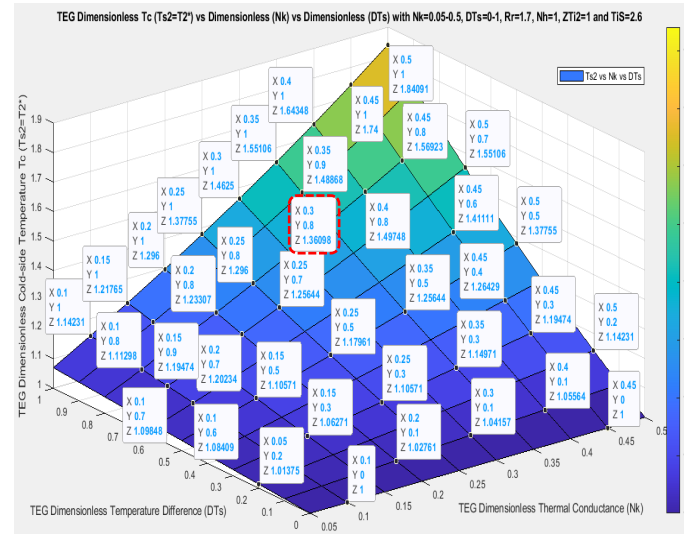


(j)

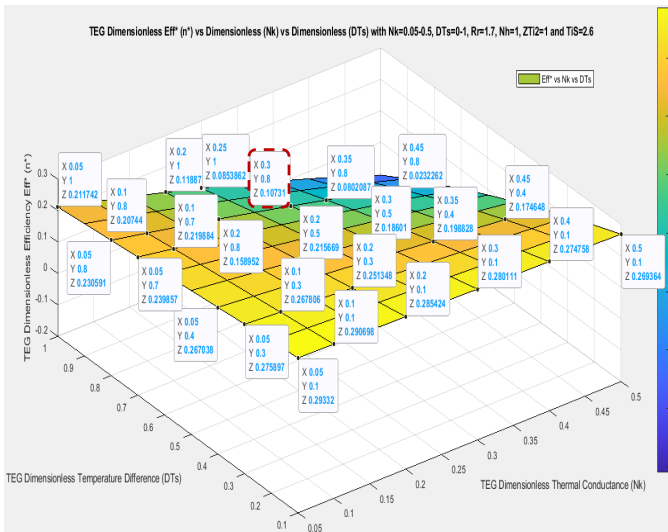




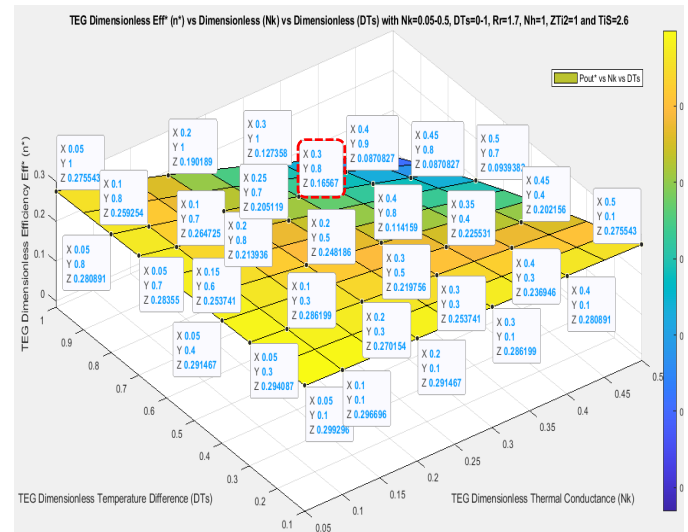
(e)



(k)



(f)



(l)

**Figure 6.** Performance and comparison plots of the: i) simple Eqs 32 and 33; (a)  $Q_{s1}$  vs  $N_k$  vs  $DT_s$ ; (b)  $Q_{s2}$  vs  $N_k$  vs  $DT_s$ ; (c)  $P_{os}$  vs  $N_k$  vs  $DT_s$ ; (d)  $T_{s1}$  vs  $N_k$  vs  $DT_s$ ; (e)  $T_{s2}$  vs  $N_k$  vs  $DT_s$ ; (f)  $Eff^*$  vs  $N_k$  vs  $DT_s$ ; versus ii) simpler Eqs 36 and 37; (g)  $Q_{s1}$  vs  $N_k$  vs  $DT_s$ ; (h)  $Q_{s2}$  vs  $N_k$  vs  $DT_s$ ; (i)  $P_{os}$  vs  $N_k$  vs  $DT_s$ ; (j)  $T_{s1}$  vs  $N_k$  vs  $DT_s$ ; (k)  $T_{s2}$  vs  $N_k$  vs  $DT_s$ ; (l)  $Eff^*$  vs  $N_k$  vs  $DT_s$ .

In the first part of Section 4, the study results were variously and extensively displayed, revealing what combinations of  $R_r$  vs  $N_k$  vs  $DT_s$  values that will give optimal  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  outcomes; by employing our newly introduced analytical Eqs 32 and 33 which are termed the “simple equations” and comparing with the further simplified versions, Eqs 36 and 37 which as well are termed the “simpler equations”. It should be noted that each set of figures results, validate each

other set of figures results. That is, Figure 3 results validates Figure 4 results which in turn validates Figure 5 results and consequently which validates Figure 6 results. Furthermore, the figures on the left results (based on Eqs 32 and 33 exclusively) validate the figures on the right results (based on Eqs 36 and 37 exclusively). In the second part of Section 4, the highlights of our presented findings are discussed next and lastly the results are validated where applicable with reference to the original results presented in [7].

Beginning with Figure 3, parameters  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  are plotted against  $R_r$  with  $N_k = 0.1 - 0.4$  and  $DT_s = 0.8$  as well as  $ZT_{i2} = 1$ ,  $N_h = 1$ ,  $T_i = 2.6$ —which were fixed throughout our entire study and therefore have no relevance in our results/discussions. NB:  $N_k = 0.1 - 0.4$  instead of just  $N_k = 0.3$  was used to see the effects of different  $N_k$  values on  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  at also different  $R_r$  values. As evident,  $Q_{s1}$ ,  $Q_{s2}$  and  $T_{s2}$  are inversely proportional to  $R_r$  with  $N_k = 0.3$  and  $DT_s = 0.8$ .  $T_{s1}$  is directly proportional to  $R_r$  whereas  $P_{os}$  and  $Eff^*$  are initially directly proportional to  $R_r$ , until  $P_{os}$  and  $Eff^*$  reach their respective maximum value and then becomes inversely proportional to  $R_r$  and also with the rates of  $P_{os}$  and  $Eff^*$  incline and decline, being faster using the “simpler” Eqs 36 and 37. With the “simple” equations, our optimal values for  $P_{os}$  is 0.045518 and for  $Eff^*$  is 0.112407 and both occur at approximately  $R_r = 2$  and not at exactly  $R_r = 1.7$  as reported in [7]; however, at  $R_r = 1.7$ , our  $P_{os}$  and  $Eff^*$  values of 0.0451302 and 0.10731 respectively, are exactly the same as those reported in [7]. With the “simpler” equations, our optimal values for  $P_{os}$  is 0.0893268 and for  $Eff^*$  is 0.170213 and both occur at different  $R_r$  values—at  $R_r = 0.5$  for  $P_{os}$  and at  $R_r = 1.1$  for  $Eff^*$ ; however, at  $R_r = 1.7$ , both the  $P_{os}$  and  $Eff^*$  values are respectively 0.0716775 and 0.16567, as well as respectively 0.0669887 and 0.161491 at  $R_r = 2$ . The rest parameters  $Q_{s1}$ ,  $Q_{s2}$ ,  $T_{s1}$  and  $T_{s2}$  values are closely the same using either the “simple” or “simpler” analytical equations. Further observable, the results dynamics have the following interesting aspects. i)  $Q_{s1}$ ,  $Q_{s2}$  and  $T_{s2}$  values increase with increasing  $N_k$  values; however, they decrease with increasing  $R_r$  values as noticed and explained already. ii)  $T_{s1}$  values increase with decreasing  $N_k$  values; as well as increase with decreasing  $R_r$  values as noticed and already explained. iii)  $Eff^*$  values also increases with decreasing  $N_k$  values with the increase being more significant at lower values of  $R_r$ , especially at  $R_r$  values below 1.0. iv)  $P_{os}$  values are interesting—as the dynamics are irregular with different  $N_k$  values, with  $P_{os}$  values sharply increasing initially with decreasing  $N_k$  values and at very low  $R_r$  values and once after their respective optimal points,  $P_{os}$  values again increase but with now increasing  $N_k$  values and at high  $R_r$  values.

In Figure 4, parameters  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  are plotted against  $N_k$  with  $R_r = 0.5 - 2$  and  $DT_s = 0.8$  and using  $ZT_{i2} = 1$ ,  $N_h = 1$ ,  $T_i = 2.6$ —which were fixed throughout the study.  $R_r = 0.5 - 2$  instead of only  $R_r = 1.7$  was used to see the effects of different  $R_r$  values on  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  at also over different  $N_k$  values. As can be seen,  $Q_{s1}$ ,  $Q_{s2}$  and  $T_{s2}$  values are directly proportional to  $N_k$ . However,  $T_{s1}$  and  $Eff^*$  values are inversely proportional to  $N_k$  values.  $P_{os}$  initially increases proportionally to  $N_k$  till it reaches optimal point at  $N_k = 0.25$  in Figure 4c (simple equation) and  $N_k = 0.3$  in Figure 4i (simpler equation); after which  $P_{os}$  values becomes inversely proportional to  $N_k$ . Further noticeable,  $Q_{s1}$ ,  $Q_{s2}$  and  $T_{s2}$  values are inversely proportional to  $R_r$  values, though directly proportional to  $N_k$  values as indicated earlier. Nevertheless,  $T_{s1}$  is directly proportional to  $R_r$  values but indirectly proportional to  $N_k$ . Initially, with increasing  $N_k$ ,  $P_{os}$  increases more with less  $R_r$  at mostly low  $N_k$  values till maximum  $P_{os}$  is attained and thereafter,  $P_{os}$  decreases more with less  $R_r$  at high  $N_k$  values. The optimal  $P_{os}$  of 0.0478788 using our simple equation occurs at  $R_r = 1.1$  with  $N_k = 0.2$ , whereas at  $R_r = 1.7$ , the optimal  $P_{os} = 0.0474483$  with  $N_k = 0.25$ —slightly contrary to [7] which

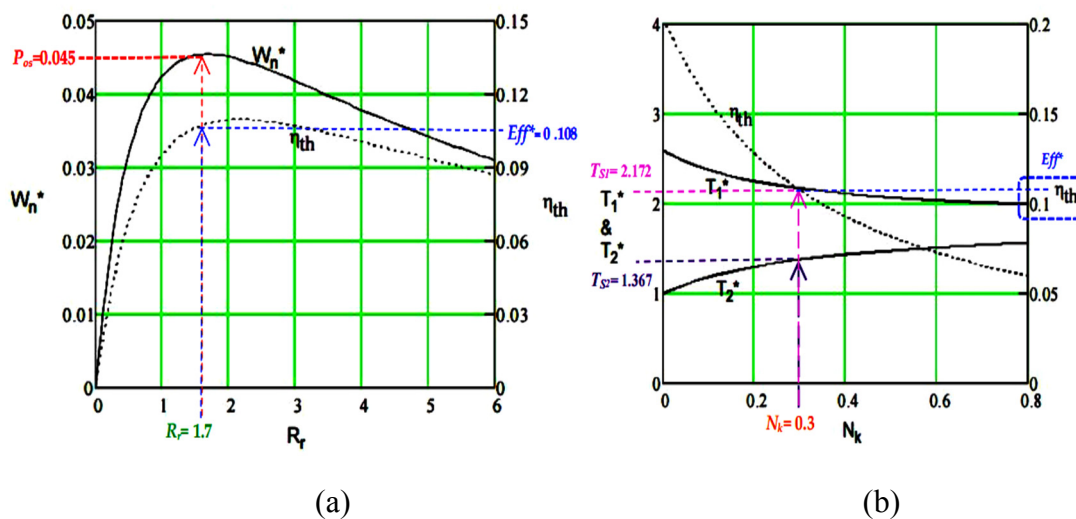


reported an optimal  $P_{os}$  of 0.045 at  $R_r = 1.7$  with  $N_k = 0.3$ —which we also have exactly the same result of  $P_{os} = 0.0451302$  at  $R_r = 1.7$  with  $N_k = 0.3$ ; however, this result was not the exact optimal outcome in our case. Using our simpler equation, we have at  $R_r = 0.5$ , two  $P_{os}$  optimal values of 0.0966733 and 0.0977376 at respectively  $N_k = 0.2$  and  $N_k = 0.25$ . Initially  $Eff^*$  with increasing  $N_k$ , decreases more with more  $R_r$  at mostly low  $N_k$  values till optimal  $Eff^*$  is attained and thereafter,  $Eff^*$  decreases more with less  $R_r$  at high  $N_k$  values. This  $Eff^*$  dynamics is mostly and clearly noticeable in Figure 4l using our simpler equation.

Figure 5 is a 3D plot of  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  parameters against  $R_r = 0.2 - 3.2$  but with now  $DT_s = 0 - 1$  and  $N_k$  fixed at 0.3. The results summarily reveal that  $P_{os}$  and  $Eff^*$  increase proportionally with increasing  $DT_s$ , reach maximum and decrease, especially at lower  $R_r$  values but at higher  $R_r$ ,  $P_{os}$  and  $Eff^*$  increase linearly with  $DT_s$ . Also,  $Q_{s1}$ ,  $Q_{s2}$ ,  $T_{s1}$  and  $T_s$  parameters exhibit comparable dynamics to those of Figures 3 and 4 results.

Figure 6 is another 3D plot of  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  parameters against  $N_k = 0.05 - 0.5$  but now with  $DT_s = 0 - 1$  and  $R_r$  fixed at 1.7. As apparent,  $Q_{s1}$ ,  $Q_{s2}$  and  $T_{s2}$  have similar dynamics as already noted and discussed earlier in the previous figures. The only difference now is, these dynamics happen across different values of  $DT_s$ . The same dynamics applies to  $T_{s1}$  and  $Eff^*$ .  $P_{os}$  generally increases proportionally to  $DT_s$  at especially lower  $N_k$  values but at higher  $N_k$  values,  $P_{os}$  decreases with  $DT_s$  as revealed.

It's worth stating that, these different plots simply show the different dynamics involved and generally, it's up to designers to now choose optimal values depending on the design constraints and design objectives.



**Figure 7.** Figures 2–6 results validator adapted from [7] (Lee H, 2013) (a)  $P_{os}$  ( $W_n^*$ ) &  $Eff^*(n_{th})$  vs  $R_r$ ; (b)  $T_1^*$  &  $T_2^*$  &  $n_{th}$  vs  $N_k$ .

To validate our findings in Figures 2–6 and Tables 1 and 2 where applicable, Figure 7 and Table 3 results adapted from [7] were used. In summary, validating our findings using [7] results affirms i) exactly the accuracy of our simple equations results and ii) fairly the approximation of our simpler equations results. It should be noted that, just reference [7] was used to validate our findings because a) reference [7] is the original research now developed and simplified with direct analytical formulas

to easily calculate  $T_{s1}$  and  $T_{s2}$  and therefore it's only prudent to validate the new developments with the original study and b) reference [7] is the only study we know with the aforementioned method and having the stated datasets that we can use.

**Table 3.** TEG input and output dimensionless and actual results adapted from [7] (Lee H, 2013) to validate Tables 1 and 2.

Inputs	Dimensionless ( $W_{n,opt}^*$ )	Actual ( $W_{n,opt}$ )
$T_{\infty 1} = 500 \text{ }^\circ\text{C}$ , $T_{\infty 2} = 25 \text{ }^\circ\text{C}$ , $\Delta T_{\infty 1} = 475 \text{ }^\circ\text{C}$	$N_k = 0.3$	$n = 254$
$A = 2 \text{ mm}^2$ , $L = 1 \text{ mm}$	$N_h = 1$	$\eta_1 h_1 A_1 = 4.8 \text{ W/K}$
$\eta_2 = 0.8$ , $h_2 = 60 \text{ W/m}^2\text{K}$ , $A_2 = 1000 \text{ cm}^2$	$R_r = 1.7$	$R_L = 1.7 \times n \times R = 4.32 \text{ } \Omega$
$\eta_2 h_2 A_2 = 4.8 \text{ W/K}$	$T_{\infty}^* = 2.6$	$T_{\infty 1} = 500 \text{ }^\circ\text{C}$
Base area $A_b$ of module = $5 \text{ cm} \times 5 \text{ cm}$	$ZT_{\infty 2} = 1.0$	$ZT_{\infty 2} = 1.0$
$\alpha_p = -\alpha_n = 220 \text{ } \mu\text{V/K}$	$T_1^* = 2.172$	$T_1 = 374 \text{ }^\circ\text{C}$
$P_p = P_n = 1.0 \times 10^{-3} \text{ } \Omega\text{cm}$	$T_2^* = 1.367$	$T_2 = 137 \text{ }^\circ\text{C}$
$k_p = k_n = 1.4 \times 10^{-2} \text{ W/cmK}$	$W_{n,opt}^* = 0.045$	$W_n = 65 \text{ W}$
$(Z = 3.457 \times 10^{-3} \text{ K}^{-1})$	$\eta_{th} = 0.108$	$\eta_{th} = 0.108$
$(R = 0.01 \text{ } \Omega \text{ per thermocouple})$	$N_l = 0.306$	$I = 3.9 \text{ A}$
$(\eta_1 = 0.8$ , $h_1 = 60 \text{ W/m}^2\text{K}$ , $A_1 = 1000 \text{ cm}^2)$	$N_v = 0.5$	$V = 16.7 \text{ V}$
$(\text{Power Density } P_d = W_n/A_b \text{ W/cm}^2)$	—	$P_d = 2.6 \text{ W/cm}^2$

Compare values with values in Figure 2/Table 2

Check colour coding with the markings on Figure 7

Compare values with values in Figure 2/Table 2

## 5. Conclusions

Sustainable energy is transcending to become the future of energy to complement the national grid and for private use. As a result, we've researched thermoelectricity (TEG) as an alternative energy source for household applications requiring low DC power and lighting. However, practical TEG use requires heatsinks to work efficiently and reliably but regrettably adding heatsinks add thermal resistances, which consequently degrades the TEG efficiency as well as its output power. We investigated various techniques, especially dimensional analysis and shortlisted the approach by [7]—which converts thermal resistance to convection conductance, making it easier for practical use. However, the formulations in [7] could not find the exact analytical formulas to directly calculate  $T_{s1}$  and  $T_{s2}$ ; as a result, [7] used numerical analysis (a bit cumbersome) which we developed further by introducing  $DT_s$  to simplify and derive new simple accurate analytical formulas that can be applied to compute  $T_{s1}$  and  $T_{s2}$  directly. Furthermore, these simple formulas were further simplified to obtain simpler analytical equations for  $T_{s1}$  and  $T_{s2}$ . Finally, our simplest  $T_{s1}$  and  $T_{s2}$  formulas and their optimal relationships were established. These formulas were all verified with chosen optimal values and all gave approximate results that correlated each other. We further used these newly introduced formulas to model, numerically simulate and plotted various characteristics curves of  $Q_{s1}$ ,  $Q_{s2}$ ,  $P_{os}$ ,  $T_{s1}$ ,  $T_{s2}$  and  $Eff^*$  against  $R_r$  vs  $N_k$  vs  $DT_s$  using Matlab and Simulink. These results were articulated variously in both 2D and 3D plots and finally the equivalent outcomes were comparatively discussed and validated using each other and as well with results asserted in [7]. In [7],  $P_{os}$  of 0.045 is optimal with  $N_k = 0.3$  at  $R_r = 1.7$ , contrary to our study which gave optimal  $P_{os}$  of 0.0474483 at  $N_k = 0.25$  using our simple equations; however, using our simpler equations, it gave optimal  $P_{os}$  of 0.0716775 at  $N_k = 0.3$ . Notwithstanding, our simple equations gave  $P_{os}$  of 0.0451302 at  $N_k = 0.3$  (though not optimal in our case) which corresponds exactly to optimal  $P_{os}$  value of 0.045 with  $N_k = 0.3$  as in [7]. In addition, the magnitude of  $P_{os}$  and  $Eff^*$  are more (almost doubled) using our simpler Eqs 36 and 37, compared to using our simple Eqs 32 and 33. Furthermore, the optimal values

of  $P_{os}$  and  $Eff^*$  using both our “simple” and “simpler” equations, respectively occurred at different values of  $R_r$ . In sum,  $Eff^*$  is best at very low  $N_k$  values. The highlights of our study are marked in the various figures and also summarised in Tables 1 and 2. It’s worth mentioning that,  $DT_s = 0.8$  for this set of optimal values, is rightly only equal to  $T_{s1} - T_{s2} = \sim 0.8$  only at  $R_r = 1.7$  and  $N_k = 0.3$  as summarised in Table 1 and not at any other values when used in both our simple and simpler equations. Finally, in as much as our newly introduced simpler analytical formulas didn’t give exact  $P_{os}$  and  $Eff^*$  results correlating those in i) [7] and ii) our newly introduced analytical simple equations (that gave accurate results), we reckon the simpler equations can be used as first approximation to quickly find  $T_{s1}$  and  $T_{s2}$  as well as  $Q_{s1}$  and  $Q_{s2}$  values with fair accuracy. In sum,  $T_{s1}$  and  $T_{s2}$  are the most vital physical parameters, as they’re those that can be easily practically manipulated to achieve the other values. However, first ascertaining the electrical load or  $R_r$  value to ensure maximum power transfer is most paramount to achieve optimal result, as a TEG as well TEC, are non-linear devices whose dynamics must be well understood before embarking on a practical design. The next phase of our research is to validate and refine our study practically and then design a household TEG alternative DC power source.

## Acknowledgments

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## Conflicts of interest

The authors declare no conflict of interest.

## Supplementary

Figures 1–6 are provided in link below in picture format for better quality viewing/review.

[https://drive.google.com/drive/folders/1VHN2mHJ\\_wtYaztunL\\_Sn21XJmppc0o8z?usp=sharing](https://drive.google.com/drive/folders/1VHN2mHJ_wtYaztunL_Sn21XJmppc0o8z?usp=sharing)

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