Mathematics

## Research article

# A conserved phase-field model based on type II heat conduction 

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#### Abstract

Our aim in this paper is to study the well-posedness of Caginalp phase-field model based on the theory of type II thermomechanics. More precisely, we prove the existence and uniqueness of solutions.


Keywords: conserved Caginalp model; type II heat conduction; well-posedness
Mathematics Subject Classification: 35K55, 35J60, 80A22

## 1. Introduction

G. Caginalp introduced in [1] and [2] the following phase-field systems:

$$
\begin{gather*}
\frac{\partial u}{\partial t}+\Delta^{2} u-\Delta f(u)=-\Delta \theta,  \tag{1.1}\\
\frac{\partial \theta}{\partial t}-\Delta \theta=-\frac{\partial u}{\partial t}, \tag{1.2}
\end{gather*}
$$

where $u$ is the order parameter and $\theta$ is the (relative) temperature. These equations model phase transition processes such as melting/solidification processes and have been studied, e.g., in [4] for a similar phase-field model with a memory term. Eqs. (1.1) - (1.2) consist of the coupling of the Cahn-Hilliard equation introduced in [18] with the heat equation and are known as the conserved phase-field model, in the sens that, when endowed with Neumann boundary conditions, the spatial average of the order parameter is a conserved quantity (see below). We refer the reader to, e.g., $[6-11,13,14,16,17,19,20,22-$ 25].

Equations (1.1) and (1.2) are based on the total free energy

$$
\begin{equation*}
\psi(u, \theta)=\int_{\Omega}\left(\frac{1}{2}|\nabla u|^{2}+F(u)-u \theta-\frac{1}{2} \theta^{2}\right) \mathrm{d} x, \tag{1.3}
\end{equation*}
$$

where $\Omega$ is the domain occupied by the material (we assume that it is a bounded and smooth domain of $\mathbb{R}^{n}, n=2$ or 3 ) and $F^{\prime}=f$ (typically, $F$ is the double-well potential $F(s)=\frac{1}{4}\left(s^{2}-1\right)^{2}$, hence
$\left.f(s)=s^{3}-s\right)$. We then introduce the enthalpy $H$ defined by

$$
\begin{equation*}
H=-\partial_{\theta} \psi, \tag{1.4}
\end{equation*}
$$

where $\partial$ denotes a variational derivative, so that

$$
\begin{equation*}
H=u+\theta . \tag{1.5}
\end{equation*}
$$

The gouverning equations for $u$ and $\theta$ are finally given by

$$
\begin{gather*}
\frac{\partial u}{\partial t}=\Delta \partial_{u} \psi  \tag{1.6}\\
\frac{\partial H}{\partial t}=-\operatorname{div} q \tag{1.7}
\end{gather*}
$$

where $q$ is the thermal flux vector. Assuming the classical Fourier law

$$
\begin{equation*}
q=-\nabla \theta \tag{1.8}
\end{equation*}
$$

we obtain (1.1) and (1.2).
Now, one drawback of the Fourier law is that it predicts that thermal signals propagate with an infinite speed, which violates causality (the so-called "paradox of heat conduction", see, e.g. [5]). Therefore, several modifications of (1.8) have been proposed in the literature to correct this unrealistic feature, leading to a second order in time equation for the temperature.

In particular, we considered in [15] (see also [19] the Maxwell-Cattaneo law)

$$
\begin{equation*}
\left(1+\eta \frac{\partial}{\partial t}\right) q=-\nabla \theta, \quad \eta>0 \tag{1.9}
\end{equation*}
$$

which leads to

$$
\begin{equation*}
\eta \frac{\partial^{2} \theta}{\partial t^{2}}+\frac{\partial \theta}{\partial t}-\Delta \theta=-\eta \frac{\partial^{2} u}{\partial t^{2}}-\frac{\partial u}{\partial t} . \tag{1.10}
\end{equation*}
$$

Green and Naghdi proposed in [21] an alternative treatment for a thermomechanical theory of deformable media. This theory is based on an entropy balance rather than the usual entropy inequality and is proposed in a very rational way. If we restrict our attention to the heat conduction, we recall that proposed three different theories, labelled as type I, type II and type III, respectively. In particular, when type I is linearized, we recover the classical theory based on the Fourier law. The linearized versions of the two other theories are decribed by the constitutive equation of type II (see [12])

$$
\begin{equation*}
q=-k \nabla \alpha, \quad k>0, \tag{1.11}
\end{equation*}
$$

where

$$
\begin{equation*}
\alpha(t)=\int_{t_{0}}^{t} \theta(\tau) \mathrm{d} \tau+\alpha_{0} \tag{1.12}
\end{equation*}
$$

is called the thermal displacement variable. It is pertinent to note that these theories have received much attention in the recent years.

If we add the constitutive equation (1.9) to equation (1.7), we then obtain the following equations for $\alpha$ (note that $\frac{\partial \alpha}{\partial t}=\theta$ ):

$$
\begin{equation*}
\frac{\partial^{2} \alpha}{\partial t^{2}}-k \Delta \alpha=-\frac{\partial u}{\partial t} . \tag{1.13}
\end{equation*}
$$

Our aim in this paper is to study the model consisting the equation (1.1) $\left(\theta=\frac{\partial \alpha}{\partial t}\right)$ and the temperature equation (1.13). In particular, we obtain the existence and the uniqueness of the solutions.

## 2. Setting of the problem

We consider the following initial and boundary value problem (for simplificity, we take $k=1$ ):

$$
\begin{gather*}
\frac{\partial u}{\partial t}+\Delta^{2} u-\Delta f(u)=-\Delta \frac{\partial \alpha}{\partial t},  \tag{2.1}\\
\frac{\partial^{2} \alpha}{\partial t^{2}}-\Delta \alpha=-\frac{\partial u}{\partial t},  \tag{2.2}\\
u=\Delta u=\alpha=0 \quad \text { on } \quad \Gamma,  \tag{2.3}\\
\left.u\right|_{t=0}=u_{0},\left.\quad \alpha\right|_{t=0}=\alpha_{0},\left.\quad \frac{\partial \alpha}{\partial t}\right|_{t=0}=\alpha_{1}, \tag{2.4}
\end{gather*}
$$

where $\Gamma$ is the boundary of the spatial domain $\Omega$.
We make the following assumptions:

$$
\begin{gather*}
f \text { is of class } C^{2}(\mathbb{R}), \quad f(0)=0  \tag{2.5}\\
f^{\prime}(s) \geqslant-c_{0}, \quad c_{0} \geqslant 0, \quad s \in \mathbb{R}  \tag{2.6}\\
f(s) s \geqslant c_{1} F(s)-c_{2} \geqslant-c_{3}, \quad c_{1}>0, \quad c_{2}, c_{3} \geqslant 0, \quad s \in \mathbb{R} \tag{2.7}
\end{gather*}
$$

where $F(s)=\int_{0}^{s} f(\tau) \mathrm{d} \tau$. In particular, the usual cubic nonlinear term $f(s)=s^{3}-s$ satisfies these assumptions.

We futher assume that

$$
\begin{equation*}
u_{0} \in H_{0}^{1}(\Omega) \cap H^{2}(\Omega) . \tag{2.8}
\end{equation*}
$$

Remark 2.1. We take here, for simplicity, Dirichlet boundary conditions. However, we can obtain the same results for Neumann boundary conditions, namely,

$$
\begin{equation*}
\frac{\partial u}{\partial v}=\frac{\partial \Delta u}{\partial v}=\frac{\partial \alpha}{\partial v}=0 \quad \text { on } \quad \Gamma, \tag{2.9}
\end{equation*}
$$

where $v$ denotes the unit outer normal to $\Gamma$. To do so, we rewrite, owing to (2.1) and (2.2), the equations in the form

$$
\begin{gather*}
\frac{\partial \bar{u}}{\partial t}+\Delta^{2} \bar{u}-\Delta(f(u)-\langle f(u)\rangle)=-\Delta \frac{\partial \bar{\alpha}}{\partial t}  \tag{2.10}\\
\frac{\partial^{2} \bar{\alpha}}{\partial t^{2}}-\Delta \bar{\alpha}=-\frac{\partial \bar{u}}{\partial t} \tag{2.11}
\end{gather*}
$$

where $\bar{v}=v-\langle v\rangle,\left|\left\langle v_{0}\right\rangle\right| \leqslant M_{1},\left|\left\langle\alpha_{0}\right\rangle\right| \leqslant M_{2}$, for fixed positive constants $M_{1}$ and $M_{2}$. Then, we note that

$$
v \mapsto\left(\left\|(-\Delta)^{-\frac{1}{2}} \bar{v}\right\|^{2}+\langle\nu\rangle^{2}\right)^{\frac{1}{2}},
$$

where, here, $-\Delta$ denotes the minus Laplace operator with Neumann boundary conditions and acting on functions with null average and where it is understood that

$$
\langle.\rangle=\frac{1}{\operatorname{vol}(\Omega)}\langle., 1\rangle_{H^{-1}(\Omega), H^{1}(\Omega)} .
$$

Furthermore,

$$
\begin{aligned}
v & \mapsto\left(\|\bar{v}\|^{2}+\langle v\rangle^{2}\right)^{\frac{1}{2}}, \\
v & \mapsto\left(\|\nabla \bar{v}\|^{2}+\langle v\rangle^{2}\right)^{\frac{1}{2}},
\end{aligned}
$$

and

$$
v \mapsto\left(\|\Delta \overline{\|}\|^{2}+\langle\nu\rangle^{2}\right)^{\frac{1}{2}}
$$

are norms in $H^{-1}(\Omega), L^{2}(\Omega), H^{1}(\Omega)$ and $H^{2}(\Omega)$, respectively, which are equivalent to the usual ones. We further assume that

$$
\begin{equation*}
|f(s)| \leqslant \epsilon F(s)+c_{\epsilon}, \quad \forall \epsilon>0, \quad s \in \mathbb{R} \tag{2.12}
\end{equation*}
$$

which allows to deal with term $\langle f(u)\rangle$.
We denote by $\|$.$\| the usual L^{2}$-norm (with associated scalar product ((...))) and set $\|\cdot\|_{-1}=\left\|(-\Delta)^{-\frac{1}{2}}.\right\|$, where $-\Delta$ denotes the minus Laplace operator with Dirichlet boundary conditions. More generally, $\|.\|_{X}$ denotes the norm in the Banach space X.

Throughout this paper, the same letters $c, c^{\prime}$ and $c^{\prime \prime}$ denotes (generally positive) constants which may change from line to line, or even in a same line. Similary, the same letter $Q$ denotes monotone increasing (with respect to each argument) functions which may change from line to line, or even in a same line.

## 3. A priori estimates

The estimates derived in this section are formal, but they can easily be justified within a Galerkin scheme.

We rewrite (2.1) in the equivalent form

$$
\begin{equation*}
(-\Delta)^{-1} \frac{\partial u}{\partial t}-\Delta u+f(u)=\frac{\partial \alpha}{\partial t} . \tag{3.1}
\end{equation*}
$$

We multiply (3.1) by $\frac{\partial u}{\partial t}$ and have, integrating over $\Omega$ and by parts,

$$
\begin{equation*}
\frac{d}{d t}\left(\|\nabla u\|^{2}+2 \int_{\Omega} F(u) \mathrm{d} x\right)+2\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2}=2\left(\left(\frac{\partial \alpha}{\partial t}, \frac{\partial u}{\partial t}\right)\right) \tag{3.2}
\end{equation*}
$$

We then multiply (2.2) by $\frac{\partial \alpha}{\partial t}$ and obtain

$$
\begin{equation*}
\frac{d}{d t}\left(\|\nabla \alpha\|^{2}+\left\|\frac{\partial \alpha}{\partial t}\right\|^{2}\right)=-2\left(\left(\frac{\partial \alpha}{\partial t}, \frac{\partial u}{\partial t}\right)\right) \tag{3.3}
\end{equation*}
$$

Summing (3.2) and (3.3), we find a differential inequality of the form

$$
\begin{equation*}
\frac{d E_{1}}{d t}+c\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2} \leqslant c^{\prime}, \quad c>0, \tag{3.4}
\end{equation*}
$$

where

$$
E_{1}=\|\nabla u\|^{2}+2 \int_{\Omega} F(u) \mathrm{d} x+\|\nabla \alpha\|^{2}+\left\|\frac{\partial \alpha}{\partial t}\right\|^{2}
$$

satisfies

$$
\begin{equation*}
E_{1} \geqslant c\left(\|u\|_{H^{1}(\Omega)}+\int_{\Omega} F(u) \mathrm{d} x+\|\alpha\|_{H^{1}(\Omega)}^{2}+\left\|\frac{\partial \alpha}{\partial t}\right\|^{2}\right)-c^{\prime}, \quad c>0, \tag{3.5}
\end{equation*}
$$

hence estimates on $u, \alpha \in L^{\infty}\left(0, T ; H_{0}^{1}(\Omega)\right)$, on $\frac{\partial u}{\partial t} \in L^{2}\left(0, T ; H^{-1}(\Omega)\right)$ and on $\frac{\partial \alpha}{\partial t} \in L^{\infty}\left(0, T ; L^{2}(\Omega)\right)$.
We multiply (3.1) by $-\Delta \frac{\partial u}{\partial t}$ to find

$$
\frac{1}{2} \frac{d}{d t}\|\Delta u\|^{2}+\left\|\frac{\partial u}{\partial t}\right\|^{2}=\left(\left(\Delta f(u), \frac{\partial u}{\partial t}\right)\right)-\left(\left(\Delta \frac{\partial \alpha}{\partial t}, \frac{\partial u}{\partial t}\right)\right),
$$

which yields, owing to (2.5) and the continuous embedding $H^{2}(\Omega) \subset C(\bar{\Omega})$,

$$
\begin{equation*}
\frac{d}{d t}\|\Delta u\|^{2}+\left\|\frac{\partial u}{\partial t}\right\|^{2} \leqslant Q\left(\|u\|_{H^{2}(\Omega)}\right)-2\left(\left(\Delta \frac{\partial \alpha}{\partial t}, \frac{\partial u}{\partial t}\right)\right) . \tag{3.6}
\end{equation*}
$$

Multiplying also (2.2) by $-\Delta \frac{\partial \alpha}{\partial t}$, we have

$$
\begin{equation*}
\frac{d}{d t}\left(\|\Delta \alpha\|^{2}+\left\|\nabla \frac{\partial \alpha}{\partial t}\right\|^{2}\right)=2\left(\left(\Delta \frac{\partial \alpha}{\partial t}, \frac{\partial u}{\partial t}\right)\right) . \tag{3.7}
\end{equation*}
$$

Summing then (3.6) and (3.7), we obtain

$$
\begin{equation*}
\frac{d}{d t}\left(\|\Delta u\|^{2}+\|\Delta \alpha\|^{2}+\left\|\nabla \frac{\partial \alpha}{\partial t}\right\|^{2}\right)+\left\|\frac{\partial u}{\partial t}\right\|^{2} \leqslant Q\left(\|u\|_{H^{2}(\Omega)}\right) \tag{3.8}
\end{equation*}
$$

In particular, setting

$$
y=\|\Delta u\|^{2}+\|\Delta \alpha\|^{2}+\left\|\nabla \frac{\partial \alpha}{\partial t}\right\|^{2}
$$

we deduce from (3.8) an inequation of the form

$$
\begin{equation*}
y^{\prime} \leqslant Q(y) . \tag{3.9}
\end{equation*}
$$

Let z be the solution to the ordinary differential equation

$$
\begin{equation*}
z^{\prime}=Q(z), \quad z(0)=y(0) . \tag{3.10}
\end{equation*}
$$

It follows from the comparison principle that there exists $T_{0}=T_{0}\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right)$ belonging to, say, $\left(0, \frac{1}{2}\right)$ such that

$$
\begin{equation*}
y(t) \leqslant z(t), \quad \forall t \in\left[0, T_{0}\right], \tag{3.11}
\end{equation*}
$$

hence

$$
\begin{equation*}
\|u(t)\|_{H^{2}(\Omega)}^{2}+\|\alpha(t)\|_{H^{2}(\Omega)}^{2}+\left\|\frac{\partial \alpha}{\partial t}(t)\right\|_{H^{1}(\Omega)}^{2} \leqslant Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right), \quad t \leqslant T_{0} . \tag{3.12}
\end{equation*}
$$

We now differentiate (3.1) with respect to time and have, noting that $\frac{\partial^{2} \alpha}{\partial t^{2}}=\Delta \alpha-\frac{\partial u}{\partial t}$,

$$
\begin{equation*}
(-\Delta)^{-1} \frac{\partial}{\partial t} \frac{\partial u}{\partial t}-\Delta \frac{\partial u}{\partial t}+f^{\prime}(u) \frac{\partial u}{\partial t}=\Delta \alpha-\frac{\partial u}{\partial t} . \tag{3.13}
\end{equation*}
$$

We multiply (3.13) by $t \frac{\partial u}{\partial t}$ and find, owing to (2.6)

$$
\frac{d}{d t}\left(t\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2}\right)+\frac{3}{2} t\left\|\nabla \frac{\partial u}{\partial t}\right\|^{2} \leqslant c t\left(\left\|\frac{\partial u}{\partial t}\right\|^{2}+\|\nabla \alpha\|^{2}\right)+\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2},
$$

hence, noting that $\left\|\frac{\partial u}{\partial t}\right\|^{2} \leqslant c\left\|\frac{\partial u}{\partial t}\right\|-1\left\|\nabla \frac{\partial u}{\partial t}\right\|$,

$$
\begin{equation*}
\frac{d}{d t}\left(t\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2}\right)+t\left\|\nabla \frac{\partial u}{\partial t}\right\|^{2} \leqslant c t\left(\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2}+\|\nabla \alpha\|^{2}\right)+\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2} . \tag{3.14}
\end{equation*}
$$

In particular, we deduce from (3.4), (3.12), (3.14) and Gronwall's lemma that

$$
\begin{equation*}
\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2} \leqslant \frac{1}{t} Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right), \quad t \in\left(0, T_{0}\right] . \tag{3.15}
\end{equation*}
$$

Multiplying then (3.13) by $\frac{\partial u}{\partial t}$, we have, proceeding as above,

$$
\begin{equation*}
\frac{d}{d t}\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2}+\left\|\nabla \frac{\partial u}{\partial t}\right\|^{2} \leqslant c\left(\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2}+\|\nabla \alpha\|^{2}\right) . \tag{3.16}
\end{equation*}
$$

It thus follows from (3.4), (3.16) and Gronwall's lemma that

$$
\begin{equation*}
\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2} \leqslant e^{c t} Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right)\left\|\frac{\partial u}{\partial t}\left(T_{0}\right)\right\|_{-1}^{2}, \quad t \geqslant T_{0}, \tag{3.17}
\end{equation*}
$$

hence, owing to (3.15),

$$
\begin{equation*}
\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2} \leqslant e^{c t} Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right), \quad t \geqslant T_{0} . \tag{3.18}
\end{equation*}
$$

We now rewrite (3.1) in the forme

$$
\begin{equation*}
-\Delta u+f(u)=h_{u}(t), \quad u=0 \quad \text { on } \quad \Gamma, \tag{3.19}
\end{equation*}
$$

for $t \geqslant T_{0}$ fixed, where

$$
\begin{equation*}
h_{u}(t)=-(-\Delta)^{-1} \frac{\partial u}{\partial t}+\frac{\partial \alpha}{\partial t} \tag{3.20}
\end{equation*}
$$

satisfies, owing to (3.4) and (3.18)

$$
\begin{equation*}
\left\|h_{u}(t)\right\| \leqslant e^{c t} Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right), \quad t \geqslant T_{0} . \tag{3.21}
\end{equation*}
$$

We multiply (3.19) by $u$ and have, noting that $f(s) s \geqslant-c, c \geqslant 0, s \in \mathbb{R}$,

$$
\begin{equation*}
\|\nabla u\|^{2} \leqslant c\left\|h_{u}(t)\right\|^{2}+c^{\prime} \tag{3.22}
\end{equation*}
$$

Then, multipying (3.19) by $-\Delta u$, we find, owing to (2.6),

$$
\begin{equation*}
\|\Delta u\|^{2} \leqslant c\left(\left\|h_{u}(t)\right\|^{2}+\|\nabla u\|^{2}\right) . \tag{3.23}
\end{equation*}
$$

We thus deduce from (3.21) - (3.23) that

$$
\begin{equation*}
\|u(t)\|_{H^{2}(\Omega)}^{2} \leqslant e^{c t} Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right), \quad t \geqslant T_{0}, \tag{3.24}
\end{equation*}
$$

and, thus, owing to (3.12)

$$
\begin{equation*}
\|u(t)\|_{H^{2}(\Omega)}^{2} \leqslant e^{c t} Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right), \quad t \geqslant 0 . \tag{3.25}
\end{equation*}
$$

Returning to (3.7), we have

$$
\begin{equation*}
\frac{d}{d t}\left(\|\Delta \alpha\|^{2}+\left\|\nabla \frac{\partial \alpha}{\partial t}\right\|^{2}\right) \leqslant\left\|\Delta \frac{\partial \alpha}{\partial t}\right\|^{2}+\left\|\frac{\partial u}{\partial t}\right\|^{2} . \tag{3.26}
\end{equation*}
$$

Noting that it follows from (3.4), (3.16) and (3.18) that

$$
\begin{equation*}
\int_{T_{0}}^{t}\left(\left\|\Delta \frac{\partial \alpha}{\partial t}\right\|^{2}+\left\|\frac{\partial u}{\partial t}\right\|^{2}\right) \mathrm{d} \tau \leqslant e^{c t} Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right), \quad t \geqslant T_{0} \tag{3.27}
\end{equation*}
$$

we finally deduce from (3.12) and (3.25) - (3.27) that

$$
\begin{equation*}
\|u(t)\|_{H^{2}(\Omega)}^{2}+\|\alpha(t)\|_{H^{2}(\Omega)}^{2}+\left\|\frac{\partial \alpha}{\partial t}(t)\right\|_{H^{1}(\Omega)}^{2} \leqslant e^{c t} Q\left(\left\|u_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}\right\|_{H^{2}(\Omega)},\left\|\alpha_{1}\right\|_{H^{1}(\Omega)}\right), \quad t \geqslant 0 \tag{3.28}
\end{equation*}
$$

## 4. Existence and uniqueness of solutions

We first have the following.
Theorem 4.1. We assume that (2.5) - (2.8) hold and ( $\alpha_{0}, \alpha_{1}$ ) $\left(H_{0}^{1}(\Omega) \cap H^{2}(\Omega)\right) \times H_{0}^{1}(\Omega)$. Then, (2.1) - (2.4) possesses at last one solution ( $u, \alpha, \frac{\partial \alpha}{\partial t}$ ) such that

$$
u, \alpha \in L^{\infty}\left(0, T ; H_{0}^{1}(\Omega) \cap H^{2}(\Omega)\right), \quad \frac{\partial u}{\partial t} \in L^{2}\left(0, T ; H^{-1}(\Omega)\right) \quad \text { and } \quad \frac{\partial \alpha}{\partial t} \in L^{\infty}\left(0, T ; H_{0}^{1}(\Omega)\right) .
$$

Proof. The proof is based on (3.28) and, e.g., a standard Galerkin scheme.
We have, concerning the uniqueness, the following.
Theorem 4.2. We assume that the assumptions of Theorem 4.1 hold. Then, the solution obtained in Theorem 4.1 is unique

Proof. Let ( $u^{(1)}, \alpha^{(1)}, \frac{\partial \alpha^{(1)}}{\partial t}$ ) and ( $u^{(2)}, \alpha^{(2)}, \frac{\partial \alpha^{(2)}}{\partial t}$ ) be two solutions to (2.1) - (2.3) with initial data $\left(u_{0}^{(1)}, \alpha_{0}^{(1)}, \alpha_{1}^{(1)}\right)$ and $\left(u_{0}^{(2)}, \alpha_{0}^{(2)}, \alpha_{1}^{(2)}\right)$, respectively. We set

$$
\left(u, \alpha, \frac{\partial \alpha}{\partial t}\right)=\left(u^{(1)}, \alpha^{(1)}, \frac{\partial \alpha^{(1)}}{\partial t}\right)-\left(u^{(2)}, \alpha^{(2)}, \frac{\partial \alpha^{(2)}}{\partial t}\right)
$$

and

$$
\left(u_{0}, \alpha_{0}, \alpha_{1}\right)=\left(u_{0}^{(1)}, \alpha_{0}^{(1)}, \alpha_{1}^{(1)}\right)-\left(u_{0}^{(2)}, \alpha_{0}^{(2)}, \alpha_{1}^{(2)}\right)
$$

Then, $(u, \alpha)$ satisfies

$$
\begin{gather*}
\frac{\partial u}{\partial t}+\Delta^{2} u-\Delta\left(f\left(u^{(1)}\right)-f\left(u^{(2)}\right)\right)=-\Delta \frac{\partial \alpha}{\partial t}  \tag{4.1}\\
\frac{\partial^{2} \alpha}{\partial t^{2}}-\Delta \alpha=-\frac{\partial u}{\partial t}  \tag{4.2}\\
u=\alpha=0 \quad \text { on } \quad \partial \Omega  \tag{4.3}\\
\left.u\right|_{t=0}=u_{0},\left.\alpha\right|_{t=0}=\alpha_{0},\left.\frac{\partial \alpha}{\partial t}\right|_{t=0}=\alpha_{1} \tag{4.4}
\end{gather*}
$$

We multiply (4.1) by $(-\Delta)^{-1} \frac{\partial u}{\partial t}$ and (4.2) by $\frac{\partial \alpha}{\partial t}$ and have, summing the two resulting equations,

$$
\begin{equation*}
\frac{d}{d t}\left(\|\nabla u\|^{2}+\|\nabla \alpha\|^{2}+\left\|\frac{\partial \alpha}{\partial t}\right\|^{2}\right)+\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2} \leqslant\left\|\nabla\left(f\left(u^{(1)}\right)-f\left(u^{(2)}\right)\right)\right\|^{2} . \tag{4.5}
\end{equation*}
$$

Furthermore,

$$
\begin{align*}
& \| \nabla\left(f\left(u^{(1)}\right)-f\left(u^{(2)}\right)\|=\| \nabla\left(\int_{0}^{1} f^{\prime}\left(u^{(1)}+s\left(u^{(2)}-u^{(1)}\right)\right) \mathrm{d} s u\right) \|\right. \\
& \leqslant\left\|\int_{0}^{1} f^{\prime}\left(u^{(1)}+s\left(u^{(2)}-u^{(1)}\right)\right) \mathrm{d} s \nabla u\right\|+\left\|\int_{0}^{1} f^{\prime \prime}\left(u^{(1)}+s\left(u^{(2)}-u^{(1)}\right)\right)\left(\nabla u^{(1)}+s \nabla\left(u^{(2)}-u^{(1)}\right)\right) \mathrm{d} s u\right\| \\
& \leqslant Q\left(\left\|u_{0}^{(1)}\right\|_{H^{2}(\Omega)},\left\|u_{0}^{(2)}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}^{(1)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{0}^{(2)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{1}^{(1)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{1}^{(2)}\right\|_{H^{1}(\Omega)}\right) \\
& \times\left(\|\nabla u\|+\|u\| \nabla u^{(1)}\|+\| u\left\|\nabla u^{(2)}\right\|\right) \\
& \leqslant Q\left(\left\|u_{0}^{(1)}\right\|_{H^{2}(\Omega)},\left\|u_{0}^{(2)}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}^{(1)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{0}^{(2)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{1}^{(1)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{1}^{(2)}\right\|_{H^{1}(\Omega)}\right)\|\nabla u\| . \tag{4.6}
\end{align*}
$$

We thus deduce from (4.5) and (4.6) that

$$
\begin{align*}
& \frac{d}{d t}\left(\|\nabla u\|^{2}+\|\nabla \alpha\|^{2}+\left\|\frac{\partial \alpha}{\partial t}\right\|^{2}\right)+\left\|\frac{\partial u}{\partial t}\right\|_{-1}^{2} \\
& \leqslant Q\left(\left\|u_{0}^{(1)}\right\|_{H^{2}(\Omega)},\left\|u_{0}^{(2)}\right\|_{H^{2}(\Omega)},\left\|\alpha_{0}^{(1)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{0}^{(2)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{1}^{(1)}\right\|_{H^{1}(\Omega)},\left\|\alpha_{1}^{(2)}\right\|_{H^{1}(\Omega)}\right)\|\nabla u\|^{2} \tag{4.7}
\end{align*}
$$

In particular, we have a differential inequality of the form

$$
\begin{equation*}
\frac{d E_{2}}{d t} \leqslant Q E_{2} \tag{4.8}
\end{equation*}
$$

where

$$
E_{2}=\|\nabla u\|^{2}+\|\nabla \alpha\|^{2}+\left\|\frac{\partial \alpha}{\partial t}\right\|^{2}
$$

satisfies

$$
\begin{equation*}
E_{2} \geqslant c\left(\|u\|_{H^{1}(\Omega)}^{2}+\|\alpha\|_{H^{1}(\Omega)}^{2}+\left\|\frac{\partial \alpha}{\partial t}\right\|^{2}\right)-c^{\prime} . \tag{4.9}
\end{equation*}
$$

It follows from (4.8) - (4.9) and Gronwall's lemma that
hence the uniqueness, as well as the continuous dependence with respect to the initial data in the $H^{1} \times H^{1} \times L^{2}$-norm.

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## Conflict of interest

All authors declare no conflicts of interest in this paper.

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