Mathematics

Research article

# Mahgoub transform and Hyers-Ulam stability of $n^{\text {th }}$ order linear differential equations 

S. Deepa ${ }^{1}$, S. Bowmiya ${ }^{2}$, A. Ganesh ${ }^{3}$, Vediyappan Govindan ${ }^{4}$, Choonkil Park ${ }^{5, *}$ and Jung Rye Lee ${ }^{6, *}$<br>${ }^{1}$ Department of Mathematics, Adhiyamaan College of Engineering and Technology, Hosur-365109, Tamilnadu, India<br>${ }^{2}$ Department of Mathematics, Unique College of Arts and Sciences, Karapattu, Tamilnadu, India<br>${ }^{3}$ Department of Mathematics, Government Arts and Science College (Model College), Hosur-365109, Tamilnadu, India<br>${ }^{4}$ Department of Mathematics, Dmi St John The Baptist University, Mangochi 409, Central Africa, Malawi<br>${ }^{5}$ Research Institute for Natural Sciences, Hanyang University, Seoul 04763, Korea<br>${ }^{6}$ Department of Data Sciences, Daejin University, Kyunggi 11159, Korea<br>* Correspondence: Email: baak@hanyang.ac.kr, jrlee @ daejin.ac.kr; Tel: +82222200892;<br>Fax: +82222810019.


#### Abstract

The main aim of this paper is to investigate various types of Hyers-Ulam stability of linear differential equations of $n^{\text {th }}$ order with constant coefficients using the Mahgoub transform method. We also show the Hyers-Ulam constants of these differential equations and give some main results.


Keywords: Mahgoub transform; Hyers-Ulam stability; $n^{\text {th }}$ order linear differential equation; functional equation
Mathematics Subject Classification: 26D10, 34A40, 34K20, 39A30, 39B82, 44A10

## 1. Introduction

In 1940 Ulam [25] proposed a very general Hyers-Ulam stability problem: When is the statement of the theorem still true or nearly true despite slight variations on the theorems hypothesis? In the following year Hyers [10] come up with the first two positive answer to Ulam's question by proving the stability of the additive functional equation in Banach spaces. Since then, Hyers result has been widely generalised in terms of the control conditions used to do define the concept of an approximate solution (see [5-9, 18, 19, 23, 26, 28]).

The generalization of Ulam's questions has been relatively recently proposed by replacing functional equations with differential equations.

Let $I$ be a subinterval of $\mathbb{R}$, let $\mathbb{K}$ denote either $\mathbb{R}$ or $\mathbb{C}$ and let $n$ be a positive integer. The differential equation

$$
\rho\left(h, w, w^{1}, w^{\prime \prime}, \cdots, w^{(n)}\right)=0
$$

has the Hyers-Ulam stability if there exists a constant $K>0$ such that the following statement is true for any $\epsilon>0$ : if an $n$ times continuously differentiable function

$$
\tau: I \rightarrow \mathbb{K}
$$

satisfies the inequality

$$
\left|\rho\left(t, \tau, \tau^{\prime}, \tau^{\prime \prime}, \ldots, \tau^{(n)}\right)\right| \leq \epsilon
$$

for all $t \in I$, then there exists a solution $\zeta: I \rightarrow \mathbb{K}$ of the differential equation that satisfies the inequality

$$
|\tau(t)-\zeta(t)| \leq K \epsilon,
$$

for all $t \in I$.
Obloza seems to the first author who has investigated the Hyers-Ulam stability of linear differential equation (see [16, 17]). In 1998, Alsina and Ger continued the study of Obloza's Hyers-Ulam stability of differential equations. Indeed they proved [4] in the following theorem.

Theorem 1.1. Let I be a non-empty open subinterval of $\mathbb{R}$. If a differentiable function $w: I \rightarrow \mathbb{R}$ satisfies the differential inequality

$$
\left\|w^{\prime}(t)-w(t)\right\| \leq \epsilon,
$$

for any $t \in I$ and for some $\epsilon>0$, then there exists a differentiable function $\zeta: I \rightarrow \mathbb{R}$ satisfying $\zeta^{\prime}(t)=w(t)$ and

$$
\|w(t)-\zeta(t)\| \leq K \epsilon
$$

for all $t \in I$.
This result of Alisina and Ger has been generalized by Takahashi et al. [22]. They proved that the Hyers-Ulam stability holds true for the Banach space valued differential equation $w^{\prime}(t)=\chi w(t)$. Indeed the Hyers-Ulam stability has been proved for the first order linear differential equations in more general settings (see [11, 12, 15]).

In 2006 Jung [13] investigated the Hyers-Ulam stability of a system of first order linear differential equations with constant coefficients by using matrix method. In 2008, Wang et al. [27] studied the Hyers-Ulam stability of linear differential equations of first order using the integral factor method. Meanwhile, Rus [21] discussed various types of Hyers-Ulam stability of the ordinary differential equations

$$
w^{\prime}(t)=p w(t)+h .
$$

In 2014, Alqifiary and Jung [3] proved the Hyers-Ulam stability of linear differential equation of the form

$$
w^{(n)}(t)+\sum_{k=0}^{n-1} \gamma_{k} w^{(k)}(t)=h(t)
$$

by using the Laplace transform method, where $\gamma_{k}$ scalars and $w(t)$ is an $n$ times continuously differentiable function of the exponential order (see [20]).

In 2016, Mahgoub [14] introduced a Mahgoub transform for solving linear ordinary differential equations with constant coeffcient. Aggarwal et al. [2] used Mahgoub transform for solving linear Volterra integral equations. Kumar and Viswanathan [24] used Mahgoub transform to mechanics and electrical circuit problems. Recently, Aggarwal [1] introduced a comparative study of Mohand and Mahgoub transform.

Based on the above results, our main goal is to more efficiently prove the Hyers-Ulam stability of the $n^{\text {th }}$ order linear differential equations

$$
\begin{equation*}
w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)=0 \tag{1.1}
\end{equation*}
$$

and

$$
\begin{equation*}
w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)=m(t) \tag{1.2}
\end{equation*}
$$

by using Mahgoub integral transform method, where $a_{n-1}, \cdots, a_{2}, a_{1}, a_{0}$ are scalars and $w(t)$ is a continuously differentiable function in exponential order.

## 2. Preliminaries

In this section, we introduce some standard notations and definitions which will be useful to prove our main results.

Throughout this paper, $\mathbb{K}$ denotes either the real field $\mathbb{R}$ or complex field $\mathbb{C}$. A function $h:[0, \infty) \rightarrow$ $\mathbb{K}$ is called of exponential order if there exist constants $P, Q \in R$ such that

$$
|h(t)| \leq P e^{Q t}
$$

for all $t \geq 0$. Similarly, a function $j:(-\infty, 0] \rightarrow \mathbb{K}$ is called of exponential order if there exist constants $P, Q \in R$ such that

$$
|j(t)| \leq P e^{Q t}
$$

for all $t \leq 0$.
Definition 2.1. The Mahgoub (integral) transform of the function $h:[0, \infty) \rightarrow \mathbb{K}$ is defined by

$$
\psi(h(t))=a \int_{0}^{\infty} h(s) e^{-a s} d s:=H(a),
$$

where $\psi$ is the Mahgoub integral transform operator.
The Mahgoub integral transform for the function $h:[0, \infty) \rightarrow \mathbb{K}$ exist if $h(t)$ is piecewise continuous and of exponential order.

These conditions are the only sufficient conditions for the existence of Mahgoub transform of the function $h(t)$.

Linearity: If h and j are have Mahgoub transform as $\psi(h)$ and $\psi(j)$, then $\psi(\alpha h(s)+\beta j(s))=$ $\alpha \psi(h)+\beta \psi(j)$, where $\alpha \beta \in R_{+}$.

Proof.

$$
\begin{aligned}
\psi(\alpha h(s)+\beta j(s)) & =a \int_{0}^{\infty}(\alpha h(s)+\beta j(s)) \cdot e^{-a s} d s \\
& =a \int_{0}^{\infty} \alpha h(s) \cdot e^{-a s} d s+a \int_{0}^{\infty} \beta j(s) \cdot e^{-a s} d s \\
& =\alpha \int_{0}^{\infty} a h(s) \cdot e^{-a s} d s+\beta \int_{0}^{\infty} a j(s) \cdot e^{-a s} d s \\
& =\alpha \psi(h)+\beta \psi(j) .
\end{aligned}
$$

Definition 2.2 (Convolution of two functions). The convolution is, the change in the form of a value or expression without change in the value.

The convolutionn of two functions $h(t)$ and $j(t)$ is denoted by $h(t) * j(t)$ and is defined by

$$
h(t) * j(t)=(h * j)(t)=\int_{0}^{t} h(s) j(t-s) d s=\int_{0}^{t} h(t-s) j(s) d s .
$$

The convolution theorem of two functions $h$ and $j$ of Mahgoub transform is given by

$$
\begin{aligned}
\psi(h * j)(a) & =\frac{1}{a} \psi(h) \cdot \psi(j), \\
\psi(h * j)(a) & =\int_{0}^{\infty}(h * j)(t)\left[a e^{-a t}\right] d t \\
& =\int_{0}^{\infty} \int_{0}^{\infty} h(s) j(t-s) d s\left(a e^{-a t}\right) d t \\
& =\int_{0}^{\infty} h(s) d s \int_{0}^{\infty} j(t-s)\left(a e^{-a t}\right) d t .
\end{aligned}
$$

Letting $t-s=y$, we have

$$
\begin{aligned}
\psi(h * j)(a) & =\int_{0}^{\infty} h(s) d s \int_{0}^{\infty} j(y)\left(a e^{-a(y+s)}\right) d t \\
& =\int_{0}^{\infty} h(s) e^{-a u} d s \int_{0}^{\infty} j(y)\left(a e^{-a y}\right) d t \\
& =\frac{1}{a}\left\{a \int_{0}^{\infty} h(s) e^{-a u} d s \cdot a \int_{0}^{\infty} j(y) e^{-a y} d t\right\} \\
& =\frac{1}{a} \psi(h) \cdot \psi(j)
\end{aligned}
$$

Theorem 2.3 (Convolution theorem for Mahgoub transform). Let $h, j \in H^{\prime}(R)$. Then

$$
\psi(h * j)(v)=\frac{\psi(h) \psi(j)}{v}
$$

Proof.

$$
\begin{aligned}
\psi(h * j)(a) & =<(h * j), a e^{-a s}>=<h(s),<j(t), a e^{-a(s+t)} \gg \\
& =<h(s),<j(t), a e^{-a s} \cdot e^{-a t} \gg=<h(s), a e^{-a s}><j(t), e^{-a t}> \\
& =\frac{1}{a}<h(s), a e^{-a s}>\cdot<j(t), v e^{-a t}> \\
& =\frac{1}{a} \psi(h) \cdot \psi(j)
\end{aligned}
$$

This completes the proof.
Lemma 2.4. If Mahgoub transform of function $F(s)$ is $\psi(a)$, then Mahgoub transform of function $F(b s)$ is given by $\psi\left(\frac{a}{b}\right)$.

Proof. By the definition of Mahgoub transform, we have

$$
\begin{equation*}
\psi(F(b s))=a \int_{0}^{\infty} F(b s) e^{-a s} d s \tag{2.1}
\end{equation*}
$$

Putting $b s=p \Rightarrow b d s=d p$ in (2.1), we have

$$
\begin{aligned}
& \psi(F(b s))=\frac{a}{b} \int_{0}^{\infty} F(p) e^{-\frac{a p}{b}} d p \\
& \psi(F(b s))=\psi\left(\frac{a}{b}\right)
\end{aligned}
$$

Lemma 2.5. If Mahgoub transform of function $F(s)$ is $\psi(a)$, then Mahgoub transform of function $e^{b s} F(s)$ is given by $\frac{a}{a-b} \psi(a-b)$.
Proof. By the definition of Mahgoub transform, we have

$$
\begin{aligned}
\psi\left(e^{b s} F(s)\right) & =a \int_{0}^{\infty} e^{b s} F(s) e^{-a s} d s=a \int_{0}^{\infty} F(s) e^{-(a-b) s} d s=\frac{a}{(a-b)}(a-b) \int_{0}^{\infty} F(s) e^{-(a-b) s} d s \\
& =\frac{a}{(a-b)} \psi(a-b)
\end{aligned}
$$

Lemma 2.6. If $\psi(F(s))=\psi(a)$, then $\psi(s F(s))=\left[\frac{1}{a}-\frac{d}{d a}\right] \psi(a)$.
Proof. By the definition of Mahgoub transform, we have

$$
\psi(F(s))=a \int_{0}^{\infty} F(s) e^{-a s} d s=\psi(a)
$$

Then

$$
\frac{d}{d a} \psi(a)=\int_{0}^{\infty} F(s) e^{-a s} d s+a \int_{0}^{\infty}(-s) F(s) e^{-a s} d s=\frac{1}{a} a \int_{0}^{\infty} F(s) e^{-a s} d s-a \int_{0}^{\infty} s F(s) e^{-a s} d s
$$

$$
\begin{aligned}
& =\frac{1}{a} \psi(a)-\psi(s F(s)), \\
\psi(s F(s)) & =\frac{1}{a} \psi(a)-\frac{d}{d a} \psi(a), \\
\psi(s F(s)) & =\left[\frac{1}{a}-\frac{d}{d a}\right] \psi(a) .
\end{aligned}
$$

Definition 2.7 (Inverse Mahgoub transform). If $\psi(h(t))=H(a)$, then $h(t)$ is called the inverse Mahgoub transform of $H(a)$ and is denoted as $h(t)=\psi^{-1}(H(a))$, where $\psi^{-1}$ is the inverse Mahgoub transform operator.
Definition 2.8. The Mitteg-Liffler function of one parameter is denoted by $E_{\beta}(t)$ and defined by

$$
E_{\beta}(t)=\sum_{k=0}^{\infty} \frac{t^{k}}{\Gamma(\beta k+1)},
$$

where $t, \beta \in C$ and $R(\beta)>0$. If we put $\beta=1$, then the above equation becomes

$$
E_{1}(t)=\sum_{k=0}^{\infty} \frac{t^{k}}{\Gamma(k+1)}=\sum_{k=0}^{\infty} \frac{t^{k}}{k!}=e^{t} .
$$

Now, we give the different definitions of Hyers-Ulam stability and Hyers-Ulam $\sigma$-stability of the differential equations (1.1) and (1.2).

Throughout this section, consider

$$
H=\{h:[0, \infty) \rightarrow \mathbb{K} \mid h \text { is a continuously differentiable function of exponential order }\}
$$

Definition 2.9. (i) The linear differential equation (1.1) is said to have the Hyers-Ulam stability (for class $H$ ) if there exists a constant $K>0$ such that the following statement is true: For every $\epsilon>0$, if a function $w \in H$ satisfies the inequality

$$
\begin{equation*}
\left|w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)\right| \leq \epsilon \tag{2.2}
\end{equation*}
$$

for all $t \geq 0$, then there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.1) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K \epsilon
$$

for all $t \geq 0$.
(ii) We say that the nonhomogeneous linear differential equation (1.2) has the Hyers-Ulam stability if there exists a constant $K>0$ such that the following statement is true: For each $\epsilon>0$, if a function $w \in H$ satisfies the inequality

$$
\begin{equation*}
\left|w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)\right| \leq \epsilon \tag{2.3}
\end{equation*}
$$

for all $t \geq 0$, then there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.2) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K \epsilon,
$$

for all $t \geq 0$, where the constant $K$ is called as Hyers-Ulam constant.

Definition 2.10. Let $\sigma:[0, \infty) \rightarrow(0, \infty)$ be a function.
(i) We say that the homogeneous linear differential equation (1.1) has the Hyers-Ulam $\sigma$-stability (for the class $H$ ) if there exists a constant $K>0$ such that the following statement is true: For every $\epsilon>0$, if a function $w \in H$ satisfies the inequality

$$
\begin{equation*}
\left|w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)\right| \leq \sigma(t) \epsilon \tag{2.4}
\end{equation*}
$$

for all $t \geq 0$, then there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.1) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K \sigma(t) \epsilon
$$

for all $t \geq 0$.
(ii) We say that the nonhomogeneous linear differential equation (1.2) has the Hyers-Ulam stability if there exists a constant $K>0$ such that the following statement is true: For each $\epsilon>0$, if a function $w \in H$ satisfies the inequality

$$
\begin{equation*}
\left|w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)\right| \leq \sigma(t) \epsilon \tag{2.5}
\end{equation*}
$$

for all $t \geq 0$, then there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.2) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K \sigma(t) \epsilon,
$$

for all $t \geq 0$, where the constant $K$ is called as Hyers-Ulam constant.
Finally, we introduce the definitions of Mitteg-Liffler-Hyers-Ulam stability and Mitteg-Liffler-Hyers-Ulam $\sigma$-stability of the differential equations (1.1) and (1.2).

Definition 2.11. Let $E_{\beta}(t)$ be the Mitteg-Liffler function.
(i) We say that the differential equation (1.1) has the Mitteg-Liffler-Hyers-Ulam stability if their exists a constant $K>0$ such that the following statement holds true: For every $\epsilon>0$, if a function $w \in H$ satisfies the inequality

$$
\begin{equation*}
\left|w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)\right| \leq E_{\beta}(t) \epsilon \tag{2.6}
\end{equation*}
$$

for all $t \geq 0$, then there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.1) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K E_{\beta}(t) \epsilon
$$

for all $t \geq 0$.
(ii) We say that the nonhomogeneous linear differential equation (1.2) has the Mitteg-Liffler-HyersUlam stability if there exists a constant $K>0$ such that the following statement is true: For each $\epsilon>0$, if a function $w \in H$ satisfies the inequality

$$
\begin{equation*}
\left|w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)\right| \leq E_{\beta}(t) \epsilon \tag{2.7}
\end{equation*}
$$

for all $t \geq 0$, then there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.2) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K E_{\beta}(t) \epsilon,
$$

for all $t \geq 0$, where the constant $K$ is called as Mitteg-Liffler-Hyers-Ulam constant.

Definition 2.12. Let $E_{\beta}(t)$ be the Mitteg-Liffler function.
(i) We say that the differential equation (1.1) has the Mitteg-Liffler-Hyers-Ulam $\sigma$-stability, if their exists a constant $K>0$ such that the following statement holds true: For every $\epsilon>0$, if a function $w \in H$ satisfies the inequality

$$
\begin{equation*}
\left|w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)\right| \leq \sigma(t) E_{\beta}(t) \epsilon \tag{2.8}
\end{equation*}
$$

for all $t \geq 0$, then there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.1) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K \sigma(t) E_{\beta}(t) \epsilon,
$$

for all $t \geq 0$.
(ii) We say that the nonhomogeneous linear differential equation (1.2) has the Mitteg-Liffler-HyersUlam $\sigma$-stability if there exists a constant $K>0$ such that the following statement is true: For each $\epsilon>0$, if a function $w \in H$ satisfies the inequality

$$
\begin{equation*}
\left|w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)\right| \leq \sigma(t) E_{\beta}(t) \epsilon \tag{2.9}
\end{equation*}
$$

for all $t \geq 0$, then there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.2) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K \sigma(t) E_{\beta}(t) \epsilon,
$$

for all $t \geq 0$, where the constant $K$ is called as Mitteg-Liffler-Hyers-Ulam $\sigma$-constant.

## 3. Hyers-Ulam stability of (1.1)

In this section, we prove several types of Hyers-Ulam stability of homogeneous $n^{\text {th }}$ order linear differential equation (1.1) by using Mahgoub transform.

It should be noted that in this and the next section we investigate various types of Hyers-Ulam stability for the class $H$, where $H$ is the class of all continuously differentiable functions $\tau:[0, \infty) \rightarrow \infty$ of exponential order.

For any $a \in K$, we denote the real part of $a$ by $R(a)$.
Theorem 3.1. Assume that $a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}$ is a constant with $R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)>0$. Then the homogeneous linear differential equation (1.1) is Hyers-Ulam stable in the class $H$.

Proof. Assume that $w \in H$ satisfies the inequality (2.2) for all $t \geq 0$. Let us define a function $i$ : $[0, \infty) \rightarrow \mathbb{K}$ by

$$
\begin{equation*}
i(t)=w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2}(t) w^{\prime \prime}(t)+a_{1}(t) w^{\prime}(t)+a_{0} w(t) \tag{3.1}
\end{equation*}
$$

for all $t \geq 0$.
In view of (2.2), the inequality $|i(t)| \leq \epsilon$ holds for all $t \geq 0$. Mahgoub transform of $i(t)$ gives the following:

$$
\begin{aligned}
I(a) & =\psi(i(t))=\psi\left[w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)\right] \\
& =\psi\left[w^{(n)}(t)\right]+a_{n-1} \psi\left[w^{(n-1)}(t)\right]+\cdots+a_{2} \psi\left[w^{\prime \prime}(t)\right]+a_{1} \psi\left[w^{\prime}(t)\right]+a_{0} \psi[w(t)]
\end{aligned}
$$

where $\Omega(a)=\psi[w(t)]$, since

$$
\begin{align*}
\psi\left[w^{\prime}(t)\right] & =a \psi[w(t)]-a w(0)=a \Omega(a)-a w(0), \\
\psi\left[w^{\prime \prime}(t)\right] & =a^{2} \Omega(a)-a^{2} w(0)-a w^{\prime}(0), \\
\psi\left[w^{\prime \prime \prime}(t)\right] & =a^{3} \Omega(a)-a^{3} w(0)-a^{2} w^{\prime}(0)-a w^{\prime \prime}(0), \\
\vdots & \\
\psi\left[w^{(n-1)}(t)\right] & =a^{n-1} \Omega(a)-\sum_{K=0}^{n-2} a^{n-K-1} w^{K}(0),  \tag{3.2}\\
\psi\left[w^{(n)}(t)\right] & =a^{n} \Omega(a)-\sum_{K=0}^{n-1} a^{n-K} w^{K}(0) .
\end{align*}
$$

Now,

$$
\begin{align*}
I(a)= & a^{n} \Omega(a)-\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+a_{2}\left(a^{2} \Omega(a)-a^{2} w(0)-a w^{\prime}(0)\right)+a_{1}(a \Omega(a)-a w(0))+a_{0} \Omega(a), \\
\psi[w(t)]= & \Omega(a)=I(a)+\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1} \sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{3.3}
\end{align*}
$$

If we put $\tau(t)=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} w(0)$, then $\tau(0)=w(0)$ and $\tau \in H$. Mahgoub transform of $\tau(t)$ gives the following:

$$
\begin{align*}
\psi[\tau(t)]=T(a) & =\frac{1}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}  \tag{3.4}\\
& \left\{\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1} \sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)+\cdots+a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)\right\} .
\end{align*}
$$

Thus

$$
\begin{aligned}
\psi\left[\tau^{(n)}(t)+\right. & \left.a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right] \\
= & a^{n} T(a)-\sum_{k=0}^{n-1} a^{n-k} \tau^{(k)}(0)+a_{n-1}\left(a^{n-1} T(a)-\sum_{k=0}^{n-2} a^{n-k-1} \tau^{(k)}(0)\right) \\
& +\cdots+a_{2}\left(a^{2} T(a)-a^{2} \tau(0)-a \tau^{\prime}(0)\right)+a_{1}(a T(a)-a \tau(0))+a_{0} T(a) \\
= & a^{n} T(a)-\sum_{k=0}^{n-1} a^{n-k} \tau^{(k)}(0)+a_{n-1} a^{n-1} T(a)-a_{n-1} \sum_{k=0}^{n-2} a^{n-k-1} \tau^{(k)}(0) \\
& +\cdots+a_{2} a^{2} T(a)-a_{2} a^{2} \tau(0)-a_{2} a \tau^{1}(0)+a_{1} a T(a)-a_{1} a \tau(0)+a_{0} T(a),
\end{aligned}
$$

$$
\begin{aligned}
& \begin{aligned}
& a^{n} T(a)+a_{n-1} a^{n-1} T(a)+\cdots+a_{2} a^{2} T(a)+a_{1} a T(a)+a_{0} T(a) \\
&=\sum_{k=0}^{n-1} a^{n-k} \tau^{(k)}(0)+a_{n-1} \sum_{k=0}^{n-2} a^{n-k-1} \tau^{(k)}(0)+\cdots+a_{2} a^{2} \tau(0)+a_{2} a \tau^{\prime}(0)+a_{1} a \tau(0), \\
& T(a)\left[a^{n}\right.\left.+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}\right] \\
&=\sum_{k=0}^{n-1} a^{n-k} \tau^{(k)}(0)+a_{n-1} \sum_{k=0}^{n-2} a^{n-k-1} \tau^{(k)}(0)+\cdots+a_{2} a^{2} \tau(0)+a_{2} a \tau^{\prime}(0)+a_{1} a \tau(0), \\
& T(a)=\frac{1}{\left[a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}\right]} \\
&\left\{\sum_{k=0}^{n-1} a^{n-k} \tau^{(k)}(0)+a_{n-1}^{n-2} \sum_{k=0}^{n-k-1} \tau^{(k)}(0)+\cdots+a_{2} a^{2} \tau(0)+a_{2} a \tau^{\prime}(0)+a_{1} a \tau(0)\right\}
\end{aligned}
\end{aligned}
$$

By (3.4), we have

$$
\psi\left[\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right]=0 .
$$

Since $\psi$ is a one-to-one operator,

$$
\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)=0
$$

Hence $\tau(t)$ is a solution of the differential equation (1.1).
By (3.3) and (3.4), we obtain

$$
\begin{aligned}
\psi[w(t)]-\psi[\tau(t)] & =\Omega(a)-T(a)=\frac{I(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =I(a) \frac{1}{a} \frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& \left.=\frac{1}{a} I(a) L(a)=\psi[i(t) * l(t)], \quad \text { (by using Theorem } 2.3\right)
\end{aligned}
$$

where $L(a)=\frac{a}{\left(a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}\right) t}$.
Here, we use the inverse Mahgoub transform method.
We know that, $\psi^{-1}\{L(a)\}=l(t)$. This implies

$$
l(t)=\psi^{-1}\left\{\frac{a}{\left(a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}\right) t}\right\} .
$$

So, $l(t)=\left[\left(a^{n}+a^{n-1}+\cdots+a^{2}+a^{1}+a^{0}\right)+\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)\right] t$.
For this, $e^{-V t}=\psi^{-1}\left(\frac{a}{V+a}\right)$. Thus we have

$$
e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}=\psi^{-1}\left\{\frac{a}{\left(a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}\right) t}\right\} .
$$

Then

$$
l(t)=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} .
$$

Consequently,

$$
\psi[w(t)-\tau(t)]=\psi[i(t) * l(t)]
$$

and thus

$$
w(t)-\tau(t)=i(t) * l(t) .
$$

Taking modulus on both sides, we have

$$
|w(t)-\tau(t)|=|i(t) * l(t)|=\left|\int_{0}^{t} i(s) l(t-s) d s\right| \leq \int_{0}^{t}|i(s)||l(t-s)| d s \leq \epsilon \int_{0}^{t}|l(t-s)| d s .
$$

Since $l(t)=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}$ (or) $l(t)=e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}$,

$$
\begin{aligned}
|w(t)-\tau(t)| & \leq \epsilon \int_{0}^{t} e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)} d s \\
& \leq \epsilon \int_{0}^{t} e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)} d s \\
& \leq \epsilon \int_{0}^{t} e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} \int_{0}^{t} e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\left[\frac{e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s}}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\right]_{0}^{t} \\
& \leq \epsilon\left[\frac{e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} \cdot e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}-\frac{e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\right] \\
& \leq \epsilon\left[\frac{1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\right] \\
& \leq \frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\left(1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right) \\
& \leq K \epsilon
\end{aligned}
$$

for all $t \geq 0$, where $K=\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}$.
This implies that the homogeneous linear differential equation (1.1) has Hyers-Ulam stability for the class $H$.

We note that if $-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)<0$, then

$$
\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\left(1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right)
$$

diverges to infinity as $t$ tends to infinity.
Hence, in the case of $-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)<0$, we notice that we cannot prove the Hyers-Ulam stability by applying the Mahgoub transform method.

Similar to Theorem 3.1, we will prove the Hyers-Ulam $\sigma$-stability for the differential equation (1.1). For the sake of the completeness of this paper, the proof is introduced here in detail.

Theorem 3.2. Assume that $\sigma:[0, \infty) \rightarrow(0, \infty)$ is an increasing function and $a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}$ is a constant with $R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)>0$. Then the differential equation (1.1) has the Hyers-Ulam $\sigma$-stability for the class $H$.

Proof. Assume that $w \in H$ and $\sigma:[0, \infty) \rightarrow(0, \infty)$ is an increasing function the inequality (2.4) for all $t \geq 0$. If we define a function $i:[0, \infty) \rightarrow \mathbb{K}$ by

$$
i(t)=w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)
$$

for all $t \geq 0$, then $|i(t)| \leq \sigma(t) \epsilon$ for all $t \geq 0$.
As we did in the first part of theorem 3.1, we can prove that $\tau(t)=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} w(0)$ is a solution of the differential equation (1.1). Of course, $\tau \in H$. On the other hand,

$$
L(a)=\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}
$$

which gives

$$
l(t)=\psi^{-1}\left[\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}\right]=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+\left[a_{0}-x\right]\right) t} .
$$

Moreover, it follows from (3.3) and (3.4) that

$$
\begin{aligned}
\psi[w(t)]-\psi[\tau(t)] & =\Omega(a)-T(a)=\frac{I(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =I(a) \frac{1}{a} \frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =\frac{1}{a} I(a) L(a)=\psi[i(t) * l(t)],
\end{aligned}
$$

which yields that

$$
\begin{equation*}
\psi[w(t)-\tau(t)]=\psi[i(t) * l(t)] . \tag{3.5}
\end{equation*}
$$

Therefore,

$$
w(t)-\tau(t)=i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} .
$$

By a similar method to the proof of Theorem 3.1, we can show that

$$
\begin{aligned}
|w(t)-\tau(t)| & =\left|i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right|=\left|\int_{0}^{t} i(s) e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)} d s\right| \\
& \leq \int_{0}^{t}|i(s)|\left|e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)}\right| d s \\
& \leq \sigma(t) \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)} \int_{0}^{t} e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq \frac{\sigma(t) \epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\left(1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right) \\
& \leq K \sigma(t) \epsilon
\end{aligned}
$$

for all $t \geq 0$, where $K=\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}$.

Now, we are going to establish the Mittag-Liffler-Hyers-Ulam stability of the differential equation (1.1) by using Mahgoub transform.

Theorem 3.3. Let $a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}$ and $\beta$ be constants satisfying $R\left(a_{n-1}+\ldots+a_{2}+a_{1}+a_{0}\right)>0$ and $\beta>0$. Then the homogeneous linear differential equation (1.1) has Mittag-Liffler-Hyers-Ulam stability for the class $H$.

Proof. Assume that $w(t) \in H$ and it satisfies the inequality (2.6) for all $t \geq 0$. Let $i:[0, \infty) \rightarrow \mathbb{K}$ be a function defined by

$$
i(t)=w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)
$$

for all $t \geq 0$.
In view of (2.6), we have $|i(t)| \leq \epsilon$ for all $t \geq 0$. Mahgoub transform of $i(t)$ gives the following:

$$
\begin{aligned}
I(a)=\psi(i(t)) & =\psi\left[w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)\right] \\
& =a^{n} \Omega(a)-\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+a_{2}\left(a^{2} \Omega(a)-a^{2} w(0)-a w^{\prime}(0)\right)+a_{1}(a \Omega(a)-a w(0))+a_{0} \Omega(a) .
\end{aligned}
$$

Thus we get

$$
\begin{align*}
\psi[w(t)] & =\Omega(t)=I(a)+\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{3.6}
\end{align*}
$$

If we put $\tau(t)=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} w(0)$, then $\tau(0)=w(0)$ and $\tau \in H$. Mahgoub transform of $\tau(t)$ gives

$$
\begin{align*}
\psi[\tau(t)]=T(t) & =\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{3.7}
\end{align*}
$$

Thus, it follows from (3.7) that

$$
\begin{aligned}
\psi\left[\tau^{(n)}(t)\right. & \left.+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right] \\
& =a^{n} T(a)-\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+a_{2}\left(a^{2} T(a)-a^{2} \tau(0)-a \tau^{\prime}(0)\right)+a_{1}(a T(a)-a \tau(0))+a_{0} T(a)=0 .
\end{aligned}
$$

Since $\psi$ is a one-to-one operator,

$$
\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)=0
$$

If we set $L(a)=\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}$, then we get

$$
\begin{equation*}
l(t)=\psi^{-1}\left[\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}\right]=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} . \tag{3.8}
\end{equation*}
$$

By (3.6) and (3.7), we obtain

$$
\begin{align*}
\psi[w(t)]-\psi[\tau(t)] & =\Omega(a)-T(a)=\frac{I(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =I(a) \frac{1}{a} \frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =\frac{1}{a} I(a) L(a)=\psi[i(t) * l(t)] . \tag{3.9}
\end{align*}
$$

This gives $w(t)-\tau(t)=i(t) * l(t)=i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}$.
Taking modulus on both sides and using the fact that $|i(t)| \leq \epsilon E_{\beta}(t)$ for $t \geq 0$ and $E_{\beta}(t)$ is increasing for $t \geq 0$, we have

$$
\begin{aligned}
|w(t)-\tau(t)| & =\left|i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right| \\
& =\left|\int_{0}^{t} i(s) e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)} d s\right| \\
& \leq \int_{0}^{t}|i(s)|\left|e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)}\right| d s \\
& \leq E_{\beta}(t) \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)} \int_{0}^{t} e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq \frac{E_{\beta}(t) \epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\left(1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right) \\
& \leq K E_{\beta}(t) \epsilon
\end{aligned}
$$

for all $t \geq 0$, where $K=\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}$.
Then, by Definition 2.11, we can confirm that the homogeneous linear differential equation (1.1) has Mittag-Liffler-Hyers-Ulam stability for the class $H$.

Similar to the case of Theorem 3.3, the Mittag-Liffler-Hyers-Ulam $\sigma$-stability for the linear differential equation (1.1) can be proved.

Theorem 3.4. Assume that $\sigma:[0, \infty) \rightarrow(0, \infty)$ is an increasing function and $a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}$ and $\beta$ are constants which satisfy $R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)>0$. Then the differential equation (1.1) has the Mittag-Liffler-Hyers-Ulam $\sigma$-stability for the class $H$.

Proof. Assume that $w \in H$ and $\sigma:[0, \infty) \rightarrow(0, \infty)$ is a function and that $w(t)$ and $\tau(t)$ satisfy the inequality (2.8) for all $t \geq 0$. We will prove that there exist a positive integer $K>0$ (independent of $\epsilon$ ) and a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.1) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K \sigma(t) \epsilon E_{\beta}(t)
$$

for all $t \geq 0$.

If we define a function $i:[0, \infty) \rightarrow \mathbb{K}$ by

$$
\begin{equation*}
i(t)=w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t) \tag{3.10}
\end{equation*}
$$

for all $t \geq 0$, then we have $|i(t)| \leq \sigma(t) \epsilon E_{\beta}(t)$ for all $t \geq 0$.
Then, by applying the same method as presented in the proof of Theorem 3.3, we can easily get

$$
\begin{aligned}
|w(t)-\tau(t)| & =\left|i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right|=\left|\int_{0}^{t} i(s) e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)} d s\right| \\
& \leq \int_{0}^{t}\left|i(s) \| e^{-\left(\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)\right.}\right| d s \\
& \leq \sigma(t) E_{\beta}(t) \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)} \int_{0}^{t} e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq \frac{\sigma(t) E_{\beta}(t) \epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\left(1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right) \\
& \leq K \sigma(t) E_{\beta}(t) \epsilon
\end{aligned}
$$

for all $t \geq 0$, where $K=\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}$.
Then, by Definition 2.12, we can confirm that the homogeneous linear differential equation (1.1) has Mittag-Liffler-Hyers-Ulam $\sigma$-stability for the class $H$.

## 4. Hyers-Ulam stability of (1.2)

In this section, we prove several types of Hyers-Ulam stability of the nonhomogeneous $n^{\text {th }}$ order linear differential equation (1.2) by using Mahgoub transform.

Theorem 4.1. Assume that $m:[0, \infty) \rightarrow \infty$ is a continuous function of exponential order and $a_{n-1}+$ $\cdots+a_{2}+a_{1}+a_{0}$ is a constant with $R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)>0$. The homogeneous linear differential equation (1.1) has the Hyers-Ulam stability for the class $H$.

Proof. Suppose that $w \in H$ satisfies the inequality (2.3) for all $t \geq 0$. Consider the function $i:[0, \infty) \rightarrow$ $\mathbb{K}$ by

$$
\begin{equation*}
i(t)=w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0}(t) w(t)-m(t) \tag{4.1}
\end{equation*}
$$

for all $t \geq 0$.
Then it holds that $|i(t)| \leq \epsilon$ holds for all $t \geq 0$. Mahgoub transform of $i(t)$ gives the following:

$$
\begin{equation*}
I(a)=\psi(i(t))=\psi\left[w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)\right] . \tag{4.2}
\end{equation*}
$$

This implies that

$$
\begin{align*}
\psi[w(t)] & =\Omega(t)=I(a)+\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)-M(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{4.3}
\end{align*}
$$

If we set

$$
\tau(t)=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} w(0)+\left(m(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right),
$$

then $\tau(0)=w(0)$ and $\tau \in H$. Mahgoub transform of $\tau(t)$ gives the following:

$$
\begin{align*}
\psi[\tau(t)]=T(a) & =\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)+M(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{4.4}
\end{align*}
$$

On the other hand,

$$
\begin{aligned}
\psi\left[\tau^{(n)}(t)\right. & \left.+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right] \\
& =a^{n} T(a)-\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} T(a)-\sum_{k=0}^{n-2} a^{n-k-1} \tau^{(k)}(0)\right) \\
& +\cdots+a_{2}\left(a^{2} T(a)-a^{2} \tau(0)-a \tau^{\prime}(0)\right)+a_{1}(a T(a)-a \tau(0))+a_{0} T(a) .
\end{aligned}
$$

By (4.4), we have

$$
\psi\left[\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right]=M(a)=\psi[m(t)]
$$

and thus

$$
\begin{equation*}
\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)=m(t) . \tag{4.5}
\end{equation*}
$$

Hence $\tau(t)$ is a solution of the differential equation (1.1).
In addition, by applying (4.3) and (4.4), we obtain

$$
\begin{aligned}
\psi[w(t)]-\psi[\tau(t)] & =\Omega(a)-T(a)=\frac{I(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =I(a) \frac{1}{a} \frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =\frac{1}{a} I(a) L(a)=\psi[i(t) * l(t)],
\end{aligned}
$$

where $L(a)=\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}$. This gives

$$
l(t)=\psi^{-1}\left[\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}\right]=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}
$$

Therefore, we have

$$
\psi[w(t)-\tau(t)]=\psi[i(t) * l(t)]=\psi\left[i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right],
$$

which yields

$$
\begin{equation*}
w(t)-\tau(t)=i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} . \tag{4.6}
\end{equation*}
$$

Furthermore,

$$
\begin{aligned}
|w(t)-\tau(t)| & =\left|\int_{0}^{t} i(s) l(t-s) d s\right| \leq \int_{0}^{t}|i(s)||l(t-s)| d s \leq \epsilon \int_{0}^{t}|l(t-s)| d s \\
& \leq \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+\left[a_{0}-x\right]\right)(t)} \int_{0}^{t} e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq \frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\left(1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right) \\
& \leq K \epsilon
\end{aligned}
$$

for all $t \geq 0$, where $K=\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}$.
For the Hyers-Ulam $\sigma$-stability of the nonhomogeneous linear differential equation (1.2), we obtain the following theorem.

Theorem 4.2. Assume that $m:[0, \infty) \rightarrow(0, \infty)$ is an continuous function of exponential order and $\sigma:[0, \infty) \rightarrow(0, \infty)$ is an increasing function and that $a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}$ is a constant with $R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)>0$. Then the differential equation (1.2) has the Hyers-Ulam $\sigma$-stability for the class $H$.

Proof. We consider an arbitrary function $w \in H$ that satisfies the inequality (2.5) for all $t \geq 0$. Now, we define a function $i:[0, \infty) \rightarrow \mathbb{K}$ by

$$
i(t)=w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)
$$

for all $t \geq 0$. Then $|i(t)| \leq \sigma(t) \epsilon$ for all $t \geq 0$.
It is not difficult to check that

$$
\begin{align*}
\psi[w(t)] & =\Omega(t)=I(a)+\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)+M(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{4.7}
\end{align*}
$$

If we set

$$
\tau(t)=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} w(0)+\left(m(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right),
$$

then $\tau(0)=w(0)$ and $\tau \in H$. Further, we apply the Mahgoub transform on both sides to get

$$
\begin{align*}
\psi[\tau(t)]=T(a) & =\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)=M(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{4.8}
\end{align*}
$$

On the other hand,

$$
\psi\left[\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right]
$$

$$
\begin{aligned}
& =a^{n} T(a)-\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+a_{2}\left(a^{2} T(a)-a^{2} \tau(0)-a \tau^{\prime}(0)\right)+a_{1}(a T(a)-a \tau(0))+a_{0} T(a) .
\end{aligned}
$$

The relation (4.8) implies that

$$
\psi\left[\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right]=M(a)=\psi[m(t)]
$$

and thus

$$
\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)=m(t) .
$$

That is, $\tau(t)$ is a solution of the differential equation (1.2). Using (4.7) and (4.8), we obtain

$$
\begin{aligned}
\psi[w(t)]-\psi[\tau(t)] & =\Omega(a)-T(a)=\frac{I(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =I(a) \frac{1}{a} \frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =\frac{1}{a} I(a) L(a)=\psi[i(t) * l(t)],
\end{aligned}
$$

where $L(a)=\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}$. This gives

$$
l(t)=\psi^{-1}\left[\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}\right]=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} .
$$

Therefore, we have

$$
\psi[w(t)-\tau(t)]=\psi[i(t) * l(t)],
$$

which gives

$$
w(t)-\tau(t)=i(t) * l(t) .
$$

Similar to the proof of Theorem 3.2, we have

$$
\begin{aligned}
|w(t)-\tau(t)| & =|i(t) * l(t)|=\left|\int_{0}^{t} i(s) l(t-s) d s\right| \leq \int_{0}^{t}|i(s)||l(t-s)| d s \leq \epsilon \int_{0}^{t}|l(t-s)| d s \\
& \leq \sigma(t) \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)} \int_{0}^{t} e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq K \sigma(t) \epsilon
\end{aligned}
$$

for all $t \geq 0$, where $K=\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}$.
Now, we prove the Mittag-Liffler-Hyers-Ulam stability of the nonhomogeneous linear differential equation (1.1) by using Mahgoub transform method.

Theorem 4.3. Assume that $m:[0, \infty) \rightarrow(0, \infty)$ is an continuous function of exponential order and that $a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}$ and $\beta$ are constants satisfying $R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)>0$ and $\beta>0$. Then the nonhomogeneous linear differential equation (1.2) has Mittag-Liffler-Hyers-Ulam stability for the class $H$.

Proof. Suppose that $w \in H$ and $w(t)$ satisfies the inequality (2.7) for alll $t \geq 0$. Consider a function $i:[0, \infty) \rightarrow \mathbb{K}$ defined by

$$
i(t)=w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)
$$

for all $t \geq 0$.
It follows from (2.7) that $|i(t)| \leq E_{\beta}(t) \epsilon$ for all $t \geq 0$. Mahgoub transform of $i(t)$ gives the following:

$$
I(a)=\psi(i(t))=\psi\left[w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)\right] .
$$

That is,

$$
\begin{align*}
\psi[w(t)] & =\Omega(t)=I(a)+\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)+M(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{4.9}
\end{align*}
$$

If we set $\tau(t)=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} w(0)+\left(m(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right)$, then $\tau(0)=w(0)$ and $\tau \in H$. We apply the Mahgoub transform on both sides of the last equality to get

$$
\begin{align*}
\psi[\tau(t)]=T(a) & =\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} \Omega(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+\frac{a_{2} a^{2} w(0)+a_{2} a w^{\prime}(0)+a_{1} a w(0)+M(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} . \tag{4.10}
\end{align*}
$$

On the other hand

$$
\begin{aligned}
\psi\left[\tau^{(n)}(t)\right. & \left.+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right] \\
& =a^{n} T(a)-\sum_{k=0}^{n-1} a^{n-k} w^{(k)}(0)+a_{n-1}\left(a^{n-1} T(a)-\sum_{k=0}^{n-2} a^{n-k-1} w^{(k)}(0)\right) \\
& +\cdots+a_{2}\left(a^{2} T(a)-a^{2} \tau(0)-a \tau^{\prime}(0)\right)+a_{1}(a T(a)-a \tau(0))+a_{0} T(a)=0 .
\end{aligned}
$$

Then by (4.10), we have

$$
\psi\left[\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)\right]=M(a)=\psi[m(t)]
$$

and thus

$$
\tau^{(n)}(t)+a_{n-1} \tau^{(n-1)}(t)+\cdots+a_{2} \tau^{\prime \prime}(t)+a_{1} \tau^{\prime}(t)+a_{0} \tau(t)=m(t)
$$

Hence $\tau(t)$ is a solution of the differential equation (1.2). In addition, by applying (3.6) and (4.10), we can obtain

$$
\psi[w(t)]-\psi[\tau(t)]=\Omega(a)-T(a)=\frac{I(a)}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}
$$

$$
\begin{align*}
& =I(a) \frac{1}{a} \frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}} \\
& =\frac{1}{a} I(a) L(a)=\psi[i(t) * l(t)], \tag{4.11}
\end{align*}
$$

where $L(a)=\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}$. This gives

$$
\begin{equation*}
l(t)=\psi^{-1}\left[\frac{a}{a^{n}+a_{n-1} a^{n-1}+\cdots+a_{2} a^{2}+a_{1} a+a_{0}}\right]=e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t} . \tag{4.12}
\end{equation*}
$$

Therefore, we have $\psi[w(t)]-\psi[\tau(t)]=\psi[i(t) * l(t)]$, which yields $w(t)-\tau(t)=i(t) * l(t)$ for all $t \geq 0$.
Furthermore,

$$
\begin{aligned}
|w(t)-\tau(t)| & =\left|i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right|=\left|\int_{0}^{t} i(s) e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)} d s\right| \\
& \leq \int_{0}^{t}\left|i(s) \| e^{-\left(\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)\right.}\right| d s \\
& \leq E_{\beta}(t) \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)} \int_{0}^{t} e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq \frac{E_{\beta}(t) \epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\left(1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right) \\
& \leq K E_{\beta}(t) \epsilon
\end{aligned}
$$

for all $t \geq 0$, where $K=\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}$. This completes the proof.
Similar to the case of Theorem 4.3, the Mittag-Liffler-Hyers-Ulam $\sigma$-stability for the linear differential equation (1.2) can be proved.

Theorem 4.4. Assume that $m:[0, \infty) \rightarrow(0, \infty)$ is an continuous function of exponential order and that $\sigma:[0, \infty) \rightarrow(0, \infty)$ is an increasing function and $a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}$ and $\beta$ are constants which satisfy $R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)>0$. Then the nonhomogeneous linear differential equation (1.2) has the Mittag-Liffler-Hyers-Ulam $\sigma$-stability for the class $H$.

Proof. Assume that $w \in H$ satisfies the inequality (2.9) for all $t \geq 0$. It is easy to prove that there exist a constant $K>0$ (independent of $\epsilon$ ) and a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of the differential equation (1.2) such that $\tau \in H$ and

$$
|w(t)-\tau(t)| \leq K \sigma(t) \epsilon E_{\beta}(t),
$$

for all $t \geq 0$.
If we define a function $i:[0, \infty) \rightarrow \mathbb{K}$ by

$$
i(t)=w^{(n)}(t)+a_{n-1} w^{(n-1)}(t)+\cdots+a_{2} w^{\prime \prime}(t)+a_{1} w^{\prime}(t)+a_{0} w(t)-m(t)
$$

for all $t \geq 0$, then we have $|i(t)| \leq \sigma(t) \epsilon E_{\beta}(t)$ for all $t \geq 0$.
By applying a similar method as in the proof of Theorem 4.3, we can easily prove that there exists a solution $\tau:[0, \infty) \rightarrow \mathbb{K}$ of (1.2) satisfying $\tau \in H$ and

$$
|w(t)-\tau(t)|=\left|i(t) * e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right|=\left|\int_{0}^{t} i(s) e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)} d s\right|
$$

$$
\begin{aligned}
& \leq \int_{0}^{t}\left|i(s) \| e^{-\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)(t-s)}\right| d s \\
& \leq \sigma(t) E_{\beta}(t) \epsilon e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)} \int_{0}^{t} e^{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) s} d s \\
& \leq \frac{\sigma(t) E_{\beta}(t) \epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}\left(1-e^{-R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right) t}\right) \\
& \leq K \sigma(t) E_{\beta}(t) \epsilon
\end{aligned}
$$

for all $t \geq 0$, where $K=\frac{\epsilon}{R\left(a_{n-1}+\cdots+a_{2}+a_{1}+a_{0}\right)}$. This completes the proof.

## 5. Conclusions

In this paper, we demonstrated the Hyers-Ulam stability, Hyers-Ulam $\sigma$-stability, Mittag-Leffler-Hyers-Ulam stability, and Mittag-Leffler-Hyers-Ulam $\sigma$-stability of the linear differential equations of $n^{\text {th }}$-order with constant coefficients using Mahgoub transform method. All in all, we set up adequate models for the Hyers-Ulam stability of $n^{\text {th }}$-order linear differential equations with steady coefficients utilizing the Mahgoub transform method. Additionally, this paper gives another technique to research the Hyers-Ulam stability of differential equations. This is the primary endeavor to utilize the Mahgoub transform to demonstrate the Hyers-Ulam stability for linear differential equations of the $n^{\text {th }}$-order. Besides, this paper shows that the Mahgoub transform method is more convenient for investigating the stability problems for linear differential equations with constant coefficients.

## Acknowledgments

We would like to express our sincere gratitude to the anonymous referee for his/her helpful comments that will help to improve the quality of the manuscript. This work was supported by Basic Science Research Program through the National Research Foundation of Korea funded by the Ministry of Education, Science and Technology (NRF-2017R1D1A1B04032937).

## Conflict of interest

The authors declare that they have no competing interests.

## References

1. S. Aggarwal, Comparative study of Mohand and Mahgoub transforms, J. Adv. Res. Appl. Math. Stat., 4 (2019), 1-7.
2. S. Aggarwal, R. Chauhan, N. Sharma, A new application of Mahgoub transform for solving linear Volterra integral equations, Asian Resonance, 7 (2018), 46-48.
3. Q. H. Alqifiary, S. Jung, Laplace transform and generalized Hyers-Ulam stability of linear differential equations, Electron. J. Diff. Equ., 2014 (2014), 80.
4. C. Alsina, R. Ger, On some inequalities and stability results related to the exponential function, $J$. Inequal. Appl., 2 (1998), 373-380.
5. T. Aoki, On the stability of the linear transformation in Banach spaces, J. Math. Soc. Japan, 2 (1950), 64-66. https://doi.org/10.2969/jmsj/00210064
6. L. Backes, D. Dragičević, Shadowing for infinite dimensional dynamics and exponential trichotomies, P. Roy. Soc. Edinb. A, 151 (2021), 863-884. https://doi.org/10.1017/prm.2020.42
7. L. Backes, D. Dragičević, L. Singh, Shadowing for nonautonomous and nonlinear dynamics with impulses, Monatsh. Math., in press. https://doi.org/10.1007/s00605-021-01629-2
8. D. Dragičević, Hyers-Ulam stability for nonautonomous semilinear dynamics on bounded intervals, Mediterr. J. Math., 18 (2021), 71. https://doi.org/10.1007/s00009-021-01729-1
9. D. Dragičević, Hyers-Ulam stability for a class of perturbed Hill's equations, Results Math., 76 (2021), 129. https://doi.org/10.1007/s00025-021-01442-1
10. D. H. Hyers, On the stability of the linear functional equation, PNAS, 27 (1941), 222-224. https://doi.org/10.1073/pnas.27.4.222
11. S. Jung, Hyers-Ulam stability of linear differential equations of first order, Appl. Math. Lett., 17 (2004), 1135-1140. https://doi.org/10.1016/j.aml.2003.11.004
12. S. Jung, Hyers-Ulam stability of linear differential equations of first order. III, J. Math. Anal. Appl., 311 (2005), 139-146. https://doi.org/10.1016/j.jmaa.2005.02.025
13. S. Jung, Hyers-Ulam stability of a system of first order linear differential equations with constant coefficients, J. Math. Anal. Appl., 320 (2006), 549-561. https://doi.org/10.1016/j.jmaa.2005.07.032
14. M. M. A. Mahgoub, The new integral transform "Mahgoub transform", Adv. Theoret. Appl. Math., 11 (2016), 391-398.
15. T. Miura, On the Hyers-Ulam stability of a differentiable map, Sci. Math. Japon., 55 (2002), 17-24.
16. M. Obloza, Hyers stability of the linear differential equation, Rocznik Nauk.-Dydakt. Prace Mat., 13 (1993), 259-270.
17. M. Obloza, Connections between Hyers and Lyapunov stability of the ordinary differential equations, Rocznik Nauk.-Dydakt. Prace Mat., 14 (1997), 141-146.
18. J. M. Rassias, On approximation of approximately linear mappings by linear mappings, J. Funct. Anal., 46 (1982), 126-130. https://doi.org/10.1016/0022-1236(82)90048-9
19. Th. M. Rassias, On the stability of the linear mapping in Banach spaces, Proc. Amer. Math. Soc., 72 (1978), 297-300. https://doi.org/10.1090/S0002-9939-1978-0507327-1
20. H. Rezaei, S. Jung, Th. M. Rassias, Laplace transform and Hyers-Ulam stability of linear differential equations, J. Math. Anal. Appl., 403 (2013), 244-251. https://doi.org/10.1016/j.jmaa.2013.02.034
21. I. A. Rus, Ulam stabilities of ordinary differential equations in a Banach space, Carpathian J. Math., 26 (2010), 103-107.
22. S. E. Takahasi, T. Miura, S. Miyajima, On the Hyers-Ulam stability of the Banach spacevalued differential equation $y^{\prime}=\lambda y$, Bull. Korean Math. Soc., 39 (2002), 309-315. https://doi.org/10.4134/BKMS.2002.39.2.309
23. M. Sarfraz, Y. Li, Minimum functional equation and some Pexider-type functional equation, AIMS Mathematics, 6 (2021), 11305-11317. https://doi.org/10.3934/math. 2021656
24. P. S. Kumar, A. Viswanathan, Application of Mahgoub transform to mechanics, electrical circuit problems, Int. J. Sci. Res., 7 (2018), 195-197.
25. S. M. Ulam, Problems in modern mathematics, New York: John Wiley \& Sons Inc., 1964.
26. H. Vaezi, Hyers-Ulam stability of weighted composition operators on disc algebra, Int. J. Math. Comput., 10 (2011), 150-154.
27. G. Wang, M. Zhou, L. Sun, Hyers-Ulam stability of linear differential equations of first order, Appl. Math. Lett., 21 (2008), 1024-1028. https://doi.org/10.1016/j.aml.2007.10.020
28. Z. Wang, Approximate mixed type quadratic-cubic functional equation, AIMS Mathematics, 6 (2021), 3546-3561. https://doi.org/10.3934/math. 2021211
© 2022 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (http://creativecommons.org/licenses/by/4.0)
