



Research article

# Non-singular solutions of $p$ -Laplace problems, allowing multiple changes of sign in the nonlinearity

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**Abstract:** For the  $p$ -Laplace Dirichlet problem (where  $\varphi(t) = t|t|^{p-2}$ ,  $p > 1$ )

$$\varphi(u'(x))' + f(u(x)) = 0 \quad \text{for } -1 < x < 1, \quad u(-1) = u(1) = 0$$

assume that  $f'(u) > (p - 1)\frac{f(u)}{u} > 0$  for  $u > \gamma > 0$ , while  $\int_u^\gamma f(t) dt < 0$  for all  $u \in (0, \gamma)$ . Then any positive solution, with  $\max_{(-1,1)} u(x) = u(0) > \gamma$ , is non-singular, no matter how many times  $f(u)$  changes sign on  $(0, \gamma)$ . The uniqueness of solution follows.

**Keywords:** non-singular positive solutions;  $p$ -Laplace problems

We consider positive solutions of

$$\varphi(u'(x))' + f(u(x)) = 0 \quad \text{for } -1 < x < 1, \quad u(-1) = u(1) = 0, \tag{1}$$

where  $\varphi(t) = t|t|^{p-2}$ ,  $p > 1$ , so that  $\varphi'(t) = (p - 1)|t|^{p-2}$ . The linearized problem is

$$\begin{aligned} (\varphi'(u'(x))w'(x))' + f'(u(x))w(x) &= 0 \quad \text{for } -1 < x < 1, \\ w(-1) = w(1) &= 0. \end{aligned} \tag{2}$$

Recall that any positive solution of (1) is an even function  $u(-x) = u(x)$ , satisfying  $xu'(x) < 0$  for  $x \neq 0$  so that  $\max_{(-1,1)} u(x) = u(0)$ , and that any non-trivial solution of (2) is of one sign, so that we may assume that  $w(x) > 0$  for  $x \in (-1, 1)$ , see e.g., P. Korman [5], [6].

If  $f'(u) > (p - 1)\frac{f(u)}{u} > 0$  for  $u > 0$ , it is well known that any positive solution of (1) is *non-singular*, i.e., the problem (2) admits only the trivial solution  $w(x) \equiv 0$ . Now suppose that  $f'(u) > (p - 1)\frac{f(u)}{u} > 0$  holds only for  $u > \gamma$ , for some  $\gamma > 0$ . It turns out that positive solutions of (1), with maximum value greater than  $\gamma$  are still non-singular, provided that  $\int_u^\gamma f(t) dt < 0$  for all  $u \in (0, \gamma)$ . The main result is stated next. It is customary to denote  $F(u) = \int_0^u f(t) dt$ .

**Theorem 1.** Assume that  $f(u) \in C^1(\bar{R}_+)$ , and for some  $\gamma > 0$  it satisfies

$$f(\gamma) = 0, \text{ and } f(u) > 0 \text{ on } (\gamma, \infty), \quad (3)$$

$$f'(u) > (p-1)\frac{f(u)}{u}, \text{ for } u > \gamma, \quad (4)$$

$$F(\gamma) - F(u) = \int_u^\gamma f(t) dt < 0, \text{ for } u \in (0, \gamma). \quad (5)$$

Then any positive solution of (1), satisfying

$$u(0) > \gamma, \text{ and } u'(1) < 0, \quad (6)$$

is non-singular, which means that the linearized problem (2) admits only the trivial solution.

In case  $p = 2$  this result was proved in P. Korman [7], while for general  $p > 1$  a weaker result, requiring that  $f(u) < 0$  on  $(0, \gamma)$ , was given in J. Cheng [3] (and before that by R. Schaaf [10] for  $p = 2$  case), see also P. Korman [5], [6] for a different proof, and a more detailed description of the solution curve. Other multiplicity results on  $p$ -Laplace equations include [1], [2], [4] and [9].

**Proof:** Assume, on the contrary, that the problem (2) admits a non-trivial solution  $w(x) > 0$ . Let  $x_0 \in (0, 1)$  denote the point where  $u(x_0) = \gamma$ . Define

$$q(x) = (p-1)(1-x)\varphi(u'(x)) + \varphi'(u'(x))u(x).$$

We claim that

$$q(x_0) < 0. \quad (7)$$

Rewrite (using that  $(p-1)\varphi(t) = t\varphi'(t)$ )

$$q(x) = \varphi'(u'(x))[(1-x)u'(x) + u(x)].$$

Since  $\varphi'(t) > 0$  for all  $t \neq 0$ , it suffices to show that the function  $z(x) \equiv (1-x)u'(x) + u(x) < 0$  satisfies  $z(x_0) < 0$ . Indeed,

$$z(x_0) = \int_{x_0}^1 [u'(x_0) - u'(x)] dx < 0,$$

which implies the desired inequality (7), provided we can prove that

$$u'(x_0) - u'(x) < 0, \text{ for } x \in (x_0, 1). \quad (8)$$

The “energy” function  $E(x) = \frac{p-1}{p}|u'(x)|^p + F(u(x))$  is seen by differentiation to be a constant, so that  $E(x) = E(x_0)$ , or

$$\frac{p-1}{p}|u'(x)|^p + F(u(x)) = \frac{p-1}{p}|u'(x_0)|^p + F(\gamma), \text{ for all } x.$$

By the assumption (5), it follows that

$$\frac{p-1}{p}[|u'(x)|^p - |u'(x_0)|^p] = F(\gamma) - F(u(x)) < 0, \text{ for } x \in (x_0, 1),$$

justifying (8), and then giving (7).

Next, we claim that

$$(p-1)w(x_0)\varphi(u'(x_0)) - u(x_0)w'(x_0)\varphi'(u'(x_0)) > 0, \quad (9)$$

which implies, in particular, that

$$w'(x_0) < 0. \quad (10)$$

Indeed, by a direct computation, using (1) and (2),

$$[(p-1)w(x)\varphi(u'(x)) - u(x)w'(x)\varphi'(u'(x))]' = \left[ f'(u) - (p-1)\frac{f(u)}{u} \right] uw.$$

The quantity on the right is positive on  $(0, x_0)$ , in view of our condition (4). Integration over  $(0, x_0)$ , gives (9).

We have for all  $x \in [-1, 1]$

$$\varphi'(u')(u'w' - u''w) = \text{constant} = \varphi'(u'(1))u'(1)w'(1) > 0, \quad (11)$$

as follows by differentiation, and using the assumption  $u'(1) < 0$ . Hence

$$u'(x)w'(x) - u''(x)w(x) > 0, \quad \text{for } x \in (x_0, 1). \quad (12)$$

Since  $f(u(x_0)) = 0$ , it follows from Eq (1) that  $u''(x_0) = 0$ . Then (11) implies

$$\begin{aligned} \varphi'(u'(1))u'(1)w'(1) &= \varphi'(u'(x_0))u'(x_0)w'(x_0) \\ &= (p-1)\varphi(u'(x_0))w'(x_0). \end{aligned} \quad (13)$$

We need the following function, motivated by M. Tang [11] (which was introduced in P. Korman [5], and used in Y. An et al. [2])

$$T(x) = x[(p-1)\varphi(u'(x))w'(x) + f(u(x))w(x)] - (p-1)\varphi(u'(x))w(x).$$

One verifies that

$$T'(x) = pf(u(x))w(x). \quad (14)$$

Integrating (14) over  $(x_0, 1)$ , and using (5) and (12), obtain

$$\begin{aligned} T(1) - T(x_0) &= p \int_{x_0}^1 f(u(x))w(x) dx \\ &= p \int_{x_0}^1 [F(u(x)) - F(\gamma)]' \frac{w(x)}{u'(x)} dx \\ &= -p \int_{x_0}^1 [F(u(x)) - F(\gamma)] \frac{w'(x)u'(x) - w(x)u''(x)}{u'^2(x)} dx < 0, \end{aligned}$$

which implies that

$$L \equiv (p - 1)\varphi(u'(1))w'(1) - (p - 1)x_0\varphi(u'(x_0))w'(x_0) + (p - 1)\varphi(u'(x_0))w(x_0) < 0.$$

On the other hand, using (13), then (9), followed by (10) and (7), we estimate the same quantity as follows

$$\begin{aligned} L &> (p - 1)\varphi(u'(x_0))w'(x_0) - (p - 1)x_0\varphi(u'(x_0))w'(x_0) + u(x_0)w'(x_0)\varphi'(u'(x_0)) \\ &= w'(x_0)q(x_0) > 0, \end{aligned}$$

a contradiction. ◇

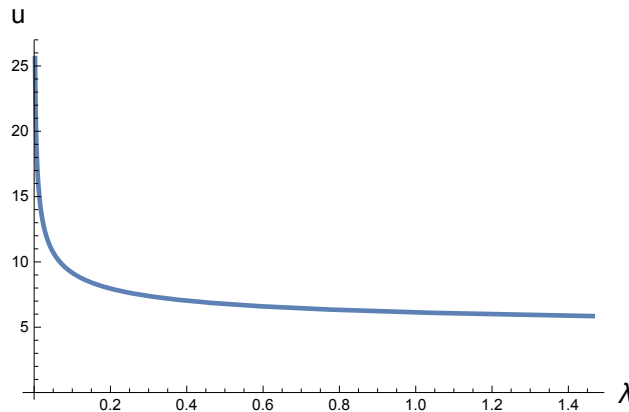
We remark that in case  $f(0) < 0$  it is possible to have a singular positive solution with  $u'(1) = 0$ , so that the assumption  $u'(1) < 0$  is necessary.

We now consider the problem (where  $\varphi(t) = t|t|^{p-2}$ ,  $p > 1$ )

$$\varphi(u'(x))' + \lambda f(u(x)) = 0 \quad \text{for } -1 < x < 1, \quad u(-1) = u(1) = 0, \tag{15}$$

depending on a positive parameter  $\lambda$ . The following result follows the same way as the Theorem 3.1 in [5].

**Theorem 2.** *Assume that  $f(u) \in C^1(\bar{R}_+)$ , and the conditions (3), (4) and (5) hold. Then there exists  $0 < \lambda_0 \leq \infty$  so that the problem (15) has a unique positive solution for  $0 < \lambda < \lambda_0$ . All positive solutions, satisfying  $u(0) > \gamma$ , lie on a continuous solution curve that is decreasing in the  $(\lambda, u(0))$  plane (see Figure 1). In case  $f(0) < 0$ , one has  $\lambda_0 < \infty$ , and at  $\lambda = \lambda_0$  a positive solution with  $u'(\pm 1) = 0$  exists, and no positive solutions exist for  $\lambda > \lambda_0$ . In case  $f(0) = 0$  and  $f'(0) < 0$ , we have  $\lambda_0 = \infty$ .*



**Figure 1.** The curve of positive solutions for the problem (15), in case  $p = 3$  and  $f(u) = u(u - 1)(u - 2)(u - 4)$ .

**Example** In Figure 1 we present the solution curve of the problem (15) in case  $p = 3$  and  $f(u) = u(u - 1)(u - 2)(u - 4)$ . Here  $\gamma = 4$ , and one verifies that the Theorem 2 applies. The *Mathematica* program to perform numerical computations for this problem is explained in detail in [8] (it uses the shoot-and-scale method). The solution curve in Figure 1 exhausts the set of all positive solutions (since  $\int_0^2 f(u) du < 0$ , there are no solutions with  $u(0) = \max_{(-1,1)} u(x) \in (1, 2)$ ).

## Conflict of interest

The author declares there is no conflicts of interest.

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