## Research article

# On the existence of almost periodic solutions of impulsive non-autonomous Lotka-Volterra predator-prey system with harvesting terms 

Li Wang*, Hui Zhang and Suying Liu

School of Mathematics and Statistics, Northwestern Polytechnical University, Xi'an, Shaanxi 710072, China

* Correspondence: Email: lwangmath@ nwpu.edu.cn.


#### Abstract

In this paper, by using the Mawhin's continuation theorem, some easily verifiable sufficient conditions are obtained to guarantee the existence of almost periodic solutions of impulsive nonautonomous Lotka-Volterra predator-prey system with harvesting terms. Our result corrects the result obtained in [13]. An example and some remarks are given to illustrate the advantage of this paper.


Keywords: Mawhin's continuation theorem; almost periodic solution; impulsive differential equation; Lotka-Volterra system
Mathematics Subject Classification: 34C23, 34C25, 92D25

## 1. Introduction

Lotka-Volterra systems are very important mathematical models in the theory of mathematical biology, often deeply perturbed by activities of human exploitation, such as, crop-dusting, deforestation, hunting, harvesting. To accurately describe these systems, one need to use impulsive differential equations. Basic theory of impulsive differential equations can be found in monographs [1-3].

Over the years, much attention has been paid to the dynamical behaviors (such as, the permanence, extinction, global asymptotic behavior) of Lotka-Volterra systems with impulsive effects (see [4-6]). Thereinto, the existence of positive periodic solutions is important direction. Many important and interesting results can be found in [7-10] and references therein.

In paper [10], by applying the Mawhin's continuation theorem, the authors obtained the existence of periodic solutions of a non-autonomous Lotka-Volterra network-like predator-prey system with harvesting terms:

$$
\left\{\begin{array}{l}
N_{i}^{\prime}(t)=N_{i}(t)\left[a_{i}(t)-b_{i}(t) N_{i}(t)-\sum_{r=1, r \neq i}^{n} c_{i, r}(t) N_{r}(t)-\sum_{j=1}^{m} d_{i, j}(t) N_{n+j}(t)\right]-h_{i}(t),  \tag{1.1}\\
N_{n+j}^{\prime}(t)=N_{n+j}(t)\left[\alpha_{j}(t)-\beta_{j}(t) N_{n+j}(t)-\sum_{l=1, l \neq j}^{m} \gamma_{l, j}(t) N_{n+l}(t)+\sum_{i=1}^{n} \delta_{i, j}(t) N_{i}(t)\right]-e_{j}(t) .
\end{array}\right.
$$

The properties of almost periodic solutions of different classes of biological models have been extensively investigated during the years [11-15] since these states are more general that the pure periodicity and consistent with real world. In addition, as the generalization of periodicity, the interest in the investigation of almost periodic solutions of models is sometimes caused by the absence of periodic solutions [16].

In fact, the Mawhin's continuation theorem is one of the powerful and effective methods on the existence of periodic solutions to periodic systems (regardless of the systems with impulse or not). Concerning the almost periodic solutions, to our best knowledge, it is usually employed to prove the existence of almost periodic solutions for differential equations without impulse, such as [17, 18]. There are rarely articles applied this method to prove the existence of almost periodic solutions for impulsive differential equations, except $[19,20]$. Li and $\mathrm{Ye}[19]$ considered the existence of almost periodic solutions of impulsive non-autonomous Lotka-Volterra predator-prey system with harvesting terms:

$$
\left\{\begin{array}{l}
N_{i}^{\prime}(t)=N_{i}(t)\left[a_{i}(t)-b_{i}(t) N_{i}(t)-\sum_{r=1, r \neq i}^{n} c_{i, r}(t) N_{r}\left(t-\tau_{i, r}(t)\right)\right.  \tag{1.2}\\
\left.\quad-\sum_{j=1}^{m} d_{i, j}(t) N_{n+j}\left(t-\sigma_{i, j}(t)\right)\right]-h_{i}(t), t \neq t_{k}, i=1,2, \ldots n, \\
N_{n+j}^{\prime}(t)=N_{n+j}(t)\left[\alpha_{j}(t)-\beta_{j}(t) N_{n+j}(t)-\sum_{l=1, l \neq j}^{m} \gamma_{l, j}(t) N_{n+l}\left(t-\theta_{l, j}(t)\right)\right. \\
\left.\quad+\sum_{i=1}^{n} \delta_{i, j}(t) N_{i}\left(t-v_{i, j}(t)\right)\right]-e_{j}(t), \quad t \neq t_{k}, j=1,2, \ldots m, \\
N_{h}\left(t_{k}^{+}\right)=\left(1+\rho_{h k}\right) N_{h}\left(t_{k}\right), \quad h=1,2, \ldots n+m, k \in \mathbb{Z}^{+} .
\end{array}\right.
$$

where, $i=1,2, \ldots n, j=1,2, \ldots m, a_{i}(\cdot), b_{i}(\cdot)$, and $h_{i}(\cdot)$ are the ith prey species birth rate, death rate and harvesting rate, respectively; $\alpha_{j}(\cdot), \beta_{j}(\cdot)$ and $e_{j}(\cdot)$ stand for the jth predator species birth rate, death rate and harvesting rate, respectively; $c_{i, r}(\cdot)(i \neq r)$ represent the competition rate between the ith prey species and the rth prey species; $d_{i, j}(\cdot)$ represent the $j$ th predator species predation rate on the ith prey species; $\gamma_{l, j}(\cdot)(l \neq j)$ stand for the competition rate between the lth predator species and the jth predator species; $\delta_{i, j}(\cdot)$ stand for the transformation rate between the ith prey species and the $j$ th predator species; $\tau_{i, r}(\cdot), \sigma_{i, j}(\cdot), \theta_{l, j}(\cdot), v_{i, j}(\cdot)$ are the time delays; $\rho_{h k}$ are the impulsive oscillations.

In order to obtain the existence of almost periodic solutions of Eq (1.2), Li and Ye [19] transformed Eq (1.2) into Eq (3.1) in [19].

By employing Lemmas 2.3 and 2.4 in [19] and the Mawhin's continuation theorem in coincidence degree theory, the existence of almost periodic solutions of Eq (3.1) in [19] was obtained. Based on this, the existence of almost periodic solutions of Eq (1.2) was obtained (Theorem 3.1 in [19]). In the proving process, Li and Ye acquiesced that the almost periodic solutions of Eq (3.1) in [19] belonged to $C^{1}$, which is also an important and necessary condition in order to use Lemmas 2.3 and 2.4. However, obviously, the solutions of Eq (3.1) in [19] don't belong to $C^{1}$.

Motivated by these, we still use the Mawhin's continuation theorem to investigate the existence of almost periodic solutions of Eq (1.2). The main contribution of this paper is: (1) The result of this paper corrects and generalizes the previous results in [10, 19]; (2) The method used in this paper can
be applied to study the existence of almost periodic solutions of impulsive differential equations with linear impulsive perturbations.

The remaining parts of this paper are organized as follows: The next section presents some preliminaries; In section 3, by employing the Mawhin's continuation theorem of coincidence degree theory, a criterion is established for the existence of almost periodic solutions of system (1.2). Finally, an example and its corresponding numerical simulation are presented to explain our theoretical result.

## 2. Preliminaries

Some preliminaries will be presented in this section in order to prove our main result in Section 3.
Definition 2.1. ([21]) $\varphi(\cdot) \in C\left(\mathbb{R}, \mathbb{R}^{n}\right)$ is said to be almost periodic in sense of Bohr if $\forall \varepsilon>0$, there exists a relatively dense set $T(\varphi, \varepsilon)$ such that if $\tau \in T(\varphi, \varepsilon)$, then $|\varphi(t)-\varphi(t+\tau)|<\varepsilon$ for all $t \in \mathbb{R}$. Denote by ap $\left(\mathbb{R}, \mathbb{R}^{n}\right)$ all such functions.

Definition 2.2. ([3]) Let $\phi(\cdot)=\left(\phi_{1}(\cdot), \phi_{2}(\cdot), \ldots \phi_{n}(\cdot)\right)$ be a piecewise continuous function with first kind discontinuities at the points of a fixed sequence $\left\{t_{k}\right\}$, we call $\phi$ almost periodic if:

1) $\left\{t_{k}\right\}$ is equipotentially almost periodic, that is, $\forall \varepsilon>0$ there exists a relatively dense set of $\varepsilon$-almost periodic common for any sequences $\left\{t_{k}^{j}\right\}, t_{k}^{j}=t_{k+j}-t_{k}$;
2) $\forall \varepsilon>0, \exists \delta>0$ such that if the points $t^{\prime}, t^{\prime \prime}$ belong to the same interval of continuity and $\left|t^{\prime}-t^{\prime \prime}\right|<\delta$, then $\left|\phi_{i}\left(t^{\prime}\right)-\phi_{i}\left(t^{\prime \prime}\right)\right|<\varepsilon, i=1,2, \ldots n$;
3) $\forall \varepsilon>0$, there exists a relatively dense set $T\left(\phi_{i}, \varepsilon\right)$ such that if $\tau \in T\left(\phi_{i}, \varepsilon\right)$, then $\left|\phi_{i}(t)-\phi_{i}(t+\tau)\right|<\varepsilon$ for all $t \in \mathbb{R}$ which satisfy the condition $\left|t-t_{k}\right|>\varepsilon, i=1,2, \ldots n, k=0, \pm 1, \pm 2, \ldots$.

Denote by $A P\left(\mathbb{R}, \mathbb{R}^{n}\right)$ all such functions.
Now we introduce some basic notations. Let $g$ be continuous or piecewise continuous function, we denote $g^{M}=\sup _{t \in \mathbb{R}}|g(t)|, g^{L}=\inf _{t \in \mathbb{R}}|g(t)|$. Suppose $f \in a p\left(\mathbb{R}, \mathbb{R}^{n}\right)$ or $f \in A P\left(\mathbb{R}, \mathbb{R}^{n}\right), a(\lambda, f)$, $\Lambda_{f}=\{\lambda, a(\lambda, f) \neq 0\}$ and $m(f)$ denote the Fourier coefficient, Fourier exponent set and the mean value of $f$, respectively. $\bmod (f)$ means the module of $f$.

Further theory of almost periodic functions can be found in the literatures [22-28]. Besides, The following lemmas are important for our result.

Lemma 2.3. ([20] Favard's theorem of AP function) Suppose $f \in A P$, there exist $\alpha_{1}>\alpha>0$ such that $\forall \lambda \in \Lambda_{f}, \alpha_{1}>|\lambda|>\alpha, \Sigma_{i=1}^{\infty}\left|a\left(\lambda_{i}, f\right)\right|<+\infty$, then the primitive function of $f$ is almost periodic function in sense of Bohr.

Lemma 2.4. ([22]) Suppose $f, g \in a p$, the following two conditions are equivalent:

1) $\bmod (f) \subset \bmod (g)$;
2) For any $\varepsilon>0$, there exist $\delta>0$ such that $T(g, \delta) \subset T(f, \varepsilon)$.

Lemma 2.5. ([23]) The necessary and sufficient condition that a family $\mathcal{F}$ of functions from ap be relatively compact is that the following properties hold true:

1) $\mathcal{F}$ is equi-continuous;
2) $\mathcal{F}$ is equi-almost periodic;
3) For any $t \in \mathbb{R}$, the set of values of functions from $\mathcal{F}$ be relatively compact.

Let $X$ and $Z$ be real Banach spaces, $L: d o m L \subset X \rightarrow Z$ be a linear mapping, $N: X \rightarrow Z$ be a continuous mapping. $L$ is called a Fredholm mapping of index zero if $\operatorname{dimKer} L=\operatorname{codimIm} L<\infty$ and $\operatorname{ImL}$ is close in $Z$. If $L$ is a Fredholm mapping of index zero, there are continuous projects $P: X \rightarrow$ $X, Q: Z \rightarrow Z$ such that $\operatorname{Im} P=\operatorname{Ker} L, \operatorname{Im} L=\operatorname{Ker} Q=\operatorname{Im}(I-Q)$. It follows that $L \mid d o m L \cap \operatorname{Ker} P:$ $(I-P) X \rightarrow I m L$ is invertible. We denote the inverse of that map by $K_{p}$. If $\Omega$ is a open subset of $X$, the mapping $N$ on $\Omega \times[0,1]$ will be called $L$-compact on $\Omega$ if $Q N(\bar{\Omega} \times[0,1])$ is bounded and $K_{p}(I-Q) N: \bar{\Omega} \times[0,1] \rightarrow X$ is compact. Since ImQ is isomorphic to KerL, there exist isomorphisms $J: \operatorname{Im} Q \rightarrow \operatorname{KerL}$. The following result is proved in [29].
Lemma 2.6. (Mawhins continuation theorem) Let $\Omega \subset X$ be an open bounded set, L be a Fredholm mapping of index zero and $N$ be $L$-compact on $\bar{\Omega} \times[0,1]$. Assume

1) For each $\lambda \in(0,1)$, every solution $x$ of $L x=\lambda N(x, \lambda)$ is such that $x \notin \partial \Omega$;
2) For each $x \in \operatorname{Ker} L \cap \partial \Omega, Q N(x, 0) \neq 0$;
3) $\operatorname{deg}(J Q N(x, 0), \operatorname{Ker} L \cap \Omega, 0) \neq 0$.

Then $L x=N(x, 1)$ has at least one solution in domL $\cap \bar{\Omega}$.

## 3. Main results

In this section, by means of the Mawhin's continuation theorem of coincidence degree theory, we investigate the existence of almost periodic solutions of Eq (1.2). To do so, we firstly consider the following equation:

$$
\left\{\begin{array}{c}
y_{i}^{\prime}(t)=y_{i}(t)\left[a_{i}(t)-\bar{b}_{i}(t) y_{i}(t)-\sum_{r=1, r \neq i}^{n} \bar{c}_{i, r}(t) y_{r}\left(t-\tau_{i, r}(t)\right)\right.  \tag{3.1}\\
\left.\quad-\sum_{j=1}^{m} \bar{d}_{i, j}(t) y_{n+j}\left(t-\sigma_{i, j}(t)\right)\right]-\bar{h}_{i}(t), i=1,2, \ldots n, \\
y_{n+j}^{\prime}(t)=y_{n+j}(t)\left[\alpha_{j}(t)\right. \\
\quad-\bar{\beta}_{j}(t) y_{n+j}(t)-\sum_{l=1, l \neq j}^{m} \bar{\gamma}_{l, j}(t) y_{n+l}\left(t-\theta_{l, j}(t)\right) \\
\left.\quad+\sum_{i=1}^{n} \bar{\delta}_{i, j}(t) y_{i}\left(t-v_{i, j}(t)\right)\right]-\bar{e}_{j}(t), \quad j=1,2, \ldots m
\end{array}\right.
$$

where

$$
\begin{gathered}
\bar{b}_{i}(t)=b_{i}(t) \prod_{0<t_{k}<t}\left(1+\rho_{i k}\right), \quad \bar{h}_{i}(t)=h_{i}(t) \prod_{0<t_{k}<t}\left(1+\rho_{i k}\right)^{-1}, i, r=1,2, . . n, \\
\bar{c}_{i, r}(t)=c_{i, r}(t) \prod_{0<t_{k}<t-\tau_{i, t}(t)}\left(1+\rho_{r k}\right), \quad \bar{d}_{i, j}(t)=d_{i, j}(t) \prod_{0<t_{k}<t-\sigma_{i, j}(t)}\left(1+\rho_{n+j, k}\right), r \neq i ; \\
\bar{\beta}_{j}(t)=\beta_{j}(t) \prod_{0<t_{k}<t}\left(1+\rho_{n+j, k}\right), \quad \bar{e}_{j}(t)=e_{j}(t) \prod_{0<t_{k}<t}\left(1+\rho_{n+j, k}\right)^{-1}, l, j=1,2, \ldots m, \\
\bar{\gamma}_{l, j}(t)=\gamma_{l, j}(t) \prod_{0<t_{k}<t-\theta_{l j}(t)}\left(1+\rho_{n+l, k}\right), \quad \bar{b}_{i, j}(t)=\delta_{i, j}(t) \prod_{0<t_{k}<t-v_{i, j}(t)}\left(1+\rho_{i k}\right), l \neq j .
\end{gathered}
$$

Remark 3.1. In paper [19], the authors define $\bar{c}_{i, r}(t), \bar{d}_{i, j}(t), \bar{\gamma}_{l, j}(t)$ and $\bar{\delta}_{i, j}(t)$ in other forms. We think those should be the forms above. Throughout this paper, we suppose the following hypotheses hold:
$(H 1) a_{i}(\cdot), b_{i}(\cdot), c_{i, r}(\cdot), \tau_{i, r}(\cdot), d_{i, j}(\cdot), \sigma_{i, j}(\cdot), h_{i}(\cdot), \alpha_{j}(\cdot), \beta_{j}(\cdot), \gamma_{l, j}(\cdot), \theta_{l, j}(\cdot) \delta_{i, j}(\cdot), v_{i, j}(\cdot)$ and $e_{j}(\cdot)$ are all positive almost periodic functions in sense of Bohr, $i, r=1,2, \ldots n, l, j,=1,2, \ldots m .\left\{\rho_{h k}\right\}$ are almost periodic sequences, $h=1,2, \ldots, n+m,\left\{t_{k}\right\}$ is an equipotentially almost periodic sequence.
(H2) $\prod_{0<t_{k}<t}\left(1+\rho_{i k}\right), \prod_{0<t_{k}<t}\left(1+\rho_{n+j, k}\right), \prod_{0<t_{k}<t-\tau_{i, r}(t)}\left(1+\rho_{r k}\right), \prod_{0<t_{k}<t-\sigma_{i, j}(t)}\left(1+\rho_{n+j, k}\right), \prod_{0<t_{k}<t-\theta_{l, j}(t)}(1+$ $\left.\rho_{n+l, k}\right)$, and $\prod_{0<t_{k}<t-v_{i, j}(t)}\left(1+\rho_{i k}\right)$ are all positive almost periodic functions, $\inf _{t \in \mathbb{R}} \prod_{0<t_{k}<t}\left|\left(1+\rho_{i, k}\right)\right|>$ $0, \inf _{t \in \mathbb{R}} \prod_{0 \leq t_{k}<t}\left|\left(1+\rho_{n+j, k}\right)\right|>0, i, r=1,2, . . n, l, j=1,2, \ldots m$.
(H3) $m\left(\bar{b}_{i}\right)>0, m\left(\bar{\beta}_{j}\right)>0, m\left(a_{i}\right)^{2}-4 m\left(\bar{b}_{i}\right) m\left(\bar{h}_{i}\right)>0, m\left(\alpha_{j}\right)^{2}-4 m\left(\bar{\beta}_{j}\right) m\left(\bar{e}_{j}\right)>0, i=1,2, . . n, j=$ $1,2, \ldots m$.

The solutions of Eqs (1.2) and (3.1) satisfy the following relations:
Lemma 3.2. Suppose (H2) is satisfied, the following results hold:

1) If $N(t)=\left(N_{1}(t), \ldots, N_{n+m}(t)\right)$ is a positive AP solution of $E q$ (1.2), then

$$
y(t)=\left(y_{1}(t), \ldots, y_{n+m}(t)\right)=\left(\prod_{0<t_{k}<t}\left(1+\rho_{1 k}\right)^{-1} N_{1}(t), \ldots, \prod_{0<t_{k}<t}\left(1+\rho_{n+m, k}\right)^{-1} N_{n+m}(t)\right)
$$

is a positive ap solution of Eq (3.1);
2) If $y(t)=\left(y_{1}(t), \ldots, y_{n+m}(t)\right)$ is a positive ap solution of $E q(3.1)$, then

$$
N(t)=\left(N_{1}(t), \ldots, N_{n+m}(t)\right)=\left(\prod_{0<t_{k}<t}\left(1+\rho_{1 k}\right) y_{1}(t), \ldots, \prod_{0<t_{k}<t}\left(1+\rho_{n+m, k}\right) y_{n+m}(t)\right)
$$

is a positive AP solution of Eq (1.2).
Proof. If $N(t)=\left(N_{1}(t), \ldots, N_{n+m}(t)\right)$ is a positive $A P$ solution of $\operatorname{Eq}(1.2)$, for any $i=1,2, \ldots, n+m$,

$$
y_{i}\left(t_{k}^{+}\right)=\prod_{0<t_{l}<t_{k}^{+}}\left(1+\rho_{i l}\right)^{-1} N_{i}\left(t_{k}^{+}\right)=\prod_{0<t_{l}<t_{k}^{+}}\left(1+\rho_{i l}\right)^{-1}\left(1+\rho_{i k}\right) N_{i}\left(t_{k}\right)=y_{i}\left(t_{k}\right) .
$$

Since $\prod_{0<t_{k}<t}\left(1+\rho_{i k}\right) \in A P$, and $\inf _{t \in \mathbb{R}} \prod_{0<t_{k}<t}\left|\left(1+\rho_{i k}\right)\right|>0$, from [20], we know $\prod_{0<t_{k}<t}\left(1+\rho_{i k}\right)^{-1} \in$ $A P, i=1, \ldots n+m$. Then, $y(t)=\left(y_{1}(t), \ldots, y_{n+m}(t)\right) \in$ ap; If $y_{i}(\cdot) \in a p$, it follow from (H2) that $N_{i}(t)=\prod_{0<t_{k}<t}\left(1+\rho_{i k}\right) y_{i}(t) \in A P, i=1, \ldots n+m$. Similar as [19], the rest proof of Lemma 3.2 can be obtained easily, we omit it here.

By making the transformations $y_{i}(t)=e^{x_{i}(t)}, y_{n+j}(t)=e^{x_{n+j}(t)}, i=1,2, \ldots n, j=1, \ldots, m$, system (3.1) is changed into:

$$
\left\{\begin{align*}
x_{i}^{\prime}(t)=a_{i}(t)- & \bar{b}_{i}(t) e^{x_{i}(t)}-\sum_{r=1, r \neq i}^{n} \bar{c}_{i, r}(t) e^{x_{r}\left(t-\tau_{i, r}(t)\right)}  \tag{3.2}\\
& \quad-\sum_{j=1}^{m} \bar{d}_{i, j}(t) e^{x_{n+j}\left(t-\sigma_{i, j}(t)\right)}-\bar{h}_{i}(t) e^{-x_{i}(t)}, i=1,2, \ldots n, \\
x_{n+j}^{\prime}(t)=\alpha_{j}(t) & -\bar{\beta}_{j}(t) e^{x_{n+j}(t)}-\sum_{l=1, l \neq j}^{m} \bar{\gamma}_{l, j}(t) e^{x_{n+l}\left(t-\theta_{l j}(t)\right)} \\
& +\sum_{i=1}^{n} \bar{\delta}_{i, j}(t) e^{x_{i}\left(t-v_{i, j}(t)\right)}-\bar{e}_{j}(t) e^{-x_{n+j}(t)}, j=1,2, \ldots m
\end{align*}\right.
$$

Obviously, the existence of $a p$ solutions of Eq (3.2) can lead to the existence of strictly positive $a p$ solutions of Eq (3.1). Then, it follow from Lemma 3.2 that there exist strictly positive $A P$ solutions of Eq (1.2). Due to this, we concentrate on solving the existence of $a p$ solutions of Eq (3.2). we take

$$
\begin{gathered}
X_{1}=\left\{x=\left(x_{1}, \ldots, x_{m+n}\right) \in \operatorname{ap}: \bmod \left(x_{i}\right) \subset \bmod (F), \forall \lambda \in \Lambda_{x_{i}}, \alpha_{1}>|\lambda|>\alpha, i=1, \ldots, m+n\right\} \cup\{0\}, \\
Z_{1}=\left\{z=\left(z_{1}, \ldots z_{m+n}\right) \in \mathrm{AP}, z_{i}(\cdot) \text { are piecewise continuous with discontinuous points }\left\{t_{k}\right\},\right. \\
\left.\bmod \left(z_{i}\right) \subset \bmod (F), \forall \lambda \in \Lambda_{z i}, \alpha_{1}>|\lambda|>\alpha, \sum_{j=1}^{\infty}\left|a\left(\lambda_{j}, z_{i}\right)\right|<+\infty, i=1, \ldots, m+n\right\} \cup\{0\}, \\
Z_{2}=X_{2}=\left\{x=\left(h_{1}, h_{2}, \ldots, h_{m+n}\right) \in \mathbb{R}^{m+n}\right\},
\end{gathered}
$$

where, $\alpha$ and $\alpha_{1}$ are given positive constants, $F$ is given almost periodic function in sense of Bohr. Define $X=X_{1} \oplus X_{2}, Z=Z_{1} \oplus Z_{2}$ with the norm $\|\phi\|=\max _{1 \leq i \leq n+m} \sup _{t \in \mathbb{R}}\left|\phi_{i}(t)\right|, \phi \in X$ or $Z$.

By using Lemma 2.3, similar to the proof of Lemma 3.3 in [20], we can obtain

Lemma 3.3. $X$ and $Z$ are Banach spaces equipped with the norm $\|\cdot\|$.
Lemma 3.4. Let

$$
L: X \rightarrow Z, L\left(x_{1}, x_{2}, \ldots, x_{m+n}\right)=\left(\frac{d x_{1}}{d t}, \frac{d x_{2}}{d t}, \ldots, \frac{d x_{m+n}}{d t}\right)
$$

then $L$ is a Fredholm mapping of index zero.
Remark 3.5. (1) In Lemma 3.4 in [19], the authors took $\mathbb{X}=\mathbb{Z}=V_{1} \bigoplus V_{2}, L: \mathbb{X} \rightarrow \mathbb{Z}, L z=$ $z^{\prime}=\left(z_{1}^{\prime}, z_{2}^{\prime}, \ldots, z_{n+m}^{\prime}\right)$. Obviously, $z^{\prime}$ should belong to a piecewise continuous function space, hence, $\mathbb{Z}$ appeared in Lemma 3.3 in [19] was not suitable.
(2) If $f \in a p, \forall \lambda \in \Lambda_{f},|\lambda|>\alpha>0$, then $f$ has $a p$ primitive function. It doesn't hold for $A P$ function. Lemma 2.3 implies that if $f \in A P, \forall \lambda \in \Lambda_{f}, \alpha_{1}>|\lambda|>\alpha>0, \sum_{i=1}^{\infty}\left|a\left(\lambda_{i}, z\right)\right|<+\infty$, then $f$ has $a p$ primitive function. That is the reason why we take $Z_{1}$ like that.

Let

$$
\begin{gathered}
P: X \rightarrow X, P\left(x_{1}, \ldots, x_{n}, \ldots, x_{m+n}\right)=\left(m\left(x_{1}\right), \ldots, m\left(x_{n}\right), \ldots, m\left(x_{m+n}\right)\right), \\
Q: Z \rightarrow Z, Q\left(z_{1}, \ldots, z_{n}, \ldots, z_{m+n}\right)=\left(m\left(z_{1}\right), \ldots, m\left(z_{n}\right), \ldots, m\left(z_{m+n}\right)\right), \\
N: X \times[0,1] \rightarrow Z, N\left(x_{1}, \ldots, x_{n}, \ldots, x_{m+n}, \lambda\right)=\left(N\left(x_{1}, \lambda\right), \ldots, N\left(x_{n}, \lambda\right), \ldots N\left(x_{m+n}, \lambda\right)\right),
\end{gathered}
$$

where

$$
\begin{aligned}
& N\left(x_{i}(t), \lambda\right)=a_{i}(t)-\bar{b}_{i}(t) e^{x_{i}(t)}-\lambda \sum_{r=1, r \neq i}^{n} \bar{c}_{i, r}(t) e^{x_{r}\left(t-\tau_{i, r}(t)\right)} \\
& \\
& \quad-\lambda \sum_{j=1}^{m} \bar{d}_{i, j}(t) e^{x_{n+j}\left(t-\sigma_{i, j}(t)\right)}-\bar{h}_{i}(t) e^{-x_{i}(t)}, i=1,2, \ldots n, \\
& N\left(x_{n+j}(t), \lambda\right)=\alpha_{j}(t)-\bar{\beta}_{j}(t) e^{x_{n+j}(t)}-\lambda \sum_{l=1, l \neq j}^{m} \bar{\gamma}_{l, j}(t) e^{x_{n+t}\left(t-\theta_{l, j}(t)\right)} \\
& \\
& \quad+\lambda \sum_{i=1}^{n} \bar{\delta}_{i, j}(t) e^{x_{i}\left(t-v_{i, j}(t)\right)}-\bar{e}_{j}(t) e^{-x_{n+j}(t)}, j=1, \ldots, m,
\end{aligned}
$$

then we have:
Lemma 3.6. $N$ is L-compact on $\bar{\Omega},(\Omega$ is an open, bounded subset of $X$ ).
Proof. Firstly, it is easy to prove that $P$ and $Q$ are continuous projectors such that

$$
\operatorname{Im} P=\operatorname{Ker} L, \operatorname{Im} L=\operatorname{Im}(I-Q)=\operatorname{Ker} Q,
$$

where $I$ is identity mapping. Hence, $L \mid \operatorname{domL} \cap \operatorname{Ker} P:(I-P) X \rightarrow I m L$ is invertible. We denote the inverse of that map by $K_{p} . K_{p}: \operatorname{ImL} \rightarrow \operatorname{Ker} P \cap \operatorname{DomL}$ has the form:

$$
K_{p} z=K_{p}\left(z_{1}, z_{2}, \ldots, z_{n+m}\right)=\left(\int_{0}^{t} z_{1}(s) d s-m\left(\int_{0}^{t} z_{1}(s) d s\right), \ldots, \int_{0}^{t} z_{m+n}(s) d s-m\left(\int_{0}^{t} z_{m+n}(s) d s\right)\right)
$$

then,

$$
\begin{gathered}
Q N(x, \lambda)=\left(Q N\left(x_{1}, \lambda\right), \ldots, Q N\left(x_{m+n}, \lambda\right)\right), \\
K_{p}(I-Q) N(x, \lambda)=\left(f\left(x_{1}(t)\right)-Q f\left(x_{1}(t)\right), \ldots, f\left(x_{m+n}(t)\right)-Q f\left(x_{m+n}(t)\right)\right),
\end{gathered}
$$

where

$$
f\left(x_{i}(t)\right)=\int_{0}^{t}\left(N\left(x_{i}(s), \lambda\right)-Q N\left(x_{i}(s), \lambda\right)\right) d s, i=1,2, \ldots, n+m .
$$

Obviously, $Q N$ and $(I-Q) N$ are continuous, so is $K_{p}$. In fact, for any $z=\left(z_{1}, z_{2}, \ldots, z_{m+n}\right) \in Z_{1}=\operatorname{ImL}$, according to Lemma 2.3, we know $\int_{0}^{t} z_{i}(s) d s \in a p$. Besides, we have:

$$
\Lambda_{\int_{0}^{t} z_{i}(s) d s} \backslash\{0\}=\Lambda_{z_{i}}=\Lambda_{\int_{0}^{t} z_{i}(s) d s-m\left(\int_{0}^{t} z_{i}(s) d s\right)}, i=1,2, . . n+m .
$$

Since $\bmod \left(z_{i}\right) \subset \bmod (F)$, then $\bmod \left(\int_{0}^{t} z_{i}(s) d s\right) \subset \bmod (F)$. It follows from Lemma 2.4 that for any $\varepsilon>0$, there exists $\delta>0$ such that $T(F, \delta) \subset T\left(\int_{0}^{t} z_{i}(s) d s, \varepsilon\right)$. Let $l$ be the inclusion interval of $T(F, \delta)$. For any $t \notin[0, l]$, there exists $\xi \in T(F, \delta) \subset T\left(\int_{0}^{t} z_{i}(s) d s, \varepsilon\right)$ such that $t+\xi \in[0, l]$, hence, for any $i=1,2, \ldots n+m$,

$$
\begin{aligned}
\sup _{t \in \mathbb{R}}\left|\int_{0}^{t} z_{i}(s) d s\right| & \leq \sup _{t \in[0, l]}\left|\int_{0}^{t} z_{i}(s) d s\right|+\sup _{t \notin[0, l]}\left|\int_{0}^{t} z_{i}(s) d s-\int_{0}^{t+\xi} z_{i}(s) d s\right|+\sup _{t \notin[0, l]}\left|\int_{0}^{t+\xi} z_{i}(s) d s\right| \\
& \leq 2 \sup _{t \in[0, l]} \int_{0}^{t}\left|z_{i}(s)\right| d s+\sup _{t \notin[0, l]}\left|\int_{0}^{t} z_{i}(s) d s-\int_{0}^{t+\xi} z_{i}(s) d s\right| \\
& \leq 2 \int_{0}^{l}\left|z_{i}(s)\right| d s+\varepsilon .
\end{aligned}
$$

We can conclude that $K_{p}$ is continuous, and consequently, $K_{p}(I-Q) N$ is also continuous. In addition, we also have $K_{p}(I-Q) N(x, \lambda)$ is uniformly bounded in $\bar{\Omega} \times[0,1], Q N(\bar{\Omega} \times[0,1])$ is bounded and $K_{p}(I-Q) N(x, \lambda)$ is equicontinuous in $\bar{\Omega} \times[0,1]$. For any $x=\left(x_{1}, \ldots, x_{n+m}\right) \in \Omega, \lambda \in[0,1]$, since

$$
(I-Q) N(x, \lambda) \in Z_{1}=I m L, \Lambda_{K_{p}(I-Q) N\left(x_{i}, \lambda\right)}=\Lambda_{(I-Q) N\left(x_{i}, \lambda\right)},
$$

then, $\bmod \left(K_{p}(I-Q) N\left(x_{i}, \lambda\right)\right)=\bmod \left((I-Q) N\left(x_{i}, \lambda\right)\right) \subset \bmod (F)$. For any $\varepsilon>0, \exists \delta>0$ such that $T(F, \delta) \subset T\left(K_{p}(I-Q) N\left(x_{i}, \lambda\right), \varepsilon\right), i=1, \ldots, n+m$, hence, $K_{p}(I-Q) N$ is equi-almost periodic in $\Omega \times[0,1]$. According to Lemma 2.5 , we can immediately conclude that $K_{p}(I-Q) N \bar{\Omega}$ is compact, thus $N$ is $L$-compact on $\bar{\Omega}$.

Combining Lemmas 3.3-3.6, for Eq (3.2), we have the result:
Lemma 3.7. If (H1)-(H3) are all satisfied, then Eq (3.2) has at least one almost periodic solution (in sense of Bohr).

Proof. Define the isomorphism $J: \operatorname{Im} Q \rightarrow K e r L$ be an identity mapping. We search for an appropriate bounded open subset $\Omega$ for the application of Lemma 2.6. Corresponding to operator equation $L x=$ $\lambda N(x, \lambda), \lambda \in(0,1)$ we have:

$$
\begin{align*}
& x_{i}^{\prime}(t)= \lambda\left(a_{i}(t)-\bar{b}_{i}(t) e^{x_{i}(t)}-\lambda \sum_{r=1, r \neq i}^{n} \bar{c}_{i, r}(t) e^{x_{r}\left(t-\tau_{i, r}(t)\right)}\right. \\
&\left.-\lambda \sum_{j=1}^{m} \bar{d}_{i, j}(t) e^{x_{n+j}\left(t-\sigma_{i, j}(t)\right)}-\bar{h}_{i}(t) e^{-x_{i}(t)}\right), i=1,2, \ldots n,  \tag{3.3}\\
& x_{n+j}^{\prime}(t)=\lambda\left(\alpha_{j}(t)-\bar{\beta}_{j}(t) e^{x_{n+j}(t)}-\lambda \sum_{l=1, l \neq j}^{m} \bar{\gamma}_{l, j}(t) e^{x_{n+1}\left(t-\theta_{l, j}(t)\right)}\right. \\
&\left.+\lambda \sum_{i=1}^{n} \bar{\delta}_{i, j}(t) e^{x_{i}\left(t-v_{i, j}(t)\right)}-\bar{e}_{j}(t) e^{-x_{n+j}(t)}\right), j=1,2, \ldots m . \tag{3.4}
\end{align*}
$$

If $x=\left(x_{1}, \ldots, x_{n+m}\right) \in X$ is an almost periodic solution of system (3.2), then

$$
m\left(e^{x_{k}(t)} x_{k}^{\prime}(t)\right)=\lim _{T \rightarrow \infty} \frac{1}{T} \int_{0}^{T} e^{x_{k}(s)} x_{k}^{\prime}(s) d s=\lim _{T \rightarrow \infty} \frac{e^{z_{k}(T)}-e^{z_{k}(0)}}{T}=0, k=1, \ldots, n+m
$$

Multiplying $e^{x_{i}(t)}, i=1, \ldots, n$, and $e^{x_{n j}(t)}, j=1,2, \ldots m$, on both sides of the Eqs (3.3) and (3.4), respectively, then, taking the limit mean, we can obtain:

$$
\begin{align*}
& \left.\lambda m\left(\sum_{r=1, r \neq i}^{n} \bar{c}_{i, r}(t) e^{x_{r}\left(t-\tau_{i, r}(t)\right.}\right) e^{x_{i}(t)}+\sum_{j=1}^{m} \bar{d}_{i, j}(t) e^{x_{n+j}\left(t-\sigma_{i, j}(t)\right)} e^{x_{i}(t)}\right) \\
= & m\left(a_{i}(t) e^{x_{i}(t)}-\bar{b}_{i}(t) e^{2 x_{i}(t)}-\bar{h}_{i}(t)\right),  \tag{3.5}\\
& \lambda m\left(\sum_{l=1, l \neq j}^{m} \bar{\gamma}_{l, j}(t) e^{x_{n+l}\left(t-\theta_{l j}(t)\right)} e^{x_{n+j}(t)}-\sum_{i=1}^{n} \bar{\delta}_{i, j}(t) e^{x_{i}\left(t-v_{i, j}(t)\right)} e^{x_{n+j}(t)}\right) \\
= & m\left(\alpha_{j}(t) e^{x_{n+j}(t)}-\bar{\beta}_{j}(t) e^{2 x_{n+j}(t)}-\bar{e}_{j}(t)\right) . \tag{3.6}
\end{align*}
$$

From Eq (3.5), we can obtain:

$$
m\left(a_{i}(t) e^{x_{i}(t)}-\bar{b}_{i}(t) e^{2 x_{i}(t)}-\bar{h}_{i}(t)\right) \geq 0
$$

hence,

$$
0 \geq m\left(\bar{b}_{i}(t) e^{2 x_{i}(t)}-a_{i}(t) e^{x_{i}(t)}+\bar{h}_{i}(t)\right) \geq m\left(\bar{b}_{i}^{L} e^{2 x_{i}(t)}-a_{i}^{M} e^{x_{i}(t)}+\bar{h}_{i}^{L}\right) .
$$

We assert that there exist $\xi_{i}, i=1, \ldots, n$ such that

$$
\frac{a_{i}^{M}-\sqrt{\left(a_{i}^{M}\right)^{2}-4 \bar{b}_{i}^{L} \bar{h}_{i}^{L}}}{4 \bar{b}_{i}^{L}} \leq e^{x_{i}\left(\xi_{i}\right)} \leq \frac{3 a_{i}^{M}+\sqrt{\left(a_{i}^{M}\right)^{2}-4 \bar{b}_{i}^{L} \bar{h}_{i}^{L}}}{4 \bar{b}_{i}^{L}}, i=1, \ldots n,
$$

then, there exist at least one $\xi_{i}, i=1, \ldots, n$ such that

$$
\begin{equation*}
\left|x_{i}\left(\xi_{i}\right)\right|<\left|\ln \frac{a_{i}^{M}-\sqrt{\left(a_{i}^{M}\right)^{2}-4 \bar{b}_{i}^{L} \bar{h}_{i}^{L}}}{4 \bar{b}_{i}^{L}}\right|+\left|\ln \frac{3 a_{i}^{M}+\sqrt{\left(a_{i}^{M}\right)^{2}-4 \bar{b}_{i}^{L} \bar{h}_{i}^{L}}}{4 \bar{b}_{i}^{L}}\right|, i=1, \ldots n . \tag{3.7}
\end{equation*}
$$

Since $x_{i}^{\prime} \in Z_{1}, \int_{a}^{t} x_{i}^{\prime}(s) d s \in \operatorname{ap}, \bmod \left(\int_{a}^{t} x_{i}^{\prime}(s) d s\right) \subset \bmod (F), \forall a \in \mathbb{R}, i=1, \ldots, n$, it follows from Lemma 2.4 that for $\varepsilon=1$, there exist $\delta>0$ such that $T(F, \delta) \subset T\left(\int_{a}^{t} x_{i}^{\prime}(s) d s, 1\right)$. Let $l$ be the inclusion interval of $T(F, \delta)$. Same argument as Lemma 3.6 can drive that

$$
\begin{align*}
\left|x_{i}(t)\right| & =\left|x_{i}\left(\xi_{i}\right)+\int_{\xi_{i}}^{t} x_{i}^{\prime}(s) d s\right| \\
& \leq\left|x_{i}\left(\xi_{i}\right)\right|+\left|\int_{\xi_{i}}^{t} x_{i}^{\prime}(s) d s\right| \\
& \leq\left|x_{i}\left(\xi_{i}\right)\right|+1+2 \int_{\xi_{i}}^{\xi_{i}+l}\left|x_{i}^{\prime}(s)\right| d s,  \tag{3.8}\\
& -\lambda \sum_{j=1}^{m} \bar{d}_{i, j}(t) e^{x_{n+j}\left(s-\sigma_{i, j}(s)\right)}-\bar{h}_{i}(s) e^{-x_{i}(s)} \mid \\
\int_{\xi_{i}}^{\xi_{i}+l}\left|x_{i}^{\prime}(s)\right| d s & =\int_{\xi_{i}}^{\xi_{i}+l} \mid a_{i}(s)-\bar{b}_{i}(s) e^{x_{i}(s)}-\lambda \sum_{\xi_{i}}^{n} \bar{c}_{i, r}(t) e^{x_{r}\left(s-\tau_{i, r}(s)\right)} d s \\
& \left|a_{i}(s)\right| d s . \tag{3.9}
\end{align*}
$$

Combining (3.7)-(3.9), we know that for any $t \in \mathbb{R}, i=1, \ldots, n$

$$
\left\lvert\, x_{i}\left(t| | \leq 3 l a_{i}^{M}+3+\left|\ln \frac{a_{i}^{M}-\sqrt{\left(a_{i}^{M}\right)^{2}-4 \bar{b}_{i}^{L} \bar{h}_{i}^{L}}}{4 \bar{b}_{i}^{L}}\right|+\left|\ln \frac{3 a_{i}^{M}+\sqrt{\left(a_{i}^{M}\right)^{2}-4 \bar{b}_{i}^{L} \bar{h}_{i}^{L}}}{4 \bar{b}_{i}^{L}}\right| \triangleq x_{i}^{M} .\right.\right.
$$

Similar argument as above, from Eq (3.6), we know that:

$$
\begin{equation*}
m\left(\alpha_{j}(t) e^{x_{n+j}(t)}-\bar{\beta}_{j}(t) e^{2 x_{n+j}(t)}-\bar{e}_{j}(t)\right) \geq m\left(-\sum_{i=1}^{n} \bar{\delta}_{i, j}(t) e^{x_{i}\left(t-v_{i, j}(t)\right)} e^{x_{n+j}(t)}\right), \tag{3.10}
\end{equation*}
$$

hence,

$$
m\left(\alpha_{j}^{M} e^{x_{n+j}(t)}-\bar{\beta}_{j}^{L} e^{2 x_{n+j}(t)}-\bar{e}_{j}^{L}\right) \geq m\left(-\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e^{x_{i}^{M}} e^{x_{n+j}(t)}\right),
$$

then,

$$
m\left(\bar{\beta}_{j}^{L} e^{2 x_{n+j}(t)}-\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} j^{x_{i}^{M}}\right) e^{x_{n+j}(t)}+\bar{e}_{j}^{L}\right) \leq 0 .
$$

We assert that there exist $\xi_{n+j}, j=1, \ldots m$, such that

$$
\begin{aligned}
& \frac{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e^{m_{i}^{M}}\right)-\sqrt{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\sigma}_{i, j}^{M} e^{k_{i}^{M}}\right)^{2}-4 \bar{\beta}_{j}^{L} \bar{e}_{j}^{L}}}{4 \bar{\beta}_{j}^{L}} \leq e^{x_{n+j}\left(\xi_{n+j}\right)}, \\
& e^{x_{n+j}\left(\xi_{n+j}\right) \leq \frac{3\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e_{i}^{M}\right)+\sqrt{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e_{i}^{M}\right)^{2}-4 \bar{\beta}_{j}^{L} \bar{e}_{j}^{L}}}{4 \bar{\beta}_{j}^{L}}},
\end{aligned}
$$

then

$$
\begin{aligned}
\left|x_{n+j}\left(\xi_{n+j}\right)\right| \leq & \left|\ln \frac{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\sigma}_{i, j}^{M} e^{e_{i}^{M}}\right)-\sqrt{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e^{e_{i}^{M}}\right)^{2}-4 \bar{\beta}_{j}^{L} e_{j}^{L}}}{4 \bar{\beta}_{j}^{L}}\right| \\
& +\left\lvert\, \ln \frac{3\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\sigma}_{i, j}^{M} e_{i}^{M}\right)+\sqrt{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e_{i}^{M}\right)^{2}-4 \bar{\beta}_{j}^{L} \bar{e}_{j}^{L}}}{4 \overline{\bar{\beta}_{j}^{L}}} .\right.
\end{aligned}
$$

Similarly, for any $t \in \mathbb{R}, j=1, \ldots, m$, we have

$$
\begin{align*}
\left|x_{n+j}(t)\right| \leq & \left|x_{n+j}\left(\xi_{n+j}\right)\right|+1+2 \int_{\xi_{n+j}}^{\xi_{n+j}+l}\left|x_{n+j}^{\prime}(s)\right| d s \\
\leq & \left|x_{n+j}\left(\xi_{n+j}\right)\right|+1+2 \int_{\xi_{n+j}}^{\xi_{n+j}+l}\left|\alpha_{j}(s)+\sum_{i=1}^{n} \bar{\delta}_{i, j}(s) e^{x_{i}^{M}}\right| d s \\
\leq & 3+3 l\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e^{x_{i}^{M}}\right) \\
& +\left|\ln \frac{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e^{x_{i}^{M}}\right)-\sqrt{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e^{x_{i}^{M}}\right)^{2}-4 \bar{\beta}_{j}^{L} \bar{e}_{j}^{L}}}{4 \bar{\beta}_{j}^{L}}\right| \\
& +\left|\ln \frac{3\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e^{e_{i}^{M}}\right)+\sqrt{\left(\alpha_{j}^{M}+\sum_{i=1}^{n} \bar{\delta}_{i, j}^{M} e^{x_{i}^{M}}\right)^{2}-4 \bar{\beta}_{j}^{L} \bar{e}_{j}^{L}}}{4 \bar{\beta}_{j}^{L}}\right| \triangleq x_{n+j}^{M} . \tag{3.11}
\end{align*}
$$

Taking $\Omega=\left\{x \in X,\|x\| \leq 2 \max \left\{x_{1}^{M}, \ldots, x_{n+m}^{M}\right\}\right\}$, combining Lemma 2.6 in [9] and condition (H3), it is easy to prove that that $\Omega$ satisfies all the requirements in Lemma 2.6, hence system (3.2) has at least one almost periodic solution in $\Omega$. The proof of the theorem is complete.

From Lemma 3.7, we know that system (3.1) has at least one strictly positive almost periodic solution in $\Omega$. It follows from Lemma 3.2 that:

Theorem 3.8. If (H1)-(H3) are all satisfied, then Eq (1.2) has at least one strictly positive almost periodic solution.

Remark 3.9. (1) In order to obtain the existence of almost periodic solutions of Eq (1.2), Li and Ye [19] transformed Eq (1.2) into Eq (3.1) in [19]. Unfortunately, Eq (3.1) in [19] was not correct. Besides, They acquiesced that the almost periodic solution of Eq (3.1) in [19] belonged to $C^{1}$, which was also an important condition to get the existence of almost periodic solutions of Eq (1.2). However, obviously, the solution of Eq (3.1) in [19] don't belong to $C^{1}$.
(2) Compared this paper with [10], Eq (1.2) is more general. Moreover, it is more realistic to study almost periodic solution for a model than periodic solution. The sufficient conditions for the existence of almost periodic solutions are more easier verification. Therefore, this paper corrects and generalizes the previous results.
(3) The aim of this paper is to apply coincidence degree to study the existence of almost periodic solution of system (1.2). we set new functional space $Z_{1}$, and use the Favard's theorem of $A P$ function to realize our purpose. Our method used in this paper can be applied to study the existence of almost periodic solution of impulsive differential equations with linear impulsive perturbations.

## 4. Example

In this section, we present an example to demonstrate Theorem 3.8 obtained in previous section. Consider the following impulsive Lotka-Volterra predator-prey system (4.1) with harvesting terms:

$$
\left\{\begin{array}{l}
N_{1}^{\prime}(t)=N_{1}(t)\left[(5+\sin t)-\frac{1+\cos \pi t}{2} N_{1}(t)-d_{1,1}(t) N_{2}(t)-d_{1,2}(t) N_{3}(t)\right]-\frac{1+\sin \pi t}{2}, t \neq t_{k}, \\
N_{2}^{\prime}(t)=N_{2}(t)\left[(5+\sin 2 t)-\frac{1+\cos 2 \pi t}{2} N_{2}(t)-\gamma_{2,1}(t) N_{3}(t)+\delta_{1,1}(t) N_{1}(t)\right]-\frac{1+\sin 2 \pi t}{2}, t \neq t_{k}, \\
N_{3}^{\prime}(t)=N_{3}(t)\left[(5+\sin 3 t)-\frac{1+\cos 3 \pi t}{2} N_{3}(t)-\gamma_{1,2}(t) N_{2}(t)+\delta_{1,2}(t) N_{1}(t)\right]-\frac{1+\sin 4 \pi t}{2}, t \neq t_{k}, \\
N_{h}\left(t_{k}^{+}\right)=\left(1+\rho_{h k}\right) N_{h}\left(t_{k}\right), \quad h=1,2,3,
\end{array}\right.
$$

where, $d_{1,1}(t)=0.1, d_{1,2}(t)=0.04, \gamma_{1,2}(t)=0.04, \gamma_{2,1}(t)=0.15, \delta_{1,1}(t)=0.6, \delta_{1,2}(t)=0.8, t_{k}=$ $\{1,2,3, \ldots\}, \rho_{h k}=\left\{-\frac{1}{2}, 1,-\frac{1}{2}, 1,-\frac{1}{2}, 1, \ldots\right\}, h=1,2,3$.

Obviously, condition $(H 1)$ is satisfied. Moreover, $\prod_{0<t_{k}<t}\left(1+\rho_{i k}\right)$ are positive piecewise continuous periodic functions, $\inf _{t \in \mathbb{R}} \prod_{0<t_{k}<t}\left|\left(1+\rho_{i, k}\right)\right|=\frac{1}{2}>0, i=1,2,3$. Hence, condition (H2) holds. Besides, we have

$$
\begin{aligned}
& m\left(a_{1}\right)=m\left(\alpha_{1}\right)=m\left(\alpha_{2}\right)=5, \\
& m\left(\bar{b}_{1}\right)=m\left(\bar{\beta}_{1}\right)=m\left(\bar{\beta}_{2}\right)=m\left(\bar{e}_{1}\right)=m\left(\bar{e}_{2}\right)=\frac{3}{8}, \\
& m\left(\bar{h}_{i}\right)=\frac{3}{8}+\frac{3 \pi}{2} .
\end{aligned}
$$

Hence, condition (H3) holds. It follows from Theorem 3.8 that system (4.1) has at least one strictly positive almost periodic solution. By matlab, we can give the simulation of Eq (4.1), see Figure 1.


Figure 1. The existence of almost periodic solution for system (4.1).

## 5. Conclusions

Based on the Mawhins continuation theorem, the existence of almost periodic solutions of impulsive non-autonomous Lotka-Volterra predator prey system with harvesting terms was obtained. An example and some remarks are given to illustrate the advantage of this paper.

## Acknowledgments

This research is supported by the Natural Science Basic Research Programs of Shaanxi (No. 2021 JQ-079, No.2020JQ-102)

## Conflict of interest

The authors declared that they have no conflicts of interest to this work.

## References

1. D. D. Bainov, P. S. Simeonov, Impulsive differential equations: Periodic solution and applications, London: Longman, 1993. doi: 10.1201/9780203751206.
2. V. Lakshmikantham, D. D. Bainov, P. S. Simeonov, Theory of impulsive differential equations, Singpore: World Scientific, 1989. doi: 10.1142/0906.
3. A. M. Samoilenko, N. A. Perestyuk, Impulsive differential equations, Singpore: World Scientific, 1995. doi: 10.1142/2892.
4. X. N. Liu, L. S. Chen, Complex dynamics of Holling type II Lotka-Volterra predator-prey system with impulsive perturbations on the predator, Chaos Solitons Fractals, 16 (2003), 311-320. doi: 10.1016/S0960-0779(02)00408-3.
5. Y. H. Xia, Global analysis of an impulsive delayed Lotka-Volterra competition system, Commun. Nonlinear Sci. Numer. Simul., 16 (2011), 1597-1616. doi: 10.1016/j.cnsns.2010.07.014.
6. M. Liu, K. Wang, Asymptotic behavior of a stochastic nonautonomous Lotka-Volterra competitive system with impulsive perturbations, Math. Comput. Model., 57 (2013), 909-925. doi: 10.1016/j.mcm.2012.09.019.
7. Q. Wang, B. X. Dai, Y. M. Chen, Multiple periodic solutions of an impulsive predator-prey model with Holling-type IV functional response, Math. Comput. Model., 49 (2009), 1829-1836. doi: 10.1016/j.mcm.2008.09.008.
8. X. L. Hu, G. R. Liu, J. R. Yan, Existence of multiple positive periodic solutions of delayed predator-prey models with functional responses, Comput. Math. Appl., 52 (2006), 1453-1462. doi: 10.1016/j.camwa.2006.08.030.
9. K. H. Zhao, Y. Ye, Four positive periodic solutions to a periodic Lotka-Volterra predatory-prey system with harvesting terms, Nonlinear Anal. Real World Appl., 11 (2010), 2448-2455. doi: 10.1016/j.nonrwa.2009.08.001.
10. K. H. Zhao, Y. K. Li, Multiple positive periodic solutions to a non-autonomous Lotka-Volterra predator-prey system with harvesting terms, Electron. J. Differ. Equ., 49 (2011), 1-11.
11. C. J. Xu, P. l. Li, Y. Guo, Global asymptotical stability of almost periodic solutions for a nonautonomous competing model with time-varying delays and feedback controls, J. Biol. Dyn., 13 (2019), 407-421. doi: 10.1080/17513758.2019.1610514.
12. C. J. Xu, P. L. Li, Y. C. Pang, Existence and exponential stability of almost periodic solutions for neutral type BAM neural networks with distributed leakage delays, Math. Methods Appl. Sci., 40 (2017), 2177-2196. doi: $10.1002 / \mathrm{mma} .4132$.
13. C. J. Xu, M. X. Liao, P. L. Li, Z. X. Liu, S. Yuan, New results on pseudo almost periodic solutions of quaternion-valued fuzzy cellular neural networks with delays, Fuzzy Sets Syst., 411 (2021), 2547. doi: 10.1016/j.fss.2020.03.016.
14. G. Stamov, I. Stamov, A. Martynyuk, T. Stamov, Almost periodic dynamics in a new class of impulsive reaction-diffusion neural networks with fractional-like derivatives, Chaos Solitons Fractals, 143 (2021), 110647. doi: 10.1016/j.chaos.2020.110647.
15. C. Xu, M. Liao, P. Li, Q. Xiao, S. Yuan, A new method to investigate almost periodic solutions for an Nicholson's blowflies model with time-varying delays and a linear harvesting term, Math. Biosci. Eng., 16 (2019), 3830-3840. doi: 10.3934/mbe. 2019189.
16. E. Kaslik, S. Sivasundaram, Non-existence of periodic solutions in fractional-order dynamical systems and a remarkable difference between integer and fractional-order derivatives of periodic functions, Nonlinear Anal. Real World Appl., 13 (2012), 1489-1497. doi: 10.1016/j.nonrwa.2011.11.013.
17. J. O. Alzabut, G. T. Stamov, E. Sermutlu, Positive almost periodic solutions for a delay logarithmic population model, Math. Comput. Model., 53 (2011), 161-167. doi: 10.1016/j.mcm.2010.07.029.
18. Y. Xie, X. Li, Almost periodic solutions of single population model with hereditary effects, Appl. Math. Comput., 203 (2008), 690-697. doi: 10.1016/j.amc.2008.05.085.
19. Y. K. Li, Y. Ye, Multiple positive almost periodic solutions to an impulsive non-autonomous LotkaVolterra predator-prey system with harvesting terms, Commun. Nonlinear Sci. Numer. Simul., 18 (2013), 3190-3201. doi: 10.1016/j.cnsns.2013.03.014.
20. L. Wang, M. Yu, Favard's theorem of piecewise continuous almost periodic functions and its application, J. Math. Anal. Appl., 413 (2014), 35-46. doi: 10.1016/j.jmaa.2013.11.029.
21. C. Y. Zhang, Almost periodic type function and ergodicity, Springer, 2003.
22. C. Y. He, Almost periodic differential equations, Beijing: Higher Education Press, 1992.
23. C. Corduneanu, Almost periodic functions, 2 Eds, Chelsea, New York, 1989.
24. T. Diagana, Almost automorphic type and almost periodic type functions in abstract spaces, New York: Springer-Verlag, 2013. doi: 10.1007/978-3-319-00849-3.
25. A. M. Fink, Almost periodic differential equations, Berlin: Springer-Verlag, 1974. doi: 10.1007/BFb0070324.
26. M. Kostić, Almost periodic and almost automorphic type solutions to integro-differential equations, Berlin: De Gruyter, 2019. doi: 10.1515/9783110641851.
27. B. M. Levitan, Almost periodic functions, Gostekhi zdat, in Russian, Moscow, 1953.
28. G. M. N'Guerekata, Almost automorphic and almost periodic functions in abstract spaces, Boston: Springer, 2001. doi: 10.1007/978-1-4757-4482-8.
29. R. E. Gaines, J. L. Mawhin, Coincidence degree and nonlinear differential equation, Berlin: Springer-Verlay, 1977. doi: 10.1007/BFb0089537.


AIMS Press
© 2022 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (http://creativecommons.org/licenses/by/4.0)

